

EE 641 Midterm Exam  
October 23, Fall 2014

Name: \_\_\_\_\_

**Instructions**

The following is an in-class closed-book exam.

- This exam contains 3 problems worth a total of 110 points.
- You may not use any notes, textbooks, or calculators.
- You are allowed up to 75 minutes to complete the exam.

Good luck.

**Problem 1.** (30pt)

Let  $X \sim N(0, R)$  where  $R$  is a  $p \times p$  symmetric positive-definite matrix. Further define the precision matrix,  $B = R^{-1}$ , and use the notation

$$B = \begin{bmatrix} 1/\sigma^2 & A \\ A^t & C \end{bmatrix},$$

where  $A \in \mathbb{R}^{1 \times (p-1)}$  and  $C \in \mathbb{R}^{(p-1) \times (p-1)}$ .

- a) Calculate the marginal density of  $X_1$ , the first component of  $X$ .
- b) Calculate the conditional density of  $X_1$  given all the remaining components,  $Y = [X_2, \dots, X_p]^t$ .
- c) What is the conditional mean and covariance of  $X_1$  given  $Y$ ?

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**Problem 2.** (40pt)

Let  $X_n$  be a 1-D zero-mean stationary Gaussian AR process with MMSE causal prediction filter given by  $h_n = \rho\delta_{n-1}$  and causal prediction variance  $\sigma_c^2$ .

- a) Calculate,  $S_X(\omega)$ , the power spectral density of the random process.
- b) Calculate,  $R_X(n)$ , the time autocorrelation of the random process.
- c) Sketch plots  $S_X(\omega)$  and  $R_X(n)$  for  $\rho = 0.95$ .
- d) Calculate  $(\sigma_{NC}^2, g_n)$  the noncausal prediction variance and the noncausal prediction filter for the equivalent GMRF.

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**Problem 3.** (40pt)

Consider the optimization problem

$$\hat{x} = \arg \min_{x \in \mathbb{R}^N} \{ \|y - Ax\|_{\Lambda}^2 + x^t B x \}$$

where  $A$  is a nonsingular  $N \times N$  matrix,  $B$  is a positive-definite  $N \times N$  matrix, and  $\Lambda$  is a diagonal and positive-definite matrix..

- a) Derive a closed form expression for the solution.
- b) Calculate an expression for the gradient descent update using step size  $\mu \geq 0$ .
- c) Calculate an expression for the update of gradient descent with line search.
- d) Calculate an expression for the coordinate descent update.

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