EE 641 Midterm Exam October 12, Fall 2012

Name:	Rey	
	/	Instructions

The following is an in-class closed-book exam. $\,$

- This exam contains 3 problems worth a total of 108 points.
- You may not use any notes, textbooks, or calculators.

Good luck.

Problem 1. (36pt)

Let $Y \in \mathbb{R}^M$ and $X \in \mathbb{R}^N$ be zero-mean jointly Gaussian random vectors. Then define the following notation for this problem. Let p(y,x) and p(y|x) be the joint and conditional density of Y given X. Let B be the joint positive-definite precision matrix (i.e., inverse covariance matrix) given by $B^{-1} = \mathbb{E}[ZZ^t]$ where $Z = \begin{bmatrix} Y \\ X \end{bmatrix}$. Furthermore, let C, D, and E be the matrix blocks that form B, so that

$$B = \left[\begin{array}{cc} C & D \\ D^t & E \end{array} \right] \ .$$

where $C \in \mathbb{R}^{M \times M}$, $D \in \mathbb{R}^{M \times N}$, and $E \in \mathbb{R}^{N \times N}$. Finally, define the matrix A so that $AX = \mathbb{E}[Y|X]$ and the matrix $\Lambda^{-1} = \mathbb{E}[YY^t|X]$.

- a) Write out an expression for p(y, x) in terms of B.
- b) Write out an expression for p(y|x) in terms of A and Λ .
- c) Derive an expression for Λ the in terms of C, D, and E.
- d) Derive an expression for A the in terms of C, D, and E.

a)
$$p(y,x) = \frac{1}{(2\pi)^{\frac{1}{2}}} \frac{1}{|B|^{\frac{1}{2}}} \exp \left\{-\frac{1}{2} \left[\frac{x}{x}\right]^{\frac{1}{2}} B\left[\frac{x}{x}\right]\right\}$$

C)
$$Y^{\dagger}CY + 2Y^{\dagger}DX + X^{\dagger}EX = Y^{\dagger}\Lambda Y - 2Y^{\dagger}\Lambda AX + X^{\dagger}A^{\dagger}\Lambda AX$$

$$A = C$$

$$A = A = D$$

$$A = -A^{-1}D$$

$$A = -C^{-1}D$$

Problem 2. (36pt)

Let X_n be a 1-D zero-mean Gaussian AR process with MMSE causal prediction filter given by $h_n = \rho \delta_{n-1}$ and causal prediction variance σ_C^2 .

- a) Calculate, $S_X(\omega)$, the power spectral density of the random process.
- b) Calculate, $R_X(n)$, the time autocorrelation of the random process.
- c) Calculate (σ_{NC}^2, g_n) the noncausal prediction variance and the noncausal prediction filter for the equivalent GMRF. Hint: Remember that

$$a) S_{x}(\omega) = \frac{\sigma_{NC}^{2}(\delta_{n} - h_{n}) * (\delta_{n} - h_{-n}) = \sigma_{C}^{2}(\delta_{n} - g_{n})}{|I - H(\omega)|^{2}} = \frac{\sigma_{C}^{2}}{|I - AC - F\omega|^{2}}$$

$$= \frac{\sigma_{C}^{2}}{|I + \rho^{2} - 2\rho \cos(\omega)}$$

$$= \frac{\sigma_{C}^{2}}{(I + \rho^{2})(I - \frac{2\rho}{I + \rho^{2}} \cos(\omega))}$$

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$$= \frac{\sigma_{C}^{2}}{(I + \rho^{2})(I - \frac{2\rho}{I + \rho^{2}} \cos(\omega))}$$

$$= \frac{\sigma_{C}^{2}}{I - \rho^{2}} \int_{-I + \rho}^{-I + \rho} \int_{-I +$$

Problem 3. (36pt)

Consider the optimization problem

$$\hat{x} = \arg\min_{x \in \mathbb{R}^N} \left\{ ||y - Ax||_{\Lambda}^2 + x^t Bx \right\}$$

where A is a nonsingular $N \times N$ matrix, B is a positive-definite $N \times N$ matrix, and Λ is a diagonal and positive-definite matrix..

- a) Derive a closed form expression for the solution.
- b) Calculate an expression for the gradient descent update using step size $\mu \geq 0$.
- c) Calculate an expression for the coordinate descent update.

a)
$$\nabla_{x} \left\{ (Y-Ax)^{\dagger} \mathcal{L} (Y-Ax) + x^{\dagger} Bx \right\} = 0$$

$$-2(Y-Ax)^{\dagger} \mathcal{L} A + 2x^{\dagger} B = 0$$

$$-A^{\dagger} \mathcal{L} (Y-Ax) + Bx = 0$$

$$-A^{\dagger} \mathcal{L} Y + A^{\dagger} \mathcal{L} Ax + Bx = 0$$

$$(A^{\dagger} \mathcal{L} Ax + B)x = A^{\dagger} \mathcal{L} Y$$

$$x = (A^{\dagger} \mathcal{L} A + B)^{-1} A^{\dagger} \mathcal{L} Y$$

$$b) x^{(K+1)} = x^{(K+1)} + x (A^{\dagger} \mathcal{L} (Y-Ax) - Bx)$$

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$$f(x) = y(e = x A_{xi})^{t} \Lambda(e - x A_{xi}) + (x + x E_{i})^{t} B(x - x E_{i})$$

$$f(x) = c + \theta_1 x + \frac{1}{2}\theta_2 x^2$$

$$O_1 = \frac{df(\kappa)}{d\alpha}\Big|_{\kappa=0} = -2e^{\frac{\pi}{2}} \Lambda A_{\kappa i} + 2x^{\frac{\pi}{2}} B_{\kappa i}$$

$$\theta_2 = \frac{\partial^2 f(x)}{\partial x} = 2A_{xi}^{\dagger} A_{xi} + 2B_{ii}$$

$$\frac{df(\alpha)}{d\alpha} = 0 = Q_1 + Q_2 \alpha \qquad \alpha = \frac{-Q_1}{Q_2}$$