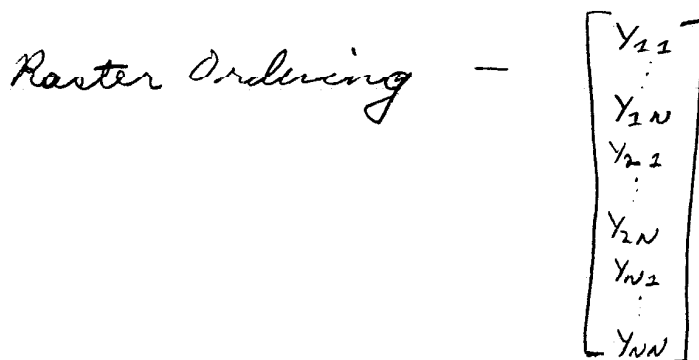
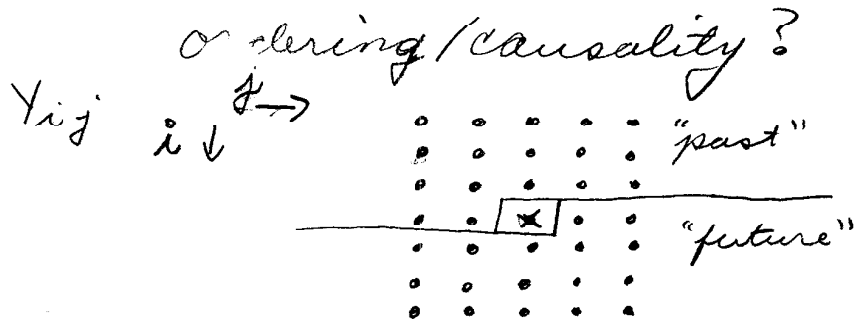


# Lecture 6

## 2-D AR Process



past - Nonsymmetric half plane (NHP)

$$Y_{ij} = X_{ij} + \sum_{k=1}^p \sum_{l=-p}^p h_{k,l} Y_{i-k,j-l} + \sum_{l=1}^p h_{0,l} Y_{i,j-l}$$

Set  $S = (s_1, s_2)$

$r = (r_1, r_2)$

$S < r \Leftrightarrow (s_1 < r_1) \text{ or } (s_1 = r_1 \text{ and } s_2 < r_2)$

$$Y_S = X_S + \sum_{r>0} h_r Y_{S-r}$$

( $a_p = 0$  outside prediction window)

$$G_y(\bar{\omega}) = \left| \frac{\sigma^2}{1-H(\bar{\omega})} \right|^2 \quad \bar{\omega} = (\omega_1, \omega_2)$$

$$H(\bar{\omega}) = \sum_{\vec{s}} h_s e^{-j\bar{\omega} \cdot \vec{s}} \quad \bar{\omega} \cdot \vec{s} = \omega_1 s_1 + \omega_2 s_2$$

↑  
2D DTFT

$$= \sum_{s_1, s_2} h_{(s_1, s_2)} e^{-j(\omega_1 s_1 + \omega_2 s_2)}$$

## Matrix Representation of 2-D Filter

$$\begin{array}{cccccc}
 & & & Y & & & & & & X \\
 & \bullet & \bullet & \bullet & \bullet & \bullet & & & & 0 & 0 & 0 & 0 & 0 \\
 & \bullet & \bullet & \bullet & \bullet & \bullet & & & & 0 & 0 & 0 & 0 & 0 \\
 & \bullet & \bullet & \bullet & \bullet & \bullet & & & & 0 & 0 & 0 & 0 & 0 \\
 & \bullet & \bullet & \bullet & \bullet & \bullet & & & & 0 & 0 & 0 & 0 & 0 \\
 & \bullet & \bullet & \bullet & \bullet & \bullet & & & & 0 & 0 & 0 & 0 & 0 \\
 & \bullet & \bullet & \bullet & \bullet & \bullet & & & & 0 & 0 & 0 & 0 & 0
 \end{array}$$

$$\begin{array}{c}
 \longrightarrow \\
 h_{11} \ h_{10} \ h_{1-1} \\
 h_{01} \ h_{00}
 \end{array}
 \quad \text{order } P = 1$$

$$X_s = \sum_{n \geq (0,0)} h_n Y_{s-n}$$

$\bar{Y}_i$  -  $i^{\text{th}}$  row of  $Y$

$$Y = \begin{bmatrix} \bar{Y}_1 \\ \vdots \\ \bar{Y}_N \end{bmatrix} \quad X = \begin{bmatrix} \bar{X}_1 \\ \vdots \\ \bar{X}_N \end{bmatrix}$$

$$X = AY \quad A = ?$$

$$\bar{X}_1 = A_0 \bar{Y}_1$$

$$\bar{X}_2 = A_0 \bar{Y}_2 + A_1 \bar{Y}_1$$

$$\bar{X}_3 = A_0 \bar{Y}_3 + A_1 \bar{Y}_2$$

$\vdots$

$$\bar{X}_N = A_0 \bar{Y}_N + A_1 \bar{Y}_{N-1}$$

$$\begin{bmatrix} \bar{x}_1 \\ \vdots \\ \bar{x}_N \end{bmatrix} = \begin{bmatrix} A_0 & & & \\ & A_1 & & \\ & & \ddots & \\ & & & A_1 & A_0 \end{bmatrix} \begin{bmatrix} \bar{y}_1 \\ \vdots \\ \bar{y}_N \end{bmatrix}$$

Vertical Causal  $\Rightarrow$  Block lower triangular  
 Vert. invariant  $\Rightarrow$  Block Toeplitz  
 Vert. FIR  $\Rightarrow$  Block  $P+1$  diagonal

$$A_0 = \begin{bmatrix} h_{00} & & & \\ h_{01} & & & \\ & 0 & & \\ & & h_{01} & h_{00} \end{bmatrix}$$

$$A_1 = \begin{bmatrix} h_{10} & h_{1-1} & & & \\ h_{11} & h_{10} & h_{1-1} & & \\ & 0 & & h_{11} & h_{10} \end{bmatrix}$$

Horizontal Causal  $\Rightarrow$   $A_0$  lower triangular  
 Hor. Invariant  $\Rightarrow$   $A_i$  Toeplitz  
 Hor. FIR  $\Rightarrow$   $A_0$   $P+1$  diagonal  
 $A_i$   $2P+1$  diag.

## Computation of Parameters for 2-D AR Model

Let  $S = \{(i, j) : i = \text{row}, j = \text{column of image}\}$

$Y_S = \text{pixel at position } S = (S_1, S_2)$

$$\begin{array}{ccccccc} y(S_2-p, S_2-p) & \cdots & y(S_2, S_2-p) & \cdots & y(S_2+p, S_2-p) & & \\ \vdots & & \vdots & & \vdots & & \\ \vdots & & y(S_2, S_2-1) & & y(S_2+p, S_2-1) & & \\ \vdots & & \vdots & & \vdots & & \\ y(S_2-p, S_2) & \cdots & y(S_2-1, S_2) & \cdots & y(S_2+p, S_2) & & \end{array}$$

Define

$$Z_S = \begin{bmatrix} y(S_2-1, S_2) \\ \vdots \\ y(S_2-p, S_2) \\ y(S_2+p, S_2-1) \\ \vdots \\ y(S_2-1, S_2-1) \\ \vdots \\ y(S_2+p, S_2-p) \\ \vdots \\ y(S_2-p, S_2-p) \end{bmatrix}$$

$h = \text{column vector of corresponding filter coefficients}$

Then

$$X_S = Y_S - h^T Z_S$$