

EE 637 Final
May 7, Spring 2014

Name: _____

Instructions:

- This is a 120 minute exam containing **five** problems.
- Each problem is worth 20 points for a total score of 100 points
- You may **only** use your brain and a pencil (or pen) to complete this exam.
- You **may not** use your book, notes, or a calculator, or any other electronic or physical device for communicating or accessing stored information.

Good Luck.

Fact Sheet

- Function definitions

$$\text{rect}(t) \triangleq \begin{cases} 1 & \text{for } |t| < 1/2 \\ 0 & \text{otherwise} \end{cases}$$

$$\Lambda(t) \triangleq \begin{cases} 1 - |t| & \text{for } |t| < 1 \\ 0 & \text{otherwise} \end{cases}$$

$$\text{sinc}(t) \triangleq \frac{\sin(\pi t)}{\pi t}$$

- CTFT

$$X(f) = \int_{-\infty}^{\infty} x(t) e^{-j2\pi f t} dt$$

$$x(t) = \int_{-\infty}^{\infty} X(f) e^{j2\pi f t} df$$

- CTFT Properties

$$x(-t) \stackrel{CTFT}{\longleftrightarrow} X(-f)$$

$$x(t - t_0) \stackrel{CTFT}{\longleftrightarrow} X(f) e^{-j2\pi f t_0}$$

$$x(at) \stackrel{CTFT}{\longleftrightarrow} \frac{1}{|a|} X(f/a)$$

$$X(t) \stackrel{CTFT}{\longleftrightarrow} x(-f)$$

$$x(t) e^{j2\pi f_0 t} \stackrel{CTFT}{\longleftrightarrow} X(f - f_0)$$

$$x(t)y(t) \stackrel{CTFT}{\longleftrightarrow} X(f) * Y(f)$$

$$x(t) * y(t) \stackrel{CTFT}{\longleftrightarrow} X(f)Y(f)$$

$$\int_{-\infty}^{\infty} x(t)y^*(t)dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(f)Y^*(f)df$$

- CTFT pairs

$$\text{sinc}(t) \stackrel{CTFT}{\longleftrightarrow} \text{rect}(f)$$

$$\text{rect}(t) \stackrel{CTFT}{\longleftrightarrow} \text{sinc}(f)$$

For $a > 0$

$$\frac{1}{(n-1)!} t^{n-1} e^{-at} u(t) \stackrel{CTFT}{\longleftrightarrow} \frac{1}{(j2\pi f + a)^n}$$

- CSFT

$$F(u, v) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-j2\pi(ux+vy)} dx dy$$

$$f(x, y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} F(u, v) e^{j2\pi(ux+vy)} du dv$$

- DTFT

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n}$$

$$x(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) e^{j\omega n} d\omega$$

- DTFT pairs

$$a^n u(n) \stackrel{DTFT}{\longleftrightarrow} \frac{1}{1 - ae^{-j\omega}}$$

- Rep and Comb relations

$$\text{rep}_T[x(t)] = \sum_{k=-\infty}^{\infty} x(t - kT)$$

$$\text{comb}_T[x(t)] = x(t) \sum_{k=-\infty}^{\infty} \delta(t - kT)$$

$$\text{comb}_T[x(t)] \stackrel{CTFT}{\longleftrightarrow} \frac{1}{T} \text{rep}_{\frac{1}{T}}[X(f)]$$

$$\text{rep}_T[x(t)] \stackrel{CTFT}{\longleftrightarrow} \frac{1}{T} \text{comb}_{\frac{1}{T}}[X(f)]$$

- Sampling and Reconstruction

$$y(n) = x(nT)$$

$$Y(e^{j\omega}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X\left(\frac{\omega - 2\pi k}{2\pi T}\right)$$

$$s(t) = \sum_{k=-\infty}^{\infty} y(k) \delta(t - kT)$$

$$S(e^{j\omega}) = Y(e^{j\omega T})$$

Name: _____

Problem 1. (20pt)

Consider the continuous space signal $g(x, y)$ with corresponding CSFT $G(u, v)$, and the sampled signal $f(m, n) = g(Tx, Ty)$ with corresponding DSFT $F(e^{j\mu}, e^{j\nu})$.

- Write a formula for $F(e^{j\mu}, e^{j\nu})$ in terms of the function $G(u, v)$.
- Give sufficient conditions for perfect reconstruction of $g(x, y)$ from $f(m, n)$.
- Derive a discrete approximation for the gradient, $\nabla g(x, y)$, as a function of $f(m, n)$.
- Derive a discrete approximation for the Laplacian, $\nabla^2 g(x, y)$, as a function of $f(m, n)$.
- Use the two expressions of parts c) and d) above to specify a useful edge detection algorithm.

$$a) \quad F(e^{j\mu}, e^{j\nu}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} G\left(\frac{\mu - 2\pi k}{2\pi T}, \frac{\nu - 2\pi l}{2\pi T}\right)$$

- b) In order to meet the Nyquist criteria, it is necessary that sampling rate is greater than or equal to the highest spatial frequency. So the frequencies must be limited to

$$\max\{|u|, |v|\} \leq \frac{1}{2T}$$

$$c) \quad \nabla g(x, y) \approx D f(m, n) = \left[\frac{f(m+1, n) - f(m-1, n)}{2T}, \frac{f(m, n+1) - f(m, n-1)}{2T} \right]$$

$$d) \quad \nabla^2 g(x, y) \approx D_2 f(m, n) = \frac{-4}{T^2} \left\{ f(m, n) - \frac{1}{4} [f(m+1, n) + f(m, n+1) + f(m-1, n) + f(m, n-1)] \right\}$$

- e). A typical edge detection algorithm checks that the magnitude of the gradient is ^{above} a threshold and the Laplacian is at a zero crossing

$$|D f(m, n)| \geq T$$

and $[(D_2 f(m, n) \cdot D_2 f(m+1, n) < 0) \text{ or } (D_2 f(m, n) \cdot D_2 f(m, n-1) < 0)]$

Name: _____

Problem 2. (20pt)

Consider a 2D zero mean Gaussian random vector $X = [X_1, X_2]^t$ with $E[X_1^2] = E[X_2^2] = 1$. Furthermore, let ρ denote the correlation between X_1 and X_2 , so that $E[X_1 X_2] = \rho$.

a) Sketch a contour plot given by $p(x) = \text{constant}$ when $\rho = 0.9$. Label all relevant quantities on the sketch.

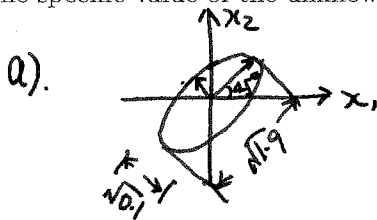
b) Let $R = E[XX^t]$ be the covariance matrix for the vector X . Determine the **eigen vectors** of R .

c) Let $R = E[XX^t]$ be the covariance matrix for the vector X . Determine the **eigen values** of R .

d) Imagine that you have two zero mean Gaussian random variables, Y_1 and Y_2 with variance σ_1^2 and σ_2^2 respectively, but with unknown correlation ρ . Furthermore, let T be a linear transform so that

$$\begin{bmatrix} Z_1 \\ Z_2 \end{bmatrix} = T \begin{bmatrix} Y_1 \\ Y_2 \end{bmatrix}.$$

Find a fixed transform, T , such that the variables, $[Z_1, Z_2]$ are always decorrelated regardless of the specific value of the unknown correlation ρ .



b.c). $R = \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix}$ eigenvalues: $\det(R - \lambda I) = 0$
 $\lambda = 1 \pm \rho$

Eigenvectors:

Case 1: $\lambda = 1 + \rho$

$$R e_1 = \lambda e_1$$

$$e_1 = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}^t$$

Case 2: $\lambda = 1 - \rho$

$$R e_2 = \lambda e_2$$

$$e_2 = \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix}^t$$

Name: _____

d). How to choose T :

Step 1. scale to get unit variance

Step 2. $y_1 + y_2$ and $y_1 - y_2$ are decorrelated

For step 1: $T_1 = \begin{bmatrix} b_1^{-1} & 0 \\ 0 & b_2^{-1} \end{bmatrix}$

Quick proof: $\begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = T_1 \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} b_1^{-1} y_1 \\ b_2^{-1} y_2 \end{bmatrix}$

$$E[z_1^2] = b_1^{-2} E[y_1^2] = 1$$

Similarly $E[z_2^2] = 1$

For step 2:

$$T_2 = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

Together $T = T_2 T_1 = \begin{bmatrix} b_1^{-1} & b_2^{-1} \\ b_1^{-1} & -b_2^{-1} \end{bmatrix}$

proof: $\begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = T \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} b_1^{-1} y_1 + b_2^{-1} y_2 \\ b_1^{-1} y_1 - b_2^{-1} y_2 \end{bmatrix}$

$$E[z_1 z_2] = E[z_2 z_1] = b_1^{-2} E[y_1^2] - b_2^{-2} E[y_2^2]$$

$$+ b_1^{-1} b_2^{-1} E[y_1 y_2] - b_1^{-1} b_2^{-1} E[y_1 y_2]$$

$$= b_1^{-2} b_1^2 - b_2^{-2} b_2^2$$

$$= 1 - 1 = 0$$

Name: _____

Problem 3.(20pt)

Consider the set of data $\{x_n\}_{n=0}^{N-1}$ for N odd. We would like to estimate a "central value" using a method known as M-estimation. To do this we compute the following function

$$\hat{\theta} = \arg \min_{\theta} \left\{ \sum_{n=0}^{N-1} \rho(x_n - \theta) \right\}$$

where ρ is a function with the properties that $\rho(\Delta) \geq 0$ and $\rho(-\Delta) = \rho(\Delta)$.

- Compute a closed form expression for the M-estimator when $\rho(\Delta) = |\Delta|^2$.
- What function $\rho(\Delta)$ will result in the M-estimator being the median?
- Derive a nonlinear equation that can be solved for $\hat{\theta}$. Hint: Do this by differentiating the cost function that is being minimized in the M-estimator.
- Give a specific example of a function $\rho(\Delta)$ so that there is no influence on $\hat{\theta}$ when $|\Delta| = |\hat{\theta} - x_k| > T$.

a) $\hat{\theta} = \arg \min_{\theta} \left\{ \sum_{n=0}^{N-1} (x_n - \theta)^2 \right\}$

$$\frac{d}{d\theta} \sum_{n=0}^{N-1} (x_n - \hat{\theta})^2 = 0$$

$$2 \sum_{n=0}^{N-1} (x_n - \hat{\theta}) = 0$$

$$\text{i.e. } N \hat{\theta} = \sum_{n=0}^{N-1} x_n$$

$$\therefore \hat{\theta} = \frac{1}{N} \sum_{n=0}^{N-1} x_n \leftarrow \text{mean value}$$

$$\frac{d}{d\theta^2} \sum_{n=0}^{N-1} (x_n - \theta)^2 = 2N > 0$$

b) $\rho(\Delta) = |\Delta|$

c) $\hat{\theta} = \arg \min_{\theta} \left\{ \sum_{n=0}^{N-1} \rho(x_n - \theta) \right\}$

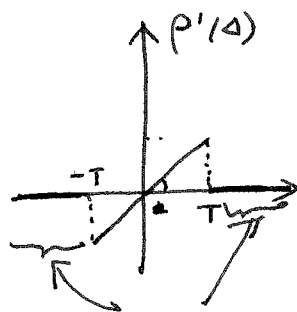
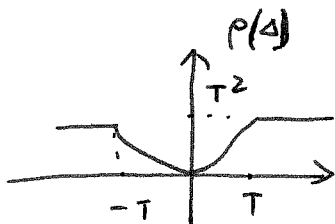
$$\frac{d}{d\theta} \sum_{n=0}^{N-1} \rho(x_n - \hat{\theta}) = 0 \leftarrow 1^{\text{st}} \text{ order condition}$$
$$\Rightarrow \sum_{n=0}^{N-1} \rho'(x_n - \hat{\theta}) = 0$$

second order condition.

$$\sum_{n=0}^{N-1} \rho''(x_n - \hat{\theta}) > 0$$

Name: _____

$$d) \quad p(\Delta) = \begin{cases} \Delta^2 & |\Delta| \leq T \\ T^2 & |\Delta| > T \end{cases}$$

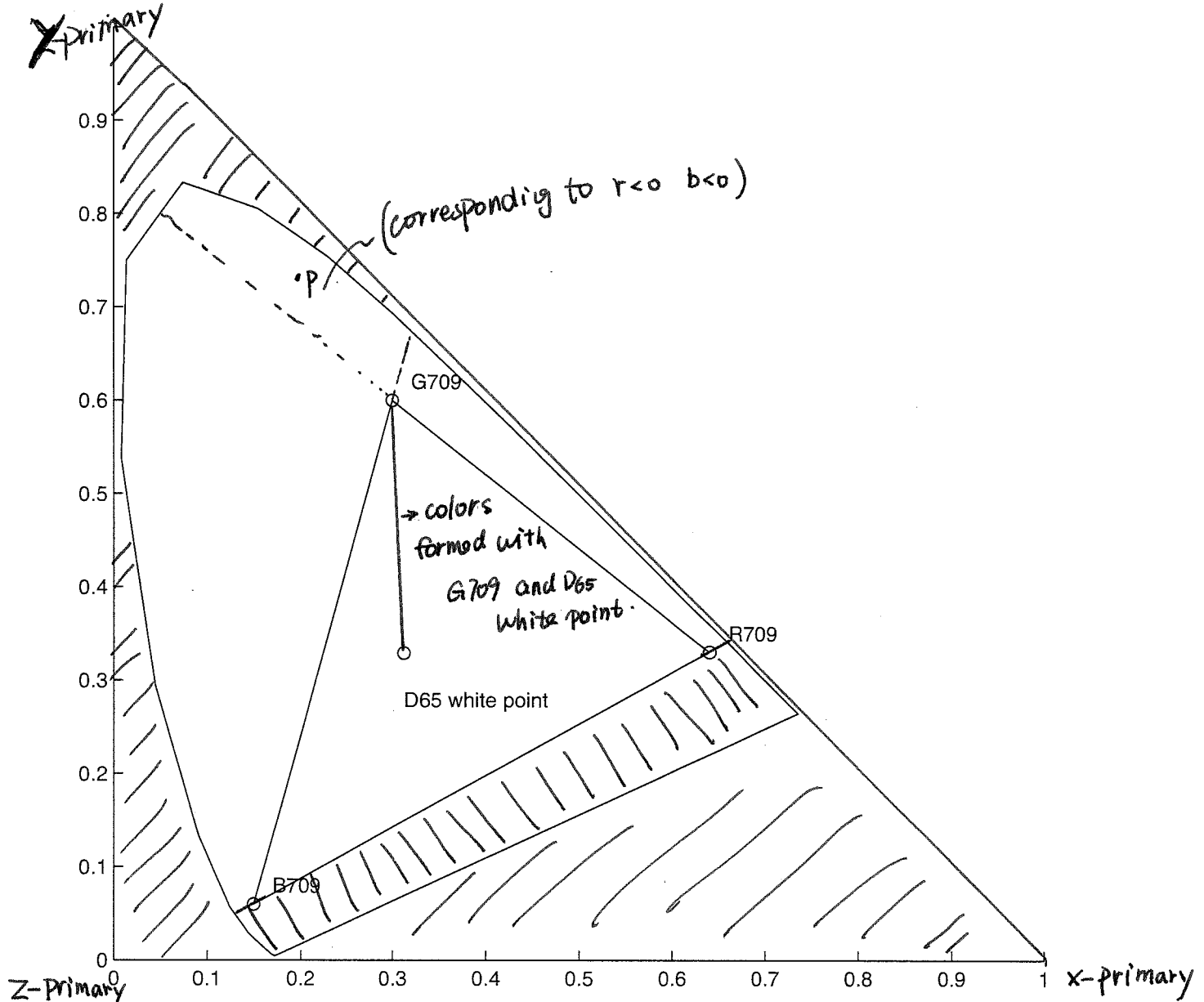


zero influence regions

Name: _____

Problem 4.(20pt)

Consider the standard chromaticity diagram below, and assume that you are using a display device with standard 709 r, g, b color primaries.



a) Draw a triangle corresponding to all colors with positive values of X , Y , and Z . Label the three primaries for this triangle as "X-primary", "Y-primary", and "Z-primary".

b) Label the region of the chromaticity diagram corresponding to imaginary colors. (Use 45 deg diagonal hash marks to indicate this region of the diagram.)

c) Label ALL real colors with $g < 0$ on the chromaticity diagram. (Use -45 deg diagonal hash marks to indicate this region of the diagram.)

- d) Draw a line on the plot corresponding to all colors that can be formed with a combination of the D65 white and G709.
- e) Place a point on the diagram corresponding to a single color with values of b and r that are both negative, i.e., $b < 0$ and $r < 0$. Label this point with the letter “P”.

Name: _____

Name: _____

Problem 5. (20pt)

Consider an MRI that only images in one dimension, x . So for example, the object being imaged might be a thin rod, $a(x)$, oriented along the x -dimension.

In this example, assume that the magnetic field strength at each location is given by

$$M_o + G_x(t)x$$

where M_o is the static magnetic field strength and $G_x(t)$ is the linear gradient field in the x dimension. Then the frequency of precession for a hydrogen atom (in rad/sec) is given by the product of γ , the gyromagnetic constant, and the magnetic field strength.

- Calculate $\omega(x, t)$, the frequency of precession of a hydrogen atom at location x and time t .
- Calculate $\phi(x, t)$, the phase of precession of a hydrogen atom at location x and time t assuming that $\phi(x, 0) = 0$.
- Calculate $r(x, t)$, the signal radiated from hydrogen atoms in the interval $[x, x + dx]$ at time t in terms of $a(x)$, the quantity of precessing hydrogen atoms along the thin rod.
- Calculate $r(t)$, the signal radiated from hydrogen atoms along the entire object.
- Design a function, $G_x(t)$, so that it is possible to reconstruct $a(x)$ from $r(t)$. Discuss the rationale behind your selection, and explain how you can then reconstruct $a(x)$ from $r(t)$.

a) $\omega(x, t) = \gamma (M_o + G_x(t)x)$

b) $\frac{d}{dt} \phi(x, t) = \omega(x, t) = \gamma (M_o + G_x(t)x)$

$$\phi(x, t) = \gamma M_o t + x \int_0^t \gamma G_x(\tau) d\tau$$
$$= \gamma M_o t + x K_x(t)$$

$$\text{where } K_x(t) = \int_0^t \gamma G_x(\tau) d\tau$$

c) $r(x, t) = a(x) e^{j\phi(x, t)} = a(x) e^{j\gamma M_o t} e^{jx K_x(t)}$

d) $r(t) = \int_{-\infty}^{\infty} r(x, t) dx = e^{j\gamma M_o t} \int_{-\infty}^{\infty} a(x) e^{-jx K_x(t)} dx$

e) Note that $r(t) = e^{j\gamma M_o t} A(-K_x(t))$

$$\text{where } A(\omega) = \text{CTFT} \{a(x)\}$$

$$\text{Therefore } a(x) = \text{CTFT}^{-1} \{A(\omega)\}$$
$$= \text{CTFT}^{-1} \left\{ \frac{r(t)}{e^{j\gamma M_o t}} \right\}$$

Name: _____

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{r(t)}{e^{j\omega t}} e^{-j \underbrace{kx(t)}_{-\omega}} d\omega \quad \left(\begin{array}{l} \text{where } \omega = -kx(t) \\ = -\int_0^t \gamma G_x(\tau) d\tau \end{array} \right)$$

$$= \frac{r(t)}{2\pi e^{j\omega t}} \int_{-\infty}^{\infty} e^{j\omega x} d\omega$$

$$G_x(t) = \begin{cases} G & t \leq T \\ -G & T < t \leq 2T \end{cases}$$

Name: _____