

EE 637 Final
May 2, Spring 2012

Name: Key

Instructions:

- This is a 120 minute exam containing **five** problems.
- Each problem is worth 20 points for a total score of 100 points
- You may **only** use your brain and a pencil (or pen) to complete this exam.
- You **may not** use your book, notes, or a calculator, or any other electronic or physical device for communicating or accessing stored information.

Good Luck.

Fact Sheet

- Function definitions

$$\text{rect}(t) \triangleq \begin{cases} 1 & \text{for } |t| < 1/2 \\ 0 & \text{otherwise} \end{cases}$$

$$\Lambda(t) \triangleq \begin{cases} 1 - |t| & \text{for } |t| < 1 \\ 0 & \text{otherwise} \end{cases}$$

$$\text{sinc}(t) \triangleq \frac{\sin(\pi t)}{\pi t}$$

- CTFT

$$X(f) = \int_{-\infty}^{\infty} x(t) e^{-j2\pi f t} dt$$

$$x(t) = \int_{-\infty}^{\infty} X(f) e^{j2\pi f t} df$$

- CTFT Properties

$$x(-t) \stackrel{CTFT}{\longleftrightarrow} X(-f)$$

$$x(t - t_0) \stackrel{CTFT}{\longleftrightarrow} X(f) e^{-j2\pi f t_0}$$

$$x(at) \stackrel{CTFT}{\longleftrightarrow} \frac{1}{|a|} X(f/a)$$

$$X(t) \stackrel{CTFT}{\longleftrightarrow} x(-f)$$

$$x(t) e^{j2\pi f_0 t} \stackrel{CTFT}{\longleftrightarrow} X(f - f_0)$$

$$x(t)y(t) \stackrel{CTFT}{\longleftrightarrow} X(f) * Y(f)$$

$$x(t) * y(t) \stackrel{CTFT}{\longleftrightarrow} X(f)Y(f)$$

$$\int_{-\infty}^{\infty} x(t)y^*(t)dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(f)Y^*(f)df$$

- CTFT pairs

$$\text{sinc}(t) \stackrel{CTFT}{\longleftrightarrow} \text{rect}(f)$$

$$\text{rect}(t) \stackrel{CTFT}{\longleftrightarrow} \text{sinc}(f)$$

For $a > 0$

$$\frac{1}{(n-1)!} t^{n-1} e^{-at} u(t) \stackrel{CTFT}{\longleftrightarrow} \frac{1}{(j2\pi f + a)^n}$$

- CSFT

$$F(u, v) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-j2\pi(ux+vy)} dx dy$$

$$f(x, y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} F(u, v) e^{j2\pi(ux+vy)} du dv$$

- DTFT

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n}$$

$$x(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) e^{j\omega n} d\omega$$

- DTFT pairs

$$a^n u(n) \stackrel{DTFT}{\longleftrightarrow} \frac{1}{1 - ae^{-j\omega}}$$

- Rep and Comb relations

$$\text{rep}_T[x(t)] = \sum_{k=-\infty}^{\infty} x(t - kT)$$

$$\text{comb}_T[x(t)] = x(t) \sum_{k=-\infty}^{\infty} \delta(t - kT)$$

$$\text{comb}_T[x(t)] \stackrel{CTFT}{\longleftrightarrow} \frac{1}{T} \text{rep}_{\frac{1}{T}}[X(f)]$$

$$\text{rep}_T[x(t)] \stackrel{CTFT}{\longleftrightarrow} \frac{1}{T} \text{comb}_{\frac{1}{T}}[X(f)]$$

- Sampling and Reconstruction

$$y(n) = x(nT)$$

$$Y(e^{j\omega}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X\left(\frac{\omega - 2\pi k}{2\pi T}\right)$$

$$s(t) = \sum_{k=-\infty}^{\infty} y(k) \delta(t - kT)$$

$$S(e^{j\omega}) = Y(e^{j\omega T})$$

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Problem 1 First Part.(8pt)

Let $X \sim N(0, \sigma_x^2)$ and $W \sim N(0, 1)$ be independent Gaussian random variables, and let

$$Y = X + W .$$

Furthermore, we know that the MMSE estimate of X given Y has a form given by

$$\hat{X} = E[X|Y] = \alpha Y ,$$

and we know that the MMSE estimate must have the property that

$$E[(X - \hat{X})Y] = 0 .$$

a) Calculate the $E[XY]$ and $E[Y^2]$.

b) Calculate the value of α .

Problem 1 Second Part.(8pt) *12pt*

Let $X \sim N(0, R)$ and $W \sim N(0, I)$ be independent Gaussian random vectors with $R = E\Lambda E^t$ where $EE^t = I$ and Λ is diagonal, and let

$$Y = X + W .$$

Use the results of Problem 1) First Part to solve the following problems.

c) Calculate the mean and covariance of the three Gaussian random vectors $\tilde{X} = E^t X$, $\tilde{W} = E^t W$, and $\tilde{Y} = E^t Y$.

d) Calculate an expression for the $Z = E[\tilde{X}|\tilde{Y}]$.

e) Use the expression of part d) to calculate an expression for the $E[X|Y]$.

$$\begin{aligned} \text{a)} \quad E[XY] &= E[X(X+W)] = \sigma_x^2 + 0 \\ E[Y^2] &= E[(X+W)(X+W)] = \sigma_x^2 + 2E[XW] + \sigma_w^2 \\ &= \sigma_x^2 + \sigma_w^2 = \sigma_x^2 + 1 \end{aligned}$$

$$\begin{aligned} \text{b)} \quad E[(X - \hat{X})Y] &= 0 = E[(X - \alpha Y)Y] \\ &= E[XY] - \alpha E[Y^2] \end{aligned}$$

$$\alpha = \frac{E[XY]}{E[Y^2]}$$

$$\alpha = \frac{\sigma_x^2}{\sigma_x^2 + 1}$$

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$$\begin{aligned} c) \quad E[\tilde{X}\tilde{X}^*] &= E[E^*XX^*E] \\ &= E^*E[XX^*]E = E^*RE \\ &= E^*E\Lambda E^*E = \Lambda \end{aligned}$$

$$E[\tilde{W}\tilde{W}^*] = I$$

$$E[\tilde{Y}\tilde{Y}^*] = \Lambda + I$$

$$d) \quad E[(X-Z)\tilde{Y}^*] = 0$$

$$E[(X - \underbrace{\theta \tilde{Y}}_{p \times p \text{ matrix}})\tilde{Y}^*] = 0$$

$$E[\tilde{X}\tilde{Y}^*] - \theta E[\tilde{Y}\tilde{Y}^*] = 0$$

$$\Lambda - \theta(\Lambda + I) = 0$$

$$\theta = (\Lambda + I)^{-1}\Lambda$$

$$Z = (\Lambda + I)^{-1}\Lambda \tilde{Y}$$

$$e) \quad \hat{X} = E[X|Y]$$

$$= EZ = E(\Lambda + I)^{-1}\Lambda E^*Y$$

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Problem 2.(20pt)

Consider the 2D system given by

$$g(x, y) = f(x, y) \circ h(x, y)$$

where \circ represents 2D convolution and

$$h(x, y) = \frac{1}{\sqrt{x^2 + y^2}}.$$

A common problem in image processing is called "deconvolution". The objective of deconvolution is to recover the signal $f(x, y)$ from knowledge of $g(x, y)$ and $h(x, y)$.

a) Use the Fourier transform to show that

$$\delta(t) = \int_{-\infty}^{\infty} e^{j2\pi r t} dr.$$

b) Use the result of a) to show that

$$\delta(u \cos \theta + v \sin \theta) = \int_{-\infty}^{\infty} e^{j2\pi r(u \cos \theta + v \sin \theta)} dr.$$

c) Show that the Fourier transform of $h(x, y)$ has the form

$$H(u, v) = \int_{-\infty}^{\infty} \int_{-\pi/2}^{\pi/2} \frac{1}{r} e^{j2\pi(ur \cos \theta + vr \sin \theta)} r d\theta dr = \int_{-\pi/2}^{\pi/2} \delta(u \cos \theta + v \sin \theta) d\theta$$

d) Use this result to show that

$$H(u, v) = \frac{1}{\sqrt{u^2 + v^2}}.$$

e) Which task is more difficult: Deconvolution with $h(x, y) = \frac{1}{\sqrt{x^2 + y^2}}$; or Deconvolution with $h(x, y) = \text{sinc}(x, y)$? Justify your answer.

$$\begin{aligned} \text{a)} \quad \int_{-\infty}^{\infty} \delta(t) e^{j2\pi t} dt &= 1 \Rightarrow \int_{-\infty}^{\infty} 1 e^{j2\pi \omega t} d\omega = \delta(t) \\ \delta(t) &= \int_{-\infty}^{\infty} e^{j2\pi r t} dr \end{aligned}$$

$$\begin{aligned} \text{b)} \quad t &\rightarrow u \cos \theta + v \sin \theta \\ \delta(u \cos \theta + v \sin \theta) &= \int_{-\infty}^{\infty} e^{j2\pi r(u \cos \theta + v \sin \theta)} dr \end{aligned}$$

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$$c) H(u, v) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h(x, y) e^{-j2\pi(ux + vy)} dx dy$$

$$\text{since } h(x, y) = h(-x, -y)$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h(x, y) e^{+j2\pi(ux + vy)} dx dy$$

in polar coordinates

$$H(u, v) = \int_{-\infty}^{\infty} \int_{-\pi/2}^{\pi/2} \frac{1}{r} e^{j2\pi(u r \cos \theta + v r \sin \theta)} r d\theta dr$$

$$= \int_0^{\pi} \int_{-\infty}^{\infty} e^{j2\pi r(u \cos \theta + v \sin \theta)} dr d\theta$$

$$= \int_0^{\pi} \delta(u \cos \theta + v \sin \theta) d\theta$$

$$d) \text{ let } (u, v) = (\rho \cos \phi, \rho \sin \phi)$$

$$\rho = \sqrt{u^2 + v^2} \quad \phi = \arctan(u, v)$$

$$= \int_0^{\pi} \delta(\rho \cos(\theta - \phi)) d\theta$$

$$= \frac{1}{\rho} = \frac{1}{\sqrt{u^2 + v^2}}$$

e) Easier to deconvolve with $\frac{1}{\sqrt{x^2 + y^2}}$
because the spectrum falls off
7 slower.

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Problem 3.(20pt)

Consider the 1D interpolation system given by

$$s(n) = \sum_{m=-\infty}^{\infty} x(m)\delta(n - mL)$$

and

$$y(n) = \sum_{m=-\infty}^{\infty} s(n - m)h(m) .$$

- a) **Derive** an expression for $S(e^{j\omega})$ in terms of $X(e^{j\omega})$.
- b) Write an expression for the ideal filter $H(e^{j\omega})$.
- c) Derive an expression for the ideal filter impulse response $h(n)$.
- d) Is the ideal $h(n)$ practical to use on streaming audio sources? Why or why not?
- e) Suggest an alternative impulse response $h(n)$ to use, and explain its advantages.

$$\begin{aligned} a) \quad S(e^{j\omega}) &= \sum_{n=-\infty}^{\infty} s(n) e^{j\omega n} \\ &= \sum_{n=-\infty}^{\infty} x(n) e^{j\omega n L} \\ &= X(e^{j\omega L}) \end{aligned}$$

$$\begin{aligned} b) \quad H(e^{j\omega}) &= \begin{cases} 1 & \text{for } |\omega| < \frac{\pi}{L} \\ 0 & \text{for } \frac{\pi}{L} \leq |\omega| < \pi \end{cases} \\ H(e^{j\omega}) &= \sum_{k=-\infty}^{\infty} L \operatorname{rect}\left(\frac{\omega - k2\pi}{2\pi/L}\right) \end{aligned}$$

$$c) \quad h(n) = \operatorname{sinc}(n/L)$$

d) No, because it requires infinite number of multiplies per output sample.

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e) $h(n) = w(n) \text{sinc}(n/L)$

↑ some window such
as Hamming window
with appropriate shift
to center it at $n=0$.

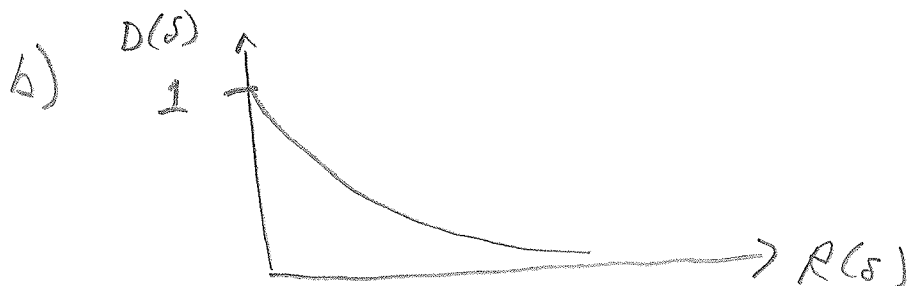
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Problem 4.(20pt)

Consider a Gaussian random variable X with mean zero and variance 1.

- Write an expression for the rate and distortion functions $R(\delta)$ and $D(\delta)$.
- Sketch the distortion-rate function for X .
- Explain the meaning of the distortion-rate function.
- Let $\{X_n\}_{n=1}^N$ be a set of independent Gaussian random variables each with zero mean and variance σ_n^2 where $\sigma_{n-1}^2 \geq \sigma_n^2$. Write an expression for the rate and distortion.
- How can one calculate the distortion-rate function for a Gaussian vector X with mean zero and covariance $R = E\Lambda E^t$ where $EE^t = I$ and Λ is diagonal?

a)
$$R(\delta) = \max\left\{\frac{1}{2} \log_2 \frac{1}{\delta}, 0\right\}$$
$$D(\delta) = \min\{1, \delta\}$$



- c) It is the lower bound on achievable rates at a given distortion.

Given $D' > D(\delta)$ and $R' > R(\delta)$, one can find a coder that achieves rate R' and distortion D' .

d)

$$R(\delta) = \sum_{n=1}^N \max\left\{\frac{1}{2} \log_2 \left(\frac{\sigma_n^2}{\delta}\right), 0\right\}$$
$$D(\delta) = \sum_{n=1}^N \min\{\sigma_n^2, \delta\}$$

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$$e) \quad R(\delta) = \sum_{n=1}^N \max \left\{ \frac{1}{2} \log \left(\frac{\lambda_{nn}}{\delta} \right), 0 \right\}$$
$$D(\delta) = \sum_{n=1}^N \min \{ \lambda_{nn}, \delta \}$$

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Problem 5.(20pt)

Let $X(m, n)$ be an achromatic image that is collected by a linear CCD with subtraction of dark current so that $X(m, n) = 0$ corresponds to zero light photons. Furthermore, assume there is a gamma-corrected display device with inputs $R(m, n)$, $G(m, n)$, and $B(m, n)$ taking integer values ranging from 0 to 255.

- Specify the (approximate) transforms of the image $X(m, n)$ that are necessary in order to display the image properly assuming that the display takes standard RGB input.
- If you were to display the image $X(m, n)$ directly so that $R(m, n) = G(m, n) = B(m, n) = X(m, n)$, then what distortion would you observe in the displayed image? Again, assume the display takes standard RGB input.
- If the display were modified so that its $\gamma = 1$, and you were to display the image $X(m, n)$ directly so that $R(m, n) = G(m, n) = B(m, n) = X(m, n)$, then what distortion would you observe in the displayed image?
- Imagine that $X(m, n)$ is collected from a half-toned print, and you would like to remove the halftone noise. Is it better to filter $X(m, n)$ directly, or to first gamma correct $X(m, n)$ and then filter it? Justify your answer.
- What is your favorite color?

a)
$$R(m, n) = G(m, n) = B(m, n) = 255 \left(\frac{X(m, n)}{X_{\max}} \right)^{\frac{1}{2.2}}$$

$$X_{\max} = \text{maximum sensor output}$$

b) It would be too dark.

c) You would see quantization artifacts in the dark regions.

d) It is better to filter $X(m, n)$.
Filtering the gamma corrected version will produce a shift in brightness.