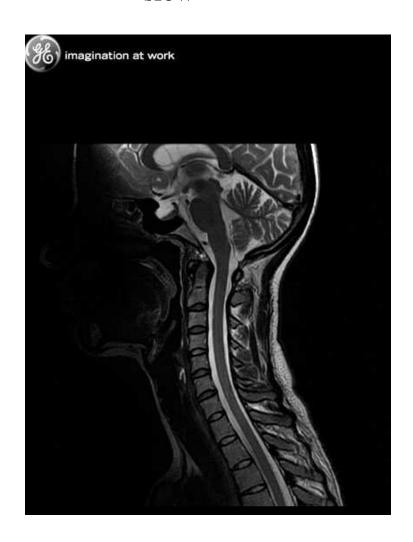
## **Magnetic Resonance Imaging (MRI)**



- Can be very high resolution
- No radiation exposure
- Very flexible and programable
- Tends to be expensive, noisy, slow

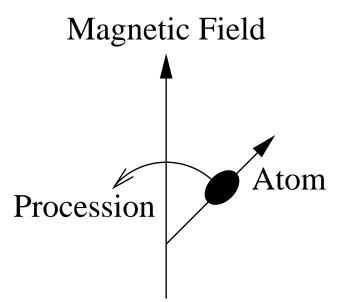


#### **MRI** Attributes

- Based on magnetic resonance effect in atomic species
- Does not require any ionizing radiation
- Numerous modalities
  - Conventional anatomical scans
  - Functional MRI (fMRI)
  - MRI Tagging
- Image formation
  - RF excitation of magnetic resonance modes
  - Magnetic field gradients modulate resonance frequency
  - Reconstruction computed with inverse Fourier transform
  - Fully programmable
  - Requires an enormous (and very expensive) superconducting magnet

3

## **Magnetic Resonance**



• Atom will precess at the Lamar frequency

$$\omega_o = LM$$

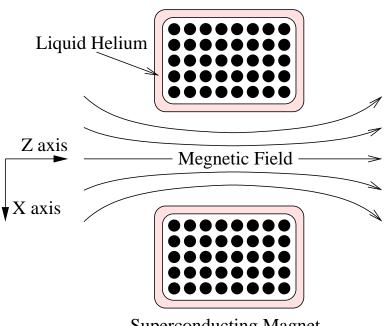
• Quantities of importance

M - magnitude of ambient magnetic field

 $\omega_o$  - frequency of procession (radians per second)

L - Lamar constant. Depends on choice of atom

### The MRI Magnet



Superconducting Magnet

- Large super-conducting magnet
  - Uniform field within bore
  - Very large static magnetic field of  $M_o$

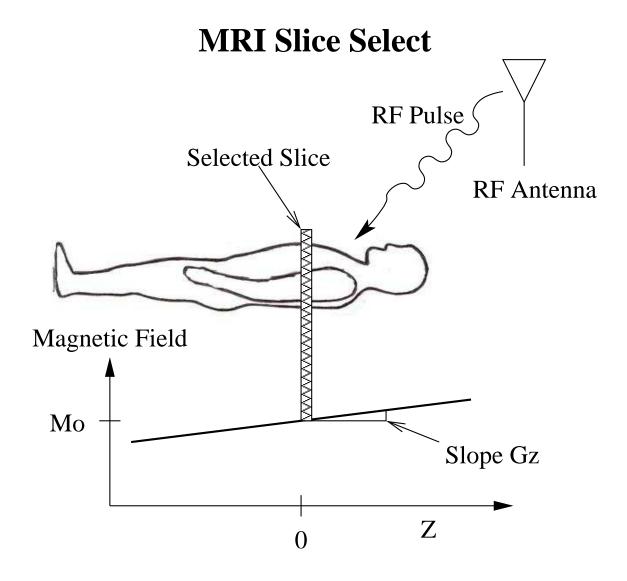
## **Magnetic Field Gradients**

ullet Magnetic field **magnitude** at the location (x,y,z) has the form

$$M(x,y) = M_o + xG_x + yG_y + zG_z$$

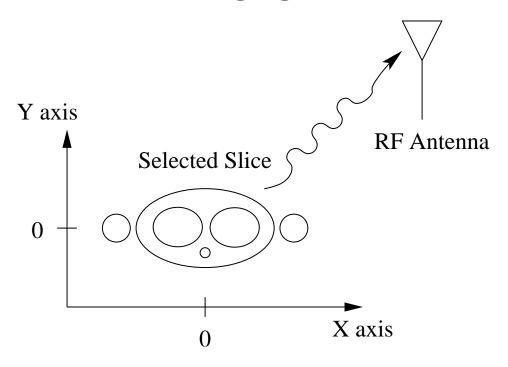
- $G_x$ ,  $G_y$ , and  $G_z$  control magnetic field gradients
- Gradients can be changed with time
- Gradients are small compared to  $M_o$
- For time varying gradients

$$M(x, y, t) = M_o + xG_x(t) + yG_y(t) + zG_z(t)$$



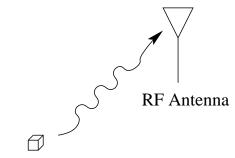
- ullet RF pulse is emitted at frequency  $\omega_o$
- ullet Atoms precess in slice corresponding to  $M_o=\omega_o/L$

#### **How Do We Imaging Selected Slice?**



- Precessing atoms radiate electromagnetic energy at RF frequencies
- Strategy
  - Vary magnetic gradients along x and y axises
  - Measure received RF signal
  - Reconstruct image from RF measurements

## Signal from a Single Voxel



Voxel of Selected Slice

• RF signal from a single voxel has the form

$$r(x, y, t) = f(x, y)e^{j\phi(t)}$$

f(x,y) voxel dependent weighting

- Depends on properties of material in voxel
- Quantity of interest
- Typically "weighted" by T1, T2, or T2\*

 $\phi(t)$  phase of received signal

- Can be modulated using  $G_x$  and  $G_y$  magnetic field gradients
- We assume that  $\phi(0) = 0$

## **Analysis of Phase**

• Frequency = time derivative of phase

$$\frac{d\phi(t)}{dt} = L M(x, y, t)$$

$$\phi(t) = \int_0^t L M(x, y, \tau) d\tau$$

$$= \int_0^t L M_o + x L G_x(\tau) + y L G_y(\tau) d\tau$$

$$= \omega_o t + x k_x(t) + y k_y(t)$$

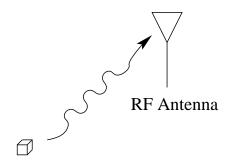
where we define

$$\omega_o = L M_o$$

$$k_x(t) = \int_0^t LG_x(\tau)d\tau$$

$$k_y(t) = \int_0^t LG_y(\tau)d\tau$$

## **Received Signal from Voxel**



Voxel of Selected Slice

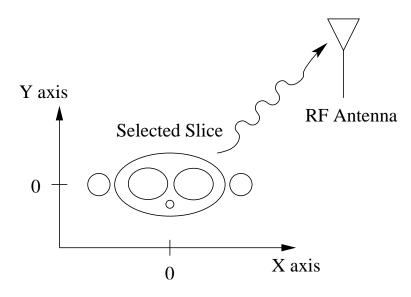
• RF signal from a single voxel has the form

$$r(t) = f(x,y)e^{j\phi(t)}$$

$$= f(x,y)e^{j(\omega_o t + xk_x(t) + yk_y(t))}$$

$$= f(x,y)e^{j\omega_o t}e^{j(xk_x(t) + yk_y(t))}$$

## **Received Signal from Selected Slice**



• RF signal from the complete slice is given by

$$R(t) = \int_{\mathbb{R}} \int_{\mathbb{R}} r(x, y, t) dx dy$$

$$= \int_{\mathbb{R}} \int_{\mathbb{R}} f(x, y) e^{j\omega_o t} e^{j(xk_x(t) + yk_y(t))} dx dy$$

$$= e^{j\omega_o t} \int_{\mathbb{R}} \int_{\mathbb{R}} f(x, y) e^{j(xk_x(t) + yk_y(t))} dx dy$$

$$= e^{j\omega_o t} F(-k_x(t), -k_y(t))$$

were F(u, v) is the CSFT of f(x, y)

## K-Space Interpretation of Demodulated Signal

• RF signal from the complete slice is given by

$$F(-k_x(t), -k_y(t)) = R(t)e^{-j\omega_o t}$$

where

$$k_x(t) = \int_0^t LG_x(\tau)d\tau$$

$$k_y(t) = \int_0^t LG_y(\tau)d\tau$$

- Strategy
  - Scan spatial frequencies by varying  $k_x(t)$  and  $k_y(t)$
  - Reconstruct image by performing (inverse) CSFT
  - $-G_x(t)$  and  $G_y(t)$  control velocity through K-space

#### **Controlling K-Space Trajectory**

• Relationship between gradient coil voltage and K-space

$$L_x \frac{di(t)}{dt} = v_x(t) \quad G_x(t) = M_x i(t)$$

$$L_y \frac{di(t)}{dt} = v_y(t) \quad G_y(t) = M_y i(t)$$

using this results in

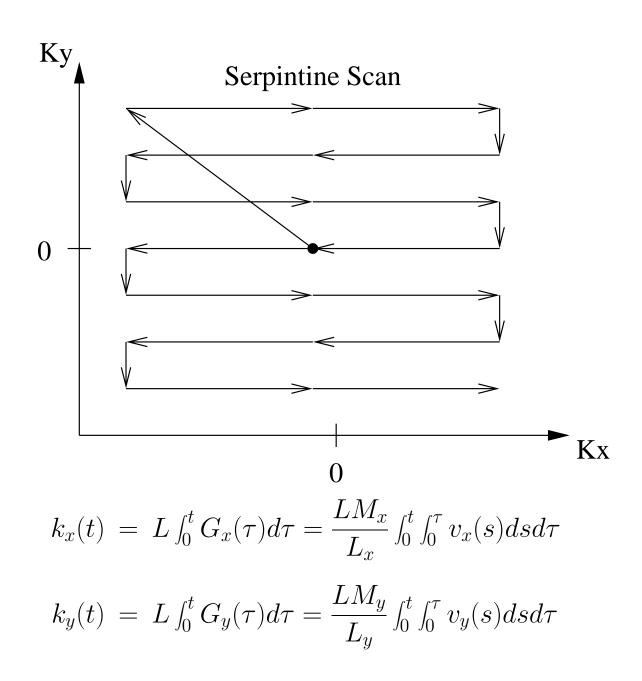
$$k_x(t) = \frac{LM_x}{L_x} \int_0^t \int_0^\tau v_x(s) ds d\tau$$

$$k_y(t) = \frac{LM_y}{L_y} \int_0^t \int_0^\tau v_y(s) ds d\tau$$

ullet  $v_x(t)$  and  $v_y(t)$  are like the accelerator peddles for  $k_x(t)$  and  $k_y(t)$ 

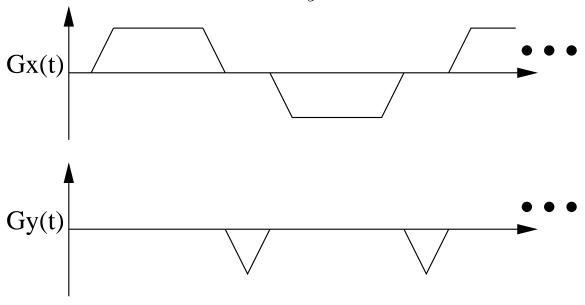
# **Echo Planer Imaging (EPI) Scan Pattern**

• A commonly used raster scan pattern through K-space



#### **Gradient Waveforms for EPI**

ullet Gradient waveforms in x and y look like



ullet Voltage waveforms in x and y look like

