

## Space Domain Models for Optical Imaging Systems

- Consider an imaging system with real world image  $f(x, y)$ , focal plane image  $g(x, y)$ , and magnification  $M$ . Then the behavior of the system may be modeled as:

$$\begin{aligned} g(x, y) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(\xi, \eta) h(x - M\xi, y - M\eta) d\xi d\eta \\ &= \frac{1}{M^2} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f\left(\frac{\xi}{M}, \frac{\eta}{M}\right) h(x - \xi, y - \eta) d\xi d\eta \end{aligned}$$

Define the function

$$\tilde{f}(x, y) \triangleq f\left(\frac{\xi}{M}, \frac{\eta}{M}\right)$$

- Then the imaging system act like a 2-D convolution.

$$g(x, y) = \frac{1}{M^2} h(x, y) * \tilde{f}(x, y)$$

## Point Spread Functions for Optical Imaging Systems

- Definition:  $h(x, y)$  is known as the *point spread function* of the imaging system.

$$g(x, y) = \frac{1}{M^2} h(x, y) * \tilde{f}(x, y)$$

- Notice that when  $f(x, y) = \delta(x, y)$

$$\begin{aligned} g(x, y) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \delta(\xi, \eta) h(x - M\xi, y - M\eta) d\xi d\eta \\ &= h(x, y) \end{aligned}$$

## Transfer Functions for Optical Imaging Systems

- In the frequency domain,

$$G(u, v) = \tilde{F}(u, v) \frac{1}{M^2} H(u, v)$$

$$\begin{aligned} g(x, y) &\overset{CSFT}{\longleftrightarrow} G(u, v) \\ h(x, y) &\overset{CSFT}{\longleftrightarrow} H(u, v) \\ \tilde{f}(x, y) &\overset{CSFT}{\longleftrightarrow} \tilde{F}(u, v) \end{aligned}$$

- The *Optical Transfer Function (OTF)* is

$$\frac{H(u, v)}{H(0, 0)}$$

- The *Modulation Transfer Function (MTF)* is

$$\left| \frac{H(u, v)}{H(0, 0)} \right|$$