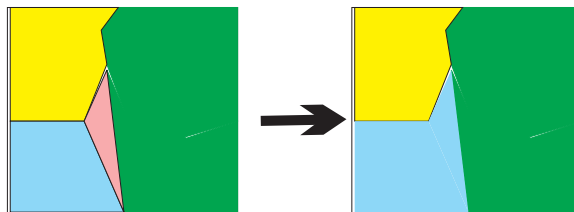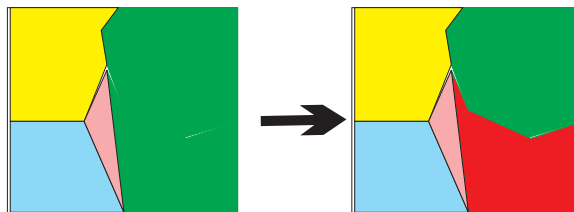# Region Segmentation

- Connected components analysis often results in many small disjointed regions.

- A connection (or break) at a single pixel can split (or merge) entire regions.

- There are three basic approaches to segmentation:

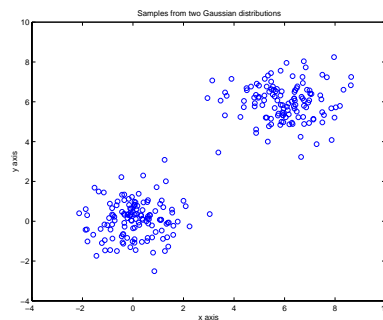 - Region Merging - recursively merge regions that are similar.

  - Region Splitting - recursively divide regions that are heterogeneous.

  - Split and merge - iteratively split and merge regions to form the "best" segmentation.

Hierarchical Clustering

- Clustering refers to techniques for separating data samples into sets with distinct characteristics.

- Clustering methods are analogous to segmentation methods.

  - Agglomerative clustering - "bottom up" procedure for recursively merging clusters $\Rightarrow$ analogous to region merging

  - Divisive clustering - "top down" procedure for recursively splitting clusters $\Rightarrow$ analogous to region splitting

Image Regions and Partitions

- Let $R_m \subset S$ denote a region of the image where $m \in \mathcal{M}$.

- We say that $\{R_m | m \in \mathcal{M}\}$ **partitions** the image if

$$\text{For all } m \neq k, \quad R_m \cap R_k = \emptyset$$
$$\bigcup_{m \in \mathcal{M}} R_m = S$$

- Each region R_m has **features** that characterize it.

Typical Region Features

- Color

  - Mean RGB value
  - 1-D color histograms in R, G, and B
  - 3-D color histogram in (R,G,B)

- Texture

  - Spatial autocorrelation
  - Joint probability distribution for neighboring pixels (e.g. the spatial co-occurrence matrix)
  - Wavelet transform coefficients

- Shape

  - Number of pixels
  - Width and height attributes
  - Boundary smoothness attributes
  - Adjacent region labels

Recursive Feature Computation

- Any two regions may be merged into a new region.

$$R_{new} = R_k \cup R_l$$

- Let $f_n = f(R_n) \in I\!\!R^k$ be a k dimensional feature vector extracted from the region R_n.

- Ideally, the features of merged regions may be computed without reference to the original pixels in the region.

$$
\begin{aligned}
f(R_k \cup R_l) &= f(R_k) \oplus f(R_l) \\
f_{new} &= f_k \oplus f_l
\end{aligned}
$$

here $\oplus$ denotes some operation on the values of the two feature vectors.

Example of Recursive Feature Computation

Example: Let $f(R_k) = (N_k, \mu_k, c_k)$ where

$$
\begin{aligned}
N_k &= |R_k| \\
\mu_k &= \frac{1}{N_k} \sum_{s \in R_k} x_s \\
c_k &= \frac{1}{N_k} \sum_{s \in R_k} s
\end{aligned}
$$

We may compute the region features for $R_{new} = R_k \cup R_l$ using the recursions

$$
\begin{aligned}
N_{new} &= N_k + N_l \\
\mu_{new} &= \frac{N_k \mu_k + N_l \mu_l}{N_{new}} \\
c_{new} &= \frac{N_k c_k + N_l c_l}{N_{new}}
\end{aligned}
$$

Recursive Merging

- Define a distance function between regions. In general, this function has the form

$$d_{k,l} = D(R_k, R_l) > 0$$

- Ideally, $D(R_k, R_l)$ is **only** a function of the feature vectors f_k and f_l.

$$d_{k,l} = D(f_k, f_l) > 0$$

- Then merge regions with minimum distance.

Example of Merging Criteria

- Distance between color means

$$d_{k,l} = \frac{N_k}{N_{new}}|\mu_k - \mu_{new}|^2 + \frac{N_l}{N_{new}}|\mu_l - \mu_{new}|^2$$

- Distance between region centers

$$d_{k,l} = \frac{N_k}{N_{new}}|c_k - c_{new}|^2 + \frac{N_l}{N_{new}}|c_l - c_{new}|^2$$

- Distance formed by a weighted combination of the two

$$\begin{aligned}
d_{k,l} &= \alpha \left(\frac{N_k}{N_{new}}|\mu_k - \mu_{new}|^2 + \frac{N_l}{N_{new}}|\mu_l - \mu_{new}|^2 \right) \\
&+ \beta \left(\frac{N_k}{N_{new}}|c_k - c_{new}|^2 + \frac{N_l}{N_{new}}|c_l - c_{new}|^2 \right)
\end{aligned}$$

Recursive Merging Algorithm

- Define a distance function between regions

$$d_{k,l} = D(f(R_k), f(R_l)) > 0$$

  Repeat until $|\mathcal{M}| = 1$ {

  Determine the minimum distance regions

$$(k^*, l^*) = \arg \min_{k,l \in \mathcal{M}} \{d_{k,l}\}$$

  Merge the minimum distance regions
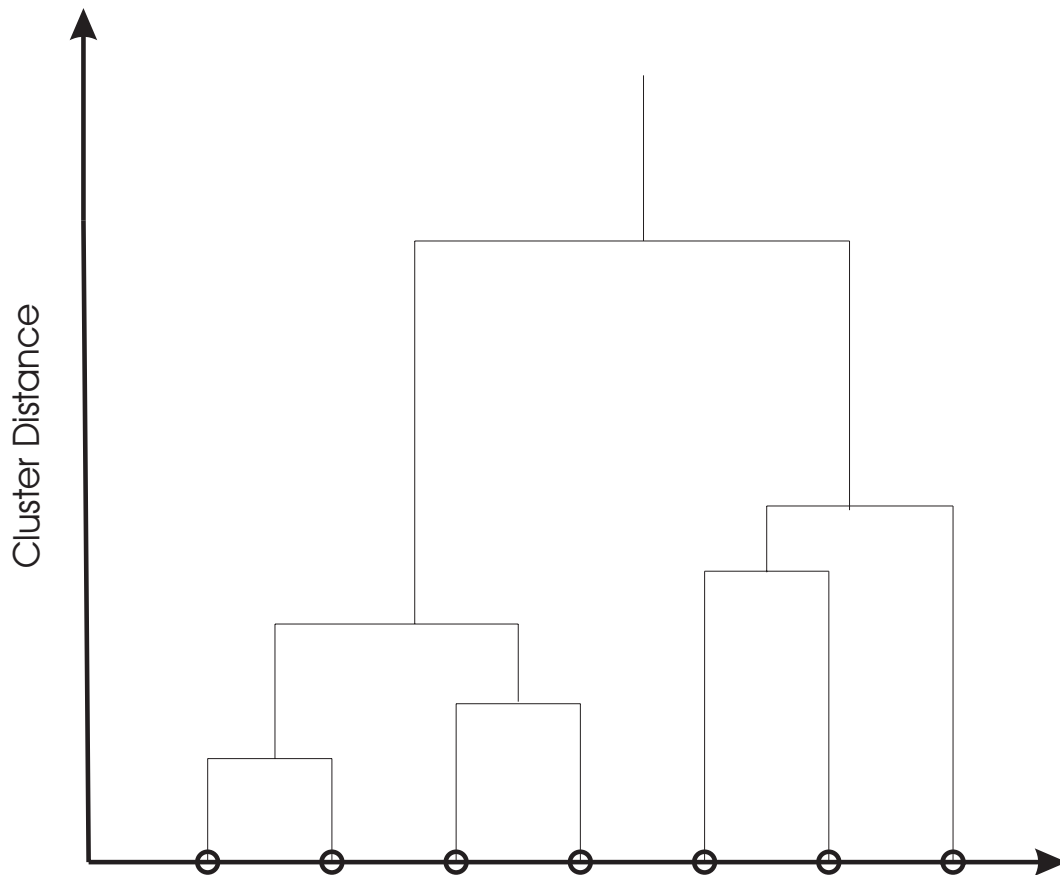
$$R_{k^*} \leftarrow R_{k^*} \cup R_{l^*}$$

  Remove unused region

$$\mathcal{M} \leftarrow \mathcal{M} - \{l^*\}$$

  }

- This recursion generates a binary tree.

Merging Hierarchy and Order Identification

- Clustering can be terminated when the distance exceeds a threshold

$$d_{k^*,l^*} > Threshold \Rightarrow \text{Stop clustering}$$

- Different thresholds result in different numbers of clusters.