Space Domain Models for Optical Imaging Systems

• Consider an imaging system with real world image f(x,y), focal plane image g(x,y), and magnification M. Then the behavior of the system may be modeled as:

$$g(x,y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(\xi,\eta) h(x - M\xi, y - M\eta) d\xi d\eta$$
$$= \frac{1}{M^2} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f\left(\frac{\xi}{M}, \frac{\eta}{M}\right) h(x - \xi, y - \eta) d\xi d\eta$$

Define the function

$$\widetilde{f}(x,y) \stackrel{\triangle}{=} f\left(\frac{\xi}{M}, \frac{\eta}{M}\right)$$

• Then the imaging system act like a 2-D convolution.

$$g(x,y) = \frac{1}{M^2}h(x,y) * \tilde{f}(x,y)$$

Point Spread Functions for Optical Imaging Systems

• Definition: h(x, y) is known as the *point spread function* of the imaging system.

$$g(x,y) = \frac{1}{M^2}h(x,y) * \tilde{f}(x,y)$$

• Notice that when $f(x,y) = \delta(x,y)$

$$\begin{array}{ll} g(x,y) \; = \; \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \delta(\xi,\eta) h(x-M\xi,y-M\eta) d\xi d\eta \\ = \; h(x,y) \end{array}$$

Transfer Functions for Optical Imaging Systems

• In the frequency domain,

$$G(u,v) = \tilde{F}(u,v) \frac{1}{M} H(u,v)$$

$$\begin{array}{ccc} g(x,y) & \overset{C \not S FT}{\Leftrightarrow} & G(u,v) \\ h(x,y) & \overset{C \not S FT}{\Leftrightarrow} & H(u,v) \\ \tilde{f}(x,y) & \overset{C \not S FT}{\Leftrightarrow} & \tilde{F}(u,v) \end{array}$$

• The Optical Transfer Function (OTF) is

$$\frac{H(u,v)}{H(0,0)}$$

ullet The Modulation Transfer Function (MTF) is

$$\left| \frac{H(u,v)}{H(0,0)} \right|$$