

EE 438 Digital Signal Processing with Applications

Homework #8 due 11/10/95

1. An analog speech signal has a bandwidth of 3kHz and can be modeled as a stationary random process with a marginal probability density that is Gaussian with mean zero and variance 1. You are asked to design a system to sample, quantize and store the speech signal on a computer.
 - a) Compute the Nyquist sampling rate for the data.
 - b) Choose a quantizer range so that the probability of overload is approximately 0.02. (**Hint:** You will need to use a table for the cumulative distribution function of a Gaussian random variable.)
 - c) Assuming that the quantization noise may be modeled as a random variable uniformly distributed between $[-\Delta/2, \Delta/2]$, and a B bit quantizer is used, determine an expression for the average signal-to-noise power ratio in dB defined as

$$SNR = 10 \log_{10} \frac{E\{(y(n))^2\}}{E\{(\varepsilon(n))^2\}}$$

where $y(n)$ are the samples of the speech signal before quantization, and $\varepsilon(n)$ are the quantization errors.

- d) Find the minimum number of bits so that $SNR \geq 30$.
 - e) Using the result of d) and a) find the number of bits/second required to digitize the speech data.
2. Compute the DSFT $X(e^{j\mu}, e^{j\nu})$ of the following functions
 - a. $x(n, m) = a^n u(n) \delta(m)$
 - b. $x(n, m) = a^{|n+m|} u(m)$

3. A 2-D linear shift invariant discrete space system has an impulse response of

$$h(m, n) = \delta(m, n) - 0.1\{u(m+1) - u(m-2)\}\{u(n+1) - u(n-2)\}$$

- a) Find the 2-D frequency response of this system by computing the 2-D DSFT

$$H(e^{j\mu}, e^{j\nu}) = \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} h(m, n) e^{-j(\mu m + \nu n)}$$

(Hint: use the fact that $h(m, n) - \delta(m, n)$ is a separable function.)

- b) Use Matlab to compute the approximate DSFT of $h(m,n)$ on the region $[-\pi, \pi] \times [-\pi, \pi]$. Plot the magnitude of the DSFT using the "mesh" command.
- c) Next find the inverse filter $g(m,n)$ which will restore an image filtered by $h(m,n)$. Use the formula

$$g(m,n) = F^{-1}\{1/H(e^{j\mu}, e^{j\nu})\}$$

and the result of part b) to compute $g(m,n)$. Plot your result using mesh.

4. The 2-D DFT is defined by

$$X(l,k) = \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} x(m,n) e^{-j2\pi(lm+kn)/N}$$

Show that the 2-D DFT can be computed by computing a 1-D DFT along n

$$\hat{X}(m,k) = \sum_{n=0}^{N-1} x(m,n) e^{-j2\pi kn/N}$$

followed by a 1-D DFT along m

$$X(l,k) = \sum_{m=0}^{N-1} \hat{X}(m,k) e^{-j2\pi lm/N}$$

5. For a real image $f(x,y)$, show that the CSFT $F(u,v) = |F(u,v)|e^{j\angle F(u,v)}$ has the following symmetry:

- a) $|F(u,v)| = |F(-u,-v)|$
b) $\angle F(u,v) = -\angle F(-u,-v)$

6. Consider the following attenuation function

$$g(x,y) = \text{circ}(x,y)$$

- a) Sketch $g(x,y)$.
b) Find its Radon transform

$$p_\theta(t) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) \delta(x \cos \theta + y \sin \theta - t) dx dy$$

- c) Sketch $p_\theta(t)$.
d) Why doesn't $p_\theta(t)$ depend on θ ?

7. The Radon transform $p_\theta(t)$ of an unknown object $g(x,y)$ is given by

$$p_\theta(t) = \delta(t - \cos(\pi/4 - \theta)) + \delta(t - \cos(-\pi/4 - \theta)) + \delta(t - \cos(3\pi/4 - \theta)) + \delta(t - \cos(-3\pi/4 - \theta))$$

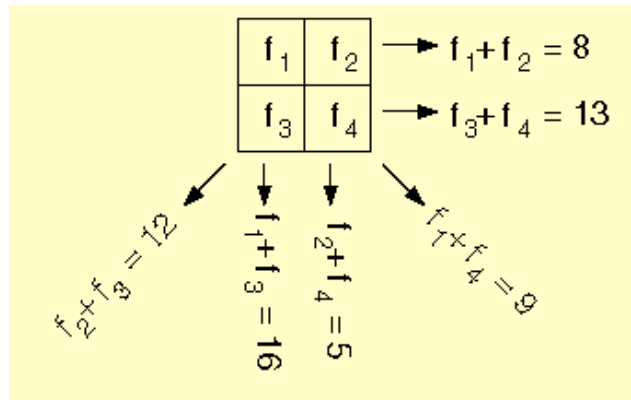
- a) Sketch $p_\theta(t)$ for $\theta = 0, \pi/4, \pi/2, 3\pi/4$, and π .
- b) Calculate

$$P_\theta(f) = \int_{-\infty}^{\infty} p_\theta(t) e^{-j2\pi ft} dt$$

- c) Use the Fourier slice theorem to determine $G(u, v)$.
- d) Take the inverse 2D continuous-space Fourier transform (CSFT) of $G(u, v)$ to determine $g(x, y)$.
- e) Sketch $g(x, y)$.
- f) Verify your answer for $g(x, y)$ by showing that it yields the correct Radon transform

$$p_\theta(t) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) \delta(x \cos \theta + y \sin \theta - t) dx dy$$

8. Consider a discrete tomography problem in which the unknown attenuation function is divided into four cells, and six ray sums are available as shown below:



(Note that the weights are assumed to be unity.) Apply the algebraic reconstruction technique to determine the unknown attenuation values f_1, f_2, f_3, f_4 .