

# EE 438 Digital Signal Processing with Applications

## Homework #3 due 9/15/95

1. Let  $y(n)$  be a D-T signal formed by sampling the C-T signal  $x(t)$  so that  $y(n) = x(nT)$ . For each case do the following:

- i) calculate an analytical expression for  $Y(e^{j\omega})$
- ii) use Matlab to plot  $y(n)$
- iii) use Matlab to plot the magnitude and phase of  $Y(e^{j\omega})$  for  $\omega \in [-\pi, \pi]$ .

- a)  $x(t) = (\text{sinc}(t))^2, T = 1$
- b)  $x(t) = (\text{sinc}(t - 1/4))^2, T = 1$
- c)  $x(t) = (\text{sinc}(t))^2, T = 1/2$
- d)  $x(t) = (\text{sinc}(t))^2, T = 3/2$
- e)  $x(t) = \cos(2\pi t) \text{rect}(t / (8\pi)), T = 1/8$
- f)  $x(t) = \cos(2\pi t) \text{rect}(t / (8\pi)), T = 9/8$
- g)  $x(t) = \cos(2\pi t) \text{rect}(t / (8\pi)), T = 17/8$

2. The analog signal  $x(t) = \cos(2\pi f_0 t)$  is sampled with an ideal sampler at a rate of 8 kHz, filtered with a digital filter having the impulse response

$$h(n) = (\delta(n) + \delta(n-1)) / 2,$$

and then reconstructed as an analog signal  $y(t)$  with an impulse generator followed by an ideal low pass filter with a cutoff frequency of 4 kHz.

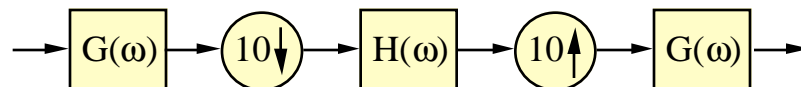
Find the output  $y(t)$  for the following values of  $f_0$ .

- a. 1 kHz,
  - b. 4 kHz,
  - c. 5 kHz.
3. Consider the digital filter described by the following difference equation

$$y[n] = (x[n] + x[n-1] + x[n-2]) / 3$$

- a. Find a simple expression for the frequency response  $H(\omega)$  of this filter.
- b. Sketch the magnitude of  $H(\omega)$ .

Now consider the following digital system,

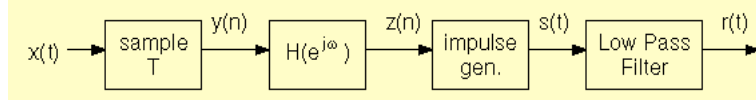


where  $H(\omega)$  is the filter from parts a and b and  $G(\omega)$  is an ideal low-pass filter with a cutoff frequency of  $\pi / 10$  rad/sample and unity gain in the passband.

- c. Find the overall frequency response  $F(\omega)$  for this system.

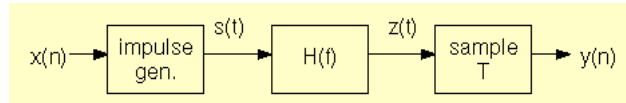
- d. Sketch the magnitude of  $F(\omega)$ .
- e. Discuss the possible advantages of a system like that shown above compared to directly implementing a digital filter with frequency response  $F(\omega)$  as a single stage.

4. The diagram below shows a digital signal processing system.



Assume that the signal  $x(t)$  is band limited to half the sampling frequency  $f_s = 1/T$ . Also assume that the low pass filter is ideal with cut off frequency  $f_s/2$ .

- a) Compute  $Z(e^{j\omega})$  in terms of  $X(f)$  and  $H(e^{j\omega})$ .
  - b) Compute  $R(f)$  in terms of  $X(f)$  and  $H(e^{j\omega})$ .
  - c) Compute the impulse response of the digital filter  $h(n)$  so that the complete system produces a delay of  $T/2$ .
  - d) Is the complete system linear? Is it time invariant? Explain your answer.
5. The following system processes a digital signal by converting it to a continuous time signal, filtering it, and converting it back to discrete time. The sampling rate is  $T = 1/f_s$ , and the filter  $H(f)$  is band limited to  $|f| < f_s/2$ .



Compute expressions for each of the following in terms of  $X(e^{j\omega})$  and  $H(f)$ .

- a)  $S(f)$
  - b)  $Z(f)$
  - c)  $Y(e^{j\omega})$
  - d) You are told that the input/output behavior of the system should be  $\frac{Y(e^{j\omega})}{X(e^{j\omega})} = G(e^{j\omega})$ . Choose  $H(f)$  in terms of  $G(e^{j\omega})$  to achieve this behavior.
6. A real A/D converter does not sample at a single instant. Instead, it averages over a small window. Mathematically, the sampled value  $y(n)$  of an analog signal  $x(t)$  is given by

$$y(n) = \int_{-\infty}^{\infty} \omega(t) x(t + nT) dt$$

where  $\omega(t)$  is a small window. Assume that  $X(f)$  is band limited to  $|f| < 1/(2T)$ .

- a) Show that  $y(n) = v(nT)$  where  $v(t) = \omega(-t) * x(t)$ .
- b) Calculate  $Y(e^{j\omega})$  in terms of  $W(f)$  and  $X(f)$ .
- c) Find a digital filter  $H(e^{j\omega})$  which will correct the distortion of the averaging window. (Hint:  $H(e^{j\omega})Y(e^{j\omega})$  should be the DTFT of the ideal sampled signal  $x(nT)$ .)