

## 2.3.2 GENERAL MODEL FOR DISPLAY AND PRINTING PROCESSES

### Line-Continuous Scanning Systems

$$g_r(x, y) = \int_{-\infty}^{\infty} p_w[x - x_s(t), y - y_s(t)] s(t) dt$$

$g_r(x, y)$  — reconstructed image

$p_w(x, y)$  — write spot

$s(t)$  — scan signal

$$s(t) = \tilde{g}[x_s(t), y_s(t)]$$

$$\tilde{g}(x, y) = p(-x, -y) ** g(x, y)$$

Recall

$$\tilde{\mathbf{g}}_s(\mathbf{x}, y) = \mathbf{q}(\mathbf{x}, y) \tilde{\mathbf{g}}(\mathbf{x}, y)$$

$$\mathbf{q}(\mathbf{x}, y) = \int_{-\infty}^{\infty} \delta[\mathbf{x} - \mathbf{x}_s(t), y - y_s(t)] dt$$

$$\mathbf{g}_r(\mathbf{x}, y) = \int_{-\infty}^{\infty} p_w[\mathbf{x} - \mathbf{x}_s(t), y - y_s(t)] \tilde{\mathbf{g}}[\mathbf{x}_s(t), y_s(t)] dt$$

$$= \int_{-\infty}^{\infty} \left\{ \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} p_w(\mathbf{x} - \xi, y - \eta) \tilde{\mathbf{g}}(\xi, \eta) \right.$$

$$\left. \times \delta[\xi - \mathbf{x}_s(t), \eta - y_s(t)] d\xi d\eta \right\} dt$$

$$\begin{aligned}
g_r(\mathbf{x}, \mathbf{y}) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} p_w(\mathbf{x} - \xi, \mathbf{y} - \eta) \tilde{g}(\xi, \mathbf{n}) \\
&\quad \times \left\{ \int_{-\infty}^{\infty} \delta[\xi - \mathbf{x}_s(t), \eta - \mathbf{y}_s(t)] dt \right\} d\xi d\eta \\
&= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} p_w(\mathbf{x} - \xi, \mathbf{y} - \eta) \tilde{g}(\xi, \eta) q(\xi, \eta) d\xi d\eta \\
&= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} p_w(\mathbf{x} - \xi, \mathbf{y} - \eta) \tilde{g}_s(\xi, \eta) d\xi d\eta \\
&= p_w(\mathbf{x}, \mathbf{y}) ** \tilde{g}_s(\mathbf{x}, \mathbf{y})
\end{aligned}$$

## Matrix-Addressable Systems

$$g_r(x, y) = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} s_{mN+n} p_w(x - mX, y - nY)$$

$$s_{mN+n} = \tilde{g}(mX, nY)$$

Recall

$$\tilde{g}_s(x, y) = q(x, y) \tilde{g}(x, y)$$

$$q(x, y) = \sum_m \sum_n \delta(x - mX, y - nY)$$

$$\begin{aligned}
g_r(x, y) &= \sum_m \sum_n \tilde{g}(mX, nY) p_w(x - mX, y - nY) \\
&= \sum_m \sum_n \left\{ \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \tilde{g}(\xi, \eta) p_w(x - \xi, y - \eta) \right. \\
&\quad \left. \times \delta(\xi - mX, \eta - nY) d\xi d\eta \right\} \\
&= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \tilde{g}(\xi, \eta) p_w(x - \xi, y - \eta) \\
&\quad \times \left\{ \sum_m \sum_n \delta(\xi - mX, \eta - nY) \right\} d\xi d\eta
\end{aligned}$$

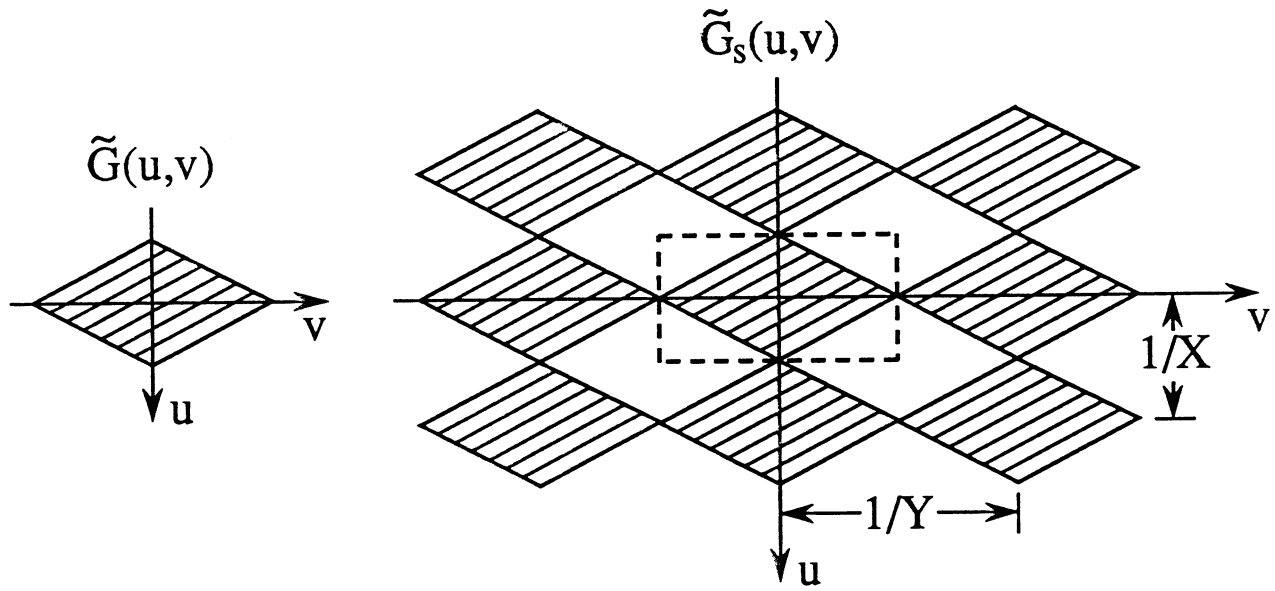
$$\begin{aligned}
g_r(\mathbf{x}, \mathbf{y}) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \tilde{g}(\xi, \eta) p_w(\mathbf{x} - \xi, \mathbf{y} - \eta) q(\xi, \eta) d\xi d\eta \\
&= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} p_w(\mathbf{x} - \xi, \mathbf{y} - \eta) \tilde{g}_s(\xi, \eta) d\xi d\eta \\
&= p_w(\mathbf{x}, \mathbf{y}) ** \tilde{g}_s(\mathbf{x}, \mathbf{y})
\end{aligned}$$

## General Model

$$g_r(x, y) = P_w(x, y) ** \tilde{g}_s(x, y)$$

$$G_r(u, v) = P_w(u, v) \tilde{G}_s(u, v)$$

# Ideal Reconstruction



$$\tilde{G}_s(u,v) = \frac{1}{XY} \sum_k \sum_l \tilde{G}(u - k/X, v - l/Y)$$

$$P_w(u,v) = XY \text{rect}(Xu, Yv)$$



## Spatial domain interpretation

$$p_w(\mathbf{x}, y) = \text{sinc}(\mathbf{x}/X, y/Y)$$

$$g_r(\mathbf{x}, y) = p_w(\mathbf{x}, y) ** \tilde{g}_s(\mathbf{x}, y)$$

$$\tilde{g}_s(\mathbf{x}, y) = q(\mathbf{x}, y) \tilde{g}(\mathbf{x}, y)$$

$$q(\mathbf{x}, y) = \sum_m \sum_n \delta(\mathbf{x} - mX, y - nY)$$

$$\tilde{g}_s(\mathbf{x}, y) = \sum_m \sum_n \tilde{g}(mX, nY) \delta(\mathbf{x} - mX, y - nY)$$

$$g_r(x, y) = \sum_m \sum_n \tilde{g}(mX, nY) \operatorname{sinc}\left(\frac{x - mX}{X}, \frac{y - nY}{Y}\right)$$

$$g_r(kX, \ell Y) = \sum_m \sum_n \tilde{g}(mX, nY) \operatorname{sinc}\left(\frac{kX - mX}{X}, \frac{\ell Y - nY}{Y}\right)$$

$$= \sum_m \sum_n \tilde{g}(mX, nY) \operatorname{sinc}(k-m, \ell-n)$$

$$= \tilde{g}(kX, \ell Y)$$

If Nyquist conditions are satisfied, *i.e.*  $\tilde{G}(u, v) = 0$   
 $|u| > 1/(2X)$ ,  $|v| > 1/(2Y)$ , then

$$g_r(x, y) \equiv \tilde{g}(x, y)$$

## Zero Order Hold Reconstruction

$$p_w(x, y) = \text{rect}(x/X, y/Y)$$

$$P_w(u, v) = XY \text{sinc}(Xu, Yv)$$

$$G_r(u, v) = \text{sinc}(Xu, Yv) \sum_k \sum_\ell \tilde{G}(u - k/X, v - \ell/Y)$$
$$\neq \tilde{G}(u, v)$$

## Aliasing Artifacts

- due to presence of replications for which  $(k, \ell) \neq (0, 0)$  in spectrum of reconstructed image

$$G_r(u, v) = P_w(u, v) \sum_k \sum_{\ell} \tilde{G}(u - k/X, v - \ell/Y)$$

- result in spurious low frequency patterns in displayed or printed image
  - moire patterns
  - jagged rendition of straight edges

# Example illustrating moire formation during sampling of a sinewave grating

