

ECE 301 HW4 Solutions

$$1) a: y(t) = \int_{-\infty}^{\infty} h(\tau) x(t-\tau) d\tau$$

$$\begin{aligned} \frac{d}{dt} y(t) &= \frac{d}{dt} \int_{-\infty}^{\infty} h(\tau) x(t-\tau) d\tau \\ &= \int_{-\infty}^{\infty} h(\tau) \frac{d}{dt} x(t-\tau) d\tau \\ &= h(t) * \frac{dx(t)}{dt} \end{aligned}$$

$$b: y[n] = \sum_k x[k] h[n-k]$$

$$\begin{aligned} \sum_n y[n] &= \sum_n \sum_k x[k] h[n-k] = \sum_k \sum_n x[k] h[n-k] \\ &= \sum_k \left[ x[k] \sum_{n=-\infty}^{\infty} h[n-k] \right] \\ &= \left( \sum_k x[k] \right) \left( \sum_n h[n] \right) = \left( \sum_n x[n] \right) \left( \sum_n h[n] \right) \end{aligned}$$

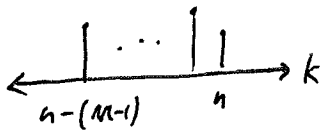
$$c: x(t) \text{ is periodic} \iff x(t+kT) = x(t) \quad k \in \mathbb{Z}$$

$$\begin{aligned} y(t+kT) &= x(t+kT) * h(t) && \text{since the system is time-invariant} \\ &= x(t) * h(t) \\ &= y(t) \iff y(t) \text{ is periodic} \end{aligned}$$

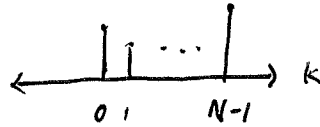
$$2) \quad x[n] : 0 \leq n < M$$

$$h[n] : 0 \leq n < N$$

$$a: \quad x[n-k]$$

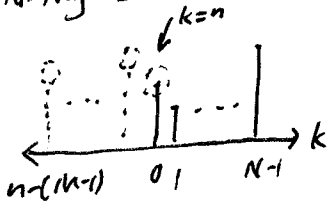


$$h[k]$$



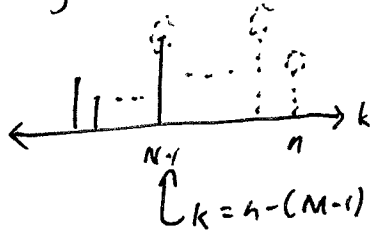
$$y[n] = \sum_k h[k] x[n-k]$$

Starting ~~Parameter~~ Condition:



$$n \geq 0$$

Ending Condition:



$$n-(M-1) \leq N-1$$

$$n \leq N+M-2$$

$$L_1 = 0 \quad L_2 = N+M-2$$

$$b: \quad x[n] = u[n] - u[n-5]$$

$$M=5$$

$$h[n] = 2(u[n] - u[n-3])$$

$$N=3$$

$$y[n] = x[n] * h[n]$$

$$= x[n] * 2(\delta[n] + \delta[n-1] + \delta[n-2])$$

$$= 2x[n] + 2x[n-1] + 2x[n-2]$$

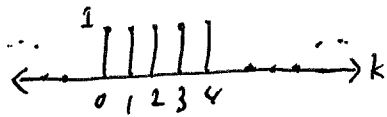
$$= 2(u[n] - u[n-5]) + 2(u[n-1] - u[n-6]) + 2(u[n-2] - u[n-7])$$

$y[n] \neq 0$  for  $0 \leq n \leq 6$  } confirmed!

$$N+M-2 = 5+3-2 = 6$$

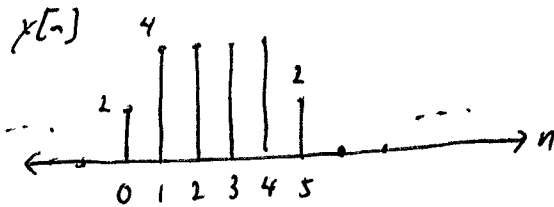
$$c: \quad x[n] = u[n] - u[n-5]$$

$$x[k] \quad M=5$$



$$h[n] = 2(u[n] - u[n-2])$$

$$h[n-k] \quad N=2$$



$$N+M-2 = 5+2-2 = 5$$

confirmed!

$$3) \quad a: \quad x[n] * y[n] = \sum_k x[k] y[n-k] = \sum_l x[n-l] y[l] = y[n] * x[n]$$

$$\text{Let } l = n-k$$

$$b: \quad (x[n] * y[n]) * z[n] = w[n] = \sum_k x[k] y[n-k]$$

$$(x[n] * y[n]) * z[n] = \sum_l w[l] z[n-l] = \sum_l \sum_k x[k] y[l-k] z[n-l]$$

$$= \sum_k \sum_l x[k] y[l-k] z[n-l]$$

$$= \sum_k x[k] \sum_l y[l-k] z[n-l]$$

$$= \sum_k x[k] \sum_m y[m] z[n-m-k]$$

$$= \sum_m y[m] \sum_k x[k] z[n-m-k]$$

$$= \sum_k x[k] \sum_m y[n-m-k] z[m]$$

$$= \sum_k x[k] q[n-k]$$

$$= x[n] * q[n] = x[n] * (y[n] * z[n])$$

~~Let m = n-l~~

$$\text{Let } m = n-l$$

$$l = n-m$$

$$\text{Let } q[n] = \sum_m y[n-m] z[m]$$

$$c: x[n] * (y[n] + z[n]) = \sum_k x[k] (y[n-k] + z[n-k])$$

$$= \sum_k x[k] y[n-k] + \sum_k x[k] z[n-k]$$

$$= x[n] * y[n] + x[n] * z[n]$$

d: Proof by contradiction ( $\Leftarrow$ )  $\left| \begin{array}{l} (\Rightarrow) \sum_k h[k] x[n-k] = \sum_{k=0}^n h[k] x[n-k] \text{ which} \\ \text{is causal} \end{array} \right.$

Suppose  $h[n_0] \neq 0$  for  $n_0 < 0$  & the system is causal

$$y[n] = x[n] * h[n] = \sum_k h[k] x[n-k]$$

$$= \sum_{k \neq n_0} h[k] x[n-k] + h[n_0] x[n-n_0]$$

Note  $y[n]$  is a function of  $x[n-n_0]$ , which is a future value of  $x[n]$  since  $n_0 < 0$ . Thus, there is a contradiction and  $h[n] = 0$  for all  $n < 0 \Leftrightarrow$  causal system

4) a:  $h[n] = \left(\frac{1}{2}\right)^n u[-n]$

non-causal:  $h[-1] = 2 \neq 0$

non-stable:  $\sum_n |h[n]| = \sum_{n=-\infty}^0 \left(\frac{1}{2}\right)^n = \sum_{n=0}^{\infty} 2^n = \infty$

b:  $h[n] = \left(-\frac{1}{2}\right)^n u[n] + (1.01)^n u[n-1]$

causal:  $h[n] = 0$  for all  $n < 0$

unstable:  $\sum_{n=1}^{\infty} (1.01)^n = \infty$

c:  $h(t) = e^{2t} u(-1-t)$

non-causal:  $h(-2) = e^{-4} \neq 0$

unstable:  $\int_{-\infty}^{\infty} |h(t)| dt = \int_{-\infty}^{-1} e^{2t} dt = \frac{1}{2} e^{2t} \Big|_{-\infty}^{-1} = \frac{1}{2} (e^{-2} - 0) < \infty$

d:  $h(t) = t e^{-t} u(t)$

causal:  $h(t) = 0$  for all  $t < 0$

stable:  $\int_{-\infty}^{\infty} |h(t)| dt = \int_0^{\infty} t e^{-t} dt = -t e^{-t} \Big|_0^{\infty} + \int_0^{\infty} e^{-t} dt = -0 + 0 - e^{-t} \Big|_0^{\infty} = 1 < \infty$

$u = t \quad dv = e^{-t} dt$   
 $du = dt \quad v = -e^{-t}$

$$5) \frac{d}{dt} y(t) = -ay(t) + x(t)$$

$$h(t) = e^{-at} u(t)$$

$$\begin{aligned} \frac{d}{dt} h(t) &= -ae^{-at} u(t) + e^{-at} \delta(t) = -ae^{-at} u(t) + \delta(t) \\ &= -ay(t) + \delta(t) \end{aligned}$$

$$6) y[n] = \frac{1}{2} y[n-1] + x[n]$$

$$a: h[n] = \left(\frac{1}{2}\right)^n u[n]$$

$$b: y[n] = \sum_{k=0}^{\infty} \left(\frac{1}{2}\right)^k x[n-k]$$

$$\begin{aligned} c: y[n] &= \sum_{k=0}^{\infty} \left(\frac{1}{2}\right)^k u[n-k] = u[n] \sum_{k=0}^n \left(\frac{1}{2}\right)^k \\ &= u[n] \frac{1 - \left(\frac{1}{2}\right)^{n+1}}{1 - \frac{1}{2}} = u[n] 2 \left(1 - \left(\frac{1}{2}\right)^{n+1}\right) \\ &= u[n] \left(2 - \left(\frac{1}{2}\right)^n\right) \end{aligned}$$

$$d: y[n] = \sum_{k=0}^{\infty} \left(\frac{1}{2}\right)^k (1) = \frac{1}{1 - \frac{1}{2}} = 2$$

$$7) S[e^{j\omega t}] = C e^{j(\omega t + \phi)} \text{ for an LTI system}$$

a: NOT LTI

b: perhaps LTI

c: NOT LTI

d: NOT LTI

e: NOT LTI

f: perhaps LTI

$$g) a: y[n] = \sum_k h[k] x[n-k]$$

$$b: x[n] = e^{j\omega n}$$

$$y[n] = \sum_k h[k] e^{j\omega(n-k)} = e^{j\omega n} \underbrace{\sum_k h[k] e^{-j\omega k}}_{C(\omega)}$$

$$c: C^*(\omega) = \sum_k h^*[k] e^{j\omega k} = \underbrace{4}_{\text{if } h[k] \text{ is real-valued}} \sum_k h[k] e^{j\omega k} \quad \text{if } h[k] \text{ is real-valued}$$

$$= C(-\omega)$$

$$d: x[n] = \cos(\omega n) = \frac{1}{2}(e^{j\omega n} + e^{-j\omega n})$$

$$y[n] = \frac{1}{2} C(\omega) e^{j\omega n} + \frac{1}{2} C(-\omega) e^{-j\omega n} = \frac{1}{2} C(\omega) e^{j\omega n} + \frac{1}{2} C^*(\omega) e^{-j\omega n}$$

$$\text{Let } C(\omega) = a + jb$$

$$= \frac{1}{2}(a + jb)(\cos(\omega n) + j \sin(\omega n)) + \frac{1}{2}(a - jb)(\cos(\omega n) - j \sin(\omega n))$$

$$= \frac{1}{2} \cos(\omega n)(a + jb + a - jb) + \frac{j}{2} \sin(\omega n)(a + jb - a + jb)$$

$$= \operatorname{Re}\{C(\omega)\} \cos(\omega n) - \operatorname{Im}\{C(\omega)\} \sin(\omega n)$$

$$e: x[n] = B \cos(\omega n + \phi) = \frac{B}{2}(e^{j(\omega n + \phi)} + e^{-j(\omega n + \phi)})$$

$$y[n] = \frac{B}{2} e^{j\phi} C(\omega) e^{j\omega n} + \frac{B}{2} e^{-j\phi} C(-\omega) e^{-j\omega n}$$

$$= \frac{B}{2} e^{j\phi} C(\omega) e^{j\omega n} + \frac{B}{2} e^{-j\phi} C^*(\omega) e^{-j\omega n}$$

$$= \frac{B}{2} e^{j\phi} (a + jb)(\cos(\omega n + \phi) + j \sin(\omega n + \phi)) + \frac{jB}{2} (a - jb)(\cos(\omega n + \phi) - j \sin(\omega n + \phi))$$

$$= \frac{B}{2} \cos(\omega n + \phi)(a + jb + a - jb) + \frac{jB}{2} \sin(\omega n + \phi)(a + jb - a + jb)$$

$$= B \operatorname{Re}\{C(\omega)\} \cos(\omega n + \phi) - B \operatorname{Im}\{C(\omega)\} \sin(\omega n)$$

$$f: x[n] = \sin(\omega n) = \frac{1}{2j} (e^{j\omega n} - e^{-j\omega n})$$

$$\begin{aligned} y[n] &= \frac{1}{2j} C(\omega) e^{j\omega n} - \frac{1}{2j} C^*(\omega) e^{-j\omega n} \\ &= \frac{1}{2j} (a+jb)(\cos(\omega n) + j\sin(\omega n)) - \frac{1}{2j} (a-jb)(\cos(\omega n) - j\sin(\omega n)) \\ &= \frac{1}{2j} \cos(\omega n)(a+jb - a+jb) + \frac{1}{2} \sin(\omega n)(a+jb - a+jb) \\ &= \operatorname{Im}\{C(\omega)\} \sin(\omega n) - \operatorname{Re}\{C(\omega)\} \cos(\omega n) \end{aligned}$$

$$g: x[n] = B \sin(\omega n + \phi) = \frac{B}{2j} (e^{j(\omega n + \phi)} - e^{-j(\omega n + \phi)})$$

$$\begin{aligned} y[n] &= \frac{B}{2j} e^{j\phi} C(\omega) e^{j\omega n} - \frac{B}{2j} e^{-j\phi} C^*(\omega) e^{-j\omega n} \\ &= \frac{B}{2j} (a+jb)(\cos(\omega n + \phi) + j\sin(\omega n + \phi)) - \frac{B}{2j} (a-jb)(\cos(\omega n + \phi) - j\sin(\omega n + \phi)) \\ &= \frac{B}{2j} \cos(\omega n + \phi)(a+jb - a+jb) + \frac{B}{2} \sin(\omega n + \phi)(a+jb + a-jb) \\ &= B \operatorname{Im}\{C(\omega)\} \sin(\omega n + \phi) + B \operatorname{Re}\{C(\omega)\} \cos(\omega n + \phi) \end{aligned}$$