

Satellite Photogrammetry Topics -- Spring 2017

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course web page: [http://engineering.purdue.edu/~bethel/photo2\\_17](http://engineering.purdue.edu/~bethel/photo2_17)  
(up later this week)

no textbook

recommended references:

1. pleiades use guide (math model), on website
2. building earth observation cameras, george joseph (system design)
3. physical principles of remote sensing, rees (radiometry)
4. notes from earlier versions of this course

2 exams: each 25%

HW: 50%

homeworks are a sequence of tasks implement the math model for worldview X, each one depends on correctness of previous ones

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motivation for mirror optics: chromatic aberration, weight  
 on-axis vs. off-axis telescope design  
 history of satellite remote sensing  
 synchronous vs. asynchronous scanning  
 digital globe: worldview 1,2,3

reference coordinate systems

coordinate transformations

- (1) phi,lambda,h -> cartesian, ECF, closed form
- (2) ECF -> phi, lambda, h, iterative
- (3) ECF -> local cartesian (topocentric)

support data: .geo, .imd, .rpb, .eph, .att

rotation parameters:

- (1) euler angles (roll, pitch, yaw), singularities
- (2) direction cosines
- (3) quaternions
- (4) axis-angle

image to ground algorithm

systematic errors:

- (1) atmospheric refraction
- (2) velocity aberration

matlab functions needed:

- (1) [X;Y;Z]'=FI2G(l,s,h)
- (2) [PHI; LAM]'=FI2G\_PL(l,s,h), just a wrapper
- (3) [dPHI; dLAM]'=FI2G\_PL\_0(l,s,h,phi,lam), just a wrapper
- (4) [l;s]=FG2I(phi,lambda,h), solve eqn (3) for l,s by iteration  
 verify that (2) & (4) are inverses

adjustable parameters

resection (refine EO given GCP's)

2-image triangulation with tie points and GCP's

replacement model

standards for replacement model parameters

coordinate normalization

solving singular NE

verify accuracy

setup stereo model in LPS

image interpolation

nearest neighbor

bilinear

bicubic

image pyramid

orthorectification

integrate with vectors in ArcGIS

radiometric units

radiometry, radiometric design

resolution, resolving power

mission design

CCD operation

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(probably not time for all these topics, maybe some)

orbit mechanics, 2-body problem

transformation state vector <-> kepler elements

time concepts solar, sidereal, ut1, utc, tai, gps, gast, JD, MJD

transformation ECF <-> ECI, precession, nutation, GAST, polar motion

velocity transformation

circular error derivation

SIFT tie point generation for triangulation

OpenGL quad buffered & anaglyph stereo

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photo2\_17\_topics