

sph01

```

sph01
np =
n = 341
      1023
u = 4
n0 = 686
r = 337
c = 341
keep_going =
  1
iter =
  1
ans =
  Columns 1 through 3
    0.00375729684859144      -0.0159687429771286      0.0101736827247065
  Column 4
    -0.0276730388451996
iter =
  2
ans =
  Columns 1 through 3
    -0.000365746146370232      8.72845926982607e-05      -9.41655491024595e-05
  Column 4
    0.000314721675637149
iter =
  3
ans =
  Columns 1 through 3
    -6.80321876722892e-07      -2.69856687137089e-06      8.28905520374631e-07
  Column 4
    -1.28339115607957e-06
iter =
  4
ans =
  Columns 1 through 3
    -5.67214488999497e-08      1.51086894033576e-08      -4.8672242006541e-09
  Column 4
    -2.7268248810915e-08
iter =
  5
ans =
  Columns 1 through 3
    -1.80250233365697e-10      -1.64591037108114e-09      3.15178651518561e-10
  Column 4
    -7.42040268208472e-10
we have converged
p =
      3.05339081347865
      1.91411585651148
     -0.539919658470921
      0.272640371428992
vTv =
  0.000631268534497871
sig0sqr_hat =
  1.87320039910347e-06
TS =
  25.2507413799148
cv1 =
  288.036334648026
cv2 =
  389.750657067005
cov_xz =
  8.47999609186644e-08      -1.19661495428317e-08
 -1.19661495428317e-08      2.65298662957026e-08
cov_yz =
  4.7087588177851e-08      -7.15667686634169e-09
 -7.15667686634168e-09      2.65298662957026e-08
vec =
  0.981075980706585
 -0.193623139321242
vec2 =
  0.193623139321242
  0.981075980706585
a =
  0.000635727132686265
b =
  0.000334757894860966
theta =
 -0.194853836285083
thetad =
 -11.1643024410683
vec =
  0.954115923426774
 -0.299437480391942
vec2 =
  0.299437480391942

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0.954115923426774
a =
0.000478277240919799
b =
0.000335557398853812
theta =
-0.304103027872592
thetad =
-17.4238200342487
diary off

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% sph01.m 4-dec-2013

% update the observations
% LS fit of sphere to point cloud
% batch solution

degrad=180/pi;
xc=3.05;
yc=1.93;
zc=-0.55;
R=0.30;
p=[xc;yc;zc;R];
% summary stats
vTv=0.0;
sumvxsqr=0;
sumvysqr=0;
sumvzsqr=0;
maxvx=0;
maxvy=0;
maxvz=0;
load sphere_m.xyz
% XYZ original observations
X=sphere_m(:,1);
Y=sphere_m(:,2);
Z=sphere_m(:,3);
[np,nn]=size(X);
% X0Y0Z0 updated observations
X0=X;
Y0=Y;
Z0=Z;
np
n=np*3
u=4
n0=u + np*2
r=n-n0
sigi=0.005; % 1 mm
sig0=0.005;
% W,Q=identity so we leave it out of the solution
c=r+u
A=zeros(c,n);
B=zeros(c,u);
f=zeros(c,1);

keep_going=1
iter=0;
while(keep_going == 1)
    iter=iter+1
    % get current parameters from the parameter vector
    xc=p(1);
    yc=p(2);
    zc=p(3);
    R=p(4);

    for i=1:np
        % c is also equal to np so we use i for row counter
        XX=X0(i);
        YY=Y0(i);
        ZZ=Z0(i);
        F=R - sqrt((XX-xc)^2 + (YY-yc)^2 + (ZZ-zc)^2);
        d=sqrt((XX-xc)^2 + (YY-yc)^2 + (ZZ-zc)^2);
        dFdX=-(XX-xc)/d;
        dFdY=-(YY-yc)/d;
        dFdZ=-(ZZ-zc)/d;
        dFdx=-dFdX;
        dFdyc=-dFdY;
        dFdzc=-dFdZ;
        dFdr=1;
        j=(i-1)*3 + 1;
        A(i,j:j+2)=[dFdX dFdY dFdZ];
        B(i,:)= [dFdx dFdy dFdz dFdr];
        f(i)=-F - A(i,j:j+2)*[X(i)-XX;Y(i)-YY;Z(i)-ZZ];
    end
    Qe=A*A';
    We=inv(Qe);
    N=B'*We*B;
    t=B'*We*f;
    del=inv(N)*t;
    del'
    k=We*(f-B*del);
    v=A'*k;
    for i=1:np
        idx=(i-1)*3 + 1;
        X0(i)=X(i) + v(idx);
        Y0(i)=Y(i) + v(idx+1);
        Z0(i)=Z(i) + v(idx+2);
    end

    p=p+del;
    if((all(abs(del) < 1e-08)) && (iter < 10))
        disp('we have converged');
    end
end

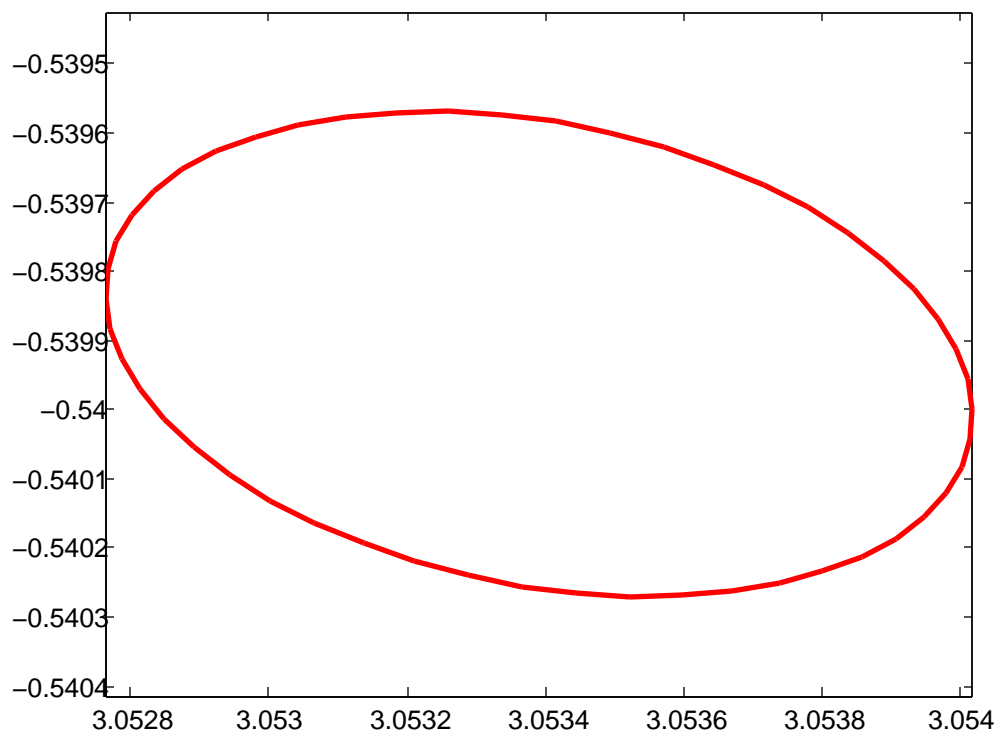
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sph01

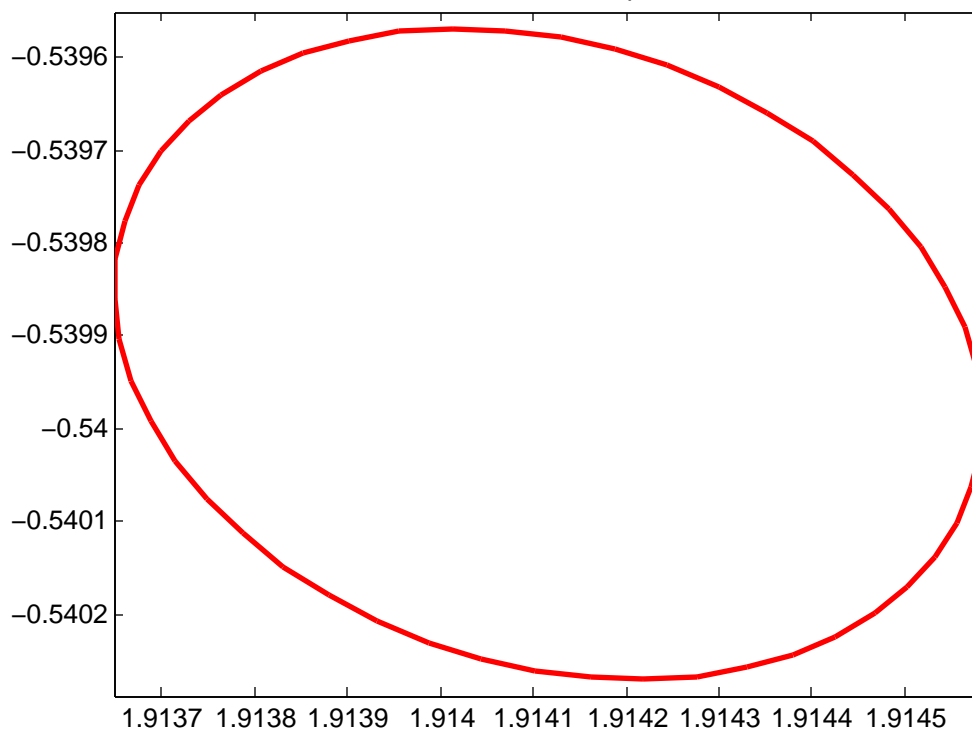
```
    keep_going=0;
else
    if(iter >= 10)
        keep_going=0;
    end
end
end % while(keep_going==1)

p
vTv=v'*v
sig0sqr_hat=vTv/r
TS=vTv/sig0^2
alpha=0.05;
cv1=icdf('chi2',alpha/2,r)
cv2=icdf('chi2',1-alpha/2,r)
Qdd=inv(N);
Sdd=sig0sqr_hat*Qdd;
cov_xz=[Sdd(1,1) Sdd(1,3); Sdd(3,1) Sdd(3,3)]
cov_yz=[Sdd(2,2) Sdd(2,3); Sdd(3,2) Sdd(3,3)]
plot_conf_ell(cov_xz,0,r,0.90,xc,zc,1.0);
title('XZ 90% conf. ellipse');
axis equal
figure(2)
plot_conf_ell(cov_yz,0,r,0.90,yc,zc,1.0);
title('YZ 90% conf. ellipse');
axis equal
```

XZ 90% conf. ellipse



YZ 90% conf. ellipse



par7

```
par7
np = 5
n = 30
n0 = 22
r = 8
u = 7
c = 15
keep_going = 1
iter = 1
del = 1
0.0804044117647059
0.0610775862068966
0.104017857142857
0.19345
0.0452518907563025
0.0350402129817446
0.0149543972761519
iter = 2
del = 2
0.0162517837416517
-0.0100162922809297
-0.00447064206642834
-0.0194416377267072
0.00129893508795582
-0.00877566736778424
-0.0313947970957667
iter = 3
del = 3
0.00020933881768169
0.000170187135229218
0.000414920367784622
0.0002478528023143
0.000158310370835561
1.74806621536016e-05
-0.0007921828719581
iter = 4
del = 4
1.71878536131082e-06
4.93194807351527e-08
-3.65480824089342e-06
-1.84925671106535e-06
-1.47665339127639e-06
-8.87469377536258e-06
6.83989953303789e-06
iter = 5
del = 5
2.16638759539708e-08
1.17808153258994e-08
8.83678929655387e-08
2.14493578151356e-08
-5.8519501312886e-08
-1.56533161879667e-08
-1.63572578424246e-07
iter = 6
del = 6
1.74454535799197e-10
-4.22210910587505e-11
-6.82690731126361e-10
-1.60870430845235e-10
-4.16139276272291e-10
-7.90524597926579e-10
1.20523032159962e-09
we have converged
p = 1.09686727494773
0.0512315421192711
0.0999585683211749
0.174254387107383
0.046707600626062
0.0262731351384978
-0.0172259051593879
vTv = 0.00607860449405709
sig0sqr_hat = 0.000759825561757137
TS = 6.75400499339677
cv1 =
```

```
cv2 = 2.17973074725265
half_intvl = 17.5345461394846
90% conf intvl scale 0.0140446015754115
ans = 1.08282267319787
diary off 1.11091187634869
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par7


```

% par7.m 4-dec-2013
% hw5 for data1

X=[1;3;3;1;2];
Y=[1;1;5;5;3];
Z=[0;0;0;0;3];
x=[1.275;3.493;4.203;2.147;2.502];
y=[0.930;0.561;4.866;5.202;3.071];
z=[0.013;0.282;0.017;-0.213;3.341];
X0=X;
Y0=Y;
Z0=Z;
x0=x;
y0=y;
z0=z;

% initial approx
lam=1.0;
om=0.0;
ph=0.0;
kp=0.0;
tx=0.0;
ty=0.0;
tz=0.0;
p=[lam;om;ph;kp;tx;ty;tz];

np=5
n=np*3*2
n0=7+np*3
r=n-n0
u=7
c=r+u
sig=0.03;
sig0=0.03;
% so W=Q=I so we leave it out of expressions

keep_going=1
iter=0;
while(keep_going == 1)
    iter=iter+1
    A=zeros(c,n);
    B=zeros(c,u);
    f=zeros(c,1);
    rowc=1;
    colc=1;
    % extract values from param vector
    lam=p(1);
    om=p(2);
    ph=p(3);
    kp=p(4);
    tx=p(5);
    ty=p(6);
    tz=p(7);
    mw=m1(om);
    mp=m2(ph);
    mk=m3(kp);
    m=mk*mp*mw;

    for i=1:np
        XYZ=[X0(i);Y0(i);Z0(i)];
        xyz=[x0(i);y0(i);z0(i)];
        Ai=[eye(3) -lam*m];
        dFdlam=-m*XYZ;
        dFdw=-lam*mk*mp*[0 0 0;0 -sin(om) cos(om);0 -cos(om) -sin(om)]*XYZ;
        dFdp=-lam*mk*[-sin(ph) 0 -cos(ph);0 0 0;cos(ph) 0 -sin(ph)]*mw*XYZ;
        dFdk=-lam*[-sin(kp) cos(kp) 0;-cos(kp) -sin(kp) 0;0 0 0]*mp*mw*XYZ;
        dFdt=-eye(3);
        Bi=[dFdlam dFdw dFdp dFdk dFdt];
        F=xyz - lam*m*XYZ - [tx;ty;tz];
        fi=-F - Ai*[x(i)-x0(i);y(i)-y0(i);z(i)-z0(i);X(i)-X0(i);Y(i)-Y0(i);Z(i)-Z0(i)];
        A(rowc:rowc+2,colc:colc+5)=Ai;
        B(rowc:rowc+2,:)=Bi;
        f(rowc:rowc+2)=fi;
        rowc=rowc+3;
        colc=colc+6;
    end
    Qe=A*A';
    We=inv(Qe);
    N=B'*We*B;
    t=B'*We*f;
    del=inv(N)*t
    p=p+del;
    k=We*(f-B*del);
    v=A'*k;
    for i=1:np
        idx=(i-1)*6 + 1;
        x0(i)=x(i) + v(idx);
        y0(i)=y(i) + v(idx+1);
        z0(i)=z(i) + v(idx+2);
        X0(i)=X(i) + v(idx+3);
        Y0(i)=Y(i) + v(idx+4);
    end
end

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                                par7
Z0(i)=Z(i) + v(idx+5);
end

if((all(abs(del) < 1e-08)) && (iter < 10))
    disp('we have converged');
    keep_going=0;
else
    if(iter >= 10)
        keep_going=0;
        disp('bailing out - no convergence');
    end
end
end % while(keep_going==1)

P
vTv=v'*v
sig0=sqr_hat=vTv/r
TS=vTv/sig0^2
alpha=0.05;
cv1=icdf('chi2',alpha/2,r)
cv2=icdf('chi2',1-alpha/2,r)
% pass !
Qdd=inv(N);
Sdd=sig0^2*Qdd;

P=0.90;
s=sqrt(Sdd(1,1));
z=icdf('norm',(P+1)/2,0,1);
half_intvl=z*s
disp('90% conf intvl scale');
[lam-half_intvl lam+half_intvl]

```