

Unified LS $Au + B\Delta = f$ (Linear) 29-1

$$\underbrace{v_x - \Delta = -x}$$

$$A\dot{v} + B\Delta = f$$

$$\Delta = x + v_x$$

\leftarrow \uparrow \uparrow
 obs. residual

$$Q_e = \begin{bmatrix} Q_e & 0 \\ 0 & Q_{xx} \end{bmatrix} : \Sigma_{xx} = \begin{bmatrix} \sigma_x^2 & \sigma_{xy} \\ \sigma_{xy} & \sigma_y^2 \end{bmatrix} \quad \Sigma = \sigma_0^2 Q$$

$$W_e = \begin{bmatrix} w_e & 0 \\ 0 & w_{xx} \end{bmatrix}$$

$$\dot{N} = \begin{bmatrix} B^T & -I \\ B^T & -I \end{bmatrix} \begin{bmatrix} w_x & 0 \\ 0 & w_{xx} \end{bmatrix} \begin{bmatrix} B \\ -I \end{bmatrix}$$

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$$\begin{bmatrix} B^T W_e & -W_{xx} \end{bmatrix} \begin{bmatrix} B \\ -I \end{bmatrix} = \begin{bmatrix} B^T W_e B + W_{xx} \end{bmatrix}$$

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$$\dot{t} = \dot{B}^T W_e \dot{f} = \begin{bmatrix} B^T W_e & -W_{xx} \end{bmatrix} \begin{bmatrix} f \\ -x \end{bmatrix} = \begin{bmatrix} B^T W_e f + W_{xx} \cdot x \end{bmatrix}$$

$$\begin{bmatrix} B^T W_e B + W_{xx} \end{bmatrix} \Delta = \begin{bmatrix} B^T W_e f + W_{xx} \cdot x \end{bmatrix}$$

add weight matrix
for parameters

add new term

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Unified LS for nonlinear case:

$$F(l, x) = 0 \quad l^0, x^0$$

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linearize and eqn: $A v + B \Delta = - \underbrace{F(l^0, x^0) - F(l-l^0)}_{f_0}$

$$l + v = l^0 + \Delta$$

$$x + v_x = x^0 + \Delta, \quad v_x - \Delta = \underbrace{x^0 - x}_{f_x}$$

$$A v + B \Delta = f_0$$

$$v_x - \Delta = f_x$$

$$\begin{bmatrix} A & 0 \\ 0 & I \end{bmatrix} \begin{bmatrix} v \\ v_x \end{bmatrix} + \begin{bmatrix} B \\ -I \end{bmatrix} \Delta = \begin{bmatrix} f_0 \\ f_x \end{bmatrix} \dots$$

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$N \Delta = t$

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$$\boxed{\begin{bmatrix} B^T W_e B + W_{xx} \end{bmatrix} \Delta = \begin{bmatrix} B^T W_e f_0 - W_{xx} f_x \end{bmatrix}}$$

U.L.S. for nonlinear problems

$$f_x = x^0 - x$$

current value original value

$\Sigma_{xx}, Q_{xx}, W_{xx}$

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Equivalent techniques in other fields

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o Bayesian Estimators: framework for estimators where you use prior knowledge & distributions

o Ridge Regression $\hat{\beta} = [X^T X + \lambda I]^{-1} X^T y$
 $y \approx X\beta$

o Tikhonov Regularization

$$Ax \approx b$$

$$P=W$$

$$\hat{x} = [A^T P A + Q]^{-1} [A^T P b + Q x_0]$$

$$Q: n \times n, x_0 \quad (1943)$$

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Blunder Detector or Robust Estimators

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$$Q: W^{-1}$$

$$(\pm 10) Q_W = Q - Q_{\mathcal{E}\mathcal{E}} = \underline{Q - B^{-1}B^T}$$

$$Q_{ii} W = \bar{W} : \text{diagonal elements}$$

$$n_i n_i \quad n_i n_i \quad n_i n_i$$

$$W_{ii} = r_i \text{ redundancy number}$$

$$\sum_{i=1}^n r_i = r$$

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properties of r_i

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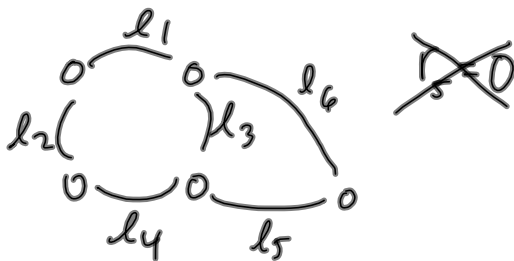
$$0 \leq r_i \leq 1 \quad \mu_i = 1 - r_i$$

$$0 \leq \mu_i \leq 1$$

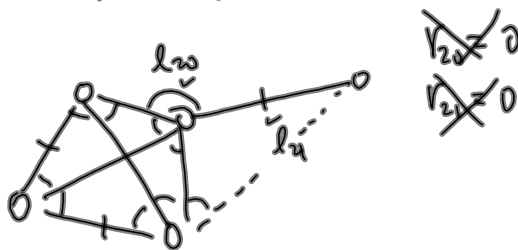
r_i : the fraction of the error in l_i which is revealed in the residual v_i

μ_i : the fraction of the error in l_i which is "absorbed" by the parameter estimator

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- IRLS iteratively reweighted LS 29-9
- Data snooping
- L1 norm minimization

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