

Matrix Inversion by partition  $A \cdot A^{-1} = I$

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$$\begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix} = \begin{bmatrix} I_m & 0 \\ 0 & I_n \end{bmatrix}$$

$$A_{11} B_{11} + A_{12} B_{21} = I_m \quad (a)$$

$$A_{11} B_{12} + A_{12} B_{22} = 0 \quad (b)$$

$$A_{21} B_{11} + A_{22} B_{21} = 0 \quad (c)$$

$$A_{21} B_{12} + A_{22} B_{22} = I_n \quad (d)$$

$$(c) \quad A_{22} B_{21} = -A_{21} B_{11}$$

$$B_{21} = -A_{22}^{-1} A_{21} B_{11}$$

sub into (a)

$$A_{11} B_{11} + A_{12} [-A_{22}^{-1} A_{21} B_{11}] = I_m$$

(derive expressions for  $B_{ij}$  by method #1)

$$(A_{11} - A_{12} A_{22}^{-1} A_{21}) B_{11} = I$$

$$B_{11} = (A_{11} - A_{12} A_{22}^{-1} A_{21})^{-1}$$

$$(d) \quad A_{22} B_{22} = I - A_{21} B_{12}$$

$$B_{22} = A_{22}^{-1} - A_{22}^{-1} A_{21} B_{12}$$

sub into (b)

$$A_{11} B_{12} + A_{12} [A_{22}^{-1} - A_{22}^{-1} A_{21} B_{12}] = 0$$

$$(A_{11} - A_{12}A_{22}^{-1}A_{21})B_{12} = -A_{12}A_{22}^{-1}$$

$$B_{12} = -\left(A_{11} - A_{12}A_{22}^{-1}A_{21}\right)^{-1}A_{12}A_{22}^{-1}$$

$$B_{12} = -B_{11}A_{12}A_{22}^{-1}$$

start with (b)

$$B_{12} = -A_{11}^{-1}A_{12}B_{22}$$

sub into (d)

$$A_{21}\left[-A_{11}^{-1}A_{12}B_{22}\right] + A_{22}B_{22} = I_m$$

$$(A_{22} - A_{21}A_{11}^{-1}A_{12})B_{22} = I$$

~~Eqn~~

Do again by method #2

$$B_{22} = (A_{22} - A_{21}A_{11}^{-1}A_{12})^{-1}$$

~~Method #1~~

$$(a) A_{11}B_{11} = I - A_{12}B_{21}$$

$$B_{11} = A_{11}^{-1} - A_{11}^{-1}A_{12}B_{21}$$

sub into (c)

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$$A_{21} A_{11}^{-1} - A_{21} A_{11}^{-1} A_{12} B_{21} + A_{22} B_{21} = 0$$

$$(A_{22} - A_{21} A_{11}^{-1} A_{12}) B_{21} = -A_{21} A_{11}^{-1}$$

$$B_{21} = - \underbrace{(A_{22} - A_{21} A_{11}^{-1} A_{12})}^{-1} A_{21} A_{11}^{-1}$$

$$B_{21} = - B_{22} A_{21} A_{11}^{-1}$$

OK, so by methods #1 & #2 we have  
2 expressions for  $B_{11}$ . Set them to be  
equal and re-arrange.

two expressions for  $B_{11}$

$$\begin{aligned}
 B_{11} &= \left( A_{11} - A_{12} A_{22}^{-1} A_{21} \right)^{-1} = A_{11}^{-1} - A_{11}^{-1} A_{12} \underbrace{B_{21}} \\
 &= A_{11}^{-1} + A_{11}^{-1} A_{12} \underbrace{B_{22} A_{21} A_{11}^{-1}} \\
 &= A_{11}^{-1} + A_{11}^{-1} A_{12} \left( A_{22} - A_{21} A_{11}^{-1} A_{12} \right)^{-1} A_{21} A_{11}^{-1}
 \end{aligned}$$

$$\left( A_{11} - A_{12} A_{22}^{-1} A_{21} \right)^{-1} = A_{11}^{-1} + A_{11}^{-1} A_{12} \left( A_{22} - A_{21} A_{11}^{-1} A_{12} \right)^{-1} A_{21} A_{11}^{-1}$$

$$(Y - UZV)^{-1} = Y^{-1} + Y^{-1}U \left( Z^{-1} - VY^{-1}U \right)^{-1} VY^{-1}$$

$$(Y + UZV)^{-1} = Y^{-1} - Y^{-1}U \left( Z^{-1} + VY^{-1}U \right)^{-1} VY^{-1}$$

ok - we have just derived the  
 S, M, W, S Matrix Inversion Lemma!

$$(Y + UZV)^{-1} = Y^{-1} + Y^{-1}U(Z^{-1} + VY^{-1}U)^{-1}VY^{-1}$$

Sherman Morrison Woodbury Schurr  
Matrix Inversion Lemma

$$\rightarrow N_i = N_{i-1} + B_i^T W_i B_i \quad (\text{notation change})$$

$$t_i = t_{i-1} + B_i^T W_i f_i$$

$$N_i = N_{i-1} + B_i^T W_i B_i$$

$$N_i^{-1} = ? = (N_{i-1} + B_i^T W_i B_i)^{-1}$$

now apply this result  
to sequential LS

$$N_i^{-1} = N_{i-1}^{-1} - N_{i-1}^{-1} B_i^T (Q_i + B_i N_{i-1}^{-1} B_i^T)^{-1} B_i N_{i-1}^{-1}$$

$$t_i = t_{i-1} + B_i^T W_i f_i$$


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$$\Delta_i = \underbrace{N_i^{-1}} \underbrace{t_i}$$

$$\Delta_i = \left[ N_{i-1}^{-1} - N_{i-1}^{-1} B_i^T (Q_i + B_i N_{i-1}^{-1} B_i^T)^{-1} B_i N_{i-1}^{-1} \right] (t_{i-1} + B_i^T W_i f_i)$$

multiply out  $\varepsilon$  get 4 terms

$$+ (A+B)^{-1} = A^{-1} (A^{-1} + B^{-1})^{-1} B^{-1}$$

⋮

$$\Delta_i = \Delta_{i-1} + N_{i-1}^{-1} B_i^T (Q_i + B_i N_{i-1}^{-1} B_i^T)^{-1} (f_i - B_i \Delta_{i-1})$$

update LS when adding observations

also need to add parameters

add dynamic model

Kalman Filter

$$B_i x_i = f_i \quad (W_0)$$

$$x_{i+1} = \Phi_i x_i, \quad -\Phi_i x_i + x_{i+1} = 0 \quad (W_t)$$



$$\begin{bmatrix}
 B_1 & & & \\
 -\Phi_1 I & & & \\
 \hline
 & B_2 & & \\
 & -\Phi_2 I & & \\
 \hline
 & & B_3 & \\
 & & -\Phi_3 I & \\
 \hline
 & & & B_4
 \end{bmatrix}
 \begin{bmatrix}
 x_1 \\
 x_2 \\
 x_3 \\
 x_4
 \end{bmatrix}
 =
 \begin{bmatrix}
 f_1 \\
 0 \\
 f_2 \\
 0 \\
 f_3 \\
 0 \\
 f_4
 \end{bmatrix}$$

$$\begin{aligned}
 Bx &\approx f \\
 V + Bx &= f \\
 \Rightarrow W &= \begin{bmatrix} w_0 & & & \\ & w_t & & \\ & & w_0 & \\ & & & w_t \end{bmatrix}
 \end{aligned}$$

(Gilbert Strang)

form N.E. symbolically

$B^T W B$

