

Numerical approximation of derivatives

13-1

$$\frac{df}{dx} = \lim_{\Delta x \rightarrow 0} \frac{f(x+\Delta x) - f(x)}{\Delta x}$$

take very small value for  $\Delta x$

$$\frac{df}{dx} \approx \frac{f(x+\Delta x) - f(x)}{\Delta x} \quad \text{eval @ current value of } x$$

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$$\frac{\partial f}{\partial x_i} = \lim_{\Delta x_i \rightarrow 0} \frac{f(x_1, x_2, \dots, x_i + \Delta x_i, \dots, x_n) - f(x_1, x_2, \dots, x_i, \dots, x_n)}{\Delta x_i} \quad 13-2$$

$$\frac{\partial f}{\partial x_i} \approx \frac{f(\dots) - f(\dots)}{\Delta x_i}$$

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function f, vector x, dx 13-3  
 $\hookrightarrow$  small perturbations  
 for i = 1:n  
 $df\_dx(i) = (f(x(i) + dx(i)) - f(x(i))) / dx(i);$   
 end

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$$\sigma_{dist} = .01 \text{ m}$$

$$\sigma_{ang} = \arctan\left(\frac{.01}{100}\right) = .0001 \text{ R} \quad (.0057 \text{ deg.})$$

$$\text{choose } \sigma_0^2 = (.01)^2 = .0001$$

$$W_d = \frac{(.01)^2}{(.01)^2} = 1$$

$$W_a = \frac{(.01)^2}{(.0001)^2} = 10,000$$

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do this again, dist units km

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$$\sigma_d = .00001 \text{ km}$$

$$\sigma_a = .0001 \text{ Rad}$$

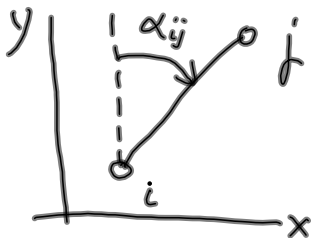
$$\sigma_b^2 = (.0001)^2$$

$$w_d = \frac{(.0001)^{-2}}{(.00001)^2} = 100$$

$$w_a = \frac{(.0001)^{-2}}{(.0001)^2} = 1$$

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linearization of some famous condition equations, 13-6  
azimuth observation (clockwise angle from north)



$$\alpha_{ij} = \text{atan} \left( \frac{x_j - x_i}{y_j - y_i} \right)$$

$$F_\alpha = \alpha_{ij} - \text{atan} \left( \frac{\Delta x}{\Delta y} \right) = 0$$



$$\frac{\partial F_\alpha}{\partial x_i} = -\frac{1}{1 + \left(\frac{\Delta x}{\Delta y}\right)^2} \cdot \frac{-1}{\Delta y} \cdot \frac{\partial y}{\partial x}$$

$$\left. \begin{aligned} \frac{d}{dx} \text{atan}(u) &= \frac{1}{1+u^2} \cdot \frac{du}{dx} \\ \frac{\partial F_\alpha}{\partial x_i} &= \frac{\Delta y}{\Delta x^2 + \Delta y^2} \end{aligned} \right\}$$

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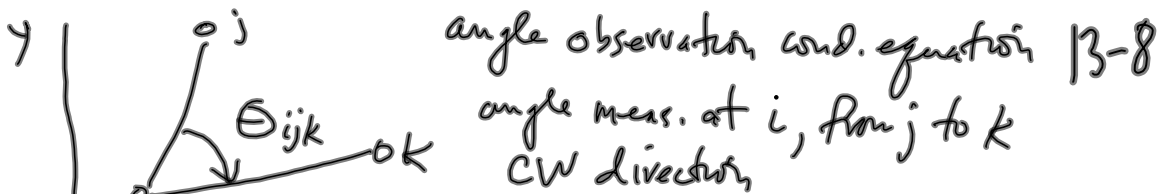
$$F_{\alpha} = \alpha_{ij} - \arctan\left(\frac{\Delta x}{\Delta y}\right) = 0 \quad \begin{array}{l} \Delta x = x_j - x_i \\ \Delta y = y_j - y_i \end{array} \quad |3-7$$

$$\frac{\partial F_{\alpha}}{\partial x_j} = \frac{-\Delta y}{\Delta x^2 + \Delta y^2} = \frac{-\Delta y}{D_{ij}^2}$$

$$\frac{\partial F_{\alpha}}{\partial y_i} = -\frac{1}{1 + \left(\frac{\Delta x}{\Delta y}\right)^2} \cdot (-1) \frac{\Delta x}{\Delta y^2} (-1) = \frac{-\Delta x}{D_{ij}^2}$$

$$\frac{\partial F_{\alpha}}{\partial y_j} = \frac{\Delta x}{D_{ij}^2}$$

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$$\theta_{ijk} = \arctan\left(\frac{\Delta y_{ik}}{\Delta x_{ik}}\right) - \arctan\left(\frac{\Delta y_{ij}}{\Delta x_{ij}}\right)$$

$$\theta_{ijk} = \tan^{-1}\left(\frac{\Delta x_{ik}}{\Delta y_{ik}}\right) - \tan^{-1}\left(\frac{\Delta x_{ij}}{\Delta y_{ij}}\right)$$

$$F_{\theta} = \theta_{ijk} - \tan^{-1}\left(\frac{\Delta x_{ik}}{\Delta y_{ik}}\right) + \tan^{-1}\left(\frac{\Delta x_{ij}}{\Delta y_{ij}}\right) = 0$$

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$$\frac{\partial F_{\theta}}{\partial x_i} = \frac{\Delta y_{ik}}{D_{ik}^2} - \frac{\Delta y_{ij}}{D_{ij}^2} \quad \Delta x_{ij} = x_j - x_i \quad 13-9$$

$$\frac{\partial F_{\theta}}{\partial x_j} = \frac{\Delta y_{ij}}{D_{ij}^2}, \quad \frac{\partial F_{\theta}}{\partial x_k} = -\frac{\Delta y_{ik}}{D_{ik}^2}$$

$$\frac{\partial F_{\theta}}{\partial y_i} = \frac{-\Delta x_{ik}}{D_{ik}^2} + \frac{\Delta x_{ij}}{D_{ij}^2}$$

$$\frac{\partial F_{\theta}}{\partial y_j} = -\frac{\Delta x_{ij}}{D_{ij}^2}, \quad \frac{\partial F_{\theta}}{\partial y_k} = \frac{\Delta x_{ik}}{D_{ik}^2}$$

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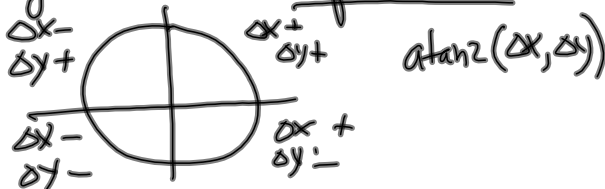
those partial deriv. become elements of B-matrix 13-10

RHS vector  $f = -F(l, x^0)$

few pitfalls in evaluating this

$$\text{atan}\left(\frac{\Delta x}{\Delta y}\right), \text{atan}^{-1}\left(\frac{\Delta x}{\Delta y}\right)$$

① get in correct quadrant

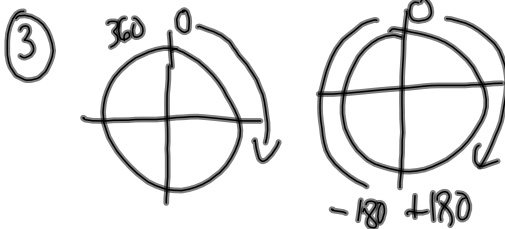


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② Sums or differences of angles, can get 13-11  
out of range

$$0 - 360, \quad 0 - 2\pi$$

$$-180 - +180, \quad -\pi - +\pi$$



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Distance or Range

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$$d_{ij} = [(x_j - x_i)^2 + (y_j - y_i)^2]^{1/2}$$

$$F_d = d_{ij} - [(x_j - x_i)^2 + (y_j - y_i)^2]^{1/2} = 0$$

$$\frac{\partial F_d}{\partial x_i} = \frac{\Delta x}{D_{ij}} \quad \frac{\partial F_d}{\partial y_i} = \frac{\Delta y}{D_{ij}}$$

$$\frac{\partial F_d}{\partial x_j} = \frac{-\Delta x}{D_{ij}} \quad \frac{\partial F_d}{\partial y_j} = \frac{-\Delta y}{D_{ij}}$$

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$$f = -F_a(l, x^0)$$

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