

10-1

$5x + 3y = 7$ linear in x, y

$x^2 + \sin(y) = 10$ nonlinear in x, y

linearity of variable: at most constant coefficient

for LS problems: unknowns: parameters
residuals (obs.)

in order for a problem to be linear, it must be linear in ALL UNKNOWN S

$$f(x) \approx f(x_0) + \frac{f'(x_0)}{1!}(x-x_0) + \frac{f''(x_0)}{2!}(x-x_0)^2 + \dots$$

truncate \rightarrow

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want to solve $f(x) = 0$ (finding a root)

$f'(x_0) = \frac{f(x_0)}{-\Delta x}$

Newton Iteration

$$\Delta x = \frac{-f(x_0)}{f'(x_0)}$$

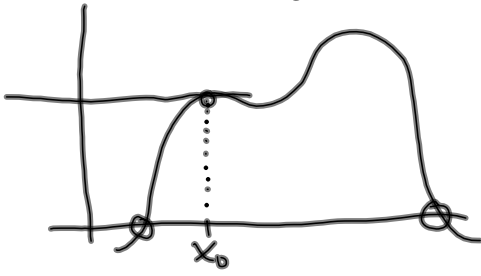
$f(x) = 0 \approx f(x_0) + f'(x_0) \Delta x \quad (\Delta x = x - x_0)$

Iteration formula

$$\Delta x = \frac{-f(x_0)}{f'(x_0)}$$

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What can go wrong with Newton Iteration ? 10-3



1. multiple solution
(+ bad initial approx)
2. solution can diverge
3. incorrect equation
linearize incorrectly

$$f(x,y) \approx f(x_0,y_0) + \frac{\partial f}{\partial x} \Delta x + \frac{\partial f}{\partial y} \Delta y$$

$$f(x_1, x_2, \dots, x_n) = f(x_1^0, x_2^0, \dots, x_n^0) + \frac{\partial f}{\partial x_1} \Delta x_1 + \frac{\partial f}{\partial x_2} \Delta x_2 + \dots + \frac{\partial f}{\partial x_n} \Delta x_n$$

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$$F_1(x_1, x_2, \dots, x_n) = 0 \approx F_1(x_1^0, x_2^0, \dots, x_n^0) + \frac{\partial F_1}{\partial x_1} \Delta x_1 + \frac{\partial F_1}{\partial x_2} \Delta x_2 + \dots + \frac{\partial F_1}{\partial x_n} \Delta x_n \quad 10-4$$

$$F_2(x_1, x_2, \dots, x_n) = 0 \approx F_2(x_1^0, x_2^0, \dots, x_n^0) + \frac{\partial F_2}{\partial x_1} \Delta x_1 + \frac{\partial F_2}{\partial x_2} \Delta x_2 + \dots + \frac{\partial F_2}{\partial x_n} \Delta x_n$$

$$\vdots$$

$$F_n(x_1, x_2, \dots, x_n) = 0 \approx F_n(x_1^0, x_2^0, \dots, x_n^0) + \frac{\partial F_n}{\partial x_1} \Delta x_1 + \frac{\partial F_n}{\partial x_2} \Delta x_2 + \dots + \frac{\partial F_n}{\partial x_n} \Delta x_n$$

$$\begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \approx \begin{bmatrix} F_1^0 \\ F_2^0 \\ \vdots \\ F_n^0 \end{bmatrix} + \underbrace{\begin{bmatrix} \frac{\partial F_1}{\partial x_1} & \frac{\partial F_1}{\partial x_2} & \dots & \frac{\partial F_1}{\partial x_n} \\ \frac{\partial F_2}{\partial x_1} & \frac{\partial F_2}{\partial x_2} & \dots & \frac{\partial F_2}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial F_n}{\partial x_1} & \frac{\partial F_n}{\partial x_2} & \dots & \frac{\partial F_n}{\partial x_n} \end{bmatrix}}_{\text{Jacobian}} \begin{bmatrix} \Delta x_1 \\ \Delta x_2 \\ \vdots \\ \Delta x_n \end{bmatrix}$$

$$\Delta X = -J^{-1} F(x_0) \quad \text{Vector Matrix}$$

$$\Delta x = \frac{-f(x_0)}{f'(x_0)} \quad \text{Scalar}$$

$$0 = F(x_0) + J \Delta x$$

$$-F(x_0) = J \Delta x$$

$$\boxed{\Delta x = -J^{-1} F(x_0)}$$

$x_0, x_1 = x_0 + \Delta x$
 $x_{i+1} = x_i + \Delta x$

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Big Picture
for NL
problems

analyze problem n, n_0, r
modeling, choose x_0

$r=0$ unique solution	$r>0$ LS problem choose I to q_0
linearize $J, F(x)$	linearize Bf, A, W
solve uniquely $\Delta = -J^{-1}F$	$\delta = (B^T W B)^{-1} B^T W f$ solve LS prob.

Newton
Heron
loop

$x_{i+1} = x_i + \Delta$
Repeat until Δ small

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Indirect Obs.

$\hat{\ell} = G(\alpha)$

$F(\hat{\ell}, x) = \hat{\ell} - G(\alpha) = 0$

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