

(75 minutes — 1 page of notes allowed)

1. Is the following 3-parameter transformation linear or nonlinear ?

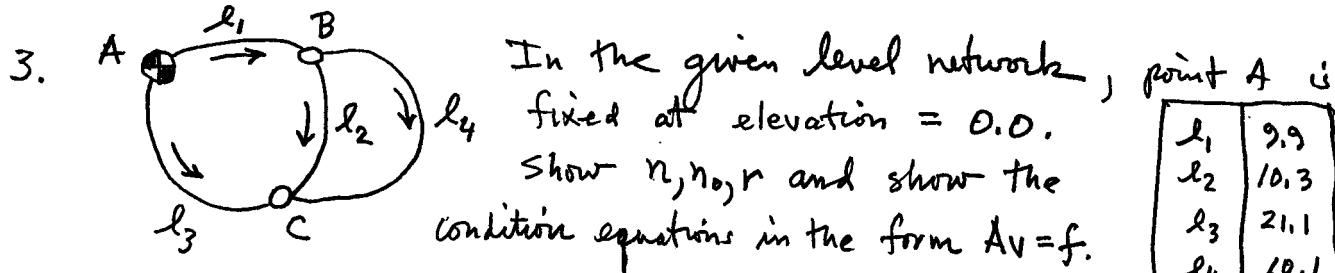
$$x = \cos\theta \cdot X + \sin\theta \cdot Y + t_x$$

$$y = -\sin\theta \cdot X + \cos\theta \cdot Y + t_y$$

x, y are observations, X, Y are constant, θ, t_x, t_y are the parameters we estimate in the adjustment.

2. $u = 2x + y$, $v = x - y$, $\Sigma_{(xy)} = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}$

what is the standard deviation σ_u ? what is the covariance σ_{uv} ?



4. Show condition equations for problem 3 in the form $V + B\Delta = f$.

5. A weight matrix is given as $W = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix}$. If $\sigma_0 = 2$, what is σ for observation number 3 ?

6. A condition equation for the indirect observation method is given as $F = \hat{l} - [4x^2 + 3y] = 0$

where l is an observation and x, y are parameters.

$l = 12$, and parameter approximations are $x \approx 1, y \approx 2$.

Show the linearized condition equation in the form $V + B\Delta = f$.
(Show numerical values.)

$$1. \begin{aligned} x &= \cos\theta \cdot X + \sin\theta \cdot Y + tx \\ y &= -\sin\theta \cdot X + \cos\theta \cdot Y + ty \end{aligned} \quad \text{nonlinear : parameter } \theta \text{ argument of trig functions, (more than scalar multiple)}$$

$$2. \begin{aligned} u &= 2x + y & \begin{pmatrix} u \\ v \end{pmatrix} &= \begin{pmatrix} 2 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}, & \Sigma_{(x)} &= \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix} \\ v &= x - y & & & & \left. \begin{array}{l} \text{application of error propagation:} \\ Y = AX, \Sigma_{xx} \\ \Sigma_{yy} = A \Sigma_{xx} A^T \end{array} \right\} \\ \Sigma_{(y)} &= \begin{pmatrix} 2 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 1 & -1 \end{pmatrix} & = & \begin{pmatrix} 7 & 5 \\ 2 & -2 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 1 & -1 \end{pmatrix} & = & \begin{pmatrix} 19 & 2 \\ 2 & 4 \end{pmatrix} \end{aligned}$$

$$\sigma_u = \sqrt{19} = 4.36, \quad \sigma_{uv} = 2$$

$$3. \quad n = 4 \quad \underbrace{\text{obs. only}}_{n_0 = 2, r = 2} \quad \begin{array}{l} l_1 + l_2 - l_3 = 0 \\ l_2 - l_4 = 0 \end{array} \quad \begin{array}{l} l_1 + v_1 + l_2 + v_2 - l_3 - v_3 = 0 \\ l_2 + v_2 - l_4 - v_4 = 0 \end{array}$$

$$v_1 + v_2 - v_3 = -(l_1 + l_2 - l_3) = -(9.9 + 10.3 - 21.1) = +0.9$$

$$v_2 - v_4 = -(l_2 - l_4) = -(10.3 - 10.1) = -0.2$$

$$A \begin{bmatrix} 1 & 1 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} = - \begin{bmatrix} 1 & 1 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} 9.9 \\ 10.3 \\ 21.1 \\ 10.1 \end{bmatrix} = \begin{bmatrix} 0.9 \\ -0.2 \end{bmatrix} = f$$

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$$4. \quad \underline{\text{indirect obs.}} \quad \text{parameters } n = n_0 = 2 \quad B, C \quad \begin{array}{l} \text{elevations of} \\ \text{2 unknown points} \end{array}$$

$$l_1 + v_1 = B \quad v_1 - B = -l_1 = -9.9$$

$$l_2 + v_2 = C - B \quad v_2 - C + B = -l_2 = -10.3$$

$$l_3 + v_3 = C \quad v_3 - C = -l_3 = -21.1$$

$$l_4 + v_4 = C - B \quad v_4 - C + B = -l_4 = -10.1$$

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} + \begin{bmatrix} -1 & 0 \\ 1 & -1 \\ 0 & -1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} B \\ C \end{bmatrix} = \begin{bmatrix} -9.9 \\ -10.3 \\ -21.1 \\ -10.1 \end{bmatrix}$$

$$v + B \Delta = f$$

$$5. W = \begin{bmatrix} 1 & \\ & 2 \\ & & 4 \end{bmatrix}, \sigma_0^2 = 2, \sigma_0^2 = 4, W = \begin{bmatrix} 4/4 & & \\ & 4/2 & \\ & & 4/1 \end{bmatrix}$$

$$\sigma_3^2 = 1, \sigma_3 = \sqrt{1} = 1$$

$$6. F = \hat{F} - [4x^2 + 3y] = 0$$

$$\begin{aligned} l &= 12 \\ x &\approx 1, x^\circ \\ y &\approx 2, y^\circ \end{aligned}$$

$$\frac{\partial F}{\partial x} = -8x, \quad \frac{\partial F}{\partial y} = -3$$

$$F^0 = 12 - [4 \cdot 1^2 + 3 \cdot 2]$$

$$F^0 = 12 - [4 + 6] = 2$$

$$V + \begin{bmatrix} \frac{\partial F}{\partial x} & \frac{\partial F}{\partial y} \\ -8x & -3 \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix} = -F^0 \quad -(2)$$

$$V + \begin{bmatrix} -8 & -3 \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix} = -2$$

F is a non linear equation

$$\left. \begin{array}{l} B = \left[\begin{array}{cc} \frac{\partial F}{\partial x} & \frac{\partial F}{\partial y} \end{array} \right] \\ f = (-F) \end{array} \right\} \begin{array}{l} \text{all evaluated} \\ \text{at current} \\ \text{approximations} \end{array}$$

the unknowns that we solve
for in the nonlinear

Iterations are $\begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix}$

with 4 equations and 2 unknown parameters you cannot
solve a LS problem - only write the linearized
condition equations, with numbers where possible.