

prior derivation :

$$Y = (x - \mu_x)^T \Sigma^{-1} (x - \mu_x) \sim \chi^2_n$$

only true if pass global test

$$\Sigma = \sigma_0^2 Q$$

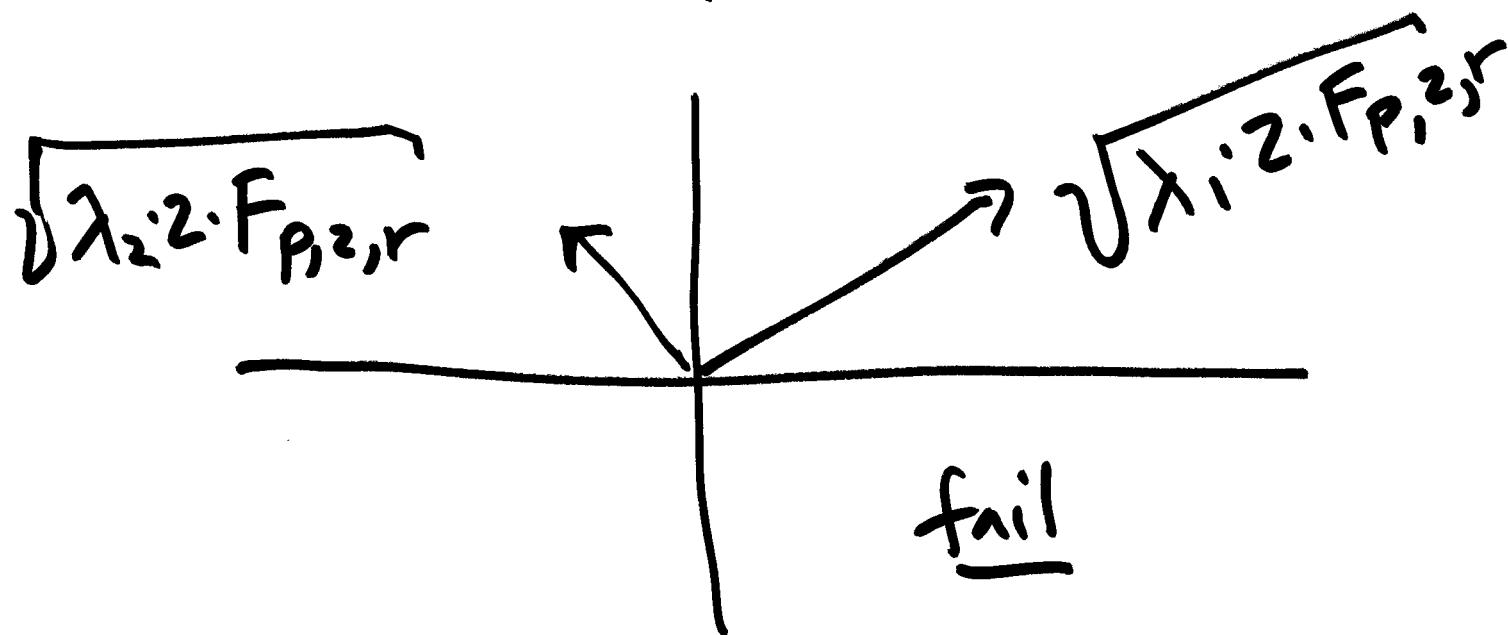
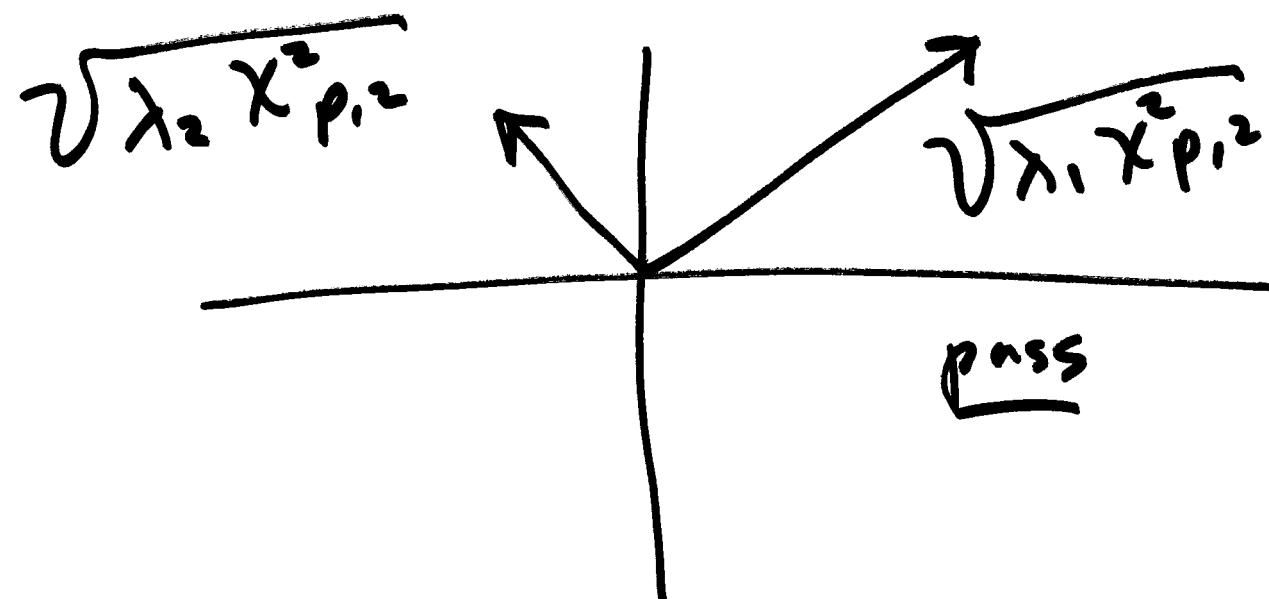
if failed global test (or did not do it)

$$Y = (x - \mu_x)^T \Sigma^{-1} (x - \mu_x) \sim n \cdot F_{n,r}$$

$$\Sigma = \hat{\sigma}_0^2 Q$$

$$\hat{\sigma}_0^2 = \frac{v^T w w^T v}{r}$$

16-2



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$$Sx = \lambda x$$

↓      ↑  
 $(\Sigma)$       eigenvalues  
 eigenvector

Columns  
 are  
 eigenvectors

matlab :

$$[V, D] = \text{eig}(S)$$

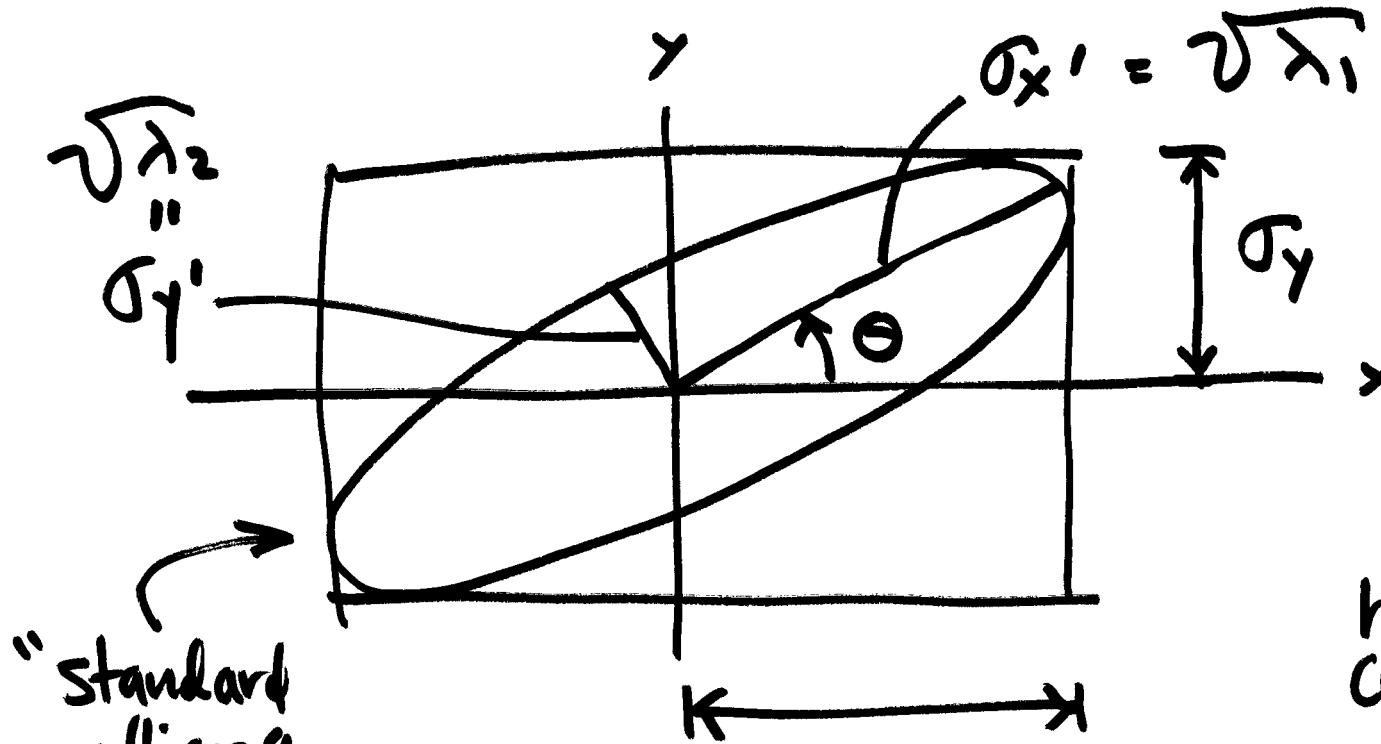
↓      ↓  
 diagonal matrix  
 (eigenvalues)

$$SV = VD$$

$$S = VDV^T$$

$$V^T S V = D \quad / \quad R \Sigma R^T = D$$

eigenvectors  
 col's of  $V$   
 row's of  $V^T$   
 rows of  $R$



"Standard  
ellipse"

hand  
computation  
of  
eigenvalues

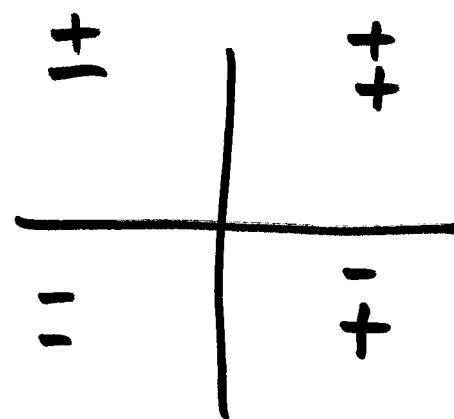
$$\Sigma = \begin{bmatrix} \sigma_x^2 & \sigma_{xy} \\ \sigma_{xy} & \sigma_y^2 \end{bmatrix}$$

$$\lambda_{1,2} = \frac{\sigma_x^2 + \sigma_y^2}{2} \pm \left[ \frac{(\sigma_x^2 - \sigma_y^2)^2}{4} + \sigma_{xy}^2 \right]^{1/2}$$

$$\sigma_{x1}^2, \sigma_{y1}^2 =$$

$$\tan 2\theta = \frac{2\sigma_{xy}}{\sigma_x^2 - \sigma_y^2}$$

Caution: obtain  $\tan 2\theta$  with signs of both numerator + denominator

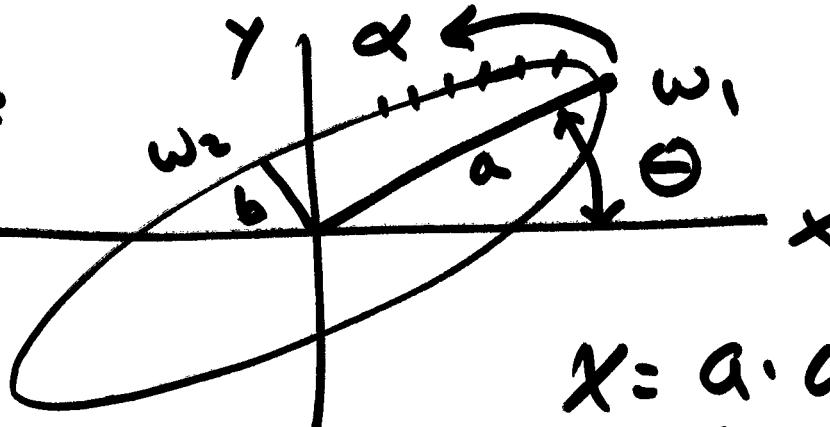


$$2\theta = \text{atan2}(\text{num}, \text{den})$$

this function returns value in the correct quadrant.

16-6

matlab code  
to draw a  
rotated  
ellipse



$$\begin{aligned}x &= a \cdot \cos \alpha \\y &= b \cdot \sin \alpha\end{aligned}$$

$$\text{th} = \Theta$$

$a$  : semi-major

$b$  : semi-minor

$$x_0 = a$$

$$y_0 = 0$$

$$nSeg = 50$$

for  $i = 1 : nSeg$

$$\text{alpha} = i * \text{dalpha}$$

$$x_i = a * \cos(\text{alpha})$$

$$y_i = b * \sin(\text{alpha})$$

$$\text{dalpha} = 2 * \pi / nSeg$$

16-7

$$px_0 = \cos(\theta_0) * x_0 - \sin(\theta_0) * y_0$$

$$py_0 = \sin(\theta_0) * x_0 + \cos(\theta_0) * y_0$$

$$px_1 = \cos(\theta_1) * x_1 - \sin(\theta_1) * y_1$$

$$py_1 = \sin(\theta_1) * x_1 + \cos(\theta_1) * y_1$$

plot([px0 px1], [py0 py1], '-r');

if ( $i == 1$ )

hold on

end

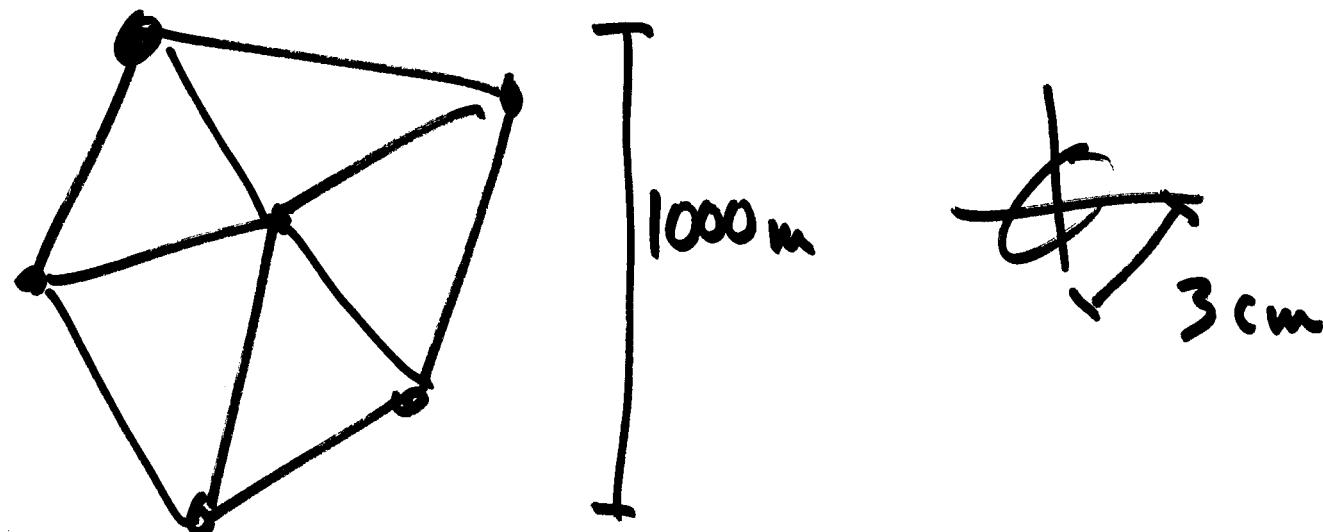
$$x_0 = x_1$$

$$y_0 = y_1$$

end

(it works!)

16-8



to see error ellipses : exaggerate scale

