

Error Propagation

$$Y = AX + b$$

↑ ↗ constant vector
 matrix of random variable
 constants Σ_{xx}

$$\Sigma_{yy} = A \Sigma_{xx} A^T$$

$$Y = Y^0 + J \Delta X$$

Taylor Series

$$\begin{matrix} \Sigma_{xx} \\ \Sigma_{\Delta X} \end{matrix}$$

$$\Sigma_{yy} = J \Sigma_{xx} J^T$$

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$$\begin{bmatrix} X_a \\ Y_a \\ X_b \\ Y_b \end{bmatrix} \leftarrow \Sigma_{xx}$$

$$\begin{bmatrix} \sigma_{X_a}^2 & \sigma_{X_a Y_a} & \cdot & \cdot \\ \sigma_{X_a Y_a} & \sigma_{Y_a}^2 & \cdot & \cdot \\ \sigma_{X_b X_a} & \sigma_{X_b Y_a} & \sigma_{X_b}^2 & \cdot \\ \sigma_{Y_b X_a} & \sigma_{Y_b Y_a} & \sigma_{Y_b X_b} & \sigma_{Y_b}^2 \end{bmatrix}$$

$$D_x = X_b - X_a \quad \text{what is } \Sigma_{(D_x)} ?$$

$$D_y = Y_b - Y_a$$

$$\begin{pmatrix} D_x \\ D_y \end{pmatrix} = \begin{pmatrix} -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} X_a \\ Y_a \\ X_b \\ Y_b \end{pmatrix}$$

$$\Sigma_{(D_x)} = \begin{pmatrix} -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \end{pmatrix} \Sigma_{xx} \begin{pmatrix} 1 & 0 \\ 0 & -1 \\ -1 & 0 \\ 0 & 1 \end{pmatrix}$$

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$$\Sigma \begin{pmatrix} D_x \\ D_y \end{pmatrix} = \begin{pmatrix} \sigma^2_{D_x} & \sigma_{DxDy} \\ \sigma_{DxDy} & \sigma^2_{Dy} \end{pmatrix}$$

error propagation with
either $\begin{cases} \Sigma & \text{abs. cov. mx} \\ Q & \text{Scaled cov. mx.} \end{cases}$

$$\Sigma = \underline{\sigma^2} Q$$

$$\Sigma_{xx} = \sigma_0^2 Q_{xx}$$

$$\Sigma_{\hat{x}\hat{x}} = \sigma_0^2 Q_{\hat{x}\hat{x}}$$

$$\Sigma_{\Delta\Delta} = \sigma_0^2 Q_{\Delta\Delta}$$

$$\Sigma_{vv} = \sigma_0^2 Q_{vv}$$

$$\Sigma_{ll} = \sigma_0^2 Q_{ll} \quad (Q^* = Q_{ll})$$

$$\Sigma_{xx} = \sigma_0^2 Q_{xx}$$

σ_0^2 either

B-4

$\left\{ \begin{array}{l} \text{prior } \sigma_0^2 \text{ chosen "a priori"} \\ \text{post adjustment } \hat{\sigma}_0^2 \text{ estimated} \\ \text{"a posteriori"} \end{array} \right.$

Indirect Observation Model

$$Q_{\delta\delta} = N^{-1} = (\mathbf{B}^T W \mathbf{B})^{-1}$$

(Q_{xx})

$$\Sigma_{\delta\delta} = \sigma_0^2 Q_{\delta\delta}$$

$$\hat{Q}_{\hat{\ell}\hat{\ell}} = ?$$

$$Q_{\hat{x}\hat{x}} = B^*(B^T W B)^{-1} B^T W \cdot Q [B(B^T W B)^{-1} B^T W]^T$$

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$$= B(B^T W B)^{-1} B^T W \underbrace{Q W}_{e} B(B^T W B)^{-1} B^T$$

$$Q_{\hat{x}\hat{x}} = BN^{-1}B^T$$

$$\stackrel{\text{I/O}}{\sum_{\hat{x}\hat{x}} = \sigma^2 Q_{\hat{x}\hat{x}}}$$

$$Q_{vv} = ? \quad v = f - B_o$$

$$v = d - l - BN^{-1}B^T W (d - l)$$

$$v = d - l - BN^{-1}B^T W d + BN^{-1}B^T W l$$

$$v = (I - BN^{-1}B^T W)d + (BN^{-1}B^T W - I)l \quad \checkmark$$

form we
need

$$\hat{l} = l + v, \quad v + B\Delta = f, \quad v = f - B\Delta \quad 13-6$$

$$f = d - l$$

$$\hat{l} = l + f - B\Delta = \underline{\underline{l}} + \underline{\underline{d}} - \underline{\underline{B\Delta}}$$

$$\hat{l} = d - B\Delta \rightarrow \Delta = (B^T W B)^{-1} B^T W (d - l)$$

$$\hat{l} = d - B(B^T W B)^{-1} B^T W (d - l)$$

$$\hat{l} = d - B(B^T W B)^{-1} B^T W d \approx +B(B^T W B)^{-1} B^T W l$$

$$\hat{l} = (I - B(B^T W B)^{-1} B^T W) d + \}$$

$$\boxed{B(B^T W B)^{-1} B^T W \cdot l}$$

} in form we need
for error prop.

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$$Q_{vv} = (BN^{-1}B^T W - I) Q (BN^{-1}B^T W - I)^T$$

$$= (BN^{-1}B^T \underbrace{WQ}_{} - Q) (WBN^{-1}B^T - I)$$

$$= (BN^{-1}B^T - Q) (WBN^{-1}B^T - I)$$

$$BN^{-1}B^T \underbrace{WBN^{-1}B^T}_{} + Q - BN^{-1}B^T - BN^{-1}B^T$$

$$Q_{vv} = Q + \underbrace{BN^{-1}B^T - BN^{-1}B^T}_{\text{Indirect Observations}} - BN^{-1}B^T$$

$$Q_{vv} = Q - BN^{-1}B^T$$

Indirect
Observations

$$Q_{vv} = Q - Q_{\hat{x}\hat{x}}, \quad Q_{\hat{x}\hat{x}} = Q - Q_{vv}$$

Observations Only

$$Av = f$$

$$Av = \underline{\underline{d - Al}}$$

$$\hat{l} = l + v$$

$$v = QA^T K$$

$$Q_e = AQA^T$$

$$K = W_e f$$

$$W_e = Q_e^{-1}$$

$$Q_v = ? \quad v = QA^T k, \quad = QA^T W_e f$$

$$v = QA^T W_e (d - Al)$$

$$v = \underline{QA^T W_e d} - \underline{QA^T W_e A} \underline{l}$$

$$Q_v = QA^T W_e A \cdot Q \cdot (QA^T W_e A)^T$$

$\underbrace{A^T W_e A Q}_{A^T W_e A Q}$

$$Q_v = QA^T W_e A Q$$

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$$\hat{l} = l + QA^T W_e d - QA^T W_e A l$$

$$\hat{l} = QA^T W_e d + (I - QA^T W_e A) l \leftarrow$$

$$\begin{aligned} Q_{\hat{l}\hat{l}} &= (I - QA^T W_e A) Q (I - QA^T W_e A)^T \\ &\quad (I - A^T W_e A Q) \\ &= (Q - QA^T W_e A Q) \left(\begin{array}{c|c} & \uparrow \\ & \end{array} \right) \end{aligned}$$

$$\begin{aligned} Q_{\hat{l}\hat{l}} &= QA^T W_e A Q - QA^T W_e A Q + \\ &\quad QA^T W_e \underbrace{A Q}_{\cancel{A Q}} \underbrace{A^T}_{\cancel{A^T}} \underbrace{W_e A Q}_{\cancel{A Q}} \end{aligned}$$

$$Q_{\hat{l}\hat{l}} = QA^T W_e A Q - \underline{QA^T W_e A Q} + \overline{QA^T W_e A Q}$$

$$\boxed{Q_{\hat{e}\hat{e}} = Q - QA^T W_e A Q}$$

$$\underline{Q_{\hat{e}\hat{e}}} = \underline{Q - Q_{VV}}, \quad \underline{Q_W} = \underline{Q - Q_{\hat{e}\hat{e}}}$$

post adjustment statistics

Global Test (are results consistent w/
prior assumptions?)

Hypothesis Test

$$H_0: \sigma^2 = \sigma_0^2$$

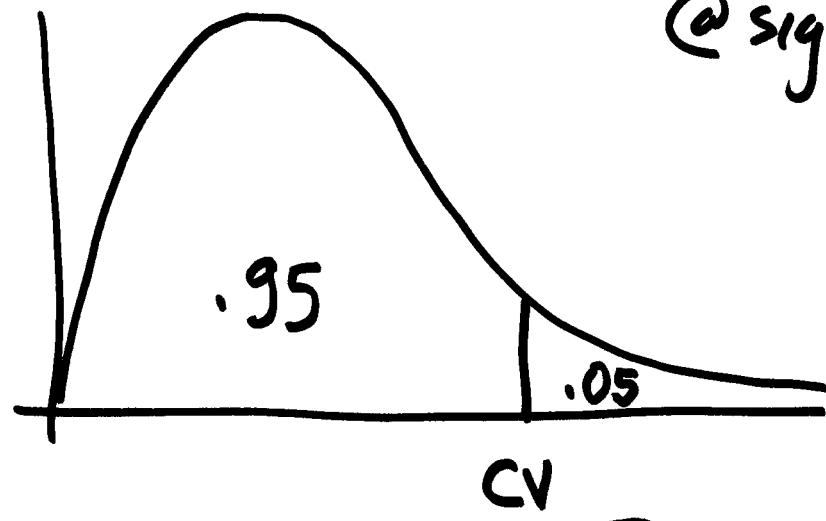
true var. of unit weight chosen value

$$H_1: \sigma^2 > \sigma_0^2$$

we know from statistics, if $\underline{\sigma^2 = \sigma_0^2}$

then $\frac{\sqrt{T_{WV}}}{\sigma_0^2} \sim \chi_r^2$

@ significance level of $\underline{.05}$



test statistic $\chi^* = \frac{\sqrt{T_{WV}}}{\sigma_0^2}$

Decision Rule :

if $\chi^* < CV$, we accept H_0

if $\chi^* > CV$, we reject H_0
accept H_1 .