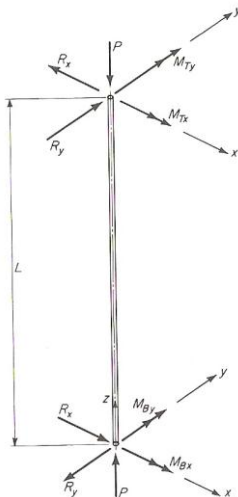


## Elastic Buckling Behavior of Beams

CE579 - Structural Stability and Design

## ELASTIC BUCKLING OF BEAMS

- Going back to the original three second-order differential equations:



Therefore,

$$1 \quad E I_x v'' + P v - \phi \left( P x_0 + M_{BY} - \frac{z}{L} (M_{TY} + M_{BY}) \right) = M_{BX} - \frac{z}{L} (M_{TX} + M_{BX})$$

$$2 \quad E I_y u'' + P u - \phi \left( -P y_0 + M_{BX} - \frac{z}{L} (M_{TX} + M_{BX}) \right) = -M_{BY} + \frac{z}{L} (M_{TY} + M_{BY})$$

$$3 \quad E I_w \phi''' - (G K_T + \bar{K}) \phi' + u' \left( -M_{BX} - \frac{z}{L} (M_{BX} + M_{TX}) + P y_0 \right)$$

$$-v' \left( M_{BY} + \frac{z}{L} (M_{BY} + M_{TY}) + P x_0 \right) - \frac{v}{L} (M_{TY} + M_{BY}) - \frac{u}{L} (M_{TX} + M_{BX}) = 0$$

## ELASTIC BUCKLING OF BEAMS

- Consider the case of a beam subjected to uniaxial bending only:
  - ♦ because most steel structures have beams in uniaxial bending
  - ♦ Beams under biaxial bending do not undergo elastic buckling
- $P=0$ ;  $M_{TY}=M_{BY}=0$
- The three equations simplify to:

$$1 \quad E I_x v'' = M_{BX} - \frac{z}{L} (M_{TX} + M_{BX})$$

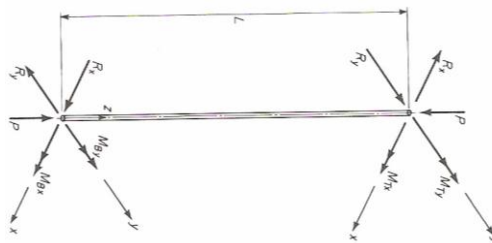
$$2 \quad E I_y u'' - \phi M_{BX} = \frac{z}{L} (M_{TX} + M_{BX}) (-\phi)$$

$$3 \quad E I_w \phi''' - (G K_T + \bar{K}) \phi' + u' \left( -M_{BX} - \frac{z}{L} (M_{BX} + M_{TX}) \right) - \frac{u}{L} (M_{TX} + M_{BX}) = 0$$

- Equation (1) is an uncoupled differential equation describing in-plane bending behavior caused by  $M_{TX}$  and  $M_{BX}$

## ELASTIC BUCKLING OF BEAMS

- Equations (2) and (3) are coupled equations in  $u$  and  $\phi$  – that describe the lateral bending and torsional behavior of the beam. In fact they define the lateral torsional buckling of the beam.
- The beam must satisfy all three equations (1, 2, and 3). Hence, beam in-plane bending will occur UNTIL the lateral torsional buckling moment is reached, when it will take over.
- Consider the case of uniform moment ( $M_o$ ) causing compression in the top flange. This will mean that
  - ♦  $-M_{BX} = M_{TX} = M_o$



## Uniform Moment Case

- For this case, the differential equations (2 and 3) will become:

$$E I_y u'' + \phi M_o = 0$$

$$E I_w \phi''' - (G K_T + \bar{K}) \phi' + u'(M_o) = 0$$

where:

$\bar{K}$  = Wagner's effect due to warping caused by torsion

$$\bar{K} = \int_A \sigma a^2 dA$$

But,  $\sigma = \frac{M_o}{I_x} y \Rightarrow$  neglecting higher order terms

$$\therefore \bar{K} = \int_A \frac{M_o}{I_x} y [(x_o - x)^2 + (y_o - y)^2] dA$$

$$\therefore \bar{K} = \frac{M_o}{I_x} \int_A y [x_o^2 + x^2 - 2xx_o + y_o^2 + y^2 - 2yy_o] dA$$

$$\therefore \bar{K} = \frac{M_o}{I_x} \left[ x_o^2 \int_A y dA + \int_A y [x^2 + y^2] dA - x_o \int_A 2xy dA + y_o^2 \int_A y dA - 2y_o \int_A y^2 dA \right]$$

## ELASTIC BUCKLING OF BEAMS

$$\therefore \bar{K} = \frac{M_o}{I_x} \left[ \int_A y [x^2 + y^2] dA - 2y_o I_x \right]$$

$$\therefore \bar{K} = M_o \left[ \frac{\int_A y [x^2 + y^2] dA}{I_x} - 2y_o \right]$$

$$\therefore \bar{K} = M_o \beta_x \quad \Rightarrow \text{where, } \beta_x = \frac{\int_A y [x^2 + y^2] dA}{I_x} - 2y_o$$

$\beta_x$  is a new sectional property

The beam buckling differential equations become:

$$(2) \quad E I_y u'' + \phi M_o = 0$$

$$(3) \quad E I_w \phi''' - (G K_T + M_o \beta_x) \phi' + u'(M_o) = 0$$

## ELASTIC BUCKLING OF BEAMS

Equation (2) gives  $u'' = -\frac{M_o}{E I_y} \phi$

Substituting  $u''$  from Equation (2) in (3) gives :

$$E I_w \phi^{iv} - (G K_T + M_o \beta_x) \phi'' - \frac{M_o^2}{E I_y} \phi = 0$$

For doubly symmetric section :  $\beta_x = 0$

$$\therefore \phi^{iv} - \frac{G K_T}{E I_w} \phi'' - \frac{M_o^2}{E^2 I_y I_w} \phi = 0$$

Let,  $\lambda_1 = \frac{G K_T}{E I_w}$  and  $\lambda_2 = \frac{M_o^2}{E^2 I_y I_w}$

$$\therefore \phi^{iv} - \lambda_1 \phi'' - \lambda_2 \phi = 0 \Rightarrow \text{becomes the combined d.e. of LTB}$$

## ELASTIC BUCKLING OF BEAMS

Assume solution is of the form  $\phi = e^{\lambda z}$

$$\therefore (\lambda^4 - \lambda_1 \lambda^2 - \lambda_2) e^{\lambda z} = 0$$

$$\therefore \lambda^4 - \lambda_1 \lambda^2 - \lambda_2 = 0$$

$$\therefore \lambda^2 = \frac{\lambda_1 + \sqrt{\lambda_1^2 + 4\lambda_2}}{2}, \quad \frac{\sqrt{\lambda_1^2 + 4\lambda_2} - \lambda_1}{2}$$

$$\therefore \lambda = \pm \sqrt{\frac{\lambda_1 + \sqrt{\lambda_1^2 + 4\lambda_2}}{2}}, \quad \pm i \sqrt{\frac{\sqrt{\lambda_1^2 + 4\lambda_2} - \lambda_1}{2}}$$

$$\therefore \text{Let, } \lambda = \pm \alpha_1, \quad \text{and } \pm i \alpha_2$$

Above are the four roots for  $\lambda$

$$\therefore \phi = C_1 e^{\alpha_1 z} + C_2 e^{-\alpha_1 z} + C_3 e^{i\alpha_2 z} + C_4 e^{-i\alpha_2 z}$$

$\therefore$  collecting real and imaginary terms

$$\therefore \phi = G_1 \cosh(\alpha_1 z) + G_2 \sinh(\alpha_1 z) + G_3 \sin(\alpha_2 z) + G_4 \cos(\alpha_2 z)$$

## ELASTIC BUCKLING OF BEAMS

- Assume simply supported boundary conditions for the beam:

$$\therefore \phi(0) = \phi''(0) = \phi(L) = \phi''(L) = 0$$

Solution for  $\phi$  must satisfy all four b.c.

$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ \alpha_1^2 & 0 & 0 & -\alpha_2^2 \\ \cosh(\alpha_1 L) & \sinh(\alpha_1 L) & \sin(\alpha_2 L) & \cos(\alpha_2 L) \\ \alpha_1^2 \cosh(\alpha_1 L) & \alpha_1^2 \sinh(\alpha_1 L) & -\alpha_2^2 \sin(\alpha_2 L) & -\alpha_2^2 \cos(\alpha_2 L) \end{bmatrix} \times \begin{Bmatrix} G_1 \\ G_2 \\ G_3 \\ G_4 \end{Bmatrix} = 0$$

For buckling coefficient matrix must be singular:

$$\therefore \text{determinant of matrix} = 0$$

$$\therefore (\alpha_1^2 + \alpha_2^2) \times \sinh(\alpha_1 L) \times \sin(\alpha_2 L) = 0$$

Of these:

$$\text{only } \sin(\alpha_2 L) = 0$$

$$\therefore \alpha_2 L = n\pi$$

## ELASTIC BUCKLING OF BEAMS

$$\therefore \alpha_2 = \frac{n\pi}{L}$$

$$\therefore \sqrt{\frac{\lambda_1^2 + 4\lambda_2 - \lambda_1}{2}} = \frac{\pi}{L}$$

$$\therefore \sqrt{\lambda_1^2 + 4\lambda_2} - \lambda_1 = \frac{2\pi^2}{L^2}$$

$$\therefore \lambda_2 = \frac{\left(\frac{2\pi^2}{L^2} + \lambda_1\right)^2 - \lambda_1^2}{4} = \frac{\left(\frac{2\pi^2}{L^2} + 2\lambda_1\right)\left(\frac{2\pi^2}{L^2}\right)}{4}$$

$$\therefore \lambda_2 = \left(\frac{\pi^2}{L^2} + \lambda_1\right)\left(\frac{\pi^2}{L^2}\right)$$

$$\therefore \lambda_2 = \frac{M_o^2}{E^2 I_y I_w} = \left(\frac{\pi^2}{L^2} + \frac{G K_T}{E I_w}\right)\left(\frac{\pi^2}{L^2}\right)$$

$$\therefore M_o = \sqrt{\left(E^2 I_y I_w\right)\left(\frac{\pi^2}{L^2} + \frac{G K_T}{E I_w}\right)\left(\frac{\pi^2}{L^2}\right)}$$

$$\therefore M_o = \sqrt{\frac{\pi^2 E I_y}{L^2} \left(\frac{\pi^2 E I_w}{L^2} + G K_T\right)}$$

## Uniform Moment Case

- The critical moment for the uniform moment case is given by the simple equations shown below.

$$M_{cr}^o = \sqrt{\frac{\pi^2 EI_y}{L^2} \times \left( \frac{\pi^2 EI_w}{L^2} + GK_T \right)}$$

$$M_{cr}^o = \sqrt{P_y \times P_\phi \times \bar{r}_o^2}$$

- The AISC code massages these equations into different forms, which just look different. Fundamentally the equations are the same.
  - The critical moment for a span with distance  $L_b$  between lateral - torsional braces.
  - $P_y$  is the column buckling load about the minor axis.
  - $P_\phi$  is the column buckling load about the torsional z- axis.

## Non-uniform moment

- The only case for which the differential equations can be solved analytically is the uniform moment.
- For almost all other cases, we will have to resort to numerical methods to solve the differential equations.
- Of course, you can also solve the uniform moment case using numerical methods

$$E I_x v'' = M_{BX} - \frac{z}{L} (M_{TX} + M_{BX})$$

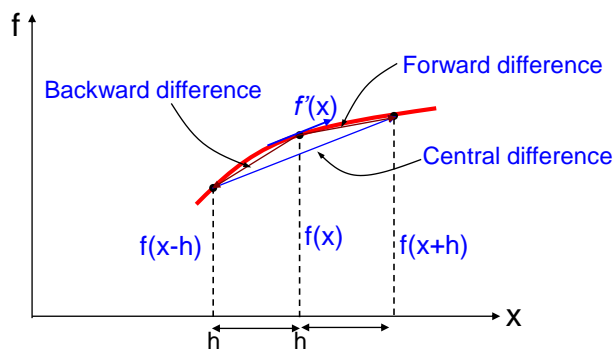
$$E I_y u'' - \phi M_{BX} = \frac{z}{L} (M_{TX} + M_{BX}) \phi$$

$$E I_w \phi''' - (G K_T + \bar{K}) \phi' + u' \left( -M_{BX} - \frac{z}{L} (M_{BX} + M_{TX}) \right) - \frac{u}{L} (M_{TX} + M_{BX}) = 0$$

## What numerical method to use

- What we have is a problem where the governing differential equations are known.
  - ♦ The solution and some of its derivatives are known at the boundary.
  - ♦ This is an ordinary differential equation and a boundary value problem.
- We will solve it using the finite difference method.
  - ♦ The FDM converts the differential equation into algebraic equations.
  - ♦ Develop an FDM mesh or grid (as it is more correctly called) in the structure.
  - ♦ Write the algebraic form of the d.e. at each point within the grid.
  - ♦ Write the algebraic form of the boundary conditions.
  - ♦ Solve all the algebraic equations simultaneously.

## Finite Difference Method



$$f(x+h) = f(x) + hf'(x) + \frac{h^2}{2!} f''(x) + \frac{h^3}{3!} f'''(x) + \frac{h^4}{4!} f^{(4)}(x) + \dots$$

$$\therefore f'(x) = \frac{f(x+h) - f(x)}{h} + \frac{h}{2!} f''(x) + \frac{h^2}{3!} f'''(x) + \frac{h^3}{4!} f^{(4)}(x) + \dots$$

$$\therefore f'(x) = \frac{f(x+h) - f(x)}{h} + O(h) \quad \Rightarrow \text{Forward difference equation}$$

## Finite Difference Method

$$f(x-h) = f(x) - hf'(x) + \frac{h^2}{2!} f''(x) - \frac{h^3}{3!} f'''(x) + \frac{h^4}{4!} f^{iv}(x) + \dots$$

$$\therefore f'(x) = \frac{f(x) - f(x-h)}{h} + \frac{h}{2!} f''(x) - \frac{h^2}{3!} f'''(x) + \frac{h^3}{4!} f^{iv}(x) + \dots$$

$$\therefore f'(x) = \frac{f(x) - f(x-h)}{h} + O(h) \quad \Rightarrow \text{Backward difference equation}$$

$$f(x+h) = f(x) + hf'(x) + \frac{h^2}{2!} f''(x) + \frac{h^3}{3!} f'''(x) + \frac{h^4}{4!} f^{iv}(x) + \dots$$

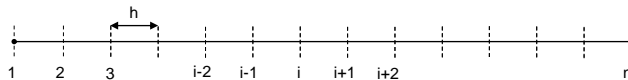
$$f(x-h) = f(x) - hf'(x) + \frac{h^2}{2!} f''(x) - \frac{h^3}{3!} f'''(x) + \frac{h^4}{4!} f^{iv}(x) + \dots$$

$$\therefore f'(x) = \frac{f(x+h) - f(x-h)}{2h} + \frac{2h^2}{3!} f'''(x) + \dots$$

$$\therefore f'(x) = \frac{f(x+h) - f(x-h)}{2h} + O(h^2) \quad \Rightarrow \text{Central difference equation}$$

## Finite Difference Method

- The central difference equations are better than the forward or backward difference because the error will be of the order of h-square rather than h.
- Similar equations can be derived for higher order derivatives of the function f(x).
- If the domain x is divided into several equal parts, each of length h.



- At each of the 'nodes' or 'section points' or 'domain points' the differential equations are still valid.



## Finite Difference Method

- Central difference approximations for higher order derivatives:

$$y'_i = \frac{1}{2h}(y_{i+1} - y_{i-1})$$

$$y''_i = \frac{1}{h^2}(y_{i+1} - 2y_i + y_{i-1})$$

$$y'''_i = \frac{1}{2h^3}(y_{i+2} - 2y_{i+1} + 2y_{i-1} - y_{i-2})$$

$$y^{iv}_i = \frac{1}{h^4}(y_{i+2} - 4y_{i+1} + 6y_i - 4y_{i-1} + y_{i-2})$$

*Notation*

$$y = f(x)$$

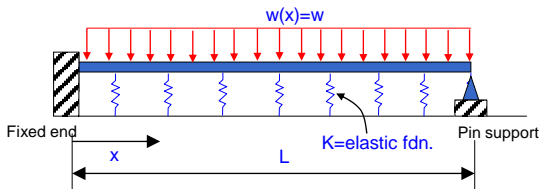
$$y_i = f(x=i)$$

$$y'_i = f'(x=i)$$

$$y''_i = f''(x=i) \text{ and so on...}$$

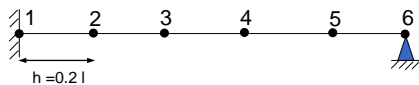
## FDM - Beam on Elastic Foundation

- Consider an interesting problemn --> beam on elastic foundation



$$EIy^{iv} + ky(x) = w(x)$$

- Convert the problem into a finite difference problem.



$$EIy_i^{iv} + ky_i = w$$

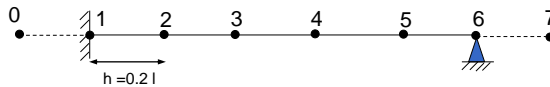
Discrete form of differential equation

## FDM - Beam on Elastic Foundation

$$EI y_i^{iv} + k y_i = w$$

$$\therefore \frac{EI}{h^4} (y_{i-2} - 4y_{i-1} + 6y_i - 4y_{i+1} + y_{i+2}) + k y_i = w$$

write 4 equations for  $i = 2, 3, 4, 5$



Need two imaginary nodes that lie within the boundary  
 Hmm.... These are needed to only solve the problem  
 They don't mean anything.

## FDM - Beam on Elastic Foundation

$$\text{At } i = 2: \frac{625 EI}{L^4} (y_0 - 4y_1 + 6y_2 - 4y_3 + y_4) + k y_2 = w$$

$$\text{At } i = 3: \frac{625 EI}{L^4} (y_1 - 4y_2 + 6y_3 - 4y_4 + y_5) + k y_3 = w$$

$$\text{At } i = 4: \frac{625 EI}{L^4} (y_2 - 4y_3 + 6y_4 - 4y_5 + y_6) + k y_4 = w$$

$$\text{At } i = 5: \frac{625 EI}{L^4} (y_3 - 4y_4 + 6y_5 - 4y_6 + y_7) + k y_5 = w$$

- Lets consider the boundary conditions:

$$y(0) = 0 \quad \Rightarrow \quad y_1 = 0 \quad (1)$$

$$y(L) = 0 \quad \Rightarrow \quad y_6 = 0 \quad (2)$$

$$M(L) = 0 \quad (3)$$

$$\theta(0) = 0 \quad \Rightarrow \quad y'(0) = 0 \quad (4)$$

## FDM - Beam on Elastic Foundation

$$y(0) = 0 \Rightarrow y_1 = 0 \quad (1)$$

$$y(L) = 0 \Rightarrow y_6 = 0 \quad (2)$$

$$M(L) = 0 \quad (3)$$

$$\therefore EI y''(L) = 0 \Rightarrow y_6'' = 0$$

$$\therefore y_6'' = \frac{1}{h^2}(y_5 - 2y_6 + y_7) = 0$$

$$\therefore y_7 = -y_5 \quad (3+)$$

$$\theta(0) = 0 \Rightarrow y'(0) = 0 \quad (4)$$

$$\therefore y_1' = \frac{1}{2h}(y_2 - y_0) = 0$$

$$\therefore y_2 = y_0 \quad (4+)$$

## FDM - Beam on Elastic Foundation

- Substituting the boundary conditions:

$$\text{At } i = 2: (7y_2 - 4y_3 + y_4) + \frac{kL^4}{625EI}y_2 = \frac{wL^4}{625EI}$$

$$\text{At } i = 3: (-4y_2 + 6y_3 - 4y_4 + y_5) + \frac{kL^4}{625EI}y_3 = \frac{wL^4}{625EI}$$

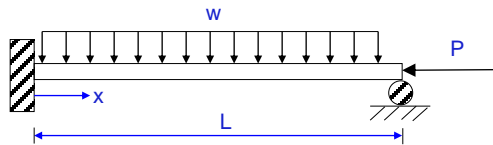
$$\text{At } i = 4: (y_2 - 4y_3 + 6y_4 - 4y_5) + \frac{kL^4}{625EI}y_4 = \frac{wL^4}{625EI}$$

$$\text{At } i = 5: (y_3 - 4y_4 + 5y_5) + \frac{kL^4}{625EI}y_5 = \frac{wL^4}{625EI}$$

Let  $a = kL^4/625EI$

$$\begin{bmatrix} 7+a & -4 & 1 & 0 \\ -4 & 6+a & -4 & 1 \\ 1 & -4 & 6+a & -4 \\ 0 & 1 & -4 & 5+a \end{bmatrix} \begin{Bmatrix} y_2 \\ y_3 \\ y_4 \\ y_5 \end{Bmatrix} = \begin{Bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{Bmatrix} \frac{wL^4}{625EI}$$

## FDM - Column Euler Buckling

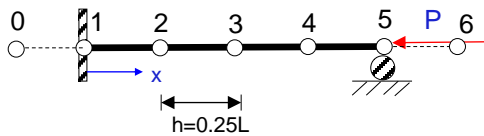


Buckling problem: Find axial load  $P$  for which the nontrivial Solution exists.

Ordinary Differential Equation

$$y^{iv}(x) + \frac{P}{EI}y''(x) = \frac{w}{EI}$$

Finite difference solution. Consider case Where  $w=0$ , and there are 5 stations



## FDM - Euler Column Buckling

*Finite difference method*

$$y_i^{iv} + \frac{P}{EI}y_i'' = 0$$

At stations  $i = 2, 3, 4$

$$\frac{1}{h^4}(y_{i-2} - 4y_{i-1} + 6y_i - 4y_{i+1} + y_{i+2}) + \frac{P}{EI} \cdot \frac{1}{h^2}(y_{i-1} - 2y_i + y_{i+1}) = 0$$

Boundary conditions

$$y_1 = 0 \quad (1)$$

$$y_5 = 0 \quad (2)$$

$$y_1' = 0$$

$$\therefore \frac{1}{2h}(y_2 - y_0) = 0$$

$$\therefore y_0 = y_2 \quad (3)$$

$$M_5 = 0$$

$$\therefore EI \cdot y_5'' = 0$$

$$\therefore (y_6 - 2y_5 + y_4) = 0$$

$$\therefore y_6 = -y_4 \quad (4)$$

## FDM - Column Euler Buckling

- Final Equations

$$\frac{1}{h^4}(7y_2 - 4y_3 + y_4) + \frac{P}{EI} \cdot \frac{1}{h^2}(-2y_2 + y_3) = 0$$

$$\frac{1}{h^4}(-4y_2 + 6y_3 - 4y_4) + \frac{P}{EI} \cdot \frac{1}{h^2}(y_2 - 2y_3 + y_4) = 0$$

$$\frac{1}{h^4}(y_2 - 4y_3 + 5y_4) + \frac{P}{EI} \cdot \frac{1}{h^2}(y_3 - 2y_4) = 0$$

*∴ Matrix Form*

$$\begin{bmatrix} 7 & -4 & 1 \\ -4 & 6 & -4 \\ 1 & -4 & 5 \end{bmatrix} \begin{Bmatrix} y_2 \\ y_3 \\ y_4 \end{Bmatrix} + \frac{PL^2}{16EI} \begin{bmatrix} -2 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & -2 \end{bmatrix} \begin{Bmatrix} y_2 \\ y_3 \\ y_4 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \\ 0 \end{Bmatrix}$$

## FDM - Euler Buckling Problem

- $[A]\{y\} + \lambda[B]\{y\} = \{0\}$ 
  - How to find P? Solve the eigenvalue problem.
- Standard Eigenvalue Problem
  - $[A]\{y\} = \lambda\{y\}$ 
    - Where,  $\lambda$  = eigenvalue and  $\{y\}$  = eigenvector
  - Can be simplified to  $[A - \lambda I]\{y\} = \{0\}$
  - Nontrivial solution for  $\{y\}$  exists if and only if
    - $|A - \lambda I| = 0$
  - One way to solve the problem is to obtain the characteristic polynomial from expanding  $|A - \lambda I| = 0$
  - Solving the polynomial will give the value of  $\lambda$
  - Substitute the value of  $\lambda$  to get the eigenvector  $\{y\}$
  - This is not the best way to solve the problem, and will not work for more than 4 or 5th order polynomial

## FDM - Euler Buckling Problem

- For solving Buckling Eigenvalue Problem
- $[A]\{y\} + \lambda[B]\{y\} = \{0\}$
- $[A + \lambda B]\{y\} = \{0\}$
- Therefore,  $\det |A + \lambda B| = 0$  can be used to solve for  $\lambda$

$$A = \begin{bmatrix} 7 & -4 & 1 \\ -4 & 6 & -4 \\ 1 & -4 & 5 \end{bmatrix} \quad B = \begin{bmatrix} -2 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & -2 \end{bmatrix}$$

$$\text{and } \lambda = \frac{PL^2}{16EI}$$

$$\begin{vmatrix} 7-2\lambda & -4+\lambda & 1 \\ -4+\lambda & 6-2\lambda & -4+\lambda \\ 1 & -4+\lambda & 5-2\lambda \end{vmatrix} = 0$$

$$\therefore \lambda = 1.11075$$

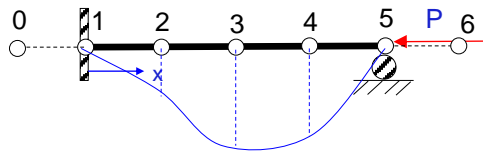
$$\therefore \frac{PL^2}{16EI} = 1.11075$$

$$\therefore P_{cr} = 17.772 \frac{EI}{L^2}$$

$$\text{Exact solution is } 20.14 \frac{EI}{L^2}$$

## FDM - Euler Buckling Problem

- 11% error in solution from FDM
- $\{y\} = \{0.4184 \ 1.0 \ 0.8896\}^T$



# FDM Euler Buckling Problem

- Inverse Power Method: Numerical Technique to Find Least Dominant Eigenvalue and its Eigenvector
  - ◆ Based on an initial guess for eigenvector and iterations
- Algorithm
  - ◆ 1) Compute  $[E] = -[A]^{-1}[B]$
  - ◆ 2) Assume initial eigenvector guess  $\{y\}^0$
  - ◆ 3) Set iteration counter  $i=0$
  - ◆ 4) Solve for new eigenvector  $\{y\}^{i+1} = [E]\{y\}^i$
  - ◆ 5) Normalize new eigenvector  $\{y\}^{i+1} = \{y\}^{i+1} / \max(y_j^{i+1})$
  - ◆ 6) Calculate eigenvalue  $= 1 / \max(y_j^{i+1})$
  - ◆ 7) Evaluate convergence:  $\lambda^{i+1} - \lambda^i < \text{tol}$
  - ◆ 8) If no convergence, then go to step 4
  - ◆ 9) If yes convergence, then  $\lambda = \lambda^{i+1}$  and  $\{y\} = \{y\}^{i+1}$

## Inverse Iteration Method

Example: Inverse Power Method to Compute the Least Dominant Eigenvalue and Eigenvector

Define matrices A, B

$$A := \begin{bmatrix} 7 & -4 & 1 \\ -4 & 6 & -4 \\ 1 & -4 & 6 \end{bmatrix}$$

$$B := \begin{bmatrix} -2 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & -2 \end{bmatrix}$$

$$E := (-1) \cdot A^{-1} \cdot B = \begin{bmatrix} 0.2727 & 0.1818 & 0.0909 \\ -0.0455 & 0.3182 & 0.1182 \\ -0.0909 & 0.2727 & 0.6364 \end{bmatrix}$$

Initial Guess of Eigenvector

$$V0 := \begin{bmatrix} 0.25 \\ 1.7 \\ 0.75 \end{bmatrix}$$

Iteration #1

$$V1 := E \cdot V0 = \begin{bmatrix} 0.2676 \\ 0.8727 \\ 0.6455 \end{bmatrix}$$

$$\lambda_1 = \frac{1.0}{\max(V1)} = 1.4865$$

Iteration #2

$$V2 := E \cdot V1 = \begin{bmatrix} 0.3759 \\ 0.9218 \\ 0.8477 \end{bmatrix}$$

$$\lambda_2 = \frac{1.0}{\max(V2)} = 1.0824$$

Iteration #3

$$V3 := E \cdot V2 = \begin{bmatrix} 0.3762 \\ 0.9098 \\ 0.8196 \end{bmatrix}$$

$$\lambda_3 = \frac{1.0}{\max(V3)} = 1.0991$$

Iteration #4

$$V4 := E \cdot V3 = \begin{bmatrix} 0.3765 \\ 0.9042 \\ 0.8184 \end{bmatrix}$$

$$\lambda_4 = \frac{1.0}{\max(V4)} = 1.1059$$

Iteration #5

$$V5 := E \cdot V4 = \begin{bmatrix} 0.3767 \\ 0.9019 \\ 0.8018 \end{bmatrix}$$

$$\lambda_5 = \frac{1.0}{\max(V5)} = 1.1098$$

Iteration #6

$$V6 := E \cdot V5 = \begin{bmatrix} 0.3767 \\ 0.901 \\ 0.8011 \end{bmatrix}$$

$$\lambda_6 = \frac{1.0}{\max(V6)} = 1.1099$$

Iteration #7

$$V7 := E \cdot V6 = \begin{bmatrix} 0.3768 \\ 0.9006 \\ 0.8011 \end{bmatrix}$$

$$\lambda_7 = \frac{1.0}{\max(V7)} = 1.1104$$

Convergence

Eigenvalue,  $\lambda = 1.1104$       Eigenvector,  $VN = \begin{bmatrix} 0.4184 \\ 1 \\ 0.8896 \end{bmatrix}$

$$P = 1.1104 \left( \frac{10^4}{L^3} \right) = 17766 \frac{EI}{L^3}$$

$$y_8 = \begin{cases} 0.4184 \\ 1 \\ 0.8896 \end{cases}$$

Physical Meaning

$P = 17766 \frac{EI}{L^3}$  Load to Cause Buckle

Buckled Shape

The differential equation for the problem is:

$$\phi^{IV} - \lambda_1 \phi'' - \lambda_2 \phi = 0$$

where  $\lambda_1 = \frac{G K_T}{E I_w}$        $\lambda_2 = \frac{M_0^2}{E^2 I_y I_w}$

$\lambda_1 = \text{constant}$       &  $\lambda_2 \rightarrow$  eigenvalue or unknown we are looking

For the WR7x94 section:

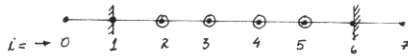
$K_T = 4.03 \text{ in}^4$        $r_y = 2.12 \text{ in}$        $G = 11200 \text{ ksi}$   
 $I_w = 21300 \text{ in}^6$        $I_y = 124 \text{ in}^4$        $E = 29000 \text{ ksi}$

length of beam = 200       $r_y = 424 \text{ in.}$

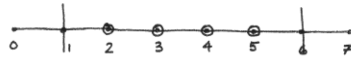
Divide into 5 segments for this solution:

$\therefore h = \frac{424}{5} = 84.8 \text{ in.}$

The original differential equation is valid at each station



$\therefore \phi_i^{IV} - \lambda_1 \phi_i'' - \lambda_2 \phi_i = 0 \rightarrow$  at each station  $i$



@  $i = 2$

$$\frac{1}{h^4} \phi_0 + \cancel{\phi_1} \left[ \frac{-4}{h^4} - \frac{\lambda_1}{h^2} \right] + \phi_2 \left[ \frac{6}{h^4} + \frac{2\lambda_1}{h^2} - \lambda_2 \right] + \cancel{\phi_3} \left[ \frac{-4}{h^4} - \frac{\lambda_1}{h^2} \right] + \phi_4 \cdot \frac{1}{h^4} = 0$$

@  $i = 3$

$$\cancel{\frac{1}{h^4} \phi_1} + \phi_2 \left[ \frac{-4}{h^4} - \frac{\lambda_1}{h^2} \right] + \phi_3 \left[ \frac{6}{h^4} + \frac{2\lambda_1}{h^2} - \lambda_2 \right] + \cancel{\phi_4} \left[ \frac{-4}{h^4} - \frac{\lambda_1}{h^2} \right] + \phi_5 \cdot \frac{1}{h^4} = 0$$

@  $i = 4$

$$\frac{1}{h^4} \phi_2 + \cancel{\phi_3} \left[ \frac{-4}{h^4} - \frac{\lambda_1}{h^2} \right] + \phi_4 \left[ \frac{6}{h^4} + \frac{2\lambda_1}{h^2} - \lambda_2 \right] + \cancel{\phi_5} \left[ \frac{-4}{h^4} - \frac{\lambda_1}{h^2} \right] + \phi_6 \cdot \frac{1}{h^4} = 0$$

@  $i = 5$

$$\frac{1}{h^4} \phi_3 + \cancel{\phi_4} \left[ \frac{-4}{h^4} - \frac{\lambda_1}{h^2} \right] + \phi_5 \left[ \frac{6}{h^4} + \frac{2\lambda_1}{h^2} - \lambda_2 \right] + \cancel{\phi_6} \left[ \frac{-4}{h^4} - \frac{\lambda_1}{h^2} \right] + \phi_7 \cdot \frac{1}{h^4} = 0$$

$\phi_1 = \phi_6 = 0$

$\phi_0 = \phi_2$       &       $\phi_5 = \phi_7$

$$\phi_2 \left[ \frac{7}{h^4} + \frac{2\lambda_1}{h^2} - \lambda_2 \right] + \phi_3 \left[ \frac{-4}{h^4} - \frac{\lambda_1}{h^2} \right] + \phi_4 \cdot \frac{1}{h^4} = 0$$

$$\phi_2 \left[ \frac{-4}{h^4} - \frac{\lambda_1}{h^2} \right] + \phi_3 \left[ \frac{6}{h^4} + \frac{2\lambda_1}{h^2} - \lambda_2 \right] + \phi_4 \left[ \frac{-4}{h^4} - \frac{\lambda_1}{h^2} \right] + \phi_5 \cdot \frac{1}{h^4} = 0$$



$$\begin{bmatrix} -\frac{4}{h^4} - \frac{\lambda_1}{h^2} & \frac{6}{h^4} + \frac{2\lambda_1}{h^2} - \lambda_2 & -\frac{4}{h^4} - \frac{\lambda_1}{h^2} & -\frac{1}{h^4} \\ \frac{1}{h^4} & -\frac{4}{h^4} - \frac{\lambda_1}{h^2} & \frac{6}{h^4} + \frac{2\lambda_1}{h^2} - \lambda_2 & -\frac{4}{h^4} - \frac{\lambda_1}{h^2} \\ 0 & \frac{1}{h^4} & -\frac{4}{h^4} - \frac{\lambda_1}{h^2} & \frac{6}{h^4} + \frac{2\lambda_1}{h^2} - \lambda_2 \end{bmatrix} \begin{Bmatrix} \phi_2 \\ \phi_3 \\ \phi_4 \\ \phi_5 \end{Bmatrix} = C$$

Multiplying all equations by  $h^4$

$$\begin{bmatrix} 7 + 2\lambda_1 h^2 - \lambda_2 h^4 & -4 - \lambda_1 h^2 & 1 & 0 \\ -4 - \lambda_1 h^2 & 6 + 2\lambda_1 h^2 - \lambda_2 h^4 & -4 - \lambda_1 h^2 & 1 \\ 1 & -4 - \lambda_1 h^2 & 6 + 2\lambda_1 h^2 - \lambda_2 h^4 & -4 - \lambda_1 h^2 \\ 0 & 1 & -4 - \lambda_1 h^2 & 7 + 2\lambda_1 h^2 - \lambda_2 h^4 \end{bmatrix} \begin{Bmatrix} \phi_2 \\ \phi_3 \\ \phi_4 \\ \phi_5 \end{Bmatrix}$$

Solve using inverse iteration:

$$\lambda_1 = \frac{GKT}{EIW} \quad \lambda_2 = \frac{M_0^2}{E^2 I_y I_w}$$

$$[A] - \lambda_2 [B] = \{0\}$$

$$\therefore [A] = \begin{bmatrix} 7 + 2\lambda_1 h^2 & -4 - \lambda_1 h^2 & 1 & 0 \\ -4 - \lambda_1 h^2 & 6 + 2\lambda_1 h^2 & -4 - \lambda_1 h^2 & 1 \\ 1 & -4 - \lambda_1 h^2 & 6 + 2\lambda_1 h^2 & -4 - \lambda_1 h^2 \\ 0 & 1 & -4 - \lambda_1 h^2 & 7 + 2\lambda_1 h^2 \end{bmatrix}$$

$$\lambda_1 = \frac{GKT}{EIW} = \frac{11200 \times 0.992}{29000 \times 21200} = 7.342 \times 10^{-5}$$

$$\lambda_2 = \frac{M_0^2}{E^2 I_y I_w}$$

$$h = \frac{L}{5} = \frac{424}{5} = 84.8 \text{ in}$$

$$\therefore \begin{bmatrix} 8.055932 & -4.52766 & 1 & 0 \\ -4.52766 & 7.055932 & -4.52766 & 1 \\ 1 & -4.52766 & 7.055932 & -4.52766 \\ 0 & 1 & -4.52766 & 8.055932 \end{bmatrix} - h^4 \lambda_2 [I] = \begin{Bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{Bmatrix}$$

Using Matlab eigenvalue command

main eigenvalue

$$h^4 \lambda_2 = \begin{pmatrix} 0.8107 \\ 4.0175 \\ 9.7735 \\ 15.6220 \end{pmatrix} \begin{matrix} \rightarrow \text{eigenvalue} \\ \rightarrow \text{other} \\ \rightarrow \text{eigenvalue} \end{matrix} \begin{matrix} = -0.3095 \\ = -0.6358 \\ = -0.6358 \\ = -0.3095 \end{matrix}$$

$$h^4 \frac{M_0^2}{E^2 I_y I_w} = 0.8107$$

$$\therefore M_0^2 = 0.8107 \times E^2 \times W^4 \times \frac{21200}{84.8^4}$$

$$\therefore M_0 = 5.887 \text{ k-in}$$

## Different Boundary Conditions

**Table 3.2. EFFECTIVE LENGTH FACTORS IN LATERAL-TORSIONAL BUCKLING**

Boundary Conditions		$K_y$	$K_z$	$K_{13}$
$z = 0$	$z = L$			
$u = u'' = \phi = \phi'' = 0$	$u = u'' = \phi = \phi'' = 0$	1.000	1.000	1.000
$u = u'' = \phi = \phi'' = 0$	$u = u'' = \phi = \phi' = 0$	0.904	0.693	0.904
$u = u'' = \phi = \phi'' = 0$	$u = u' = \phi = \phi'' = 0$	0.626	1.000	0.904
$u = u'' = \phi = \phi'' = 0$	$u = u' = \phi = \phi' = 0$	0.693	0.693	1.000
$u = u'' = \phi = \phi' = 0$	$u = u'' = \phi = \phi' = 0$	0.883	0.492	0.883
$u = u' = \phi = \phi'' = 0$	$u = u' = \phi = \phi' = 0$	0.431	0.693	0.875
$u = u' = \phi = \phi' = 0$	$u = u' = \phi = \phi' = 0$	0.492	0.492	1.000
$u = u' = \phi = \phi'' = 0$	$u = u' = \phi = \phi'' = 0$	0.434	1.000	0.883
$u = u' = \phi = \phi'' = 0$	$u = u'' = \phi = \phi' = 0$	0.606	0.492	0.875

## Beams with Non-Uniform Loading

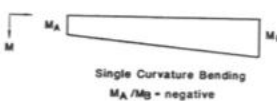
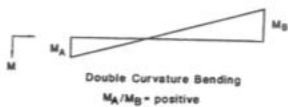
- Let  $M_0^{cr}$  be the lateral-torsional buckling moment for the case of uniform moment.
- If the applied moments are non-uniform (but varying linearly, i.e., there are no loads along the length)
  - ♦ Numerically solve the differential equation using FDM and the Inverse Iteration process for eigenvalues
  - ♦ Alternately, researchers have already done these numerical solution for a variety of linear moment diagrams
  - ♦ The results from the numerical analyses were used to develop a simple equation that was calibrated to give reasonable results.

## Beams with Non-uniform Loading

- Salvadori in the 1970s developed the equation below based on the regression analysis of numerical results with a simple equation
  - ♦  $M^{cr} = C_b M_o^{cr}$
  - ♦ Critical moment for non-uniform loading =  $C_b$  x critical moment for uniform moment.

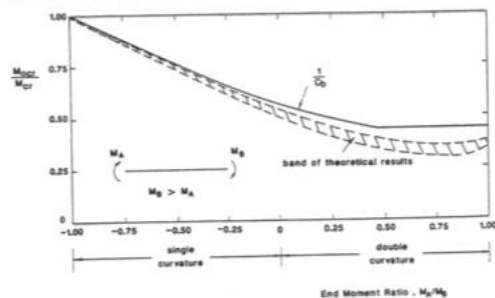
## Beams with Non-uniform Loading

FIGURE 5.13 Beam subjected to unequal bending moments



$$C_b = 1.75 + 1.05 \left( \frac{M_A}{M_B} \right) + 0.3 \left( \frac{M_A}{M_B} \right)^2 \leq 2.3 \quad (5.5.2)$$

FIGURE 5.14 Comparison of theoretical results with Eq. (5.5.1)



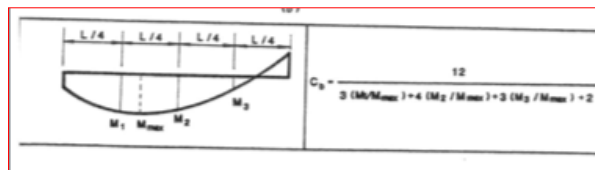
## Beams with Non-uniform Loading

Table 5.2 Values of  $C_b$  for Different Loading Cases (All Loads are Applied at Shear Center of the Cross Section)

Loadings	Bending Moment Diagrams	$M_{cr}$	$C_b$
		$M_{cr}$	1.00
		$M_{cr}$	1.75
		$M_{cr}$	2.30
		$\frac{P_{cr} L}{4}$	1.35
		$\frac{W_{cr} L^2}{8}$	1.13
		$\frac{P_{cr} L}{4}$	1.04
		$\frac{3 P_{cr} L}{16}$	1.44

## Beams with Non-Uniform Loading

- In case that the moment diagram is not linear over the length of the beam, i.e., there are transverse loads producing a non-linear moment diagram
  - The value of  $C_b$  is a little more involved



## Beams with non-simple end conditions

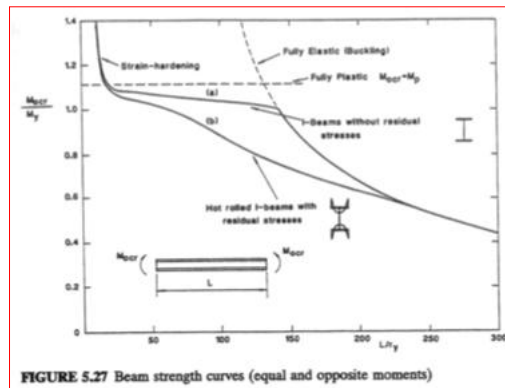
- $M_o^{cr} = (P_y P_\phi \frac{I_\Omega^2}{L^2})^{0.5}$ 
  - ♦  $P_y$  with  $K_b$
  - ♦  $P_\phi$  with  $K_t$

Table 5.6 Effective Length Factors for Beams Under Uniform Moment with Various Boundary Conditions (Adapted from Ref. 19)

Boundary Conditions		$K_b$	$K_t$
$x = 0$	$x = L$		
$u = u'' = \gamma = \gamma'' = 0$	$u = u'' = \gamma = \gamma'' = 0$	1.000	1.000
$u = u'' = \gamma = \gamma'' = 0$	$u = u'' = \gamma = \gamma' = 0$	0.904	0.693
$u = u'' = \gamma = \gamma'' = 0$	$u = u' = \gamma = \gamma'' = 0$	0.626	1.000
$u = u'' = \gamma = \gamma'' = 0$	$u = u' = \gamma = \gamma' = 0$	0.693	0.693
$u = u'' = \gamma = \gamma'' = 0$	$u = u'' = \gamma = \gamma' = 0$	0.883	0.492
$u = u'' = \gamma = \gamma'' = 0$	$u = u' = \gamma = \gamma' = 0$	0.431	0.693
$u = u' = \gamma = \gamma'' = 0$	$u = u' = \gamma = \gamma' = 0$	0.492	0.492
$u = u' = \gamma = \gamma'' = 0$	$u = u' = \gamma = \gamma' = 0$	0.434	1.000
$u = u' = \gamma = \gamma'' = 0$	$u = u'' = \gamma = \gamma' = 0$	0.606	0.492

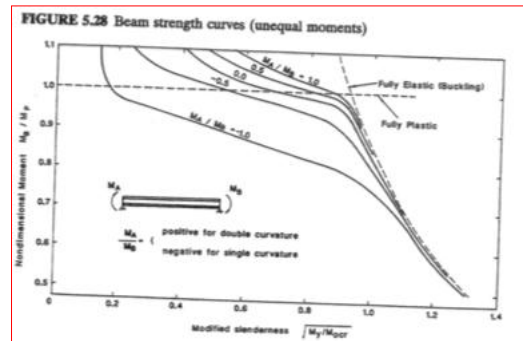
## Beam Inelastic Buckling Behavior

- Uniform moment case



## Beam Inelastic Buckling Behavior

- Non-uniform moment



## Beam In-plane Behavior

- Section capacity  $M_p$
- Section  $M-\phi$  behavior

## Beam Design Provisions

CHAPTER F in AISC Specifications