

AAE 520 Experimental Aerodynamics

Laser Doppler Anemometry

Introduction to principles and applications

adapted from
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Why Measure?

- Almost all industrial flows are turbulent.
- Almost all naturally occurring flows on earth, in oceans, and atmosphere are turbulent.

$$\rho \frac{Du_i}{Dt} = \frac{\partial \tau_{ij}}{\partial X_j} + \rho f_i - \frac{\partial p}{\partial X_j}$$

Turbulent motion is 3-D, vortical, and diffusive

⇒ governing Navier-Stokes equations are very hard (or impossible) to solve.

Measurements are easier (easy?)



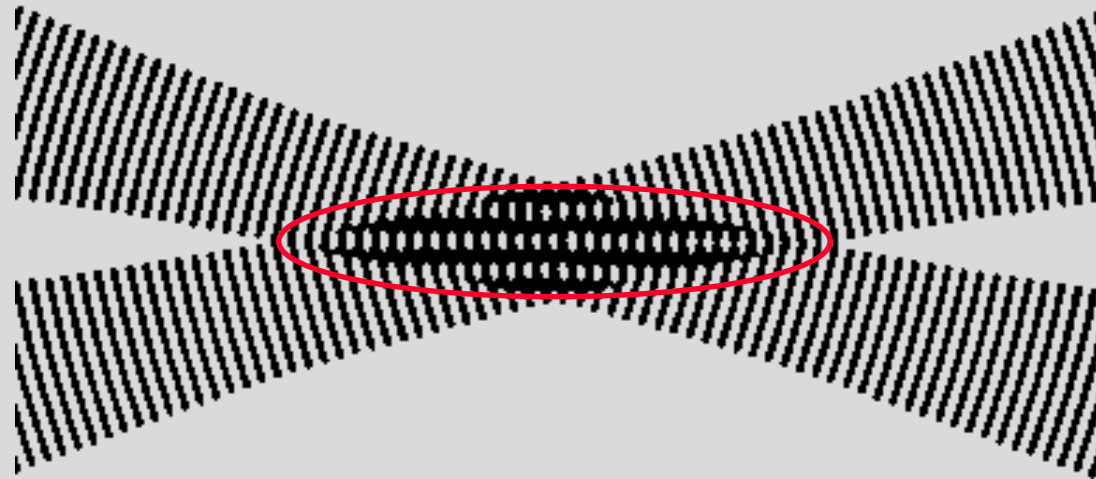
Characteristics of LDA

- Invented by Yeh and Cummins in 1964
- Velocity measurements in Fluid Dynamics (gas, liquid)
- Up to 3 velocity components
- Non-intrusive measurements (optical technique)
- Absolute measurement technique (no calibration required)
- Very high accuracy
- Very high spatial resolution due to small measurement volume
- Tracer particles are required

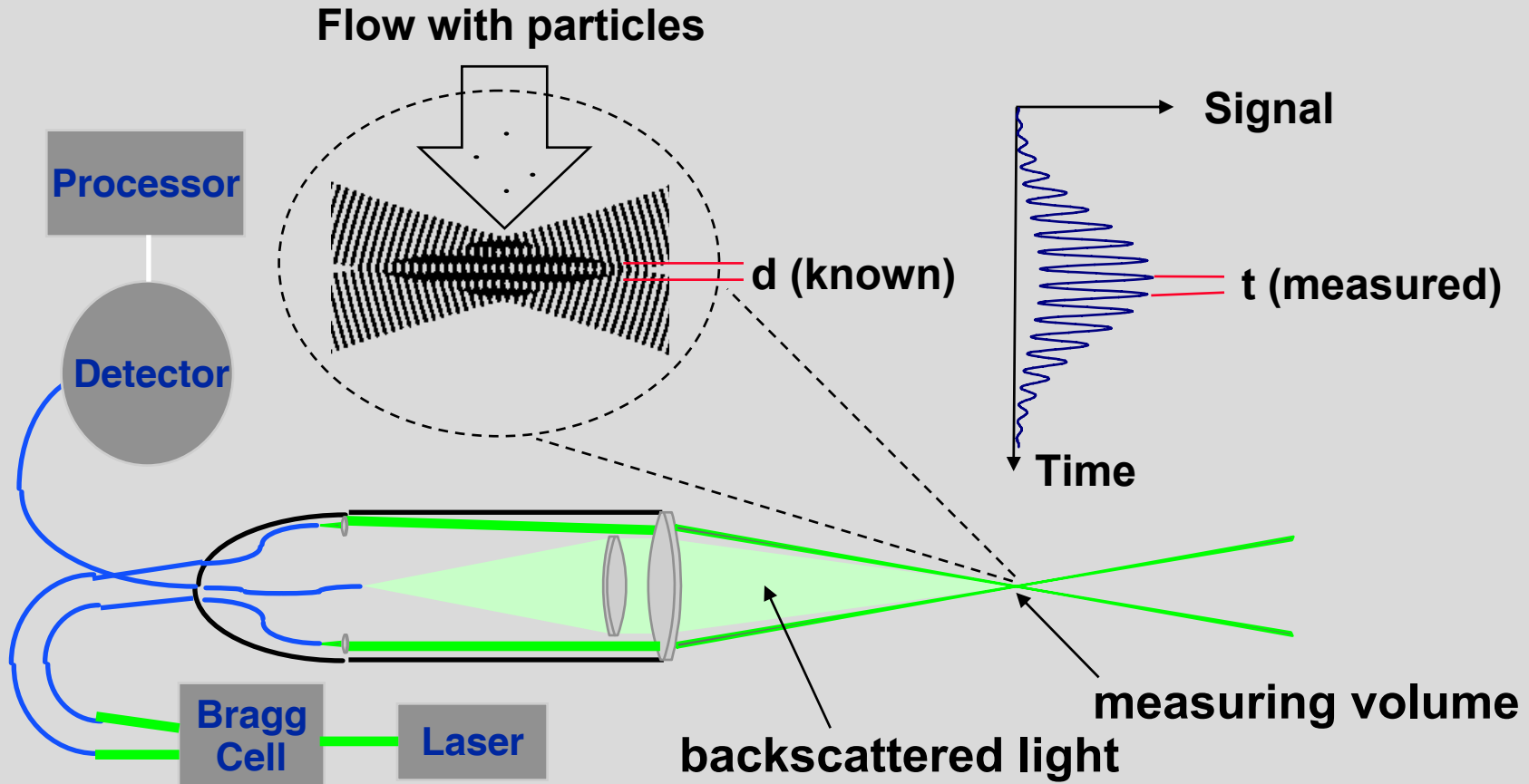


LDA - Fringe Model

- Focused Laser beams intersect and form the measurement volume
- Plane wave fronts: beam waist in the plane of intersection
- Interference in the plane of intersection
- Pattern of bright and dark stripes/planes

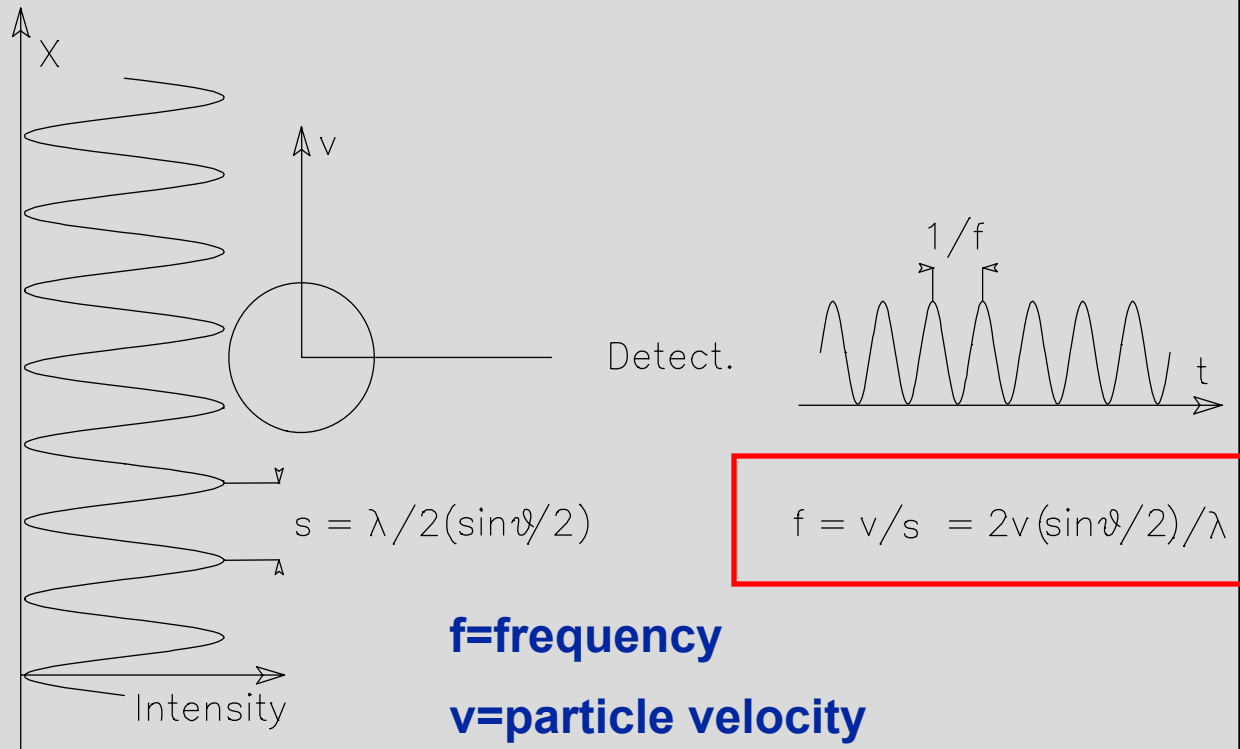


Velocity = distance/time



LDA - Fringe Model

- The fringe model assumes as a way of visualization that the two intersecting beams form a fringe pattern of high and low intensity.
- When the particle traverses this fringe pattern the scattered light fluctuates in intensity with a frequency equal to the velocity of the particle divided by the fringe spacing.



f=frequency

v=particle velocity

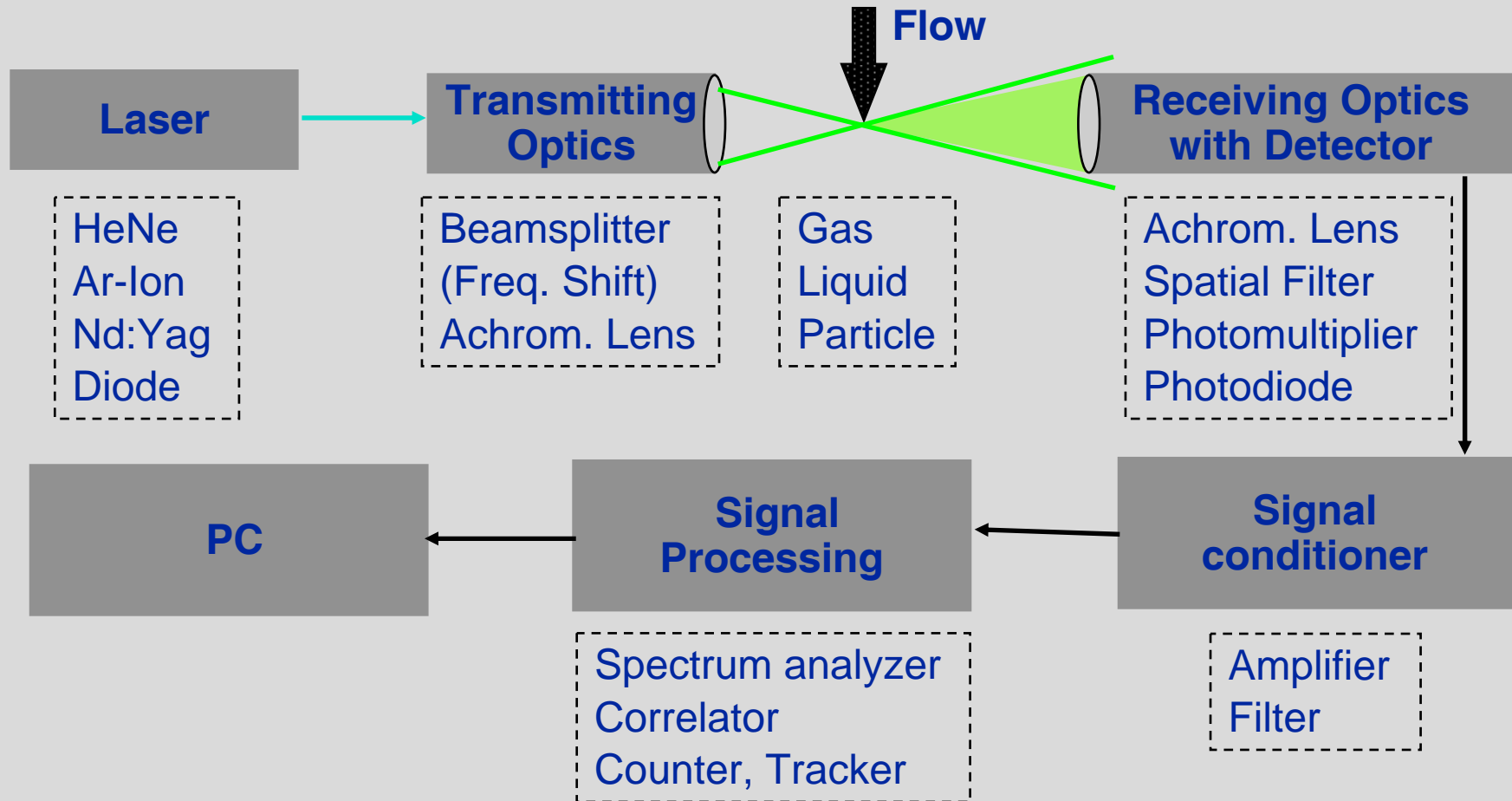
θ =angle between laser beams

λ =wavelength of laser light

See Adrian paper in Goldstein



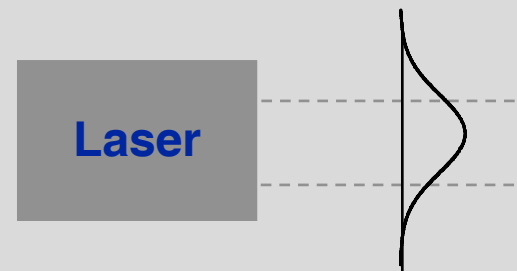
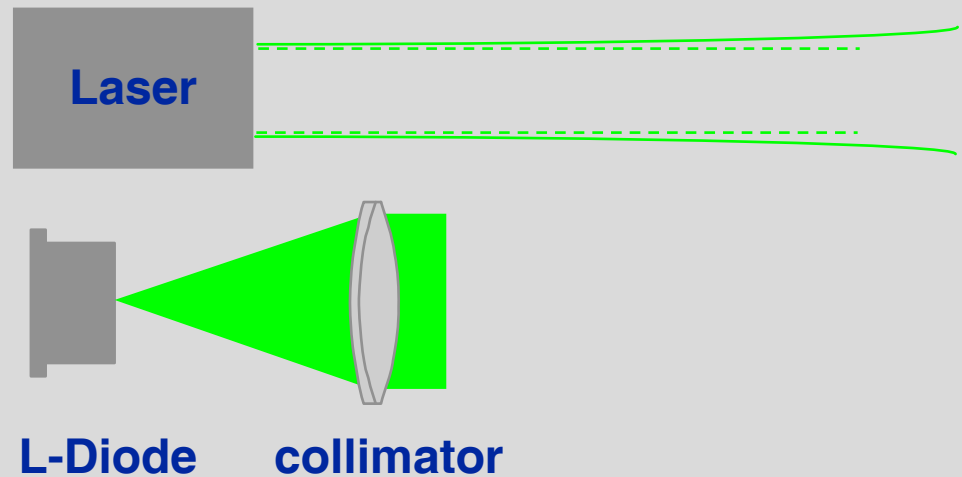
Principle of LDA, differential beam technique



Laser, Characteristics and Requirements

- Monochrome
- Coherent
- Linearly polarized
- Low divergence (collimator)

- Gaussian intensity distribution



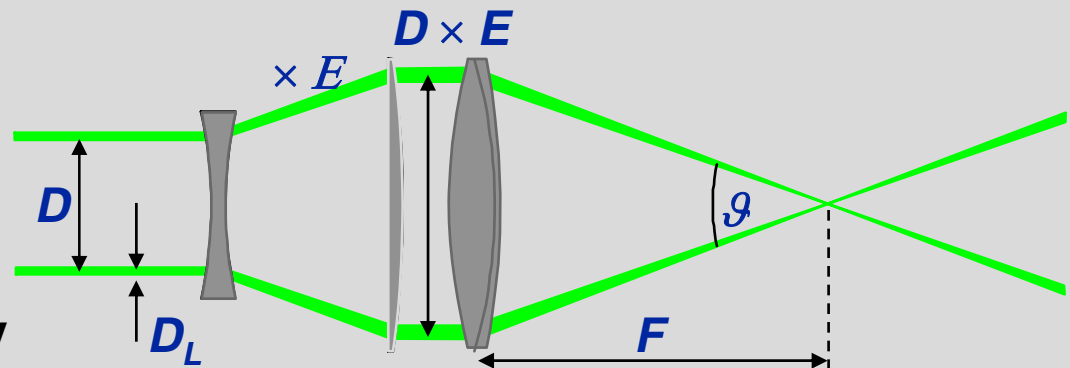
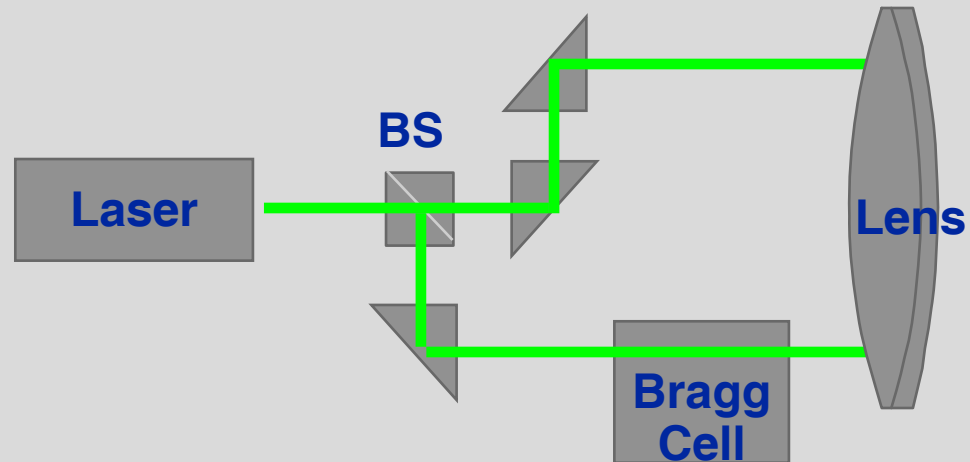
Transmitting Optics

Basic modules:

- Beam splitter
- Achromatic lens

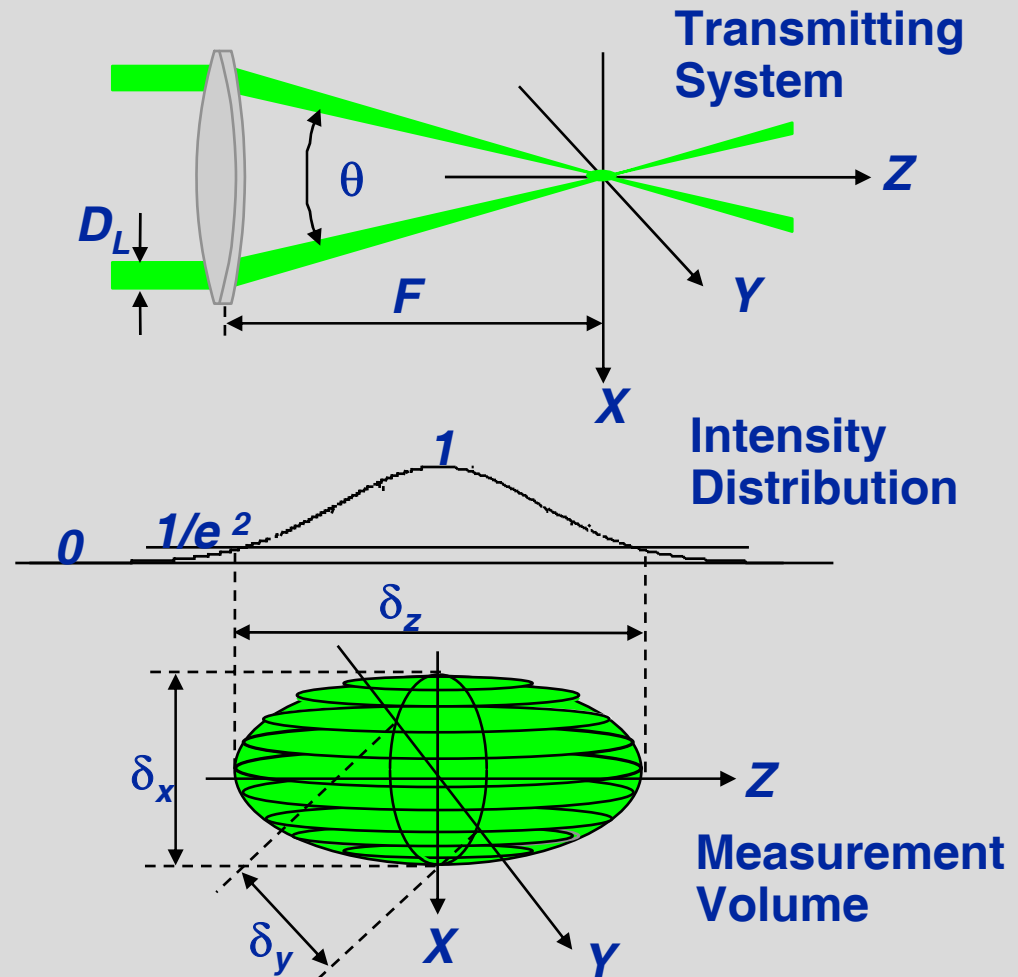
Options:

- Frequency shift (Bragg cell)
 - low velocities
 - flow direction
- Beam expanders
 - reduce measurement volume
 - increase power density



Measurement Volume

- The transmitting system generates the measurement volume
- The measurement volume has a Gaussian intensity distribution in all 3 dimensions
- The measurement volume is an ellipsoid
- Dimensions/diameters δ_x , δ_y and δ_z are given by the $1/e^2$ intensity points



Measurement Volume

Length:

$$\delta_z = \frac{4F\lambda}{\pi E D_L \sin\left(\frac{\theta}{2}\right)}$$

Width:

$$\delta_y = \frac{4F\lambda}{\pi E D_L}$$

Height:

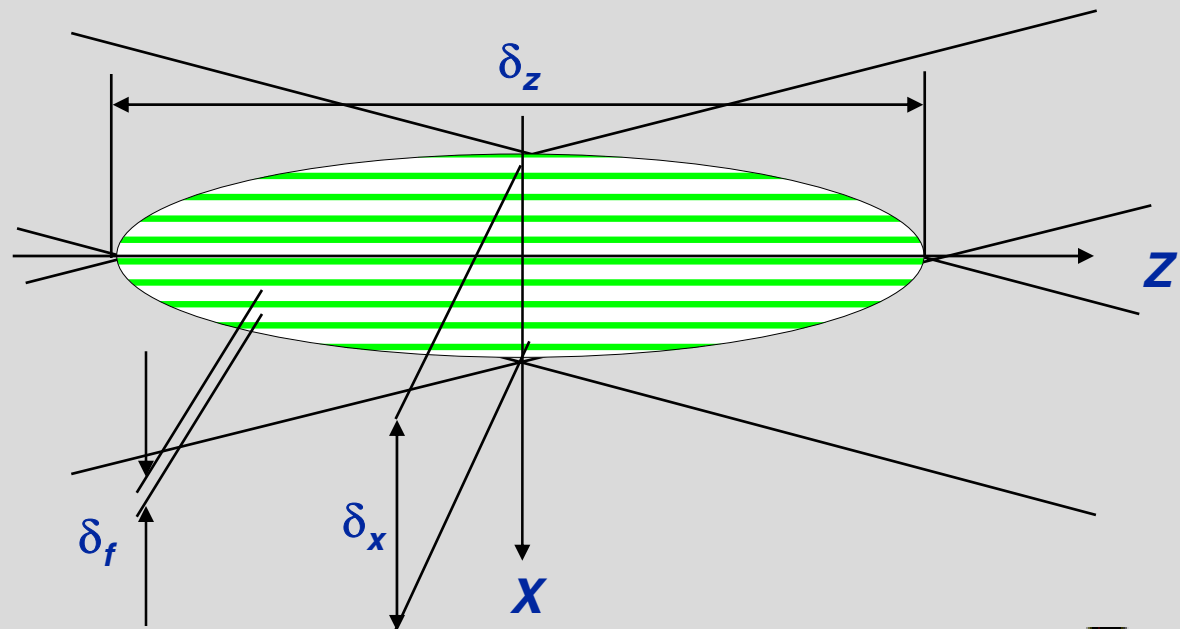
$$\delta_x = \frac{4F\lambda}{\pi E D_L \cos\left(\frac{\theta}{2}\right)}$$

Fringe Separation:

$$\delta_f = \frac{\lambda}{2 \sin\left(\frac{\theta}{2}\right)}$$

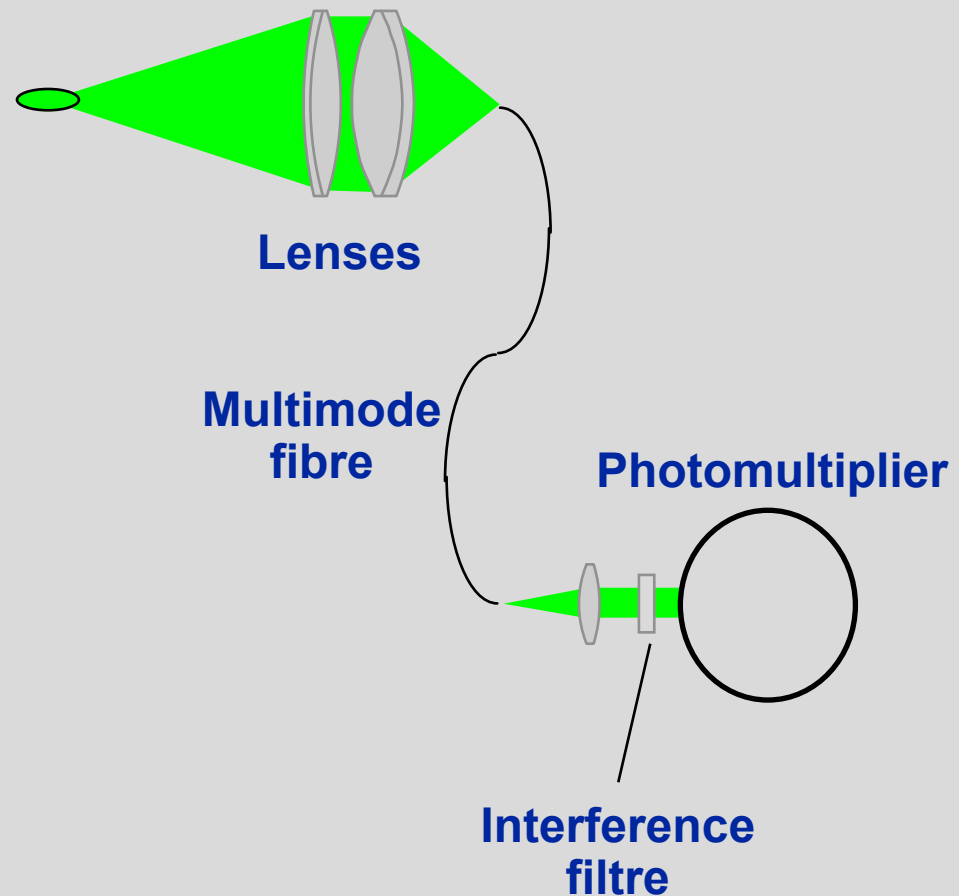
No. of Fringes:

$$N_f = \frac{8F \tan\left(\frac{\theta}{2}\right)}{\pi E D_L}$$



Receiving Systems

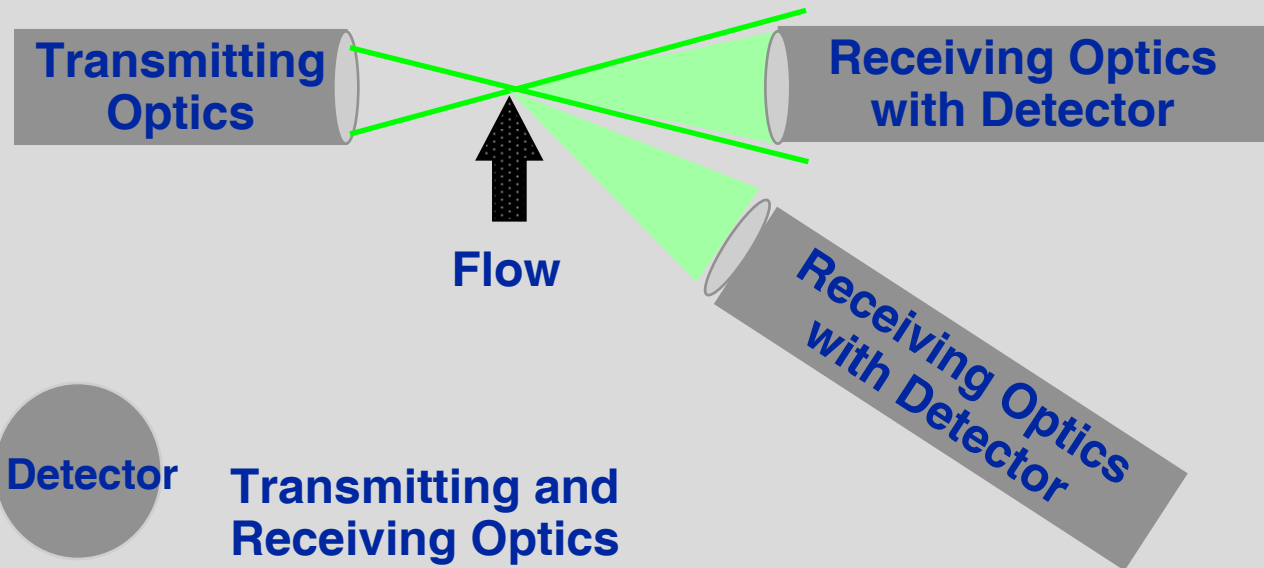
- Receiving Optics
 - Receiving optics
 - Multimode fibre acting as spatial filter
 - Interference filter
- Detector
 - Photomultiplier
 - Photodiode



System Configurations

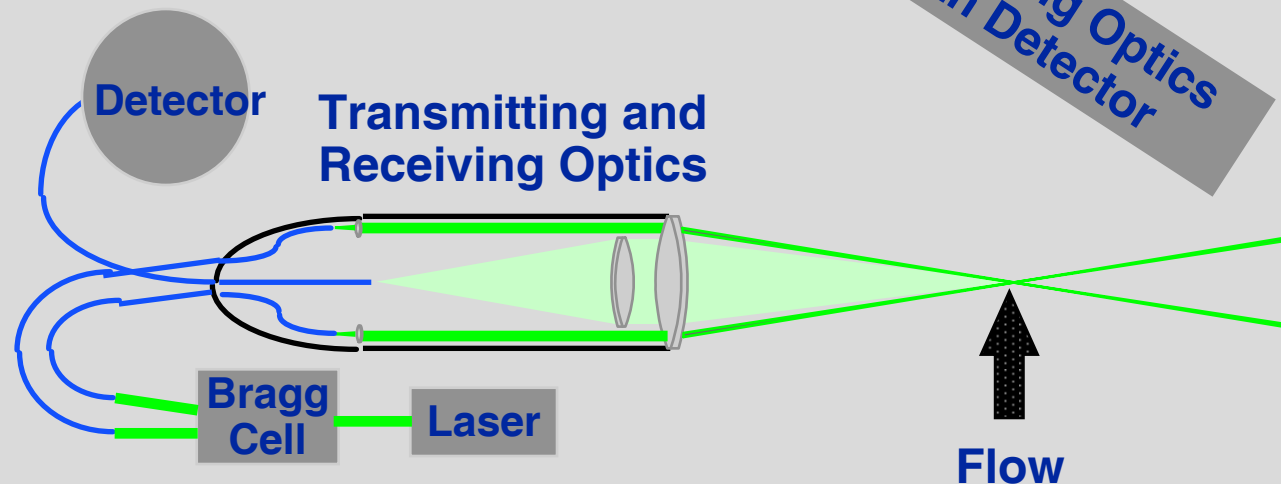
Forward scatter
and side scatter
(off-axis)

- Difficult to align,
- vibration sensitive

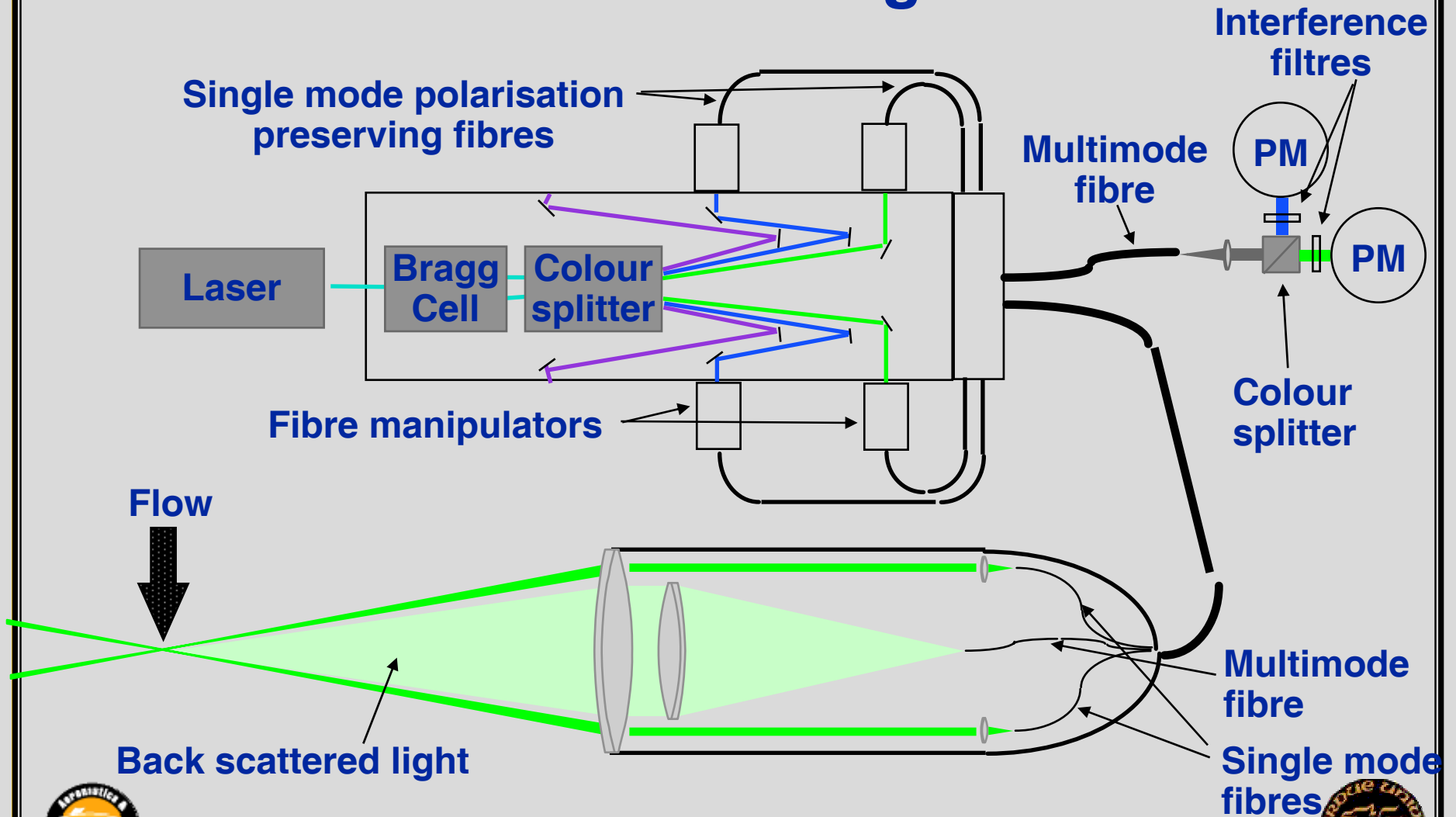


Backscatter

- Easy to align
- User friendly

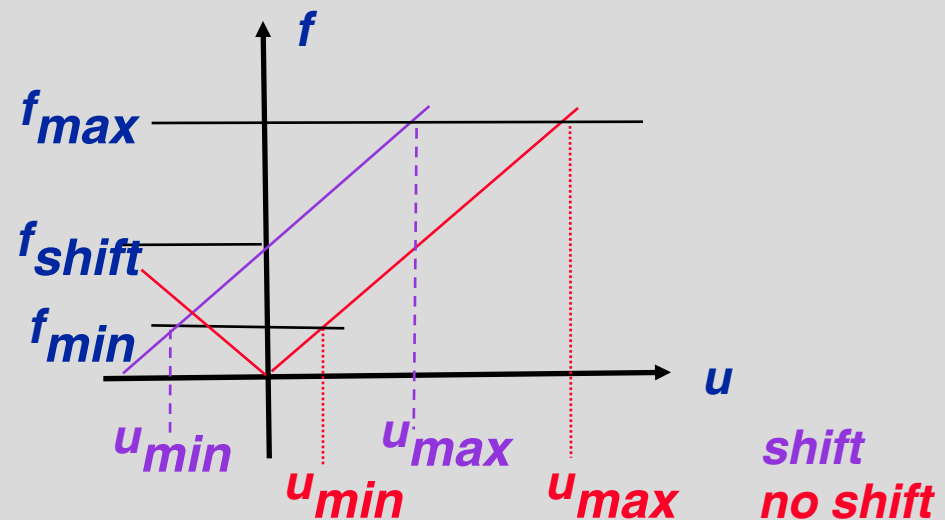
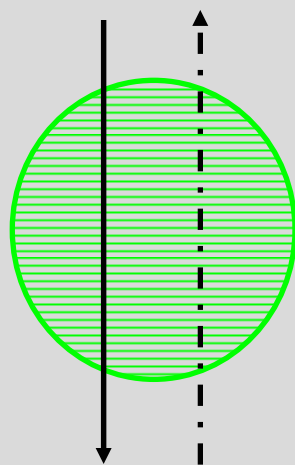


Backscatter Configuration



Directional Ambiguity / Frequency Shift

- Particles moving in either the forward or reverse direction will produce identical signals and frequencies.

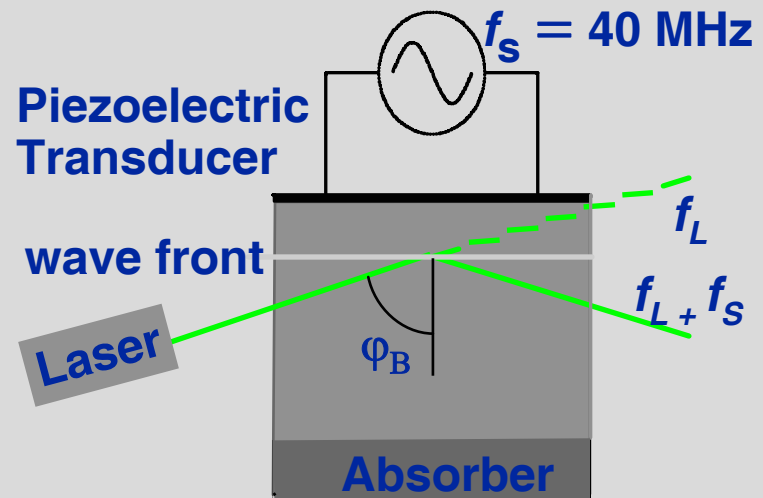


- With frequency shift in one beam relative to the other, the interference fringes appear to move at the shift frequency.
- With frequency shifting, negative velocities can be distinguished.



Frequency Shift / Bragg Cell

- Acousto-optical Modulator
- Bragg cell requires a signal generator (typically: 40 MHz)
- Frequency of laser light is increased by the shift frequency
- Beam correction by means of additional prisms



3-D LDA Applications

- **Measurements of boundary layer separation in wind tunnels**
- **Turbulent mixing and flame investigations in combustors**
- **Studies of boundary layer-wake interactions and instabilities in turbines**
- **Investigations of flow structure, heat transfer, and instabilities in heat exchangers**
- **Studies of convection and forced cooling in nuclear reactor models**
- **Measurements around ship models in towing tanks**



Seeding: ability to follow flow

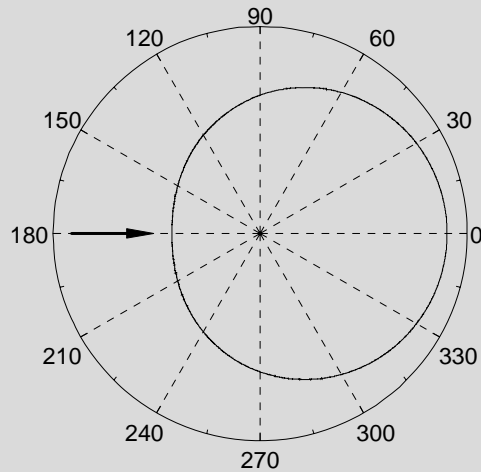
Particle Frequency Response

$$\frac{d}{dt} U_p = -18 \frac{\nu}{d_p^2} \frac{U_p - U_f}{\rho_p / \rho_f}$$

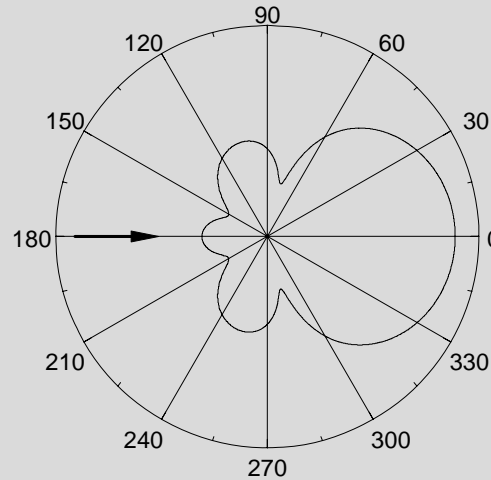
Particle	Fluid	Diameter (μm)	
		f = 1 kHz	f = 10 kHz
Silicone oil	atmospheric air	2.6	0.8
TiO ₂	atmospheric air	1.3	0.4
MgO	methane-air flame (1800 K)	2.6	0.8
TiO ₂	oxygen plasma (2800 K)	3.2	0.8



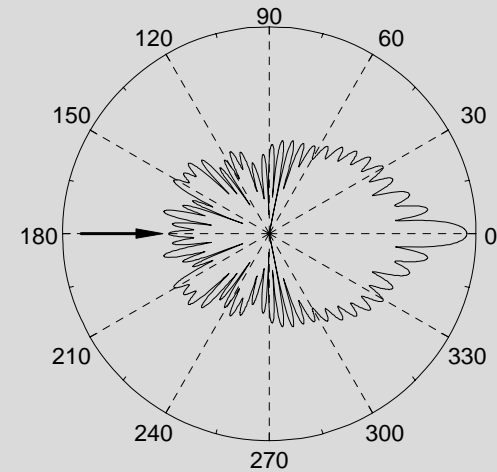
Seeding: scattered light intensity



$$d_p \approx 0.2\lambda$$



$$d_p \approx 1.0\lambda$$

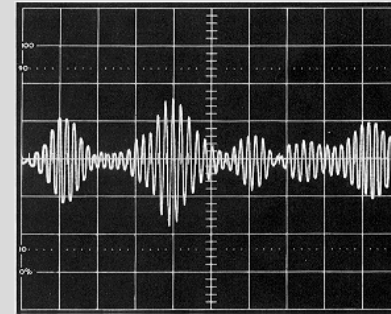
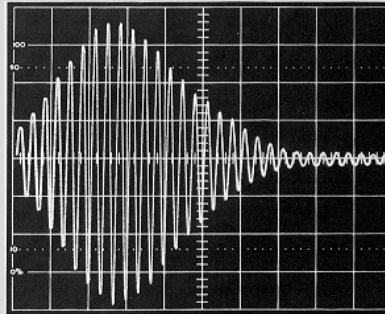
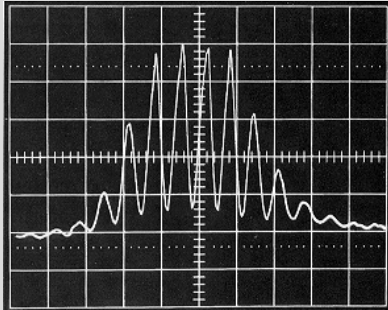


$$d_p \approx 10\lambda$$

- Polar plot of scattered light intensity versus scattering angle
- The intensity is shown on a logarithmic scale



Signal Characteristics



- Sources of noise in the LDA signal:
 - Photodetection shot noise.
 - Secondary electronic noise, thermal noise from preamplifier circuit
 - Higher order laser modes (optical noise).
 - Light scattered from outside the measurement volume, dirt, scratched windows, ambient light, multiple particles, etc.
 - Unwanted reflections (windows, lenses, mirrors, etc).
- Goal: Select laser power, seeding, optical parameters, etc. to maximize the SNR.



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Measurement of air flow around a helicopter rotor model in a wind tunnel

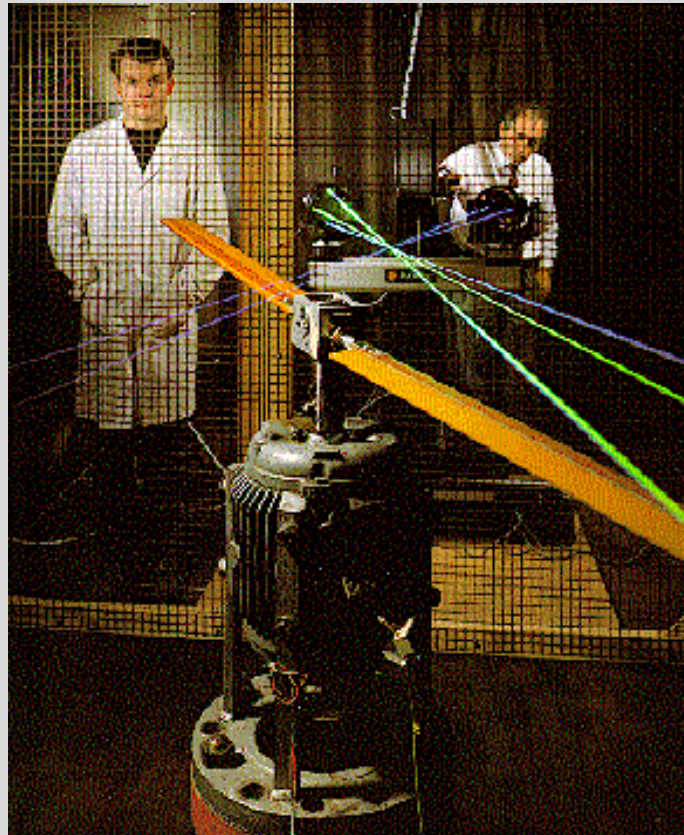


Photo courtesy of University of Bristol, UK



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Measurement of flow field around a 1:5 scale car model in a wind tunnel

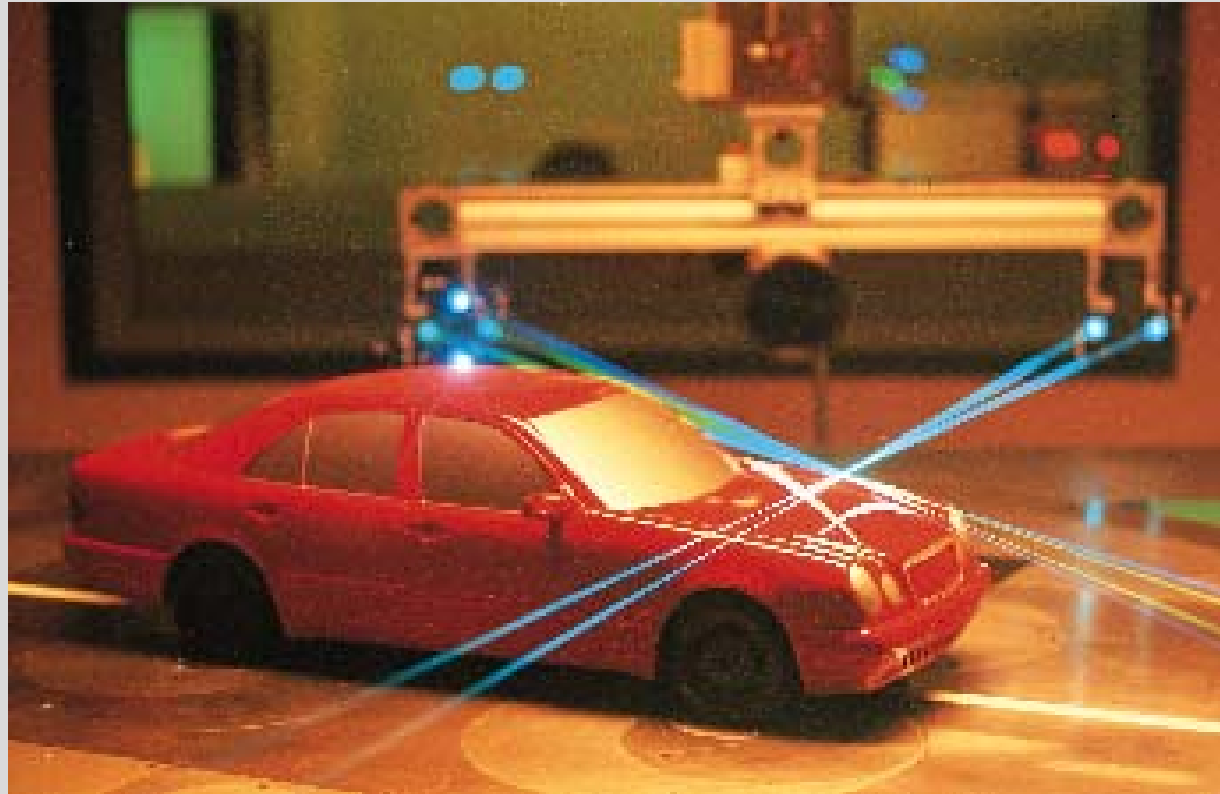


Photo courtesy of Mercedes-Benz, Germany



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Measurement of wake flow around a ship model in a towing tank

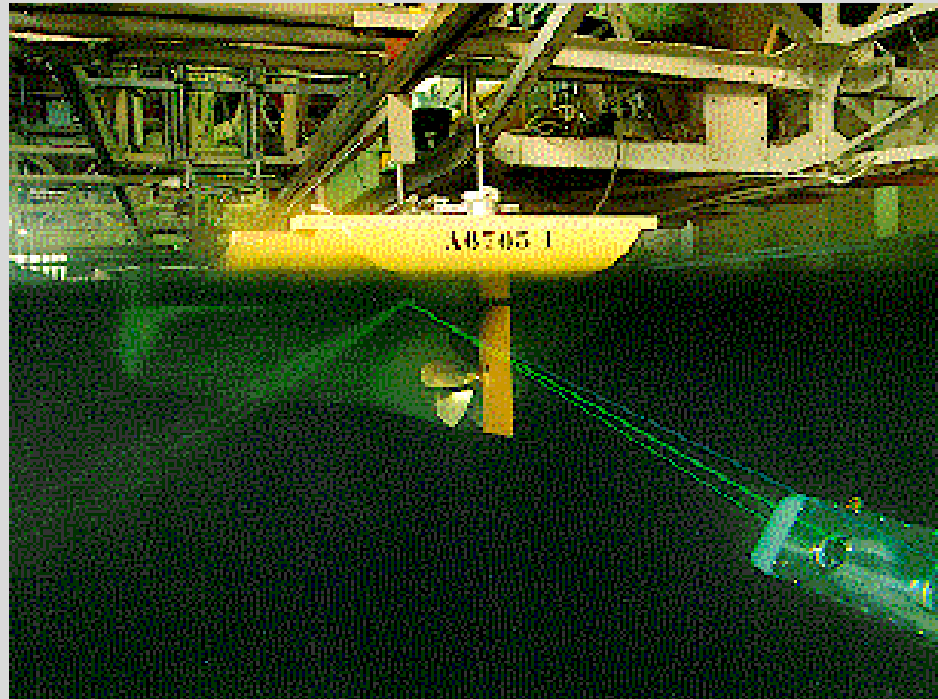


Photo courtesy of Marin, the Netherlands



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Measurement of air flow field around a ship model in a wind tunnel



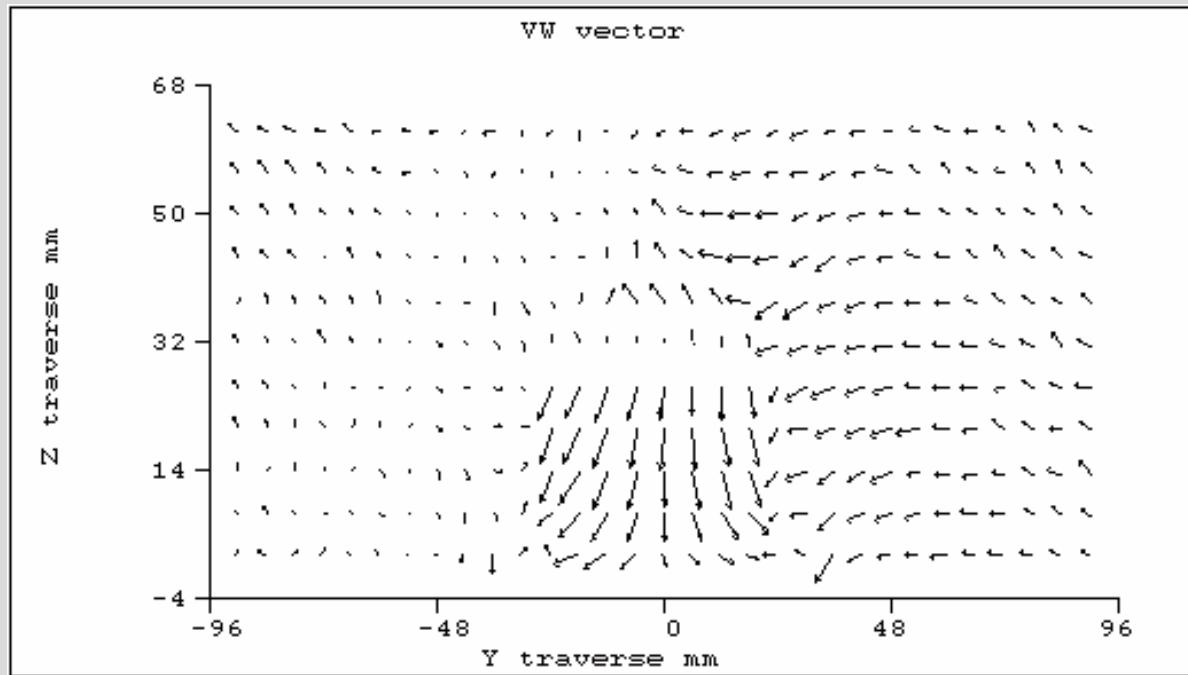
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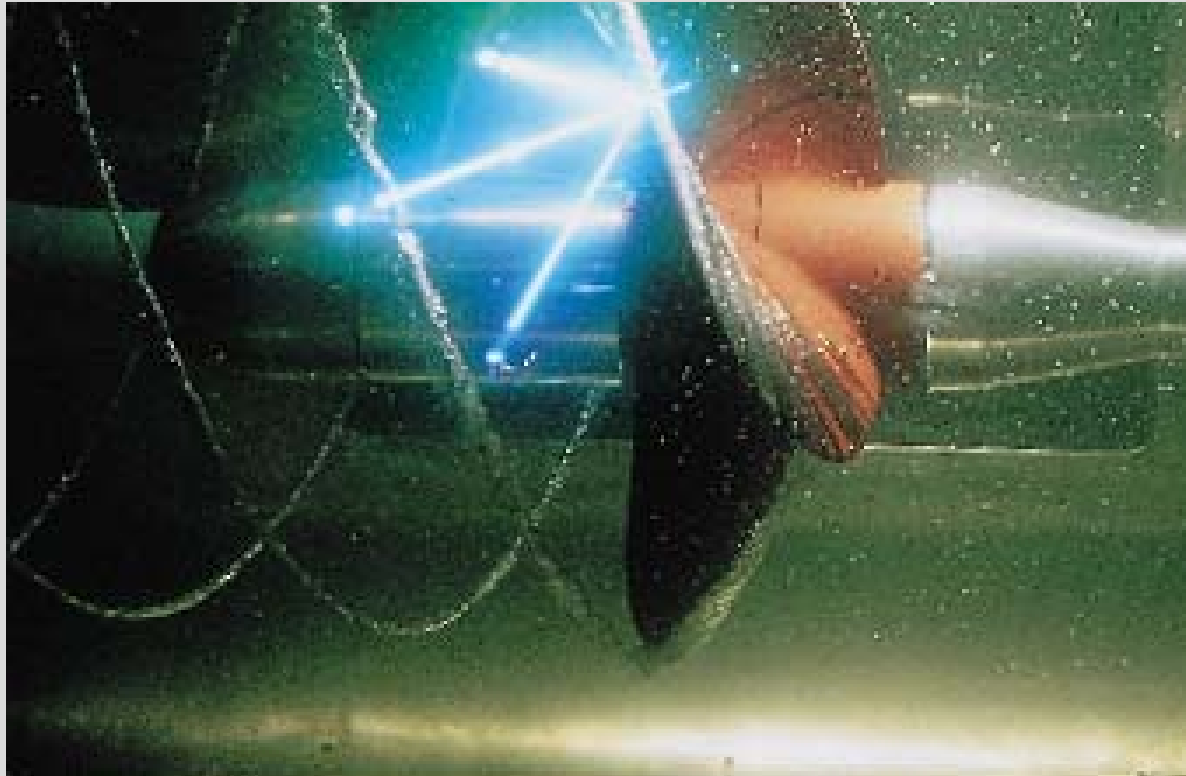


Wake flow field behind hangar



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Measurement of flow around a ship propeller in a cavitation tank



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Measurement of flow in a valve model

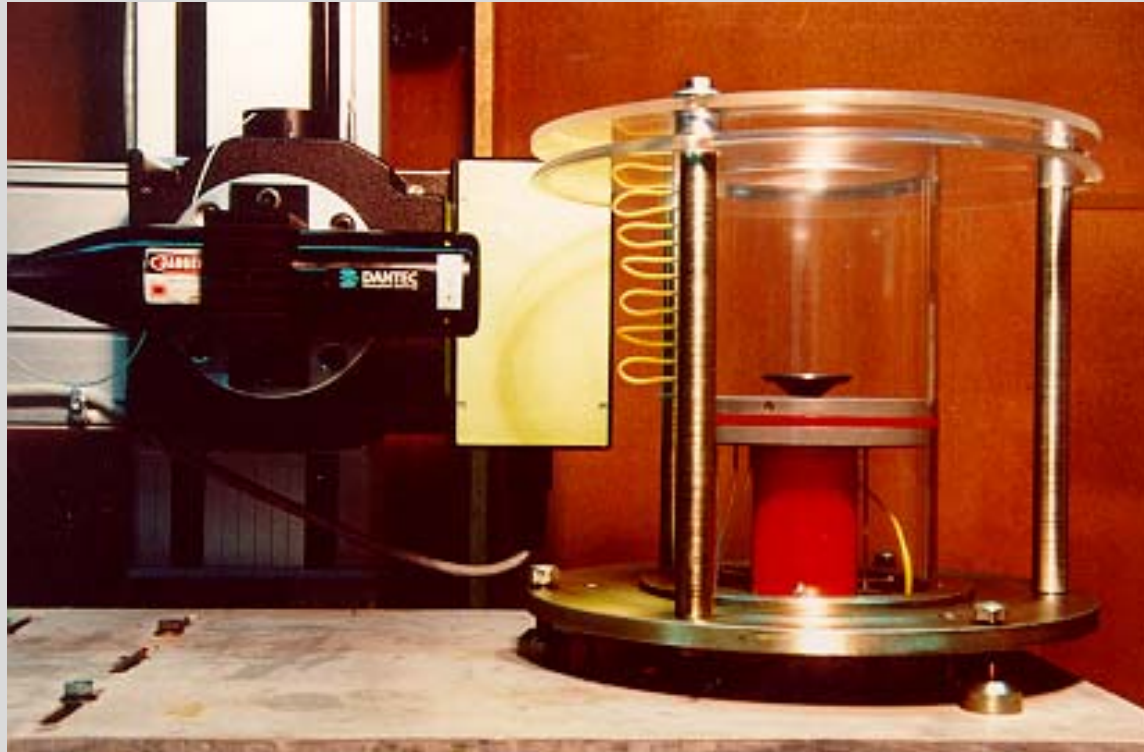


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Comparison of EFD and CFD results

