Fast algorithm for solving hybrid integral equations

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Abstract: A fast algorithm is presented to solve for the scattered field of a two-dimensional, dielectric-coated conducting cylinder using a hybrid of a combined field surface integral equation and volume integral equation. The fast algorithm is an extension of the fast multipole method and it relies on the translation of scattering centers to speed up the matrix-vector multiplication in the conjugate gradient method. The scatterer is first divided into many subscatterers. Instead of directly computing the matrix-vector multiplication, which needs $N^2$ multiplications, an efficient approach is used to reduce the floating-point operation count required. The algorithm has a computational complexity of $O(N^{1.5})$.

1 Introduction

Computation of the scattering solution by two-dimensional (2D) conducting cylinders is a classical electromagnetic problem, and many algorithms have been developed for this purpose [1-6]. In most cases, the problem is converted into an integral equation where the unknown function is the induced current distribution. The integral equation is then solved by the method of moments (MOM) [7] which requires $O(N^3)$ floating-point operations if Gaussian elimination is used to invert the $N$ by $N$ matrix, or $N^2$ operations per iteration if the conjugate gradient (CG) method is used [8].

Recently, Rokhlin [9] has developed a fast multipole method for acoustic wave scattering problems. The method has been applied to electromagnetic scattering computation of the $E_z$-polarised case by Engscha et al. [10]. In this paper, we will extend the algorithm to the $H_z$-polarised case and apply it to calculate the scattering solution of dielectric-coated conducting cylinders. A combined-field surface integral equation [11, 12, 13] will be used to remove the internal resonance problem for the metallic scatterer, and a hybrid combined-field surface integral equation and volume integral equation will be used to solve the problem involving dielectric coating. We shall also present an alternate derivation and physical interpretation of this fast algorithm. As will be obvious from the derivation, the waves are expressed as plane waves as they propagate from one scattering centre to another.

In this algorithm, a metallic scatterer is first decomposed into $N$ subscatterers [9]. When there is an incident wave, each subscatterer will carry a current distribution which is determined by the interaction equation (the discretised integral equation). To compute the total field at a subscatterer due to the other subscatterer, one needs at least $N$ multiplications. Since there are $N$ subscatterers $N^2$ multiplications are needed to compute the total interactions among them. These $N^2$ interactions correspond to a matrix-vector multiplication in a conjugate-gradient method.

The fast multipole method [9] is designed to account for this interaction more efficiently. The idea is first to divide the subscatterers into groups. Then, the addition theorem of Bessel functions (or the translation matrix) is used to translate the scattered field of different scattering centres within a group into a single centre (called group centre). Hence, one scattering centre represents the scattered field of a group of centres, reducing the number of scattering centres. Similarly, for each group, the field scattered by all the other group centres can be first 'received' by the group centre, and then redistributed to the subscatterers belonging to the group.

In fact, since each subscatterer is a monopole (for the $E_z$ wave) or a dipole (for the $H_z$ case), the group centre will be a higher-order multipole. Hence, the reduction in the number of scattering centres is at the expense of increasing the order of the multipole. However, it can be shown that by appropriately selecting the size of the groups and diagonalising the translation matrices with plane-wave basis, the number of floating-point operations needed to compute the overall interaction can be reduced from $N^2$ to $N^{1.5}$. A further nesting of the algorithm yields an $O(N^{1.33})$ algorithm.

2 New look at the fast multipole method

The fast multiple method [9] is designed to speed up the matrix–vector multiplication in the CG method when CG is used to solve a surface integral equation. We shall present here a more succinct derivation of this algorithm.

As an example, the surface integral equation which governs the scattering solution of a metallic scatterer by $E_z$-polarised waves is given by

$$ i \omega \mu_0 \int dS G_{\delta}(\rho - \rho') J_\lambda(\rho') = -E^m_{z}(\rho) \quad \rho \in S $$

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In the above
\[ g_0(\rho - \rho') = \frac{i}{4} H_0^{(1)}(k|\rho - \rho'|) \] (2)

\[ J_f(\rho') \] is the induced current on the surface of the scatterer and \( E_{in}(\rho) \) is the incident field. The above integral equation can be discretised [7] to yield
\[ \sum_{i=1}^{N} g_{ij} a_i = b_j \quad j = 1, \ldots, N \] (3)

where
\[ g_{ij} = \frac{\omega \mu_0}{4} \left( 1 + \frac{2j}{\pi} \ln \left( \frac{2k\Delta_i}{4e} \right) \right) \Delta_i, i = j \] \[ g_{ij} = \frac{\omega \mu_0}{4} \Delta_i H_0^{(1)}(k\rho_{ij}) \quad i \neq j \] (4a)

\[ b_j = E_{in}(\rho) \] (4b)

\[ a_i = J_f(\rho) \] (4c)

where \( \rho_{ij} = |\rho_j - \rho_i| \) and \( (\gamma/4e) = 0.163805 \). The matrix-vector multiplication, \( \sum_{i=1}^{N} g_{ij} a_i \), is the bottleneck in the speed of the CG algorithm. The fast multipole method expedites this matrix-vector multiplication. This is achieved by dividing the \( N \) subscatters into groups, each of which contains \( M \) subscatters. Hence, there are \( N/M \) groups altogether. Furthermore, the translational addition theorem can be used to rewrite \( g_{ij} \). Using the notation developed by us previously [14–18], we can write
\[ H_0^{(1)}(k\rho_{ij}) = \beta'_{ij} \cdot \beta_{ij} \] (5)

where \( \beta' \) and \( \beta \) are defined in Refer-

\[ \beta'_{ij} = H_0^{(1)}(k_0 \rho_{ij}) e^{-im\phi_{ij}} \] (5a)

\[ \beta_{ij} = J_f(k_0 \rho_{ij}) e^{-im\phi_{ij}} \] (5b)

where \( \phi_{ij} \) is the angle the line \( \rho_{ij} \) makes with the \( x \)-axis and similarly for \( \phi_{ij}' \). Using eqn. 5, we can rewrite eqn. 3 as
\[ \sum_{j=1}^{N/M} \sum_{i \neq j} \beta'_{ij} \cdot \beta_{ij} = b_j \] \[ \gamma \in G, \quad \lambda = 1, \ldots, N/M \] (6)

for interactions between elements of group \( G \) and group \( \gamma \) only. In the above, \( \beta_j' \) is used to indicate interactions excluding the interaction within the same group. For interactions between elements within the same group, eqn. 3 is still used.

To maintain the accuracy of eqn. 5, \( P \approx cM \) because the number of cylindrical harmonics \( P \) needed in eqn. 5 is proportional to the size of the group, and \( M \) is proportional to the size of the group. Hence, the cost of computing \( c_l = \sum_{i} a_i \beta_{ij} \Delta_i, l = 1, \ldots, N/M \) is
\[ T_1 = c_1 \frac{N}{M} M^2 = c_1 N M \] (7)

The cost of computing \( d_l' = \sum_{i=1}^{N/M} \beta'_{ij} \cdot c_l, l = 1, \ldots, N/M \) is
\[ T_2 = c_2 \left( \frac{N}{M} \right)^2 M^2 = c_2 N^2 \] (8)

The cost of computing \( \beta'_{ij} \cdot \beta_{ij}, j \in G, \lambda = 1, \ldots, N/M \) is
\[ T_3 = c_3 \left( \frac{N}{M} \right)^2 M^2 = c_3 N M \] (9)

Therefore, there is little advantage at this point in rewriting eqn. 3 as eqn. 6 as now the cost of performing eqn. 6 still requires \( O(N^2) \) operations. However, the cost of calculating eqn. 6 can be substantially reduced if \( \lambda \) can be diagonalised.

To this end, we substitute in the definition of \( \alpha \) and \( \beta \) [18] in eqn. 5, so that it can be written as
\[ H_0^{(1)}(k\rho_{ij}) = \sum_{m=-\infty}^{\infty} J_m(k\rho_{ij}) e^{im\phi_{ij}} \sum_{n=-\infty}^{\infty} H_0^{(1)}(k\rho_{ij}) e^{-im\phi_{ij}} \]
\[ \times J_m(k\rho_{ij}) e^{-im\phi_{ij}} \] (10)

Even though \( H_0^{(1)}(x) \to 0 \) when \( |m| \to \infty \), the above summations converge because \( J_0(x) \to 0 \), when \( |x| \to \infty \). Notice that the inner summation in the above is the convolution of two discrete Fourier series. Therefore, it can be expressed as a product of two functions if their respective discrete Fourier transforms (DFT) can be found. Unfortunately, the DFT of \( H_0^{(1)}(x) \) does not exist since \( H_0^{(1)}(x) \to 0 \) when \( |x| \to \infty \). However, we can truncate the inner summation since it converges and express eqn. 10 as
\[ H_0^{(1)}(k\rho_{ij}) = \sum_{m=-\infty}^{\infty} J_m(k\rho_{ij}) e^{im\phi_{ij}} \]
\[ \times \sum_{m=-\infty}^{\infty} H_0^{(1)}(k\rho_{ij}) e^{-im\phi_{ij}} \]
\[ \times J_m(k\rho_{ij}) e^{-im\phi_{ij}} \] (11)

Eqn. 11 can be expressed in the Fourier space by using the integral representation of the Bessel function [15, p. 62]
\[ J_m(k\rho_{ij}) e^{im\phi_{ij}} = \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{im(x-\phi_{ij})} \sin\left(\frac{\pi - \alpha - (m-\gamma)\phi_{ij}}{2}\right) \] (12a)
\[ J_d(k \rho_0) e^{-i \mathbf{k} \cdot \mathbf{r}} = \frac{1}{2\pi} \int_0^{2\pi} d\alpha \int_0^{\pi} d\phi \cos(\alpha + \phi) + \cos(\alpha - (\pi/2)) \] (12b)

Using eqn. 12 in eqn. 11, exchanging the order of integration and summation, we have

\[ H^{(1)}_{\rho}(k \rho_0) = \frac{1}{2\pi} \int_0^{2\pi} d\alpha \int_0^{\pi} d\phi \mathbf{\tilde{e}}_r(a) \mathbf{\tilde{e}}_d(\alpha) \mathbf{\tilde{e}}_d(\alpha) \] (13)

where

\[ \mathbf{\tilde{e}}_r(a) = \sum_{p \neq p'} H_{\rho}(k \rho_0)e^{-i(\phi_1 + \phi_2 - a)} \] (14)

and

\[ \mathbf{\tilde{e}}_d(\alpha) = e^{i k \rho_0 \cos(\alpha - \phi)} \] (15)

Notice that now, cylindrical waves are replaced by plane waves in the integrand of eqn. 13. Also, \( \mathbf{\tilde{e}} \) is now replaced by a diagonal operator \( \mathbf{\tilde{e}}_r(\alpha) \). Notice now that the series in eqn. 14 diverges if \( P \) is increased indefinitely. This results from the exchange of the order of summation and integration.

Using eqn. 13 in replacement of eqn. 5 in eqn. 6, we have

\[ \frac{\partial}{\partial n_j} \sum_{i=1}^{N} I_{i} \left[ \frac{1}{i} \right] \mathbf{\tilde{e}}_r(\alpha) \mathbf{\tilde{e}}_d(\alpha) \mathbf{\tilde{e}}_d(\alpha) = \mathbf{b}_j + \sum_{i=1}^{N} \mathbf{a}_i \] (16)

for intergroup interactions. The integral in eqn. 13 can be replaced by \( Q \)-point summation yielding

\[ \frac{\partial}{\partial n_j} \sum_{i=1}^{Q} I_{i} \left[ \frac{1}{i} \right] \mathbf{\tilde{e}}_r(\alpha) \mathbf{\tilde{e}}_d(\alpha) \mathbf{\tilde{e}}_d(\alpha) = \mathbf{b}_j + \sum_{i=1}^{Q} \mathbf{a}_i \] (17)

Notice that in the above, instead of propagating the field from one group to another using cylindrical waves, one has effectively used plane waves. These plane waves diagonalise the translation operators.

It can be shown that \( Q \) above is proportional to \( M \) from sampling theorem. With this new equation, the cost of the first step of the calculation, \( T_1 \), is still the same. However, the replacement of \( \mathbf{\tilde{e}}_r(\alpha) \) with a diagonal operator \( \mathbf{\tilde{e}}_r(\alpha) \) reduces the cost in the second stage to

\[ T_2 = C_1 \frac{N^2}{M} \] (18)

The cost in the third stage is still the same. Therefore, the total cost is

\[ T = C_1 \frac{N^2}{M} + C_2 N M \] (19)

Optimising eqn. 19 with respect to \( M \) yields \( M = \sqrt{[(C_1/C_2)N]} \). Therefore,

\[ T = 2 \sqrt{C_1 C_2} N^{1.5} \] (20)

A further nesting of this algorithm within itself yields an \( O(N^{1.5}) \) algorithm.*

3 Combined field integral equation

A straightforward solution of eqn. 1 is plagued by the problem of internal resonances as the integral operator in eqn. 1 has null spaces at these resonant frequencies. To overcome this, a combined field integral equation [11–13] is used which yields an integral equation with only complex resonant frequencies.

To obtain the combined field integral equation, we multiply both sides of eqn. 1 by a differential operator

\[ P(\rho) = 1 + \lambda \mathbf{\hat{n}} \cdot \nabla \] (21)

to obtain the combined field integral equation (CFIE)

\[ \int_{\mathbf{S}} P(\rho) \mathbf{g}_\rho(\rho - \rho') J_d(\rho') dS' = P(\rho) E_{\rho}(\rho) \] (22a)

where \( \mathbf{\hat{n}} \) is the unit outward normal at \( \rho \), and \( \lambda \) is a complex constant.

After discretisation, eqn. 21 can be written in a discretised form

\[ \sum_{i=1}^{N} G_{\mu} a_i = b_j \quad j = 1, 2, \ldots, N \] (22b)

where

\[ G_{\mu} = \frac{30 \pi k A_i \left[ 1 + i \frac{2}{\pi} \ln \left( \frac{k \Delta_i}{4} \right) - i \frac{2 \lambda}{\Delta_i} \right] i = j \]

\[ 30 \pi k A_i P_j H^{(1)}_{\rho}(k \rho_0) \]

\[ \frac{\partial}{\partial n_j} \] (22c)

and

\[ b_j = P_j E_{\rho}(\rho) \]

\[ a_i = J_d(\rho_i) \]

\[ P_j = 1 + \lambda \frac{\partial}{\partial n_j} \] (23)

For \( H_r \) polarisation, a similar equation to eqn. 22 can be obtained in a similar manner with \( b_j = P_j H_r(\rho_i), a_i = H_r(\rho_i) \) and

\[ G_{\mu} = -i \Delta_i P_j \frac{\partial}{\partial n_j} H^{(1)}_{\rho}(k \rho_0) \] (23)

Using the fact that \( (\partial/\partial n_j) = n_{\rho 0}^0 (\partial/\partial x) + n_{\rho 0}^0 (\partial/\partial y) \), where \( n_{\rho 0}^0 \) and \( n_{\rho 0}^0 \) are the \( x \) and \( y \) components of the unit normal \( \mathbf{\hat{n}}_i \), we can show from eqn. 13 that

\[ \frac{\partial}{\partial n_j} H^{(1)}_{\rho}(k \rho_0) = \frac{1}{2\pi} \int_0^{2\pi} d\alpha \tilde{e}_r(\alpha) \tilde{e}_d(\alpha) \tilde{e}_d(\alpha) \times [i(k n_{\rho 0}^0 \cos x + n_{\rho 0}^0 \sin y)] \tilde{e}_d(\alpha) \] (24)

Using similar idea, we can show that

\[ P_j H^{(1)}_{\rho}(k \rho_0) = \frac{1}{2\pi} \int_0^{2\pi} d\alpha [i + i \lambda (n_{\rho 0}^0 \cos x + n_{\rho 0}^0 \sin y)] \tilde{e}_r(\alpha) \tilde{e}_d(\alpha) \] (25)

Consequently, eqn. 22 or its variant eqn. 23, after using the discretised form of eqns. 24 or 25, becomes

\[ b_j = \sum_{\sigma \neq \sigma'} \frac{1}{Q} \tilde{P}_{\mu}(\sigma) \sum_{i=1}^{N} \tilde{e}_r(\sigma) \tilde{e}_d(\sigma) \tilde{e}_d(\sigma) + \sum_{i=1}^{N} G_{\mu} a_i \]

\[ j \in G_{\mu} \quad \mu = 1, \ldots, N/M \] (26)

where

\[ \tilde{P}_{\mu}(\sigma) = [i + i \lambda (n_{\rho 0}^0 \cos x + n_{\rho 0}^0 \sin y)] \times e^{i k \rho_0 \cos(\alpha - \phi)} \] (27)

* A reviewer has suggested the possible occurrence of relative convergence phenomenon in this algorithm, but we have not observed it.

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\[ \tilde{Q}_d(\alpha) = \left\{ \begin{array}{ll} 30n\kappa \Delta \epsilon e^{kDq \cos (\alpha_q - \phi_q)} & E_x \text{ polarisation} \\ -\frac{kDq}{2} (n^{\phi_2} \cos \alpha_q + n^{\phi_3} \sin \alpha_q) e^{kDq \cos (\alpha_q - \phi_q)} & H_z \text{ polarisation} \end{array} \right. \] (28)

The last term in eqn. 26 accounts for interaction within the same group.

4 Dielectric coating hybrid integral equation

Now we shall discuss the application of this algorithm to calculate the scattering solution of dielectric-coated conducting cylinders. Generally, the coating material is modelled by small circular dielectric cylinders as is done by many other authors [18–20]. The equations governing the induced current on the conducting surface will be the same as eqn. 22 except that the contribution from the dielectric region is added to the equations.

When an inhomogeneous dielectric scatterer is closed to a metallic scatterer, the total scattered field from the scatterers for \( E_x \) polarisation is

\[ E_x^{\text{inc}}(\rho) = \text{io}\mu_0 \int_{S'} dS' \tilde{g}_d(\rho - \rho') J_x(\rho') \]

\[ + \int_{S'} dV' \tilde{g}_d(\rho - \rho') \left[ k_0^2 \bar{E}_x(\rho') - k_L^2 \bar{E}_x(\rho') \right] \]

where \( E_x(\rho) = E_x^{\text{inc}}(\rho) + E_x^{\text{ext}}(\rho) \). The boundary condition on the metallic surface is \( E_x^{\text{inc}}(\rho) = -E_x(\rho) \). The dielectric region can be replaced by circular dielectric subscatterers [18–20]. Hence, the second part of eqn. 29 can be discretised and expressed as

\[ E_x^{\text{inc}}(\rho) = \text{io}\mu_0 \int_{S'} dS' \tilde{g}_d(\rho - \rho') J_x(\rho') + \sum_{i=1}^{N_t} \tilde{g}_x(\rho) a_i \]

(30)

This is because each dielectric subscatterer scatters like a monopole for \( E_x \) polarisation. If the isolated \( T \)-matrix of each dielectric subscatterer is known, then the constraint condition on each dielectric subscatterer is that [15, 18]

\[ a_j = T_{E_x}(\rho) \quad j = N + 1, \ldots, N' \]

(31)

Therefore, discretising the first part of eqn. 30 as well as before, and imposing the boundary condition on the metallic surface analogous to eqn. 3, we have

\[ \sum_{i=1}^{N_t} \tilde{g}_x(\rho) a_i = \sum_{i=1}^{N_t} \tilde{g}_x(\rho) a_i = b_j \quad j = 1, \ldots, N \]

(32)

Imposing eqn. 31 on the dielectric subscatterers, we have

\[ a_j = T_{E_x}(\rho) \left\{ E_x^{\text{inc}}(\rho) - \sum_{i=1}^{N_t} \tilde{g}_x(\rho) a_i \right\} \]

\[ + \sum_{i=1}^{N_t} \tilde{g}_x(\rho) a_i = b_j \quad j = N + 1, \ldots, N' \]

(33)

Eqs. 32 and 33 constitute \( N' \) equations for the \( N' \) unknowns \( a_j \), \( i = 1, \ldots, N' \). However, it is still plagued with internal resonances from the metallic scatterer. To overcome this, eqn. 30 is operated upon by the \( P(\rho) \) operator before the boundary condition is imposed on the metallic surface. By so doing, we convert eqn. 32 to

\[ \sum_{i=1}^{N_t} G_{ij} a_i + \sum_{i=N+1}^{N} P_j(\rho) \psi(\rho) a_i = b_j \quad j = 1, \ldots, N \]

(34)

analogous to eqn. 22a. Eqs. 33 and 34 constitute the equations free of internal resonance problem. The fast multipole method can be used to speed up the matrix-vector multiplication as before, if the dielectric region is a thin coating on the metallic scatterer.

Similar equations can be derived for \( H_z \) polarisation. In this case, the expression for the scattered field looks like

\[ H_z^{\text{inc}}(\rho) = \int_{S'} dS' \tilde{g}_d(\rho - \rho') \bar{H}_z(\rho') \]

\[ + \int_{S'} dV' \tilde{g}_d(\rho - \rho') \left[ k_0^2 \bar{E}_z(\rho') - k_L^2 \bar{E}_z(\rho') \right] \]

(35)

For this polarisation, the scattered field of a small dielectric cylinder is \( \psi(\rho) \cdot a_0 \) where \( a_0 \) contains the harmonics coefficient to represent a dipole scattered field. It is related to incident wave \( \phi^{\text{inc}} = \psi(\rho) \cdot a_0 \) by the isolated \( T \)-matrix [15–18] such that

\[ a = T_{E_x}(\rho) \cdot a_0 \]

(36)

Discretising the integral equation as before and using the idea of combined field integral equation, we can form the equations for coated-conductor cylinders as

\[ \sum_{i=1}^{N} G_{ij} a_i + \sum_{i=N+1}^{N} P_j(\rho) \psi(\rho) a_i = b_j \quad j = 1, 2, \ldots, N \]

(37a)

\[ a_j = T_{E_x}(\rho) \left\{ \tilde{g}_x(\rho) a_0 + \sum_{i=1}^{N} \tilde{g}_x(\rho) a_i \right\} \]

\[ + \sum_{i=N+1}^{N} \tilde{g}_x(\rho) a_i \]

(37b)

where \( \rho_i \) is the polariation vector \( \rho_i = [\text{kn}/2, 0, \text{kn}']/2 \).

5 Numerical results

To verify the algorithm, the RCS of a conducting circular cylinder is calculated for different radius \( R \) and compared with exact solutions (closed form solution).

Fig. 2A shows the RCS of an \( E_x \)-polarised wave at 0° incidence of a circular cylinder with radius \( R = 1.9658\lambda_0 \)

![Fig. 2A](image)

**RCS of an \( E_x \)-polarised wave at 0° incidence of a circular conducting cylinder with radius \( R = 1.9658\lambda_0 \)**

where internal resonance occurs
EFIE is used with this method, the error is quite large even after 83 iterations. A similar result is obtained for the $R = 2.0714\lambda_0$ case.

![Comparison of current distributions](image)

**Fig. 2B** Comparison of the current distributions for the case in Fig. 2A using this method with the combined field integral equation (CFIE), electric field integral equation (EFIE) and exact solution

Fig. 3 shows the RCS for $R = 50\lambda_0$. In this Figure, because of the fast oscillation, only a small portion in the forward direction is plotted. It is seen that the agreement with the closed-form solution is excellent both for scattered field and induced current distribution.

![RCS for a circular conducting cylinder](image)

**Fig. 3** RCS for a circular conducting cylinder with $R = 50\lambda_0$

In Fig. 4, the increase of CPU time with unknowns $N$ is plotted on a log-log scale. We find that the slope of the curve is approximately 1.5, showing the relationship CPU time $\propto N^{1.5}$.

Fig. 5A shows the RCS for a dielectric-coated circular conducting cylinder for $E_x$-polarised incident waves. Fig. 5B similarly shows that for $H_y$-polarised incident waves. The radius of the circular cylinder is $2\lambda_0$, and the thickness of the coating is 0.047$\lambda_0$. With $\varepsilon_r = 2 + j0.2$ and $\mu_r = 1.4 + j0.672$. The frequency is 300 MHz. From the Figure we can see that, even for lossy material coating, the computed result and the closed-form solution agree well.

Fig. 6 shows the RCS for a dielectric-coated ogive calculated using this method and RATMA (recursive aggreg-
coating is 0.049λ₀. The incident wave is at 90°, normal to the long axis of the ogive. The dielectric coating has εᵣ = 2 + i0.2 and μᵣ = 1.

6 Conclusion

A fast algorithm is developed for the scattering calculation of conducting cylinders for both Hₑ and Eₑ polarisation. Internal resonance problem is removed by using a combined field integral equation. We also extend the algorithm for dielectric-coated conducting cylinders using a hybrid of a combined field integral equation and a volume integral equation. Provided that the coating is thin (typically less that 0.1 wavelength), the fast multipole method is used to accelerate the speed of the solution. The computed result for a different size cylinder is in good agreement with the exact series solution. The speed of the algorithm is much faster than both the N³ and N⁴ algorithm. Hence, it can be applied to much larger objects.

7 References