

ECE 604, Lecture 6

September 6, 2018

1 Introduction

In this lecture, we will cover the following topics:

- Lorentz Force Law
- Biot-Savart Law
- Ampere's Law
- Gauss's Law for Magnetic Field
- Magnetic Vector Potential
- Vector Poisson's Equation
- Derivation of Biot-Savart Law from Ampere's Law and Gauss's Law

Additional Reading:

- Sections 2.2, 2.3, 2.4, 2.6–2.9, 2.11–2.12, Ramo et al.

2 Lorentz Force Law

The Lorentz force law is given by

$$\mathbf{F} = q\mathbf{E} + q\mathbf{v} \times \mathbf{B} \quad (2.1)$$

The first term is electric force from Coulomb's law while the second term is the magnetic force also called the $\mathbf{v} \times \mathbf{B}$ force. The magnetic force can also be written for an incremented current flowing in the wire of length $d\mathbf{l}$, or

$$d\mathbf{F} = I d\mathbf{l} \times \mathbf{B} \quad (2.2)$$

3 Biot-Savart Law

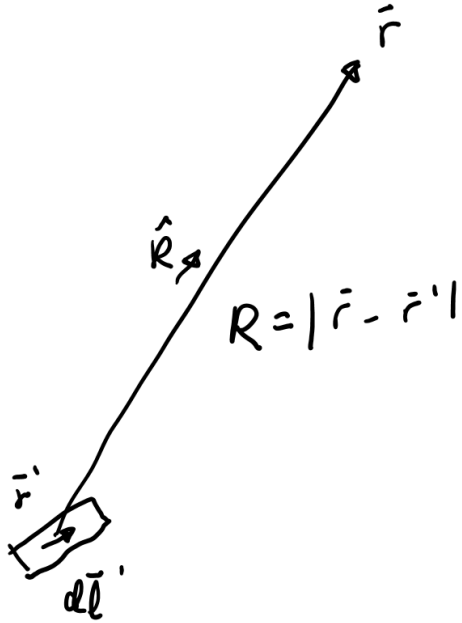


Figure 1:

Biot-Savart law states that the incremental magnetic field due to an incremental current, as shown in Figure 1, is

$$d\mathbf{H} = \frac{I d\mathbf{l} \times \mathbf{R}}{4\pi R^2} \quad (3.1)$$

where

$$R = |\mathbf{r} - \mathbf{r}'| \quad (3.2)$$

This law was first experimentally derived. But we will give a mathematical derivation of it later.

4 Ampere's Law

Ampere's law in integral form says that

$$\oint_C \mathbf{H} \cdot d\mathbf{l} = I \quad (4.1)$$

Using Stoke's theorem, one rewrites the left-hand side of the above as

$$\oint_C \mathbf{H} \cdot d\mathbf{l} = \iint_S (\nabla \times \mathbf{H}) \cdot d\mathbf{S} \quad (4.2)$$

But the right-hand side of the (4.1) can be written as

$$I = \iint_S \mathbf{J} \cdot d\mathbf{S} \quad (4.3)$$

Therefore

$$\iint_S (\nabla \times \mathbf{H}) \cdot d\mathbf{S} = \iint_S \mathbf{J} \cdot d\mathbf{S} \quad (4.4)$$

When $S \rightarrow 0$, the above implies that

$$\nabla \times \mathbf{H} = \mathbf{J} \quad (4.5)$$

5 Gauss's Law—Magnetic

Gauss's law for magnetic field says that

$$\oiint_S \mathbf{B} \cdot d\mathbf{S} = 0 \quad (5.1)$$

But from Gauss's divergence theorem,

$$\oiint_S \mathbf{B} \cdot d\mathbf{S} = \iiint_V \nabla \cdot \mathbf{B} dV \quad (5.2)$$

Therefore

$$\iiint_V \nabla \cdot \mathbf{B} dV = 0 \quad (5.3)$$

When $V \rightarrow 0$, we have

$$\nabla \cdot \mathbf{B} = 0$$

which is the partial differential equation for Gauss' law.

6 Constitutive Relation

The constitutive relation between magnetic flux \mathbf{B} and magnetic field \mathbf{H} is given as

$$\mathbf{B} = \mu\mathbf{H}, \quad \mu = \text{permeability H/m} \quad (6.1)$$

In free space,

$$\mu = \mu_0 = 4\pi \times 10^{-7} \text{ H/m} \quad (6.2)$$

In other materials, the permeability can be written as

$$\mu = \mu_0\mu_r \quad (6.3)$$

Similarly, the permittivity for electric field can be written as

$$\varepsilon = \varepsilon_0\varepsilon_r \quad (6.4)$$

7 Magnetic Vector Potential \mathbf{A}

Since from Gauss's law

$$\nabla \cdot \mathbf{B} = 0 \quad (7.1)$$

we can let

$$\mathbf{B} = \nabla \times \mathbf{A} \quad (7.2)$$

because

$$\nabla \cdot \nabla \times \mathbf{A} = 0 \quad (7.3)$$

This is similar to

$$\nabla \times \nabla \Phi = 0 \quad (7.4)$$

In this manner, Gauss's law is automatically satisfied.

8 Derivation of the Vector Poisson's Equation

From

$$\nabla \times \mathbf{H} = \mathbf{J} \quad (8.1)$$

we have

$$\nabla \times \left(\frac{\mathbf{B}}{\mu} \right) = \mathbf{J} \quad (8.2)$$

Then using (7.2)

$$\nabla \times \left(\frac{1}{\mu} \nabla \times \mathbf{A} \right) = \mathbf{J} \quad (8.3)$$

In a homogeneous medium, μ is a constant and hence

$$\nabla \times (\nabla \times \mathbf{A}) = \mu \mathbf{A} \quad (8.4)$$

We use the vector identity that (see handout on Some Useful Formulas)

$$\begin{aligned} \nabla \times (\nabla \times \mathbf{A}) &= \nabla(\nabla \cdot \mathbf{A}) - (\nabla \cdot \nabla)\mathbf{A} \\ &= \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} \end{aligned} \quad (8.5)$$

As a result, we arrive at

$$\nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = \mu \mathbf{J} \quad (8.6)$$

However, \mathbf{A} in (7.2) is not unique because one can always define

$$\mathbf{A}' = \mathbf{A} - \nabla\Psi \quad (8.7)$$

Then

$$\nabla \times \mathbf{A}' = \nabla \times (\mathbf{A} - \nabla\Psi) = \nabla \times \mathbf{A} = \mathbf{B} \quad (8.8)$$

where we have made use of that $\nabla \times \nabla\Psi = 0$. Hence, the $\nabla \times$ of both \mathbf{A} and \mathbf{A}' produce the same \mathbf{B} .

To find \mathbf{A} properly, we have to define or set the divergence of \mathbf{A} or provide a gauge condition. One way is to set the divergence of \mathbf{A} is to let

$$\nabla \cdot \mathbf{A} = 0 \quad (8.9)$$

This gauge condition is also known as Coulomb's gauge. Then

$$\nabla \cdot \mathbf{A}' = \nabla \cdot \mathbf{A} - \nabla^2\Psi \neq \nabla \cdot \mathbf{A} \quad (8.10)$$

The last non-equal sign follows if $\nabla^2\Psi \neq 0$. If we stipulate that $\nabla \cdot \mathbf{A}' = \nabla \cdot \mathbf{A} = 0$, then $-\nabla^2\Psi = 0$. This does not necessary imply that $\Psi = 0$, but if we impose that condition that $\Psi \rightarrow 0$ when $\mathbf{r} \rightarrow \infty$, then $\Psi = 0$ everywhere. By so doing, \mathbf{A} and \mathbf{A}' are equal to each other, and we obtain

$$\nabla^2\mathbf{A} = -\mu\mathbf{J} \quad (8.11)$$

In cartesian coordinates, the above can be viewed as three scalar Poisson's equations. Each of the Poisson's equation can be solved using the Green's function method. Consequently, in free space

$$\mathbf{A}(\mathbf{r}) = \frac{\mu}{4\pi} \iiint_V \frac{\mathbf{J}(\mathbf{r}')}{R} dV' \quad (8.12)$$

where

$$R = |\mathbf{r} - \mathbf{r}'| \quad (8.13)$$

9 Derivation of Biot-Savart Law

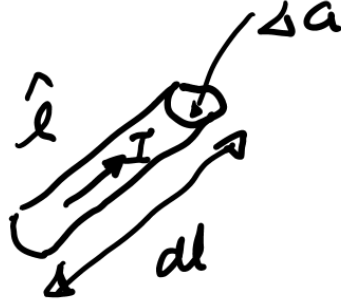


Figure 2:

From Gauss' law and Ampere's law, we have derived that

$$\mathbf{A}(\mathbf{r}) = \frac{\mu}{4\pi} \iiint_V \frac{\mathbf{J}(\mathbf{r}')}{R} dV' \quad (9.1)$$

When the current element is small, and is carried by a wire of cross sectional area Δa as shown in Figure 2, we can approximate the integrand as

$$\mathbf{J}(\mathbf{r}')dV' \approx \mathbf{J}(\mathbf{r}')\Delta V' = \underbrace{(\Delta a)\Delta l}_{\Delta V} \underbrace{\hat{l}I/\Delta a}_{\mathbf{J}(\mathbf{r}')} \quad (9.2)$$

In the above, $\Delta V = (\Delta a)\Delta l$ and $\hat{l}I/\Delta a = \mathbf{J}(\mathbf{r}')$. Here, \hat{l} is a unit vector pointing in the direction of the current flow. Hence, we can let

$$\mathbf{J}(\mathbf{r}')dV' \approx I\Delta \mathbf{l} \quad (9.3)$$

where $\Delta \mathbf{l} = \Delta l \hat{l}$. Therefore, the incremental vector potential due to an incremental current is

$$d\mathbf{A}(\mathbf{r}) \approx \frac{\mu}{4\pi} \left(\frac{\mathbf{J}(\mathbf{r}')\Delta V'}{R} \right) = \frac{\mu}{4\pi} \frac{I\Delta \mathbf{l}'}{R} \quad (9.4)$$

Since $\mathbf{B} = \nabla \times \mathbf{A}$, we have

$$d\mathbf{B} = \nabla \times d\mathbf{A}(\mathbf{r}) \cong \frac{\mu I}{4\pi} \nabla \times \frac{\Delta \mathbf{l}'}{R} = \frac{-\mu I}{4\pi} \Delta \mathbf{l}' \times \nabla \frac{1}{R} \quad (9.5)$$

where we have made use of the fact that $\nabla \times \mathbf{a}f(\mathbf{r}) = -\mathbf{a} \times \nabla f(\mathbf{r})$ when \mathbf{a} is a constant vector (see one of the HW problems). The above can be simplified further by making use of the fact that

$$\nabla \frac{1}{R} = -\frac{1}{R^2} \hat{R} \quad (9.6)$$

where \hat{R} is a unit vector pointing in the $\mathbf{r}-\mathbf{r}'$ direction. We have also made use of the fact that $R = \sqrt{(x-x')^2 + (y-y')^2 + (z-z')^2}$. Consequently, assuming that the incremental length becomes very small, or $\Delta \mathbf{l} \rightarrow \mathbf{dl}$, we have, after using (9.6) in (9.5), that

$$\mathbf{dB} = \frac{\mu I}{4\pi} \mathbf{dl}' \times \frac{1}{R^2} \hat{R} \quad (9.7)$$

$$= \frac{\mu I \mathbf{dl}' \times \hat{R}}{4\pi R^2} \quad (9.8)$$

Since $\mathbf{B} = \mu \mathbf{H}$, we have

$$\mathbf{dH} = \frac{I \mathbf{dl}' \times \hat{R}}{4\pi R^2} \quad (9.9)$$

or

$$\mathbf{H}(\mathbf{r}) = \int \frac{I(\mathbf{r}') \mathbf{dl}' \times \hat{R}}{4\pi R^2} \quad (9.10)$$

which is Biot-Savart Law