

- Constitutive Relations
- Energy and Power

Interested Readers:

- Textbook chapter 13, Balanis's book 1.3
- Textbook 3.12, Balanis 1.6

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Constitutive Relations

Relations between $\vec{D}$, $\vec{B}$ and $\vec{E}$, $\vec{H}$

1. Free space (vacuum)

$$\vec{D} = \epsilon_0 \vec{E}$$

$$\vec{B} = \mu_0 \vec{H}$$

permittivity: $\epsilon_0 = \frac{1}{36\pi} \times 10^{-9} \text{ F/m}$
 $= 8.85 \times 10^{-12} \text{ F/m}$

permeability: $\mu_0 = 4\pi \times 10^{-7} \text{ H/m}$

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}} = 3 \times 10^8 \text{ m/s}$$

↑
speed of light in vacuum

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2. Material

$$\vec{D} = \epsilon \vec{E}$$

$$\epsilon_r = \frac{\epsilon}{\epsilon_0} \quad \text{relative permittivity} \\ \text{or. dielectric constant}$$

$$\vec{B} = \mu \vec{H}$$

$$\mu_r = \frac{\mu}{\mu_0} \quad \text{relative permeability}$$

3. Conductors

electric conduction current

$$\vec{J}_c = \sigma \vec{E}$$

σ : conductivity (s/m)

4. Classification of materials

(a) According to space variables:

Homogeneous media

Inhomogeneous media

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(b) According to time variable:

Stationary media

Nonstationary media

(c) According to the value of ϵ :

Perfect dielectric ($\epsilon = 0$)

Perfect conductor ($\epsilon \rightarrow \infty$)

(d) According to the direction of $\vec{D}$ and $\vec{B}$

* If $\vec{D} \parallel \vec{E}$, $\vec{B} \parallel \vec{H} \Rightarrow$ isotropic media

$$\vec{D} = \epsilon \vec{E}: D_x = \epsilon E_x, D_y = \epsilon E_y, D_z = \epsilon E_z$$

* If $\vec{D} \nparallel \vec{E}$, $\vec{B} \nparallel \vec{H} \Rightarrow$ anisotropic media

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$$D_x = \epsilon_{xx} E_x + \epsilon_{xy} E_y + \epsilon_{xz} E_z$$

$$D_y = \epsilon_{yx} E_x + \epsilon_{yy} E_y + \epsilon_{yz} E_z$$

$$D_z = \epsilon_{zx} E_x + \epsilon_{zy} E_y + \epsilon_{zz} E_z$$

$$\begin{bmatrix} D_x \\ D_y \\ D_z \end{bmatrix} = \begin{bmatrix} \epsilon_{xx} & \epsilon_{xy} & \epsilon_{xz} \\ \epsilon_{yx} & \epsilon_{yy} & \epsilon_{yz} \\ \epsilon_{zx} & \epsilon_{zy} & \epsilon_{zz} \end{bmatrix} \begin{bmatrix} E_x \\ E_y \\ E_z \end{bmatrix}$$

or $\vec{D} = \vec{\epsilon} \cdot \vec{E}$
 $\vec{B} = \vec{\mu} \cdot \vec{H}$ — tensors

For crystals, $\vec{\epsilon} = \begin{bmatrix} \epsilon_{xx} & 0 & 0 \\ 0 & \epsilon_{yy} & 0 \\ 0 & 0 & \epsilon_{zz} \end{bmatrix}$

If $\epsilon_{xx} \neq \epsilon_{yy} \neq \epsilon_{zz}$: biaxial crystal

If two of them are equal: uniaxial crystal

Isotropic media: ϵ, μ are scalars

Anisotropic media: $\vec{\epsilon}, \vec{\mu}$ are tensors

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* Bianisotropic media:

$$\vec{D} = \vec{\epsilon} \cdot \vec{E} + \vec{\zeta} \cdot \vec{H}$$

$$\vec{B} = \vec{\mu} \cdot \vec{H} + \vec{\xi} \cdot \vec{E}$$

(e) According to the form of ϵ , μ , γ

Linear media

Nonlinear media:

$$\epsilon = \epsilon(\vec{E}, \vec{H})$$

$$\mu = \mu(\vec{E}, \vec{H})$$

$$\gamma = \gamma(\vec{E}, \vec{H})$$

(f) According to the relation of ϵ and μ with frequency:

Dispersive media

Nondispersive media

Energy and Power

Consider a medium with ϵ, μ, τ .

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} - \vec{M}_i = -\mu \frac{\partial \vec{H}}{\partial t} - \vec{M}_i \quad (1)$$

$$\nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t} + \vec{J} = \epsilon \frac{\partial \vec{E}}{\partial t} + \vec{J}_i + \nabla \vec{E} \quad (2)$$

$$\vec{H} \cdot (1) \Rightarrow \vec{H} \cdot (\nabla \times \vec{E}) = -\mu \vec{H} \cdot \frac{\partial \vec{H}}{\partial t} - \vec{H} \cdot \vec{M}_i$$

$$\vec{E} \cdot (2) \Rightarrow \vec{E} \cdot (\nabla \times \vec{H}) = \epsilon \vec{E} \cdot \frac{\partial \vec{E}}{\partial t} + \vec{E} \cdot \vec{J}_i + \nabla \vec{E} \cdot \vec{E}$$

$$\begin{aligned} \vec{H} \cdot (\nabla \times \vec{E}) - \vec{E} \cdot (\nabla \times \vec{H}) &= -\mu \vec{H} \cdot \frac{\partial \vec{H}}{\partial t} - \vec{H} \cdot \vec{M}_i \\ &\quad - \epsilon \vec{E} \cdot \frac{\partial \vec{E}}{\partial t} - \vec{E} \cdot \vec{J}_i - \nabla \vec{E} \cdot \vec{E} \end{aligned}$$

Vector identity:

$$\boxed{\nabla \cdot (\vec{E} \times \vec{H}) = \vec{H} \cdot (\nabla \times \vec{E}) - \vec{E} \cdot (\nabla \times \vec{H})}$$

$$\begin{aligned} \therefore \nabla \cdot (\vec{E} \times \vec{H}) &= -\left(\mu \vec{H} \cdot \frac{\partial \vec{H}}{\partial t} + \epsilon \vec{E} \cdot \frac{\partial \vec{E}}{\partial t} + \nabla \vec{E} \cdot \vec{E} \right. \\ &\quad \left. + \vec{H} \cdot \vec{M}_i + \vec{E} \cdot \vec{J}_i \right) \end{aligned}$$

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$$\oint_S (\vec{E} \times \vec{H}) \cdot d\vec{s} + \iiint_V \left(\mu \vec{H} \cdot \frac{\partial \vec{H}}{\partial t} + \epsilon \vec{E} \cdot \frac{\partial \vec{E}}{\partial t} + \vec{E} \cdot \vec{J} + \vec{H} \cdot \vec{M} + \vec{E} \cdot \vec{J}_i \right) dV = 0$$

* $\vec{E} \times \vec{H}$: $V/m \cdot A/m = W/m^2$ Poynting's vector

$P_e = \oint_S (\vec{E} \times \vec{H}) \cdot d\vec{s}$ — power leaving V bounded by S

* $\mu \vec{H} \cdot \frac{\partial \vec{H}}{\partial t} = \frac{1}{2} \mu \frac{\partial H^2}{\partial t} = \frac{\partial}{\partial t} \left(\frac{1}{2} \mu H^2 \right) = \frac{\partial W_m}{\partial t}$

$W_m = \frac{1}{2} \mu H^2$: $\frac{H}{m} \left(\frac{A}{m} \right)^2 = \frac{\text{Joule}}{m^3}$ — energy density

$W_m = \iiint_V w_m dV$ magnetic energy

* $\epsilon \vec{E} \cdot \frac{\partial \vec{E}}{\partial t} = \frac{1}{2} \epsilon \frac{\partial E^2}{\partial t} = \frac{\partial}{\partial t} \left(\frac{1}{2} \epsilon E^2 \right) = \frac{\partial W_e}{\partial t}$

$W_e = \frac{1}{2} \epsilon E^2$, $\frac{F}{m} \left(\frac{V}{m} \right)^2 = \frac{\text{Joule}}{m^3}$ — energy density

$W_e = \iiint_V w_e dV$ electric energy

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$$* \quad \nabla \vec{E} \cdot \vec{E} = \nabla E^2 \quad \frac{S}{m} \left(\frac{V}{m} \right)^2 = \frac{W}{m^3}$$

$$P_d = \iiint_V \nabla \vec{E} \cdot \vec{E} dV \quad - \text{power dissipated}$$

$$* \quad P_s = - \iiint_V (\vec{H} \cdot \vec{M}_i + \vec{E} \cdot \vec{J}_i) dV \quad - \text{power supplied}$$

Hence:

$$P_e + P_d - P_s + \frac{\partial}{\partial t} (W_m + W_e) = 0$$

or $\boxed{P_s = P_e + P_d + \frac{\partial}{\partial t} (W_m + W_e)}$ Poynting's theorem

Conservation of Power

Denote: $P_e = \nabla \cdot (\vec{E} \times \vec{H})$, $P_d = \nabla E^2$

$$P_s = - \vec{H} \cdot \vec{M}_i - \vec{E} \cdot \vec{J}_i$$

$$\boxed{P_s = P_e + P_d + \frac{\partial}{\partial t} (W_m + W_e)}$$