

A Petrov-Galerkin method for nonlocal convection-dominated diffusion problems



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ABSTRACT

We present a Petrov-Galerkin (PG) method for a class of nonlocal convection-dominated diffusion problems. There are two main ingredients in our approach. First, we define the norm on the test space as induced by the trial space norm, i.e., the optimal test norm, so that the inf-sup condition can be satisfied uniformly independent of the problem. We show the well-posedness of a class of nonlocal convection-dominated diffusion problems under the optimal test norm with general assumptions on the nonlocal diffusion and convection kernels. Second, following the framework of Cohen et al. (2012), we embed the original nonlocal convection-dominated diffusion problem into a larger mixed problem so as to choose an enriched test space as a stabilization of the numerical algorithm. In the numerical experiments, we use an approximate optimal test norm which can be efficiently implemented in 1d, and study its performance against the energy norm on the test space. We conduct convergence studies for the nonlocal problem using uniform h - and p -refinements, and adaptive h -refinements on both smooth manufactured solutions and solutions with sharp gradient in a transition layer. In addition, we confirm that the PG method is asymptotically compatible, following the notion in Tian and Du (2014).

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1. Introduction

In this work, we are motivated to study the numerical solution of the nonlocal convection-dominated diffusion model. Nonlocal models, usually formulated to involve integral operators, have been an area of growing research in recent decades as a result of their wide applications to many real-world phenomena [2,8,9,43,44,55]. In particular, the peridynamics model [55], a nonlocal theory of continuum mechanics, has been used in many engineering applications such as hydraulic fracturing [51], erosion [12], fatigue [64], fragmentation [38] and many others. We consider convection-diffusion equations modeled through nonlocal diffusion and nonlocal gradient operators, following the nonlocal vector calculus framework [27] and its application to the volume-constrained nonlocal diffusion models [26]. Such models share the same spirit with the peridynamics models in the sense that the nonlocal interactions are restricted to a finite range. In comparison, nonlocal

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models characterized by fractional Laplacians have infinite nonlocal interactions [53]. Mathematical analysis and numerical methods have been developed for nonlocal diffusion models [1,26,30,41,59], linear and nonlinear nonlocal advection [28,31,39], nonlocal convection-diffusion models [15,29,57,58], nonlocal Stokes equations [33], and peridynamics models [3,42,47,52,54,56,62,63]. We refer the readers to the monograph [25] and the survey work [14] for a more detailed discussion on nonlocal models.

The time-dependent linear nonlocal convection-diffusion models with volumetric constraints are studied in [29], in which the nonlocal models are connected with Markov jump processes. Later, the steady nonlocal convection-diffusion models are studied and analyzed in [15,57,58]. An important feature for these models is that the nonlocal convection-diffusion model converges to the classical convection-diffusion model as the nonlocal interaction vanishes. The nonlocal convection terms used in these works are slightly different, with which physical properties such as the maximum principle and mass conservation may or may not be preserved. The well-posedness of the weak form of the nonlocal convection-diffusion problem in all these works, however, is essentially based on the assumption of coercivity of the bilinear form. This assumption limits the model to the diffusion-dominated regime.

It is well-known for the classical convection-diffusion problem that, as the convection becomes dominant over the diffusion, the solution of the standard Galerkin method or central finite difference method deteriorates and unphysical oscillations emerge in the solution. Stabilizing numerical techniques, such as the streamline upwind/Petrov-Galerkin method [7], least-squares technique [37], exponential fitting method [5], edge stabilization [10], and various Petrov-Galerkin (PG) methods [6,13,23] are developed to solve the classical convection-dominated diffusion problem. For nonlocal convection-dominated diffusion models, it was also shown in [57] that the standard Galerkin method leads to significant instabilities, upwind nonlocal models with specially designed nonlocal convective kernels are therefore adopted in [57,58] and are numerically verified to be stable.

Discontinuous Petrov-Galerkin (DPG) method has been developed in a series of work [18,19,22,20,21,65]. The highlights of the DPG methodology include the use of ultraweak variational formulation and the computation of the discontinuous optimal test functions on the fly. Superior stability properties are demonstrated and an overview of the DPG method can be found in [23]. The use of discontinuous functions allows one to solve for optimal test functions on a local element level. This, however, cannot be immediately translated to the nonlocal problem. We therefore adopt the continuous PG method under the framework developed in [13]. The key is to embed the original variational problem into a larger mixed problem which stabilizes the numerical method using enriched test spaces.

There are two major contributions of this work. The first contribution is that we show the well-posedness result of the nonlocal convection-diffusion model where the convection could be dominant. Such result is achieved by choosing the norm on the test space in an optimal way such that the inf-sup condition or the Ladyzhenskaya–Babuška–Brezzi condition for well-posedness of the variational problem is satisfied. However, the optimal test space norm is not practical in computation, the second contribution is that we present an approximation of the optimal test norm in one dimension and conduct numerical experiments to demonstrate the effectiveness of the PG method for the convection-dominated diffusion model.

This paper is organized as follows. We briefly introduce the PG approach used in this work in section 2. The optimal test space norms and the well-posedness theorem for the nonlocal convection-diffusion model are presented in section 3. Section 4 shows the convergence results and the superiority of the PG method using numerical examples. Finally, we conclude this paper in section 5.

2. The Petrov-Galerkin method

In this section, we briefly introduce the ingredients of our PG method following the expositions in [13,17,19]. Let us consider the abstract variational problem,

$$\begin{cases} \text{Find } u \in U, \text{ such that:} \\ b(u, v) = l(v), \quad \forall v \in V, \end{cases} \tag{1}$$

where U (the “trial” space) and V (the “test” space) are Hilbert spaces with norm, $\|\cdot\|_U$ and $\|\cdot\|_V$ respectively, $l(\cdot)$ is a given real-valued continuous linear functional on V , and $b(\cdot, \cdot)$ is a continuous bilinear form defined on $U \times V$ that satisfies the inf-sup condition

$$\inf_{u \in U} \sup_{v \in V} \frac{|b(u, v)|}{\|u\|_U \|v\|_V} \geq \alpha > 0 \iff \sup_{v \in V} \frac{|b(u, v)|}{\|v\|_V} \geq \alpha \|u\|_U, \quad \forall u \in U. \tag{2}$$

We also assume that the bilinear form $b(\cdot, \cdot)$ is definite, i.e.,

$$\text{if } b(u, v) = 0, \quad \forall u \in U, \text{ then } v = 0. \tag{3}$$

Equation (1) is well-posed by the Banach-Nečas-Babuška theorem (see e.g. [34,50]). It is worth mentioning that the inf-sup constant α is 1 if U and V form a duality pairing. Namely if we define $\|\cdot\|_V$ as the norm induced by $\|\cdot\|_U$, we can recover $\|\cdot\|_U$ by the norm induced by $\|\cdot\|_V$, i.e.,

$$\|v\|_V := \sup_{u \in U} \frac{|b(u, v)|}{\|u\|_U} \implies \|u\|_U = \sup_{v \in V} \frac{|b(u, v)|}{\|v\|_V}.$$

For this reason and following the nomenclature in [17], we will call the norm on V induced by $\|\cdot\|_U$ the *optimal test norm*, denoted by

$$\|v\|_{\text{opt}, V} := \sup_{u \in U} \frac{|b(u, v)|}{\|u\|_U}, \quad \forall u_h \in U_h. \tag{4}$$

In this paper, we will explore the effectiveness of our Petrov-Galerkin method with $\|\cdot\|_V$ defined in different ways.

In computation, PG methods in general take finite-dimensional trial and test spaces $U_h \subset U$ and $V_h \subset V$ with $\dim U_h = \dim V_h$ and solve the approximate problem

$$\begin{cases} \text{Find } u_h \in U_h, \text{ such that:} \\ b(u_h, v_h) = l(v_h), \quad \forall v_h \in V_h. \end{cases} \tag{5}$$

Equation (5) is well-posed only if the discrete inf-sup condition

$$\inf_{u_h \in U_h} \sup_{v_h \in V_h} \frac{|b(u_h, v_h)|}{\|u_h\|_{U_h} \|v_h\|_{V_h}} \geq \beta > 0 \iff \sup_{v_h \in V_h} \frac{|b(u_h, v_h)|}{\|v_h\|_{V_h}} \geq \beta \|u_h\|_{U_h} \tag{6}$$

is satisfied for some $\beta > 0$. In practice, it is notoriously hard to find stable and robust discretizations in the form of (5) for accurate simulations of the convection-dominated problems. An *ideal PG method* by choosing V_h with optimal test functions that automatically guarantees the numerical stability, is presented in [19]. This is done by letting $V_h = T(U_h)$ where $T : U \rightarrow V$ is the trial-to-test operator defined by

$$(Tu, v)_V = b(u, v), \quad \forall v \in V,$$

where $(\cdot, \cdot)_V$ denotes the inner product on the test space V . It is also shown in [19] that the ideal PG method generates numerical solutions that are orthogonal projections of the exact solution in the norm induced by the test norm (the same as the trial norm if U and V form a duality pairing). However, the implementation of the ideal PG method in general is difficult. Therefore, we follow a different strategy suggested by [13] and solve the discrete mixed problem

$$\begin{cases} \text{Find } \psi_h \in V_h, u_h \in U_h, \text{ such that:} \\ (\psi_h, v_h)_V + b(u_h, v_h) = l(v_h), \quad \forall v_h \in V_h, \\ b(w_h, \psi_h) = 0, \quad \forall w_h \in U_h. \end{cases} \tag{7}$$

Equation (7) allows us to choose test spaces of much larger dimension, i.e., $\dim V_h \gg \dim U_h$, such that the discrete inf-sup condition (6) is much easier to satisfy. This is critical for the numerical stability of the convection-dominated problems, which are the major interest of this work. In addition, ψ_h serves as a natural a-posteriori error indicator for the adaptive h -refinements in the trial space. We remark that if the test space is not approximated, i.e., $V_h = V$ in (7), (7) is equivalent to the ideal PG method presented by [19].

3. Application to the nonlocal convection-dominated diffusion

In this section, we introduce the nonlocal convection-diffusion model. We derive the optimal test space norm, and show the well-posedness of the model problem utilizing the optimal test space norm. In the existing literature, the well-posedness of the weak form nonlocal convection-diffusion equation is always based on the assumption of coercivity [15,58]. This means that the results in the existing literature only apply to the diffusion-dominated regime. We establish in this section the well-posedness of the convection-dominated problem, and this is done by the PG approach presented in the previous section.

3.1. Model equations

Following [14,26], we define the *nonlocal diffusion operator* with the nonlocal length scale parameter $\delta > 0$ in dimension $d \in \mathbb{Z}^+$ by

$$\mathcal{L}_\delta u(\mathbf{x}) = 2 \int_{B_\delta(\mathbf{x})} \gamma_\delta^{\text{diff}}(|\mathbf{y} - \mathbf{x}|) (u(\mathbf{y}) - u(\mathbf{x})) d\mathbf{x}, \tag{8}$$

where $B_\delta(\mathbf{x}) \subset \mathbb{R}^d$ denotes the Euclidean ball of radius δ centered at a point $\mathbf{x} \in \mathbb{R}^d$, and $\gamma_\delta^{\text{diff}}(|\mathbf{s}|)$ is the nonlocal diffusion kernel supported on $\overline{B_\delta(\mathbf{0})}$ with the following scaling

$$\gamma_\delta^{\text{diff}}(|\mathbf{s}|) = \frac{1}{\delta^{d+2}} \gamma^{\text{diff}}\left(\frac{|\mathbf{s}|}{\delta}\right). \tag{9}$$

We assume in this work that $\gamma^{\text{diff}}(r)$ is a non-negative and non-increasing function defined on $[0, 1]$, and $\gamma^{\text{diff}}(|\mathbf{s}|)$ has a bounded second order moment, i.e.,

$$\int_{B_1(\mathbf{0})} \gamma^{\text{diff}}(|\mathbf{s}|) |\mathbf{s}|^2 d\mathbf{s} = d. \tag{10}$$

We introduce the *nonlocal gradient operator* \mathcal{G}_δ following by

$$\mathcal{G}_\delta u(\mathbf{x}) = \int_{\mathcal{H}_\delta(\mathbf{x})} \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_\delta^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) (u(\mathbf{y}) - u(\mathbf{x})) d\mathbf{y}, \tag{11}$$

where $\mathcal{H}_\delta(\mathbf{x}) \subset B_\delta(\mathbf{x})$ is an influence region surrounding \mathbf{x} , and $\gamma_\delta^{\text{conv}}(|\mathbf{s}|)$ is the nonlocal convection kernel supported on $B_\delta(\mathbf{0})$ with the scaling

$$\gamma_\delta^{\text{conv}}(|\mathbf{s}|) = \frac{1}{\delta^{d+1}} \gamma^{\text{conv}}\left(\frac{|\mathbf{s}|}{\delta}\right). \tag{12}$$

We assume that $\mathcal{H}_\delta(\mathbf{x})$ is a sector of the ball $B_\delta(\mathbf{x})$ and

$$\frac{|\mathcal{H}_\delta(\mathbf{x})|}{|B_\delta(\mathbf{x})|} = \eta, \quad \forall \mathbf{x} \in \mathbb{R}^d, \tag{13}$$

where $\eta > 0$ is independent of \mathbf{x} , and $|\mathcal{H}_\delta(\mathbf{x})|$ and $|B_\delta(\mathbf{x})|$ denote the volume of the sets $\mathcal{H}_\delta(\mathbf{x})$ and $B_\delta(\mathbf{x})$ respectively. The most common choices of $\mathcal{H}_\delta(\mathbf{x})$ are either the full ball $B_\delta(\mathbf{x})$ ($\eta = 1$) [15,32,33,48] or a hemispherical subregion of $B_\delta(\mathbf{x})$ ($\eta = 1/2$) [40,57,58]. More detailed discussions on the choices of $\mathcal{H}_\delta(\mathbf{x})$ will be given in Section 3.3. Now with eq. (13), we assume that $\gamma^{\text{conv}}(r)$ is a non-negative function on $[0, 1]$, and that $\gamma^{\text{conv}}(|\mathbf{s}|)$ satisfies

$$\int_{B_1(\mathbf{0})} \gamma^{\text{conv}}(|\mathbf{s}|) |\mathbf{s}| d\mathbf{s} = d/\eta. \tag{14}$$

As a result, eq. (11) is a nonlocal analogue of the classical gradient operator ∇u . In this work, for reasons that will be explained later, we also assume the following relation between the diffusion kernel and the convection kernel:

$$\gamma^{\text{conv}}(|\mathbf{s}|) = \frac{|\mathbf{s}|}{\eta} \gamma^{\text{diff}}(|\mathbf{s}|). \tag{15}$$

It is worth noting that eq. (15) is compatible with eqs. (10) and (14). Namely, if eq. (15) is satisfied, we also have

$$\gamma_\delta^{\text{conv}}(|\mathbf{s}|) = \frac{1}{\delta^{d+1}} \gamma^{\text{conv}}\left(\frac{|\mathbf{s}|}{\delta}\right) = \frac{1}{\delta^{d+2}} \frac{|\mathbf{s}|}{\eta} \gamma^{\text{diff}}\left(\frac{|\mathbf{s}|}{\delta}\right) = \frac{|\mathbf{s}|}{\eta} \gamma_\delta^{\text{diff}}(|\mathbf{s}|).$$

For a vector field $\mathbf{b} \in L^\infty(\mathbb{R}^d; \mathbb{R}^d)$, the nonlocal convection-diffusion model problem, defined on an open bounded domain $\Omega \subset \mathbb{R}^d$, is formulated as

$$\begin{cases} -\epsilon \mathcal{L}_\delta u(\mathbf{x}) + \mathbf{b} \cdot \mathcal{G}_\delta u(\mathbf{x}) = f_\delta(\mathbf{x}), & \mathbf{x} \in \Omega, \\ u(\mathbf{x}) = 0, & \mathbf{x} \in \Omega_{\mathcal{I}_\delta}, \end{cases} \tag{16}$$

where ϵ is a positive parameter, and $\Omega_{\mathcal{I}_\delta}$ is the interaction domain given by

$$\Omega_{\mathcal{I}_\delta} := \{\mathbf{x} \in \mathbb{R}^d \setminus \Omega : \text{dist}(\mathbf{x}, \partial\Omega) < \delta\}. \tag{17}$$

We denote $\Omega_\delta := \Omega \cup \Omega_{\mathcal{I}_\delta}$ for the rest of the work. We are interested in the convection-dominated regime, namely, $0 < \epsilon \ll \|\mathbf{b}\|_{L^\infty(\Omega)}$. Then, eq. (16) is called a nonlocal convection-dominated diffusion model, and is a nonlocal analogue of the classical convection-diffusion problem

$$\begin{cases} -\epsilon \Delta u(\mathbf{x}) + \mathbf{b} \cdot \nabla u(\mathbf{x}) = f(\mathbf{x}), & \mathbf{x} \in \Omega, \\ u(\mathbf{x}) = 0, & \mathbf{x} \in \partial\Omega. \end{cases} \tag{18}$$

Remark 3.1. The nonlocal convection term can also be formulated in a different way analogous to the differential operator $\nabla \cdot (\mathbf{b}u)$ [15,57]. For this, we need to define the *nonlocal divergence operator* \mathcal{D}_δ acting on the function $\mathbf{b}u$ by

$$\mathcal{D}_\delta(\mathbf{b}u)(\mathbf{x}) = \int_{\mathbb{R}^d} (\mathbf{b}(\mathbf{x})u(\mathbf{x})1_{\mathcal{H}_\delta(\mathbf{x})}(\mathbf{y}) + \mathbf{b}(\mathbf{y})u(\mathbf{y})1_{\mathcal{H}_\delta(\mathbf{y})}(\mathbf{x})) \cdot \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_\delta^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y}. \tag{19}$$

The analysis in this work would be similar if we replace $\mathbf{b} \cdot \mathcal{G}_\delta u(\mathbf{x})$ with $\mathcal{D}_\delta(\mathbf{b}u)(\mathbf{x})$ in eq. (16) mainly because of the integration by parts formula (20).

One can show that by defining \mathcal{D}_δ in (19), $-\mathcal{D}_\delta$ forms an adjoint of \mathcal{G}_δ in the sense that

$$(\mathbf{b} \cdot \mathcal{G}_\delta u, v) = -(u, \mathcal{D}_\delta(\mathbf{b}v)), \tag{20}$$

where (\cdot, \cdot) denotes the inner product in $L^2(\Omega)$ and $u, v \in L^2(\Omega_\delta)$ with $u|_{\Omega_{\mathcal{T}_\delta}} = v|_{\Omega_{\mathcal{T}_\delta}} = 0$. Indeed, since $u|_{\Omega_{\mathcal{T}_\delta}} = v|_{\Omega_{\mathcal{T}_\delta}} = 0$, we have

$$\begin{aligned} (\mathbf{b} \cdot \mathcal{G}_\delta u, v) &= \int_{\Omega} \int_{\mathcal{H}_\delta(\mathbf{x})} \frac{\mathbf{b}(\mathbf{x}) \cdot (\mathbf{y} - \mathbf{x})}{|\mathbf{y} - \mathbf{x}|} \gamma_\delta^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) (u(\mathbf{y}) - u(\mathbf{x})) v(\mathbf{x}) d\mathbf{y} d\mathbf{x} \\ &= \int_{\Omega_\delta} \int_{\Omega_\delta} 1_{\mathcal{H}_\delta(\mathbf{x})}(\mathbf{y}) \frac{\mathbf{b}(\mathbf{x}) \cdot (\mathbf{y} - \mathbf{x})}{|\mathbf{y} - \mathbf{x}|} \gamma_\delta^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) (u(\mathbf{y}) - u(\mathbf{x})) v(\mathbf{x}) d\mathbf{y} d\mathbf{x} \\ &= - \int_{\Omega_\delta} \int_{\Omega_\delta} (1_{\mathcal{H}_\delta(\mathbf{x})}(\mathbf{y}) \mathbf{b}(\mathbf{x}) u(\mathbf{x}) v(\mathbf{x}) + 1_{\mathcal{H}_\delta(\mathbf{y})}(\mathbf{x}) \mathbf{b}(\mathbf{y}) u(\mathbf{x}) v(\mathbf{y})) \cdot \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_\delta^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y} d\mathbf{x} \\ &= - \int_{\Omega} u(\mathbf{x}) \int_{\Omega_\delta} (1_{\mathcal{H}_\delta(\mathbf{x})}(\mathbf{y}) \mathbf{b}(\mathbf{x}) v(\mathbf{x}) + 1_{\mathcal{H}_\delta(\mathbf{y})}(\mathbf{x}) \mathbf{b}(\mathbf{y}) v(\mathbf{y})) \cdot \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_\delta^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y} d\mathbf{x} \\ &= -(u, \mathcal{D}_\delta(\mathbf{b}v)). \end{aligned}$$

With a similar reasoning which we omit here, we can show that \mathcal{L}_δ is a self-adjoint operator, i.e.,

$$(\mathcal{L}_\delta u, v) = (u, \mathcal{L}_\delta v), \tag{21}$$

if $u, v \in L^2(\Omega_\delta)$ and $u|_{\Omega_{\mathcal{T}_\delta}} = v|_{\Omega_{\mathcal{T}_\delta}} = 0$.

3.2. Weak formulation

We present the weak formulation of eq. (16) in this subsection. We define the natural energy space $\mathcal{S}_\delta(\Omega)$ associated with eq. (16) by

$$\mathcal{S}_\delta(\Omega) = \{u \in L^2(\Omega_\delta) : \int_{\Omega_\delta} \int_{\Omega_\delta} \gamma_\delta^{\text{diff}}(|\mathbf{y} - \mathbf{x}|) (u(\mathbf{y}) - u(\mathbf{x}))^2 d\mathbf{y} d\mathbf{x} < \infty, u|_{\Omega_{\mathcal{T}_\delta}} = 0\}. \tag{22}$$

The semi-norm $|u|_{\mathcal{S}_\delta(\Omega)}$ on $\mathcal{S}_\delta(\Omega)$ is defined as

$$|u|_{\mathcal{S}_\delta(\Omega)} := \left(\int_{\Omega_\delta} \int_{\Omega_\delta} \gamma_\delta^{\text{diff}}(|\mathbf{y} - \mathbf{x}|) (u(\mathbf{y}) - u(\mathbf{x}))^2 d\mathbf{y} d\mathbf{x} \right)^{1/2}.$$

It is shown in [45,46] that $\mathcal{S}_\delta(\Omega)$ is a Hilbert space equipped with the inner product

$$a(u, v) := \int_{\Omega_\delta} \int_{\Omega_\delta} \gamma_\delta^{\text{diff}}(|\mathbf{y} - \mathbf{x}|) (u(\mathbf{y}) - u(\mathbf{x})) (v(\mathbf{y}) - v(\mathbf{x})) d\mathbf{y} d\mathbf{x}.$$

Because of the nonlocal Poincaré-type inequalities [26,45,46], the semi-norm $|u|_{\mathcal{S}_\delta(\Omega)}$ is also a norm on $\mathcal{S}_\delta(\Omega)$. For the rest of the paper, we will simply denote $\|\cdot\|_{\mathcal{S}_\delta(\Omega)} = |\cdot|_{\mathcal{S}_\delta(\Omega)}$ and call it the energy norm.

Now we can define the bilinear form, $b(\cdot, \cdot)$, associated with eq. (16) by

$$b(u, v) = \epsilon a(u, v) + (\mathbf{b} \cdot \mathcal{G}_\delta u, v), \quad \forall u, v \in \mathcal{S}_\delta(\Omega). \tag{23}$$

It is trivial to show that $a(u, v) = (-\mathcal{L}_\delta u, v)$ for $u, v \in \mathcal{S}_\delta(\Omega)$, see [60]. Then, eq. (16) can be recast into the weak form

$$\begin{cases} \text{Find } u \in U, \text{ such that :} \\ b(u, v) = (f_\delta, v), \quad \forall v \in V, \end{cases} \tag{24}$$

where U and V are both spaces of all the functions in $S_\delta(\Omega)$. In this work, we always assume that U is equipped with the energy norm on $S_\delta(\Omega)$, i.e., $\|\cdot\|_U = \|\cdot\|_{S_\delta(\Omega)}$. The test space V , however, can be endowed with different norms. In the next subsection, we will show V can be equipped with the optimal test norm in the sense of eq. (4).

3.3. Optimal test space norm

Before identifying the optimal test space norm, we need to make some assumptions on the velocity field $\mathbf{b}(\mathbf{x})$. We distinguish two cases. In the first case, we assume that the velocity field is a constant and the influence region $\mathcal{H}_\delta(\mathbf{x})$ that defines the integral in eq. (11) coincides with $B_\delta(\mathbf{x})$, see Assumption 3.2. In the second case, we allow the velocity field to be a variable with additional assumptions on $\mathbf{b}(\mathbf{x})$ and $\mathcal{H}_\delta(\mathbf{x})$, see Assumption 3.3.

Assumption 3.2. Assume the velocity field $\mathbf{b}(\mathbf{x})$ is a constant, i.e.,

$$\mathbf{b}(\mathbf{x}) \equiv \mathbf{b} \in \mathbb{R}^d,$$

and $\mathcal{H}_\delta(\mathbf{x}) = B_\delta(\mathbf{x})$.

Assumption 3.2 leads to the central nonlocal convection-diffusion model termed in [57] which refers to the fact that the nonlocal gradient operator (11) takes a full spherical influence region. It was shown in [57] that the standard Galerkin approach for such central model leads to significant instabilities. We will establish, however, that such model is indeed well-posed by the PG approach with optimal test norms.

Assumption 3.3. Assume the velocity field $\mathbf{b} \in L^\infty(\mathbb{R}^d; \mathbb{R}^d)$ with $-\mathcal{D}_\delta(\mathbf{b}) \geq 0$, where

$$\mathcal{D}_\delta(\mathbf{b})(\mathbf{x}) = \int_{\mathbb{R}^d} (\mathbf{b}(\mathbf{x})1_{\mathcal{H}_\delta(\mathbf{x})}(\mathbf{y}) + \mathbf{b}(\mathbf{y})1_{\mathcal{H}_\delta(\mathbf{y})}(\mathbf{x})) \cdot \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_\delta^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y}. \tag{25}$$

In addition, $\mathcal{H}_\delta(\mathbf{x})$ is the hemisphere defined by

$$\mathcal{H}_\delta(\mathbf{x}) = \{\mathbf{y} \in B_\delta(\mathbf{x}) : -\mathbf{b}(\mathbf{x}) \cdot (\mathbf{y} - \mathbf{x}) > 0\}. \tag{26}$$

Equation (26) corresponds to the upwind model in [57,58], which has a hemispherical influence region for nonlocal convection in the direction against the velocity field. The well-posedness of such model, however, is only shown under the assumption of coercivity in [58]. The coercivity assumption is essentially not true for the convection-dominated regime as $\epsilon \rightarrow 0$. Therefore, our well-posedness result, which will be presented shortly, provides a remedy for this through the framework of Banach-Nečas-Babuška theorem and optimal test norms.

Remark 3.4. In Assumption 3.3, if $\mathbf{b}(\mathbf{x})$ is a constant, then eq. (26) implies $\mathcal{D}_\delta(\mathbf{b}) = 0$. Thus, we only need to assume eq. (26). Indeed, if $\mathbf{b}(\mathbf{x}) \equiv \mathbf{b}$, then

$$\mathcal{D}_\delta(\mathbf{b})(\mathbf{x}) = \mathbf{b} \cdot \int_{\mathbb{R}^d} (1_{\mathcal{H}_\delta(\mathbf{x})}(\mathbf{y}) + 1_{\mathcal{H}_\delta(\mathbf{y})}(\mathbf{x})) \cdot \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_\delta^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y},$$

and $\mathcal{H}_\delta(\mathbf{x})$ and $\mathcal{H}_\delta(\mathbf{y})$ become

$$\mathcal{H}_\delta(\mathbf{x}) = \{\mathbf{z} \in B_\delta(\mathbf{x}) : -\mathbf{b} \cdot (\mathbf{z} - \mathbf{x}) > 0\}, \quad \mathcal{H}_\delta(\mathbf{y}) = \{\mathbf{z} \in B_\delta(\mathbf{y}) : -\mathbf{b} \cdot (\mathbf{z} - \mathbf{y}) > 0\}.$$

For any $\mathbf{x}, \mathbf{y} \in \mathbb{R}^d$ such that $|\mathbf{y} - \mathbf{x}| < \delta$, we have

$$1_{\mathcal{H}_\delta(\mathbf{y})}(\mathbf{x}) = \begin{cases} 1 & \text{if } -\mathbf{b} \cdot (\mathbf{x} - \mathbf{y}) > 0 \\ 0 & \text{if } -\mathbf{b} \cdot (\mathbf{y} - \mathbf{x}) > 0 \end{cases} = 1 - 1_{\mathcal{H}_\delta(\mathbf{x})}(\mathbf{y}).$$

Then,

$$\mathcal{D}_\delta(\mathbf{b})(\mathbf{x}) = \mathbf{b} \cdot \int_{B_\delta(\mathbf{x})} \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_\delta^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y} = 0,$$

where the last line is understood in the sense of principal value.

Remark 3.5. In [57,58], there are major concerns on the maximum principle for nonlocal convection-diffusion models. We remark here that we do not expect the maximum principle to hold for eq. (16) in general. More specifically, when we take $\mathbf{b}(\mathbf{x})$ and $\mathcal{H}_\delta(\mathbf{x})$ as in Assumption 3.2, the nonlocal gradient operator \mathcal{G}_δ has spherical nonlocal interaction neighborhoods, and the maximum principle does not hold. On the other hand, if $\mathbf{b}(\mathbf{x})$ and $\mathcal{H}_\delta(\mathbf{x})$ are defined by Assumption 3.3, one can show with similar arguments in [58, Theorem 1] that eq. (16) satisfies the maximum principle due to the hemispherical interaction neighborhoods as defined in eq. (26). Nevertheless, the proposed PG approach works for both cases since the variational method does not rely on the maximum principle.

Now recall that for problem (24), U and V are both spaces of all functions in $\mathcal{S}_\delta(\Omega)$ with the trial norm $\|\cdot\|_U = \|\cdot\|_{\mathcal{S}_\delta(\Omega)}$. We define the optimal test norm on V by

$$\|v\|_{\text{opt},V} = \sup_{u \in U} \frac{|b(u, v)|}{\|u\|_U}, \quad \forall v \in \mathcal{S}_\delta(\Omega). \tag{27}$$

To show that eq. (27) is indeed well-defined, we have our first observation in the following lemma.

Lemma 3.6. *Suppose eq. (15) is satisfied, then for any $v \in \mathcal{S}_\delta(\Omega)$*

$$\sup_{u \in U} \frac{|b(u, v)|}{\|u\|_U} < \infty.$$

Proof. From the definition of the energy space eq. (22), the first term in eq. (23) can be bounded by

$$|a(u, v)| \leq \epsilon \|u\|_{\mathcal{S}_\delta(\Omega)} \|v\|_{\mathcal{S}_\delta(\Omega)},$$

for all $u, v \in \mathcal{S}_\delta(\Omega)$. For the second term in eq. (23), by Cauchy-Schwarz inequality and eq. (14) we have

$$\begin{aligned} |(\mathbf{b} \cdot \mathcal{G}_\delta u, v)| &= \left| \int_{\Omega} \int_{\mathcal{H}_\delta(\mathbf{x})} \frac{\mathbf{b}(\mathbf{x}) \cdot (\mathbf{y} - \mathbf{x})}{|\mathbf{y} - \mathbf{x}|} \gamma_\delta^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) (u(\mathbf{y}) - u(\mathbf{x})) v(\mathbf{x}) d\mathbf{y} d\mathbf{x} \right|, \\ &\leq \|\mathbf{b}\|_{L^\infty} \left| \int_{\Omega} \left(\int_{\mathbb{R}^d} \sqrt{|\mathbf{s}| \gamma_\delta^{\text{conv}}(|\mathbf{s}|)} \cdot \sqrt{\frac{1}{|\mathbf{s}|} \gamma_\delta^{\text{conv}}(|\mathbf{s}|)} |u(\mathbf{x} + \mathbf{s}) - u(\mathbf{x})| ds \right) v(\mathbf{x}) d\mathbf{x} \right|, \\ &\leq \|\mathbf{b}\|_{L^\infty} \int_{\Omega} \left(\int |\mathbf{s}| \gamma_\delta^{\text{conv}}(|\mathbf{s}|) ds \right)^{1/2} \left(\int \frac{1}{|\mathbf{s}|} \gamma_\delta^{\text{conv}}(|\mathbf{s}|) (u(\mathbf{x} + \mathbf{s}) - u(\mathbf{x}))^2 ds \right)^{1/2} |v(\mathbf{x})| d\mathbf{x}, \\ &\leq C \|\mathbf{b}\|_{L^\infty} \left(\int_{\Omega} \int_{B_\delta(\mathbf{0})} \frac{1}{|\mathbf{s}|} \gamma_\delta^{\text{conv}}(|\mathbf{s}|) (u(\mathbf{x} + \mathbf{s}) - u(\mathbf{x}))^2 ds d\mathbf{x} \right)^{1/2} \left(\int_{\Omega} |v(\mathbf{x})|^2 d\mathbf{x} \right)^{1/2}, \\ &\leq C \|\mathbf{b}\|_{L^\infty} \|u\|_{\mathcal{S}_\delta(\Omega)} \|v\|_{L^2(\Omega)}, \end{aligned}$$

where we have used eq. (15) in the last line. Finally, by collecting terms, we have

$$\sup_{u \in U} \frac{|b(u, v)|}{\|u\|_U} \leq C(\epsilon \|v\|_{\mathcal{S}_\delta(\Omega)} + \|v\|_{L^2(\Omega)}) < \infty, \quad \forall v \in \mathcal{S}_\delta(\Omega). \quad \square$$

From the above lemma, we know that the quantity in eq. (27) is well-defined for every $v \in \mathcal{S}_\delta(\Omega)$. Furthermore, we can characterize it more precisely as shown in the following.

Lemma 3.7. *Let $\|\cdot\|_{\text{opt},V}$ be defined by eq. (27), then $\|\cdot\|_{\text{opt},V}$ is a norm on V if Assumption 3.2 or Assumption 3.3 is satisfied. More precisely, if Assumption 3.2 is satisfied, then*

$$\|v\|_{\text{opt},V}^2 = \epsilon^2 \|v\|_{\mathcal{S}_\delta(\Omega)}^2 + (\mathcal{D}_\delta(\mathbf{b}v), (-\mathcal{L}_\delta)^{-1} \mathcal{D}_\delta(\mathbf{b}v)), \quad \forall v \in \mathcal{S}_\delta(\Omega). \tag{28}$$

If Assumption 3.3 is satisfied, then

$$\|v\|_{\text{opt},V}^2 = \epsilon^2 \|v\|_{\mathcal{S}_\delta(\Omega)}^2 + 2\epsilon (\mathbf{b} \cdot \mathcal{G}_\delta v, v) + (\mathcal{D}_\delta(\mathbf{b}v), (-\mathcal{L}_\delta)^{-1} \mathcal{D}_\delta(\mathbf{b}v)), \quad \forall v \in \mathcal{S}_\delta(\Omega). \tag{29}$$

In eqs. (28) and (29), $\mathcal{D}_\delta(\mathbf{b}v)$ is defined in (19), and $(-\mathcal{L}_\delta)^{-1}$ is the inverse of the negative nonlocal diffusion operator $-\mathcal{L}_\delta$.

Proof. Assume there is $\psi \in \mathcal{S}_\delta(\Omega)$ such that

$$a(\psi, u) = b(u, v), \quad \forall u \in \mathcal{S}_\delta(\Omega), \tag{30}$$

then from eq. (27), we have

$$\|\psi\|_{\mathcal{S}_\delta(\Omega)} = \sup_{u \in \mathcal{S}_\delta(\Omega)} \frac{|a(\psi, u)|}{\|u\|_{\mathcal{S}_\delta(\Omega)}} = \sup_{u \in U} \frac{|b(u, v)|}{\|u\|_U} = \|v\|_{\text{opt}, V}. \tag{31}$$

We only need to find $\|\psi\|_{\mathcal{S}_\delta(\Omega)}$ in order to characterize $\|v\|_{\text{opt}, V}$. By rewriting eq. (30), we arrive at, for every $u \in \mathcal{S}_\delta(\Omega)$,

$$(-\mathcal{L}_\delta \psi, u) = \epsilon(-\mathcal{L}_\delta u, v) + (\mathbf{b} \cdot \mathcal{G}_\delta u, v) = (u, -\epsilon \mathcal{L}_\delta v) - (u, \mathcal{D}_\delta(\mathbf{b}v)) = (-\epsilon \mathcal{L}_\delta v - \mathcal{D}_\delta(\mathbf{b}v), u), \tag{32}$$

where we have used eqs. (20) and (21). Equation (32) has a unique solution $\psi \in \mathcal{S}_\delta(\Omega)$ because the nonlocal diffusion problem on $\mathcal{S}_\delta(\Omega)$ is well-posedness [46], namely, \mathcal{L}_δ is invertible given the Dirichlet boundary condition. Thus, ψ is given as

$$\psi = \epsilon \mathcal{L}_\delta^{-1} \mathcal{L}_\delta v + \mathcal{L}_\delta^{-1} \mathcal{D}_\delta(\mathbf{b}v) = \epsilon v + \mathcal{L}_\delta^{-1} \mathcal{D}_\delta(\mathbf{b}v).$$

We can write the energy norm of ψ as

$$\begin{aligned} \|\psi\|_{\mathcal{S}_\delta(\Omega)}^2 &= a(\psi, \psi) = (-\mathcal{L}_\delta \psi, \psi) = (-\epsilon \mathcal{L}_\delta v - \mathcal{D}_\delta(\mathbf{b}v), \epsilon v + \mathcal{L}_\delta^{-1} \mathcal{D}_\delta(\mathbf{b}v)), \\ &= -\epsilon^2 (\mathcal{L}_\delta v, v) - \epsilon (\mathcal{L}_\delta v, \mathcal{L}_\delta^{-1} \mathcal{D}_\delta(\mathbf{b}v)) - \epsilon (\mathcal{D}_\delta(\mathbf{b}v), v) - (\mathcal{D}_\delta(\mathbf{b}v), \mathcal{L}_\delta^{-1} \mathcal{D}_\delta(\mathbf{b}v)), \\ &= -\epsilon^2 (\mathcal{L}_\delta v, v) - 2\epsilon (\mathcal{D}_\delta(\mathbf{b}v), v) - (\mathcal{D}_\delta(\mathbf{b}v), \mathcal{L}_\delta^{-1} \mathcal{D}_\delta(\mathbf{b}v)), \\ &= \epsilon^2 a(v, v) + 2\epsilon (\mathbf{b} \cdot \mathcal{G}_\delta v, v) + (\mathcal{D}_\delta(\mathbf{b}v), (-\mathcal{L}_\delta)^{-1} \mathcal{D}_\delta(\mathbf{b}v)). \end{aligned}$$

The quantity above is the same as eq. (29). In the case of Assumption 3.2, $(\mathbf{b} \cdot \mathcal{G}_\delta v, v) = 0$ by eq. (34). Therefore we arrive at eq. (28).

We are left to show eq. (28) or eq. (29) is indeed a norm, namely, if $\|v\|_{\text{opt}, V} = 0$, then $v \equiv 0$. Notice that $(-\mathcal{L}_\delta)^{-1}$ is a positive definite and self-adjoint operator, thus $(\mathcal{D}_\delta(\mathbf{b}v), (-\mathcal{L}_\delta)^{-1} \mathcal{D}_\delta(\mathbf{b}v)) \geq 0$. Moreover, by eq. (35), we have $(\mathbf{b} \cdot \mathcal{G}_\delta v, v) \geq 0$. Finally, we have $\|v\|_{\text{opt}, V} \geq \epsilon \|v\|_{\mathcal{S}_\delta(\Omega)} \geq C \epsilon \|v\|_{L^2(\Omega)} \geq 0$, and the equality holds only if $v \equiv 0$. \square

3.4. Well-posedness of the nonlocal convection-diffusion problem

In order to establish the well-posedness of eq. (24), we first need to show that the bilinear form $b(u, v)$ given by eq. (23) is definite, i.e., it satisfies eq. (3).

Lemma 3.8. *Suppose that Assumption 3.2 or Assumption 3.3 is satisfied, then $b(u, v)$ defined by (23) is definite, i.e.,*

$$\text{if } b(u, v) = 0, \quad \forall u \in \mathcal{S}_\delta(\Omega), \text{ then } v = 0.$$

Proof. Since $b(u, v) = 0$ for all $u \in \mathcal{S}_\delta(\Omega)$, taking $u = v$, we have

$$0 = b(v, v) = \epsilon a(v, v) + (\mathbf{b} \cdot \mathcal{G}_\delta v, v). \tag{33}$$

From the nonlocal Poincaré inequality on $\mathcal{S}_\delta(\Omega)$ [26,45,46], we know that

$$a(v, v) \geq C \|v\|_{L^2(\Omega)}^2 \geq 0.$$

Herein and for the rest of the work, $C > 0$ is a generic constant. Next, we address the second term on the right hand side of eq. (33) based on Assumption 3.2 and 3.3.

If Assumption 3.2 is satisfied, then we want to show

$$\begin{aligned} 0 = (\mathbf{b} \cdot \mathcal{G}_\delta v, v) &= \mathbf{b} \cdot \int_{\Omega} \int_{B_\delta(\mathbf{x})} \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_\delta^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) v(\mathbf{y}) v(\mathbf{x}) d\mathbf{y} d\mathbf{x} \\ &\quad - \mathbf{b} \cdot \int_{\Omega} \left(\int_{B_\delta(\mathbf{x})} \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_\delta^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y} \right) v^2(\mathbf{x}) d\mathbf{x}. \end{aligned} \tag{34}$$

The first term on the right hand side of eq. (34) is zero, because

$$\begin{aligned} & \int_{\Omega} \int_{B_{\delta}(\mathbf{x})} \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_{\delta}^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) v(\mathbf{y}) v(\mathbf{x}) d\mathbf{y} d\mathbf{x} \\ &= \int_{\Omega_{\delta}} \int_{\Omega_{\delta}} \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_{\delta}^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) v(\mathbf{y}) v(\mathbf{x}) d\mathbf{y} d\mathbf{x} = 0, \end{aligned}$$

where we have used the antisymmetry of the integrand in the last line. The second term on the right hand side of eq. (34) is also zero, since

$$\int_{\Omega} \left(\int_{B_{\delta}(\mathbf{x})} \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_{\delta}^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y} \right) v^2(\mathbf{x}) d\mathbf{x} = \int_{\Omega} \left(\int_{B_{\delta}(\mathbf{x})} \frac{\mathbf{s}}{|\mathbf{s}|} \gamma_{\delta}^{\text{conv}}(|\mathbf{s}|) d\mathbf{s} \right) v^2(\mathbf{x}) d\mathbf{x} = 0,$$

by the antisymmetry of the function $\mathbf{s} \gamma_{\delta}^{\text{conv}}(|\mathbf{s}|)$. Therefore, under Assumption 3.2, we have $b(v, v) \geq C \|v\|_{L^2(\Omega)}^2 \geq 0$, and the equality holds only if $v = 0$.

If Assumption 3.3 is satisfied, using eq. (20), we have

$$\begin{aligned} & (\mathbf{b} \cdot \mathcal{G}_{\delta} v, v) = -(v, \mathcal{D}_{\delta}(\mathbf{b}v)) \\ &= - \int_{\Omega_{\delta}} \int_{\Omega_{\delta}} v(\mathbf{x}) (1_{\mathcal{H}_{\delta}(\mathbf{x})}(\mathbf{y}) \mathbf{b}(\mathbf{x}) v(\mathbf{x}) + 1_{\mathcal{H}_{\delta}(\mathbf{y})}(\mathbf{x}) \mathbf{b}(\mathbf{y}) v(\mathbf{y})) \cdot \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_{\delta}^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y} d\mathbf{x} \\ &= \frac{1}{2} \int_{\Omega_{\delta}} \int_{\Omega_{\delta}} (v(\mathbf{y}) - v(\mathbf{x})) (1_{\mathcal{H}_{\delta}(\mathbf{x})}(\mathbf{y}) \mathbf{b}(\mathbf{x}) v(\mathbf{x}) + 1_{\mathcal{H}_{\delta}(\mathbf{y})}(\mathbf{x}) \mathbf{b}(\mathbf{y}) v(\mathbf{y})) \cdot \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_{\delta}^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y} d\mathbf{x} \\ &= \frac{1}{2} \int_{\Omega_{\delta}} \int_{\Omega_{\delta}} (v(\mathbf{y}) - v(\mathbf{x})) v(\mathbf{x}) (1_{\mathcal{H}_{\delta}(\mathbf{x})}(\mathbf{y}) \mathbf{b}(\mathbf{x}) + 1_{\mathcal{H}_{\delta}(\mathbf{y})}(\mathbf{x}) \mathbf{b}(\mathbf{y})) \cdot \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_{\delta}^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y} d\mathbf{x} \\ &\quad + \frac{1}{2} \int_{\Omega_{\delta}} \int_{\Omega_{\delta}} (v(\mathbf{y}) - v(\mathbf{x}))^2 1_{\mathcal{H}_{\delta}(\mathbf{y})}(\mathbf{x}) \mathbf{b}(\mathbf{y}) \cdot \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_{\delta}^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y} d\mathbf{x} \tag{35} \\ &= -\frac{1}{2} \int_{\Omega_{\delta}} v^2(\mathbf{x}) \int_{\Omega_{\delta}} (1_{\mathcal{H}_{\delta}(\mathbf{x})}(\mathbf{y}) \mathbf{b}(\mathbf{x}) + 1_{\mathcal{H}_{\delta}(\mathbf{y})}(\mathbf{x}) \mathbf{b}(\mathbf{y})) \cdot \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{y} - \mathbf{x}|} \gamma_{\delta}^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y} d\mathbf{x} \\ &\quad + \frac{1}{2} \int_{\Omega_{\delta}} \int_{\Omega_{\delta}} (v(\mathbf{y}) - v(\mathbf{x}))^2 1_{\mathcal{H}_{\delta}(\mathbf{x})}(\mathbf{y}) \mathbf{b}(\mathbf{x}) \cdot \frac{\mathbf{x} - \mathbf{y}}{|\mathbf{y} - \mathbf{x}|} \gamma_{\delta}^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y} d\mathbf{x} \\ &= -\frac{1}{2} \int_{\Omega} v^2(\mathbf{x}) \mathcal{D}_{\delta}(\mathbf{b}) d\mathbf{x} + \frac{1}{2} \int_{\Omega_{\delta}} \int_{\mathcal{H}_{\delta}(\mathbf{x})} (v(\mathbf{y}) - v(\mathbf{x}))^2 \mathbf{b}(\mathbf{x}) \cdot \frac{\mathbf{x} - \mathbf{y}}{|\mathbf{y} - \mathbf{x}|} \gamma_{\delta}^{\text{conv}}(|\mathbf{y} - \mathbf{x}|) d\mathbf{y} d\mathbf{x} \geq 0, \end{aligned}$$

where we have used eqs. (25) and (26) in the last step. Therefore, under Assumption 3.3, we have $b(v, v) \geq C \|v\|_{L^2(\Omega)}^2 \geq 0$, and the equality holds only if $v = 0$. \square

Now, we are ready to show the well-posedness of the weak form of the nonlocal convection-diffusion equation given by eqs. (23) and (24) for any given diffusion parameter $\epsilon > 0$ using the optimal test norm on V .

Theorem 3.9. Assume that Assumption 3.2 or Assumption 3.3 is satisfied and let U be equipped with the energy norm $\|\cdot\|_{\mathcal{S}_{\delta}(\Omega)}$, and V be equipped with optimal test norm $\|\cdot\|_{\text{opt},V}$ defined by (27), then the nonlocal convection-diffusion equation given by eqs. (23) and (24) is well-posed for any $\epsilon > 0$. More precisely, for any $f_{\delta} \in V^*$, there exists a unique solution $u \in U$ such that

$$\|u\|_U = \|f_{\delta}\|_{V^*},$$

where V^* denotes the dual of V and $\|f_{\delta}\|_{V^*} := \sup_{v \in V} \frac{|(f_{\delta}, v)|}{\|v\|_{\text{opt},V}}$.

Proof. Notice that under Assumption 3.2 or Assumption 3.3, $b(u, v)$ is definite, see Lemma 3.8 and $\|\cdot\|_{\text{opt},V}$ is well-defined, see Lemma 3.6. Therefore, the inf-sup condition (2) holds with $\alpha = 1$. By the Banach-Nečas-Babuška theorem [34,50], eq. (24) is well-posed and

$$\|u\|_U = \sup_{v \in V} \frac{|b(u, v)|}{\|v\|_{\text{opt},V}} = \sup_{v \in V} \frac{|(f_{\delta}, v)|}{\|v\|_{\text{opt},V}} = \|f_{\delta}\|_{V^*}. \quad \square$$

4. Numerical experiments

Even though we have found the explicit formula of the optimal test space norm, as shown in Lemma 3.7, for the nonlocal convection-dominated diffusion problem (16), it involves the computation of the inverse operator $(-\mathcal{L}_\delta)^{-1}$ which is computationally prohibitive in practice. To alleviate the computational difficulties, we now limit ourselves to one dimension ($d = 1$) and discuss an approximation of the optimal test norm (27). We further assume a constant velocity field $b(x) \equiv 1$ and $\Omega = (0, 1)$ in this section. Since the velocity field is a constant, we can choose the influence region $\mathcal{H}_\delta(x) = B_\delta(x)$ as given in Assumption 3.2. The explicit formula of the optimal test norm is given by eq. (28). For hemispherical influence regions as given in Assumption 3.3, we refer readers to [57,58] for more discussions on numerical discretization.

In this section, we first present an approximation to the optimal test space norm (28) in one dimension ($d = 1$). Then, we select a nonlocal kernel and discuss quadrature rules to calculate the matrices because the integration error plays a significant role in variational nonlocal problems. Finally, we present convergence results using manufactured solutions.

4.1. Approximations to the optimal test space norm in one dimension

The main difficulty for computing with the optimal test norm given in Lemma 3.7 is the term $(\mathcal{D}_\delta(\mathbf{b}v), (-\mathcal{L}_\delta)^{-1}\mathcal{D}_\delta(\mathbf{b}v))$, which involves the inverse operator $(-\mathcal{L}_\delta)^{-1}$. We show next that $(-\mathcal{L}_\delta)^{-1}$ can be approximated using its local limit, $(-\mathcal{L}_0)^{-1}$. Since $d = 1$ and $b(x) \equiv 1$, the local limit of the operators \mathcal{D}_δ and \mathcal{L}_δ are $\frac{d}{dx}$ and $\frac{d^2}{dx^2}$ respectively. In this case, the explicit expression of local limit of the term can be computed as shown in the following lemma.

Lemma 4.1. *Let $d = 1$ and $\Omega = (0, 1)$. Assume that $(-\frac{d^2}{dx^2})^{-1}$ is the inverse of $-\frac{d^2}{dx^2}$ understood in the sense of homogeneous Dirichlet boundary condition, then we have*

$$\left(\frac{d}{dx} v, \left(-\frac{d^2}{dx^2} \right)^{-1} \frac{d}{dx} v \right) = \|v - \bar{v}\|_{L^2(\Omega)}^2, \quad \forall v \in H_0^1(\Omega),$$

where \bar{v} denotes the average of v on Ω , i.e., $\bar{v} = \int_\Omega v$.

Proof. By letting $\frac{d}{dx} v = w$ and $(-\frac{d^2}{dx^2})^{-1} w = g$, we have

$$\begin{cases} -\frac{d^2}{dx^2} g = w = \frac{d}{dx} v, & \text{in } \Omega = (0, 1), \\ g(0) = g(1) = 0, \end{cases} \tag{36}$$

where we have used the fact that $(-\frac{d^2}{dx^2})^{-1}$ is understood with homogeneous Dirichlet boundary condition. From eq. (36), we have

$$-\frac{d}{dx} g = v + C_0,$$

where C_0 is a constant to be determined. From the boundary conditions in eq. (36), we have

$$0 = -\int_0^1 \frac{d}{dx} g = \int_0^1 v + C_0,$$

which implies $C_0 = -\bar{v}$. Therefore, we obtain

$$\begin{aligned} \left(\frac{d}{dx} v, \left(-\frac{d^2}{dx^2} \right)^{-1} \frac{d}{dx} v \right) &= -\left(v, \frac{d}{dx} \left(-\frac{d^2}{dx^2} \right)^{-1} \frac{d}{dx} v \right) = -\left(v, \frac{d}{dx} g \right) \\ &= (v, v - \bar{v}) = (v - \bar{v}, v - \bar{v}) = \|v - \bar{v}\|_{L^2(\Omega)}^2, \end{aligned}$$

where we have used $\int_\Omega (v - \bar{v}) = 0$ in the last line. \square

Using the fact that

$$(\mathcal{D}_\delta v, (-\mathcal{L}_\delta)^{-1}\mathcal{D}_\delta v) \approx \left(\frac{d}{dx} v, \left(-\frac{d^2}{dx^2} \right)^{-1} \frac{d}{dx} v \right) = \|v - \bar{v}\|_{L^2(\Omega)}^2$$

in one dimension, we arrive at an approximate optimal test norm $\|\cdot\|_{\text{app},v}$ on V given by

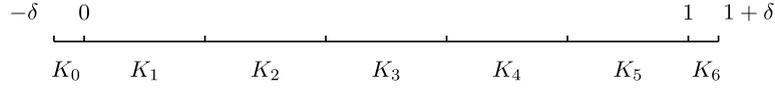


Fig. 1. Initial discretization.

$$\|v\|_{\text{app},V} := \left(\epsilon^2 \|v\|_{\mathcal{S}_\delta(\Omega)}^2 + \|v - \bar{v}\|_{L^2(\Omega)}^2 \right)^{1/2}. \tag{37}$$

A second choice of the test norm is simply the energy norm, i.e.,

$$\|v\|_{\text{eng},V} := \|v\|_{\mathcal{S}_\delta(\Omega)}. \tag{38}$$

In the rest of the paper, we conduct numerical experiments to study how the two test space norms, \$\|\cdot\|_{\text{app},V}\$ and \$\|\cdot\|_{\text{eng},V}\$ as defined in eqs. (37) and (38), perform in solving the nonlocal convection-dominated diffusion problem.

Remark 4.2. One expects that the approximation optimal test norm \$\|\cdot\|_{\text{app},V}\$ converges to the optimal test norm \$\|\cdot\|_{\text{opt},V}\$ as \$\delta \to 0\$. Indeed, we can show that \$\forall v \in H_0^1(\Omega)\$,

$$(\mathcal{D}_\delta v, (-\mathcal{L}_\delta)^{-1} \mathcal{D}_\delta v) \rightarrow \left(\frac{d}{dx} v, \left(-\frac{d^2}{dx^2} \right)^{-1} \frac{d}{dx} v \right)$$

as \$\delta \to 0\$. Here we take the case in Assumption 3.2 for illustration. In this case we have \$(\mathcal{D}_\delta v, (-\mathcal{L}_\delta)^{-1} \mathcal{D}_\delta v) = (\mathcal{G}_\delta v, (-\mathcal{L}_\delta)^{-1} \mathcal{G}_\delta v)\$ in 1d. Define \$f = dv/dx\$ and \$f_\delta = \mathcal{G}_\delta v\$, then by [49, Theorem 1.1], we have \$\|f - f_\delta\|_{L^2} \to 0\$ as \$\delta \to 0\$ since \$v \in H_0^1(\Omega)\$. Now we define \$w\$ and \$w_\delta\$ to be the solutions of the following two problems:

$$\begin{cases} -\frac{d^2}{dx^2} w = f & \text{on } \Omega, \\ w = 0 & \text{on } \partial\Omega, \end{cases} \quad \begin{cases} -\mathcal{L}_\delta w_\delta = f_\delta & \text{on } \Omega, \\ w_\delta = 0 & \text{on } \Omega_{\mathcal{T}_\delta}. \end{cases}$$

Then we only need to show \$(f_\delta, w_\delta) \to (f, w)\$ as \$\delta \to 0\$. This can be estimated by

$$(f_\delta, w_\delta) - (f, w) = (f_\delta - f, w_\delta) + (f, w_\delta - w) \leq C(\|f_\delta - f\|_{L^2} + \|w_\delta - w\|_{L^2}), \tag{39}$$

where we have used Cauchy-Schwartz inequality, energy estimate for nonlocal diffusion equation, \$\|\mathcal{G}_\delta v\|_{L^2} \leq C\$, and \$\|dv/dx\|_{L^2} \leq C\$ in the last inequality. From eq. (39), we only need to show \$\|w - w_\delta\|_{L^2} \to 0\$ as \$\delta \to 0\$. Now we extend \$w\$ to \$\mathbb{R}\$ by zero, and define \$\tilde{f}_\delta := -\mathcal{L}_\delta w\$, we find that \$w - w_\delta\$ is the solution to the nonlocal diffusion problem with the right hand side data \$\tilde{f}_\delta - f_\delta\$. Therefore \$\|w - w_\delta\|_{L^2} \leq C\|\tilde{f}_\delta - f_\delta\|_{L^2}\$ from the energy estimate. Finally, \$\|\tilde{f}_\delta - f_\delta\|_{L^2} \leq \|\tilde{f}_\delta - f\|_{L^2} + \|f - f_\delta\|_{L^2} = \|\mathcal{L}_\delta w - \Delta w\|_{L^2} + \|f - f_\delta\|_{L^2}\$. From the elliptic regularity, we have \$w \in H^2(\Omega)\$ since \$f \in L^2(\Omega)\$. We can also show \$\|\mathcal{L}_\delta w - \Delta w\|_{L^2} \to 0\$, which together with \$\|f - f_\delta\|_{L^2} \to 0\$ implies \$\|w - w_\delta\|_{L^2} \to 0\$ as \$\delta \to 0\$. Thus, we have shown the desired result.

4.2. Discretization

The domain of interest \$\Omega \cup \Omega_{\mathcal{T}_\delta} = (-\delta, 1 + \delta)\$ is partitioned into non-overlapping elements, i.e.,

$$K_i = (x_i, x_{i+1}), \quad 0 \leq i \leq N,$$

where

$$x_0 = -\delta < x_1 = 0 < x_2 < \dots < x_{i-1} < x_i < \dots < x_N = 1 < x_{N+1} = 1 + \delta.$$

For \$2 \leq i \leq N - 1\$, \$x_i\$ is arbitrarily chosen. \$K_0\$ and \$K_N\$ are fixed because volumetric boundary conditions are imposed on these two elements, i.e., \$K_0 \cup K_N \cup \{0, 1\} = \Omega_{\mathcal{T}_\delta}\$. The initial mesh consists of five equally spaced elements in \$\Omega\$ as shown in Fig. 1.

The collection of elements \$K_i\$ is denoted as \$\Omega_h = \cup_{i=0}^N K_i\$. The finite dimensional trial space \$U_h \subset U\$ is set to be

$$U_h = \{u \in U : u|_{K_i} \in \mathcal{Q}_p(K_i), \forall K_i \in \Omega_h\}, \tag{40}$$

where \$\mathcal{Q}_p(K_i)\$ is the space of polynomials of degree \$p \geq 1\$. The finite dimensional test space \$V_h \subset V\$ is set with an enriched order \$\bar{p} = p + \delta p > p\$ and

$$V_h = \{v \in V : v|_{K_i} \in \mathcal{Q}_{\bar{p}}(K_i), \forall K_i \in \Omega_h\}. \tag{41}$$

Therein, $\delta p \in \mathbb{Z}^+$ is the degree of enrichment in the test space compared with the polynomial order in the trial space. In this work, we use $\delta p = 2$ or 3 in Section 4.4, and $\delta p = 6$ in section 4.5. Next, we solve the mixed problem (7) with U_h and V_h defined by eqs. (40) and (41). We use the two different test norms given by eqs. (37) and (38). The corresponding inner products in V are given as

$$(\psi, v)_{\text{app},V} = \epsilon^2 a(\psi, v) + (\psi - \bar{\psi}, v - \bar{v})_{L^2}$$

and

$$(\psi, v)_{\text{eng},V} = a(\psi, v).$$

4.3. Nonlocal kernels

For simplicity, we choose the following nonlocal kernels

$$\gamma^{\text{diff}}(|s|) = \begin{cases} \frac{3}{2}, & |s| \leq 1, \\ 0, & |s| > 1, \end{cases} \quad \text{and} \quad \gamma^{\text{conv}}(|s|) = \begin{cases} \frac{3}{2}|s|, & |s| \leq 1, \\ 0, & |s| > 1. \end{cases} \tag{42}$$

The parameters are chosen such that eqs. (10) and (14) are satisfied. In this case, $\eta = 1$ since we let $\mathcal{H}_\delta(x) = B_\delta(x)$. As a result, the nonlocal diffusion and convection kernels are given as

$$\gamma_\delta^{\text{diff}}(|s|) = \begin{cases} \frac{3}{2\delta^3}, & |s| \leq \delta, \\ 0, & |s| > \delta, \end{cases} \quad \text{and} \quad \gamma_\delta^{\text{conv}}(|s|) = \begin{cases} \frac{3}{2\delta^3}|s|, & |s| \leq \delta, \\ 0, & |s| > \delta. \end{cases} \tag{43}$$

It is immediate that eq. (15) is also satisfied. Since the nonlocal kernels are discontinuous over \mathbb{R} , the numerical integration process involves determining the intersection of elements in Ω_h with balls of radius δ . The integration procedure is briefly discussed in Algorithm 1. We remark that the intersection of an element and horizon in one dimension, $\Omega_j \cap B_\delta(x_p)$, is an interval which is not hard to find. The intersecting geometry becomes more complicated in higher dimensions and related discussions on numerical integration for finite element implementations of nonlocal models can be found in [11,16]. To reduce the integration error, we have used $p(\bar{p}) + N_{\text{over}}$ quadrature points. Therein, $p(\bar{p})$ is the polynomial order of the trial (test) element, and $N_{\text{over}} = 13$ is the number of extra quadrature points.

Algorithm 1: Numerical integration.

For each $K_i \in \Omega_h$,
 Find $K_j \in \Omega_h$, such that $\text{dist}(\Omega_i, \Omega_j) \leq \delta$.
 Integrate over Ω_i with Gauss quadrature points $x_p \in \Omega_i$.
 Integrate over $\Omega_j \cap B_\delta(x_p)$ with Gauss quadrature points $y_q \in \Omega_j \cap B_\delta(x_p)$.

4.4. Manufactured smooth solution

In this section, we apply the proposed PG method to solve the nonlocal convection-dominated diffusion problem. We use the manufactured smooth solution $u(x) = x^5$ to test the performance of the numerical method. For the rest of this work, the model parameter ϵ is chosen to be 0.01 to characterize the dominance of the convection over diffusion. We study the convergence of the numerical solution to the nonlocal limit (δ fixed) as the mesh size $h \rightarrow 0$ and the polynomial order $p \rightarrow \infty$ in Section 4.4.1. In addition, we also study the behavior of the numerical solution with respect to the local limit as δ and h both approach zero in Section 4.4.2 to test the asymptotic compatibility of the numerical algorithm [60,61].

4.4.1. Nonlocal limit (δ fixed)

We use the PG method with the two test space norms as presented in eqs. (37) and (38) to solve the following nonlocal convection-dominated diffusion problem with fixed δ ,

$$\begin{cases} -\epsilon \mathcal{L}_\delta u(x) + \mathcal{G}_\delta u(x) = f_\delta(x), & x \in \Omega, \\ u(x) = x^5, & x \in \Omega_{\mathcal{I}_\delta}. \end{cases} \tag{44}$$

Given $u(x) = x^5$, we calculate $f_\delta = -\epsilon \mathcal{L}_\delta u + \mathcal{G}_\delta u$ and obtain

$$f_\delta(x) = -\epsilon(20x^3 + 6\delta^2x) + 5x^4 + 6\delta^2x^2 + 3/7\delta^4. \tag{45}$$

We conduct convergence analysis using uniform h - and p -, and adaptive h -refinements for different horizon sizes, $\delta = 0.1, 0.01, 0.001$ and 0.0001 . We remark that the boundary conditions are imposed using the corresponding exact values of $u(x)$.

Table 1
Relative error in $\|\cdot\|_{S_\delta}$ and convergence rates using $\|\cdot\|_{\text{app},V}$ for the test norm to solve eq. (44). Uniform h -refinements and $\delta p = 2$.

$10 \times h$	$\delta = 0.1$	$\delta = 0.01$	$\delta = 0.001$	$\delta = 0.0001$
2^1	$2.03 \times 10^{-1}(-)$	$2.48 \times 10^{-1}(-)$	$2.56 \times 10^{-1}(-)$	$2.56 \times 10^{-1}(-)$
2^0	$6.90 \times 10^{-2}(1.33)$	$1.21 \times 10^{-1}(0.88)$	$1.29 \times 10^{-1}(0.84)$	$1.30 \times 10^{-2}(0.84)$
2^{-1}	$1.39 \times 10^{-3}(2.14)$	$5.62 \times 10^{-2}(1.03)$	$6.47 \times 10^{-2}(0.92)$	$6.54 \times 10^{-2}(0.92)$
2^{-2}	$3.09 \times 10^{-3}(2.09)$	$2.33 \times 10^{-2}(1.22)$	$3.17 \times 10^{-2}(0.99)$	$3.27 \times 10^{-2}(0.96)$
2^{-3}	$7.36 \times 10^{-4}(2.03)$	$7.16 \times 10^{-3}(1.67)$	$1.54 \times 10^{-2}(1.03)$	$1.62 \times 10^{-2}(1.00)$
2^{-4}	$1.80 \times 10^{-4}(2.01)$	$1.69 \times 10^{-3}(2.07)$	$7.21 \times 10^{-3}(1.08)$	$8.08 \times 10^{-3}(0.99)$
2^{-5}	$4.46 \times 10^{-5}(2.01)$	$4.02 \times 10^{-4}(2.06)$	$3.12 \times 10^{-3}(1.20)$	$3.99 \times 10^{-3}(1.02)$
2^{-6}	$1.11 \times 10^{-5}(2.00)$	$1.02 \times 10^{-4}(1.98)$	$1.09 \times 10^{-4}(1.51)$	$1.95 \times 10^{-3}(1.03)$
2^{-7}	$2.77 \times 10^{-6}(2.00)$	$2.57 \times 10^{-5}(1.98)$	$2.39 \times 10^{-4}(2.19)$	$9.24 \times 10^{-4}(1.07)$

Table 2
Relative error in $\|\cdot\|_{S_\delta}$ and convergence rates using $\|\cdot\|_{\text{eng},V}$ for the test norm to solve eq. (44). Uniform h -refinements and $\delta p = 2$.

$10 \times h$	$\delta = 0.1$	$\delta = 0.01$	$\delta = 0.001$	$\delta = 0.0001$
2^1	$2.01 \times 10^{-1}(-)$	$2.58 \times 10^{-1}(-)$	$2.65 \times 10^{-1}(-)$	$2.66 \times 10^{-1}(-)$
2^0	$5.89 \times 10^{-2}(1.51)$	$1.24 \times 10^{-1}(0.90)$	$1.31 \times 10^{-1}(0.86)$	$1.33 \times 10^{-1}(0.85)$
2^{-1}	$1.32 \times 10^{-2}(2.00)$	$5.68 \times 10^{-2}(1.04)$	$6.53 \times 10^{-2}(0.94)$	$6.60 \times 10^{-2}(0.94)$
2^{-2}	$3.05 \times 10^{-3}(2.04)$	$2.34 \times 10^{-2}(1.23)$	$3.18 \times 10^{-2}(1.00)$	$3.28 \times 10^{-2}(0.97)$
2^{-3}	$7.33 \times 10^{-4}(2.02)$	$7.16 \times 10^{-3}(1.68)$	$1.54 \times 10^{-2}(1.03)$	$1.62 \times 10^{-2}(1.00)$
2^{-4}	$1.80 \times 10^{-4}(2.01)$	$1.69 \times 10^{-3}(2.07)$	$7.22 \times 10^{-3}(1.08)$	$8.09 \times 10^{-3}(0.99)$
2^{-5}	$4.46 \times 10^{-5}(2.00)$	$4.01 \times 10^{-4}(2.06)$	$3.12 \times 10^{-3}(1.20)$	$3.99 \times 10^{-3}(1.02)$
2^{-6}	$1.11 \times 10^{-5}(2.00)$	$1.02 \times 10^{-4}(1.98)$	$1.09 \times 10^{-3}(1.51)$	$1.95 \times 10^{-3}(1.03)$
2^{-7}	$2.77 \times 10^{-6}(2.00)$	$2.57 \times 10^{-5}(1.98)$	$2.39 \times 10^{-4}(2.19)$	$9.24 \times 10^{-4}(1.07)$

Table 3
Relative error in $\|\cdot\|_{S_\delta}$ and convergence rates using $\|\cdot\|_{\text{app},V}$ for the test norm to solve eq. (44). Uniform p -refinements and $\delta p = 2$.

N	$\delta = 0.1$	$\delta = 0.01$	$\delta = 0.001$	$\delta = 0.0001$
4	$2.03 \times 10^{-1}(-)$	$2.48 \times 10^{-1}(-)$	$2.65 \times 10^{-1}(-)$	$2.65 \times 10^{-1}(-)$
9	$2.04 \times 10^{-2}(2.83)$	$2.32 \times 10^{-2}(2.92)$	$2.50 \times 10^{-2}(2.91)$	$2.50 \times 10^{-2}(2.91)$
14	$4.55 \times 10^{-4}(8.61)$	$9.66 \times 10^{-4}(7.20)$	$1.41 \times 10^{-3}(6.51)$	$1.41 \times 10^{-3}(6.51)$
19	$9.52 \times 10^{-6}(12.66)$	$2.23 \times 10^{-5}(12.34)$	$2.29 \times 10^{-5}(13.49)$	$2.29 \times 10^{-5}(13.49)$

In the uniform h -refinements scheme, we fix the polynomial order of the trial spaces ($p = 1$) and the degree of enrichment in the test space ($\delta p = 2$, [19,21]) and refine the seven-element initial mesh, Fig. 1, uniformly. Relative errors in $\|\cdot\|_{S_\delta}$ norm and convergence rates are presented in Tables 1 and 2 for the two test space norms, eqs. (37) and (38), respectively. The results are similar for both norms. When $\delta = 0.1$ is large, second-order convergence rates in the $\|\cdot\|_{S_\delta}$ norm are observed. As δ gets smaller ($\delta = 0.0001$), the convergence rates approach the first order. This agrees with the properties of the energy space S_δ . It has been shown that for integrable kernels, if δ is fixed, $\|\cdot\|_{S_\delta}$ is equivalent to $\|\cdot\|_{L^2}$ [26]; while as $\delta \rightarrow 0$, $\|\cdot\|_{S_\delta}$ converges to $\|\cdot\|_{H_0^1}$ [4]. For a fixed δ , when the mesh is sufficiently refined, second-order convergence in the norm $\|\cdot\|_{S_\delta}$ is observed. In the case of $\delta = 0.0001$, since the values of h are not small enough in compared with δ , the norm $\|\cdot\|_{S_\delta}$ on piecewise linear functions is effectively closer to $\|\cdot\|_{H_0^1}$ than to $\|\cdot\|_{L^2}$. Thus the observed convergence rate is of first-order.

Next, we study the convergence of the uniform p -refinements by increasing the polynomial order of the trial space and keeping the mesh fixed. It is worth noting that the enrichment degree δp in the test space is fixed while we increase p of the trial space, then the polynomial order \tilde{p} of V_h in eq. (41) is augmented accordingly ($\tilde{p} = p + \delta p$). Convergence results (against the number of degrees of freedom, N) obtained using $\|\cdot\|_{\text{app},V}$ for the test norm are shown in Table 3 for $\delta p = 2$ and in Table 4 for $\delta p = 3$. Tables 5 and 6 present results obtained using $\|\cdot\|_{\text{eng},V}$ for the test norm with $\delta p = 2$ and 3, respectively. Exponential convergence rates are observed for all cases and the results hardly change by increasing the enrichment degree δp from 2 to 3.

As discussed in [13,17,20], ψ_h defined in eq. (7) also serves as an a-posteriori error estimator for adaptivity in the trial space. We adopt the Dörfler refinement strategy [24] with 10% factor for the adaptive h -refinements. A total number of 50 refinement steps are conducted. Convergence results using the adaptive h -refinements scheme are plotted in Fig. 2 using the two test space norms, namely, $\|\cdot\|_{\text{app},V}$ and $\|\cdot\|_{\text{eng},V}$. Similar algebraic convergence behavior as in the uniform h -refinement is observed. When δ is large ($\delta = 0.1$), we obtain second-order convergence rates. For $\delta = 0.0001$, the convergence rates become first-order. For the intermediate horizon size, $\delta = 0.01$, the convergence rates are between the first- and second-orders.

Table 4
Relative error in $\|\cdot\|_{S_\delta}$ and convergence rates using $\|\cdot\|_{\text{app},V}$ for the test norm to solve eq. (44). Uniform p -refinements and $\delta p = 3$.

N	$\delta = 0.1$	$\delta = 0.01$	$\delta = 0.001$	$\delta = 0.0001$
4	$2.10 \times 10^{-1}(-)$	$2.48 \times 10^{-1}(-)$	$2.62 \times 10^{-1}(-)$	$2.62 \times 10^{-1}(-)$
9	$2.08 \times 10^{-2}(2.85)$	$2.32 \times 10^{-2}(2.92)$	$2.48 \times 10^{-2}(2.91)$	$2.48 \times 10^{-2}(2.90)$
14	$4.58 \times 10^{-4}(8.63)$	$9.64 \times 10^{-4}(7.20)$	$1.40 \times 10^{-4}(6.51)$	$1.40 \times 10^{-3}(6.51)$
19	$9.53 \times 10^{-6}(12.68)$	$2.23 \times 10^{-5}(12.34)$	$2.29 \times 10^{-5}(13.47)$	$2.29 \times 10^{-5}(13.47)$

Table 5
Relative error in $\|\cdot\|_{S_\delta}$ and convergence rates using $\|\cdot\|_{\text{eng},V}$ for the test norm to solve eq. (44). Uniform p -refinements and $\delta p = 2$.

N	$\delta = 0.1$	$\delta = 0.01$	$\delta = 0.001$	$\delta = 0.0001$
4	$2.01 \times 10^{-1}(-)$	$2.58 \times 10^{-1}(-)$	$2.84 \times 10^{-1}(-)$	$2.84 \times 10^{-1}(-)$
9	$1.88 \times 10^{-2}(2.92)$	$2.39 \times 10^{-2}(2.93)$	$2.58 \times 10^{-2}(2.96)$	$2.58 \times 10^{-2}(2.96)$
14	$4.28 \times 10^{-4}(8.56)$	$1.07 \times 10^{-3}(7.03)$	$1.52 \times 10^{-3}(6.41)$	$1.52 \times 10^{-3}(6.41)$
19	$9.47 \times 10^{-6}(12.48)$	$2.26 \times 10^{-5}(12.63)$	$2.33 \times 10^{-5}(13.69)$	$2.33 \times 10^{-5}(13.69)$

Table 6
Relative error in $\|\cdot\|_{S_\delta}$ and convergence rates using $\|\cdot\|_{\text{eng},V}$ for the test norm to solve eq. (44). Uniform p -refinements and $\delta p = 3$.

N	$\delta = 0.1$	$\delta = 0.01$	$\delta = 0.001$	$\delta = 0.0001$
4	$2.01 \times 10^{-1}(-)$	$2.58 \times 10^{-1}(-)$	$2.84 \times 10^{-1}(-)$	$2.84 \times 10^{-1}(-)$
9	$1.88 \times 10^{-2}(2.92)$	$2.39 \times 10^{-2}(2.93)$	$2.58 \times 10^{-2}(2.96)$	$2.58 \times 10^{-2}(2.96)$
14	$4.28 \times 10^{-4}(8.56)$	$1.07 \times 10^{-3}(7.03)$	$1.52 \times 10^{-3}(6.41)$	$1.52 \times 10^{-3}(6.41)$
19	$7.47 \times 10^{-6}(12.48)$	$2.26 \times 10^{-5}(12.63)$	$2.33 \times 10^{-5}(13.69)$	$2.33 \times 10^{-5}(13.69)$

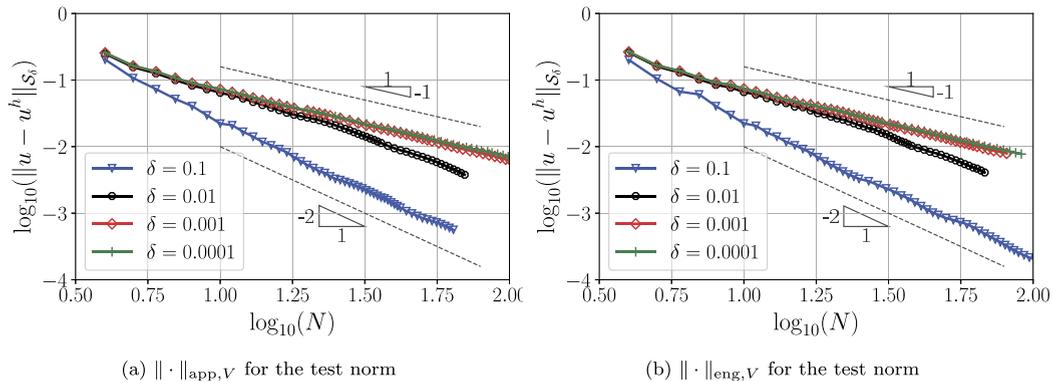


Fig. 2. Convergence profile (relative error) using $\|\cdot\|_{\text{app},V}$ and $\|\cdot\|_{\text{eng},V}$ for the test norms to solve eq. (44). Adaptive h -refinements and $\delta p = 2$.

4.4.2. Local limit ($\delta \rightarrow 0$)

In this section we study the convergence of the numerical solution to the local limit as δ and h both go to 0. The forcing function f_0 is obtained through $f_0(x) = -\epsilon u''(x) + u'(x) = -20\epsilon x^3 + 5x^4$, where $u(x) = x^5$. We solve the following nonlocal problem

$$\begin{cases} -\epsilon \mathcal{L}_\delta u(x) + \mathcal{G}_\delta u(x) = f_0(x), & x \in \Omega, \\ u(x) = x^5, & x \in \Omega_{\mathcal{I}_\delta}, \end{cases} \xrightarrow{\delta \rightarrow 0} \begin{cases} -\epsilon u''(x) + u'(x) = f_0(x), & x \in \Omega, \\ u(x) = x^5, & x \in \partial\Omega, \end{cases} \quad (46)$$

by letting $\delta \rightarrow 0$ and $h \rightarrow 0$ but at different coupling rates. Convergence results using uniform h -refinements are reported in Tables 7 and 8 using $\|\cdot\|_{\text{app},V}$ and $\|\cdot\|_{\text{eng},V}$ for the test space norm, respectively.

As shown in Tables 7 and 8, when δ and h both approach zero, first-order convergence rates are observed regardless of the coupling rate between δ and h . It is worth mentioning that for $\delta = 2h$, the convergence rate is second-order when $h \geq 2^{-3}$. This is due to the fact that the nonlocal energy norm $\|\cdot\|_{S_\delta}$ transitions from L^2 norm to H^1 -semi norm as $\delta = 2h$ decreases. As a consequence, the convergence rate is of first-order. For $\delta = \sqrt{h}$, only first-order convergence rate is obtained because the nonlocal problem converges to the local problem at a rate of $\mathcal{O}(\delta^2)$, thus $\mathcal{O}(h)$. Lastly, similar convergence behavior is obtained for both norms.

Table 7
Relative error in $\|\cdot\|_{S_\delta}$ and convergence rates using $\|\cdot\|_{\text{app},V}$ for the test norm to solve eq. (46). Uniform h -refinements and $\delta p = 2$.

$10 \times h$	$\delta = h$	$\delta = 2h$	$\delta = h^2$	$\delta = \sqrt{h}$
2^1	$4.77 \times 10^{-1} (---)$	$3.03 \times 10^0 (---)$	$2.30 \times 10^{-1} (---)$	$1.14 \times 10^1 (---)$
2^0	$1.34 \times 10^{-1} (1.56)$	$5.59 \times 10^{-1} (2.08)$	$1.21 \times 10^{-1} (0.79)$	$4.54 \times 10^0 (1.14)$
2^{-1}	$4.09 \times 10^{-2} (1.59)$	$1.01 \times 10^{-1} (2.29)$	$6.28 \times 10^{-2} (0.88)$	$1.82 \times 10^0 (1.22)$
2^{-2}	$1.37 \times 10^{-2} (1.53)$	$1.97 \times 10^{-2} (2.28)$	$3.22 \times 10^{-2} (0.93)$	$6.14 \times 10^{-1} (1.51)$
2^{-3}	$5.67 \times 10^{-3} (1.25)$	$4.80 \times 10^{-3} (2.00)$	$1.61 \times 10^{-2} (0.98)$	$2.34 \times 10^{-1} (1.36)$
2^{-4}	$2.67 \times 10^{-3} (1.08)$	$1.67 \times 10^{-3} (1.51)$	$8.16 \times 10^{-3} (0.97)$	$8.88 \times 10^{-2} (1.39)$
2^{-5}	$1.31 \times 10^{-3} (1.02)$	$7.13 \times 10^{-4} (1.22)$	$4.09 \times 10^{-3} (0.99)$	$3.43 \times 10^{-2} (1.36)$
2^{-6}	$6.50 \times 10^{-4} (1.01)$	$3.34 \times 10^{-4} (1.09)$	$2.04 \times 10^{-3} (1.00)$	$1.41 \times 10^{-2} (1.28)$
2^{-7}	$3.24 \times 10^{-4} (1.00)$	$1.63 \times 10^{-4} (1.03)$	$1.02 \times 10^{-4} (1.00)$	$8.04 \times 10^{-3} (0.81)$

Table 8
Relative error in $\|\cdot\|_{S_\delta}$ and convergence rates using $\|\cdot\|_{\text{eng},V}$ for the test norm to solve eq. (46). Uniform h -refinements and $\delta p = 2$.

$10 \times h$	$\delta = h$	$\delta = 2h$	$\delta = h^2$	$\delta = \sqrt{h}$
2^1	$2.92 \times 10^{-1} (---)$	$2.40 \times 10^0 (---)$	$2.39 \times 10^{-1} (---)$	$1.09 \times 10^1 (---)$
2^0	$9.06 \times 10^{-2} (1.44)$	$4.59 \times 10^{-1} (2.04)$	$1.24 \times 10^{-1} (0.81)$	$3.91 \times 10^0 (1.26)$
2^{-1}	$3.25 \times 10^{-2} (1.37)$	$8.29 \times 10^{-1} (2.29)$	$6.35 \times 10^{-2} (0.90)$	$1.72 \times 10^0 (1.10)$
2^{-2}	$1.28 \times 10^{-2} (1.30)$	$1.65 \times 10^{-2} (2.24)$	$3.23 \times 10^{-2} (0.94)$	$5.94 \times 10^{-1} (1.48)$
2^{-3}	$5.63 \times 10^{-3} (1.16)$	$4.47 \times 10^{-3} (1.85)$	$1.61 \times 10^{-2} (0.99)$	$2.28 \times 10^{-1} (1.35)$
2^{-4}	$2.67 \times 10^{-3} (1.07)$	$1.65 \times 10^{-3} (1.42)$	$8.17 \times 10^{-3} (0.97)$	$8.71 \times 10^{-2} (1.38)$
2^{-5}	$1.31 \times 10^{-3} (1.02)$	$7.14 \times 10^{-4} (1.20)$	$4.09 \times 10^{-3} (0.99)$	$3.39 \times 10^{-2} (1.36)$
2^{-6}	$6.50 \times 10^{-4} (1.01)$	$3.35 \times 10^{-4} (1.09)$	$2.04 \times 10^{-3} (1.00)$	$1.41 \times 10^{-2} (1.27)$
2^{-7}	$3.24 \times 10^{-4} (1.00)$	$1.64 \times 10^{-4} (1.03)$	$1.02 \times 10^{-4} (1.00)$	$8.03 \times 10^{-3} (0.80)$

In conclusion, optimal convergence rates in the energy norm to the nonlocal limit (fixed δ) are observed using the proposed PG method under uniform h - and p -refinements, and adaptive h -refinements. As δ and h both go to zero at different coupling rates, first-order convergence rates in $\|\cdot\|_{S_\delta}$ are observed. Therefore, the proposed PG method is asymptotically compatible [60,61]. Moreover, the convergence rates measured in the energy norm also reflect the properties of the norm $\|\cdot\|_{S_\delta}$ with integrable kernels, i.e., it transitions from $\|\cdot\|_{L^2}$ to $\|\cdot\|_{H^1_0}$ as the size of δ changes from large to small. We remark that convergence rates measured in L^2 norm are shown in Appendix A for reference.

4.5. Manufactured solution with a sharp gradient transition

In this section, we show the effectiveness of the proposed PG method using the following manufactured solution,

$$u(x) = \frac{e^{((x-1)/\epsilon)} - 1}{e^{(-1/\epsilon)} - 1}, \tag{47}$$

and the corresponding forcing function is given by

$$f_\delta(x) = \left[\frac{3\epsilon}{2\delta^2} (4 + e^{\delta/\epsilon} + e^{-\delta/\epsilon}) - \frac{9\epsilon^2}{2\delta^3} (e^{\delta/\epsilon} - e^{-\delta/\epsilon}) \right] \frac{e^{((x-1)/\epsilon)}}{e^{(-1/\epsilon)} - 1}. \tag{48}$$

The manufactured solution given by eq. (47) is plotted in Fig. 3. As shown in Fig. 3, $u(x)$ transitions from 1 to 0, and the width of the transition region depends on ϵ . We remark that $\epsilon = 0.01$ in this work and the gradient of $u(x)$ changes rapidly near $x = 1$. Traditional numerical methods suffer from oscillations. Various stabilizing techniques are effective in eliminating such oscillations for classical convection-diffusion equations [7,5,10,13,23,36,37]. We show next that the proposed PG method is stable and optimal convergence rates are recovered. More importantly, the superiority of using $\|\cdot\|_{\text{app},V}$ (eq. (37)) other than $\|\cdot\|_{\text{eng},V}$ (eq. (38)) as the test norm for numerical stability in the pre-asymptotic regime is demonstrated.

4.5.1. Uniform refinement

We use the proposed PG method to solve the nonlocal convection-dominated diffusion problem with the manufactured solution given in eq. (47) when δ is fixed. The initial mesh is shown in Fig. 1. Linear elements ($p = 1$) are used for the trial space U_h and the order of enrichment in the test space is $\delta p = 6$. Convergence results using uniform h -refinements agree with section 4.4 and are presented in Fig. 4. It is shown in Figs. 4a and 4b, optimal convergence rates are recovered only after the mesh size is small enough ($h \leq 2^{-3}$), and the performances of the two test space norms are similar. When δ is large ($\delta = 0.01$), second-order convergence rates are observed. The convergence rate is only first-order for small $\delta = 0.00001$.

In addition, to demonstrate that the PG approach with optimal test norm provides much more accurate solutions in the pre-asymptotic regime, we performed a numerical test comparing three different methods (standard Galerkin method, PG

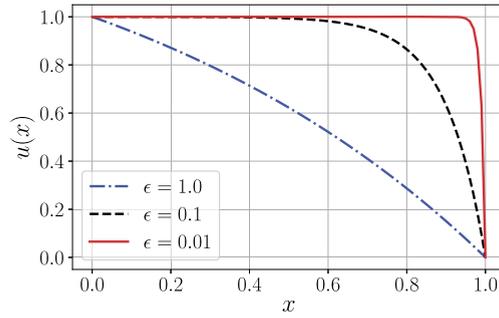


Fig. 3. Manufactured solution, eq. (47), for different ϵ .

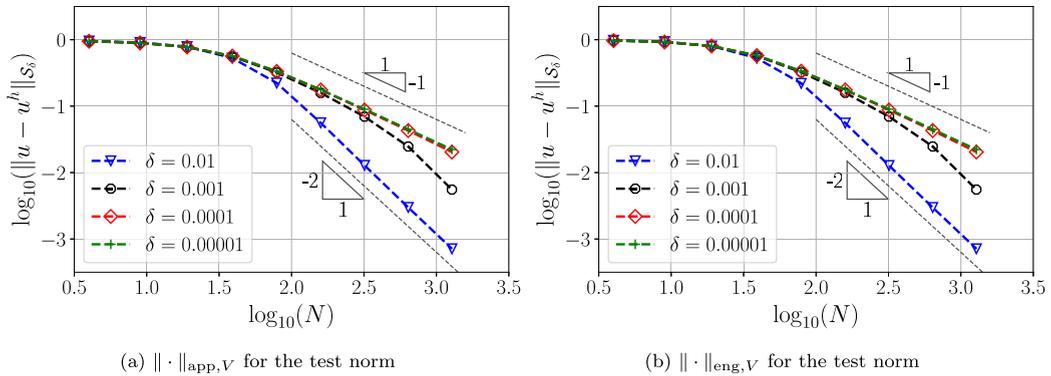


Fig. 4. Convergence profile (relative error) using $\|\cdot\|_{app,V}$ and $\|\cdot\|_{eng,V}$ for the test norms to solve the nonlocal convection-dominated diffusion problem with the manufactured solution given in eq. (47). Uniform h -refinements and $\delta p = 6$.

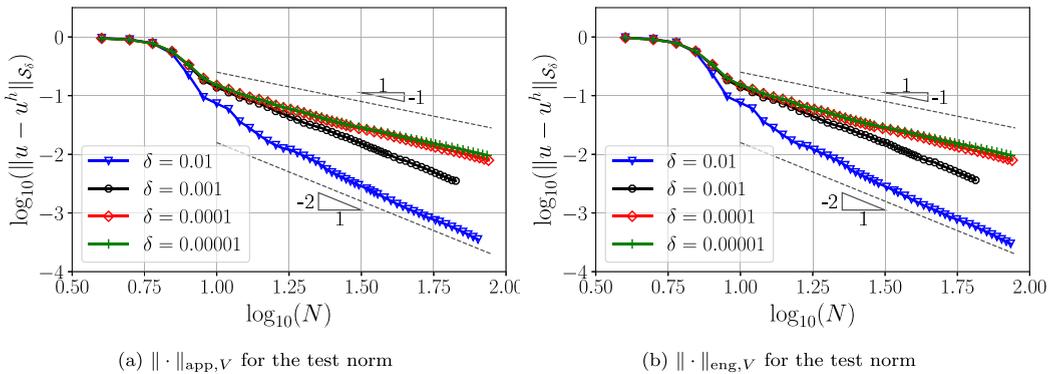


Fig. 5. Convergence profile (relative error) using $\|\cdot\|_{app,V}$ and $\|\cdot\|_{eng,V}$ for the test norms to solve the nonlocal convection-dominated diffusion problem with the manufactured solution given in eq. (47). Adaptive h -refinements and $\delta p = 6$.

method with $\|\cdot\|_{app,V}$ and PG method with $\|\cdot\|_{eng,V}$) using the initial mesh given in Fig. 1. Fig. 6 indicates that for both cases of $\delta = 0.01$ and $\delta = 0.00001$, the standard Galerkin method gives the worst numerical solutions and the PG method with approximate optimal test norm $\|\cdot\|_{app,V}$ provides the most accurate approximations of the exact solution.

4.5.2. Adaptive refinement

We adopt the Dörfler refinement strategy discussed in section 4.4 for the adaptive h -refinements and convergence results are shown in Fig. 5. Unlike in Fig. 2 where the optimal convergence rates are observed at the beginning of the adaptive h -refinements, the optimal convergence rates in Figs. 5a and 5b are recovered only after some initial refinements. This is due to the existence of the sharp transition region (also called the boundary layer of the solution) near the right boundary, and it is necessary to use fine mesh to resolve this boundary layer of the solution. After resolving the boundary layer, the convergence results agree with what we have observed in section 4.4 for a manufactured smooth solution. As presented in Fig. 5, the proposed PG method with both test space norms is able to refine the mesh adaptively in an automatic fashion.

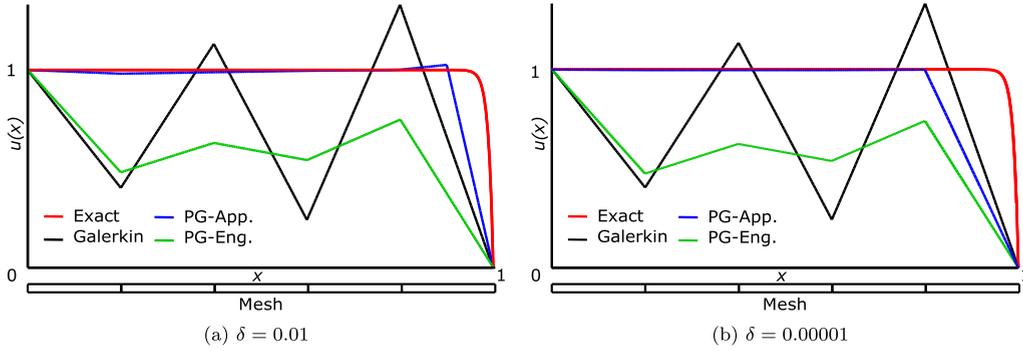


Fig. 6. Numerical solutions of standard Galerkin method (Galerkin), and the proposed PG method using $\|\cdot\|_{app,V}$ (PG-App.) and $\|\cdot\|_{eng,V}$ (PG-Eng.) for the test norms to solve the nonlocal convection-dominated diffusion problem with the manufactured solution given in eq. (47). Initial mesh with $p = 1$ ($\delta p = 0$ for Galerkin method, $\delta p = 6$ for PG method), and $\delta = 0.01$ and 0.00001 . (For interpretation of the colors in the figure(s), the reader is referred to the web version of this article.)

It is worth noting that for the first few refinements in Figs. 5a and 5b, the relative errors using $\|\cdot\|_{app,V}$ for the test norm are smaller than those using $\|\cdot\|_{eng,V}$ but the difference is indiscernible on the scale of the plots (see also Figs. B.10 and B.11 for L^2 errors where the differences in the pre-asymptotic region are more easily seen). We demonstrate the differences by presenting the evolution of the numerical solution using both test space norms. The evolution of the numerical solution for $\delta = 0.00001$ is shown in Fig. 7. When the mesh is coarse, the numerical solution using $\|\cdot\|_{app,V}$ almost interpolates the exact solution, while the numerical solution using $\|\cdot\|_{eng,V}$ suffers from significant oscillations. Thus the superiority of using the optimal test space norm becomes obvious. The proposed PG method with the test space norm eq. (37) is indeed stable in solving the nonlocal convection-dominated diffusion problem.

Finally, we remark that $\|\cdot\|_{app,V}$ in eq. (37) is sub-optimal because it is only an approximation of $\|\cdot\|_{opt,V}$ in eq. (28). When $\delta = 0$, $\|\cdot\|_{app,V}$ and $\|\cdot\|_{opt,V}$ are identical. It is then expected that the performance of $\|\cdot\|_{app,V}$ deteriorates for large δ , and this can be observed by comparing Fig. 7 ($\delta = 0.00001$) against Fig. 8 ($\delta = 0.01$). The numerical solutions in Fig. 8 using $\|\cdot\|_{app,V}$ for the test norm exhibit minor oscillations but the oscillations are much less severe than that of using $\|\cdot\|_{eng,V}$.

5. Conclusion

In this paper, we have presented a PG method for the nonlocal convection-dominated diffusion problem using optimal test functions in a general space dimension. The well-posedness of the nonlocal convection-dominated diffusion problem is established for two types of nonlocal convection kernels, with spherical or hemispherical interaction regions. The optimal test space norm is identified in both abstract and explicit forms. However, the optimal test space norm is not practical in computation as it involves inverting the nonlocal diffusion operator. We instead propose an approximate optimal test norm $\|\cdot\|_{app,V}$ which is easy to implement in one dimension. Using manufactured solutions, convergence results in the nonlocal energy norm and the performance of the approximate optimal test norm are tested in comparison with the simple nonlocal energy norm on the test space $\|\cdot\|_{eng,V}$.

For a manufactured smooth solution, uniform h - and p -refinements, and adaptive h -refinements are carried out, and the convergence results in $\|\cdot\|_{S_\delta}$ are similar for the two test space norms. For the uniform h -refinements, second-order convergence rates are observed when δ is large while we have obtained first-order convergence rates in when δ is small. The variations in convergence rates for different sizes of δ are due to the characteristics of the nonlocal energy space S_δ . For large δ , $\|\cdot\|_{S_\delta}$ is equivalent to the L^2 norm [26], and as δ approaches zero, $\|\cdot\|_{S_\delta}$ converges to the local energy norm, H^1 -semi norm [4]. Exponential rates have been observed for the uniform p -refinements. For the adaptive h -refinements, first- and second-order convergence rates are obtained when $\delta = 0.1$ and 0.00001 , respectively. Moreover, first-order convergence rates are recovered when both δ and h go to zero and the observed convergence is independent of the coupling between δ and h . This shows that the proposed PG method is asymptotically compatible.

For a manufactured solution with a sharp transition region near the boundary, uniform and adaptive h -refinements are considered. For the uniform h -refinements, convergence results in the asymptotic regime agree with what we have observed for a manufactured smooth solution, and they are similar for the two test space norms. For the adaptive h -refinement, optimal convergence rates are recovered in the asymptotic regime for both test space norms. The superiority of $\|\cdot\|_{app,V}$ over $\|\cdot\|_{eng,V}$ is observed in the pre-asymptotic regime. While numerical solutions using $\|\cdot\|_{eng,V}$ suffer from significant oscillations on coarse meshes, we observe little (for larger δ) or no (for smaller δ) oscillations of the numerical solutions by using $\|\cdot\|_{app,V}$.

There are many challenging topics remaining to be addressed in the future. The numerical experiments in this work have been limited to 1d and it would be meaningful to extend this work to higher dimensions. In higher dimensions, it would be more reasonable to look at the ultra-weak formulation [17,21,35] of the nonlocal problem to avoid the inversion of the diffusion operator in the expression of the optimal test norm. The integration error plays a significant role in the

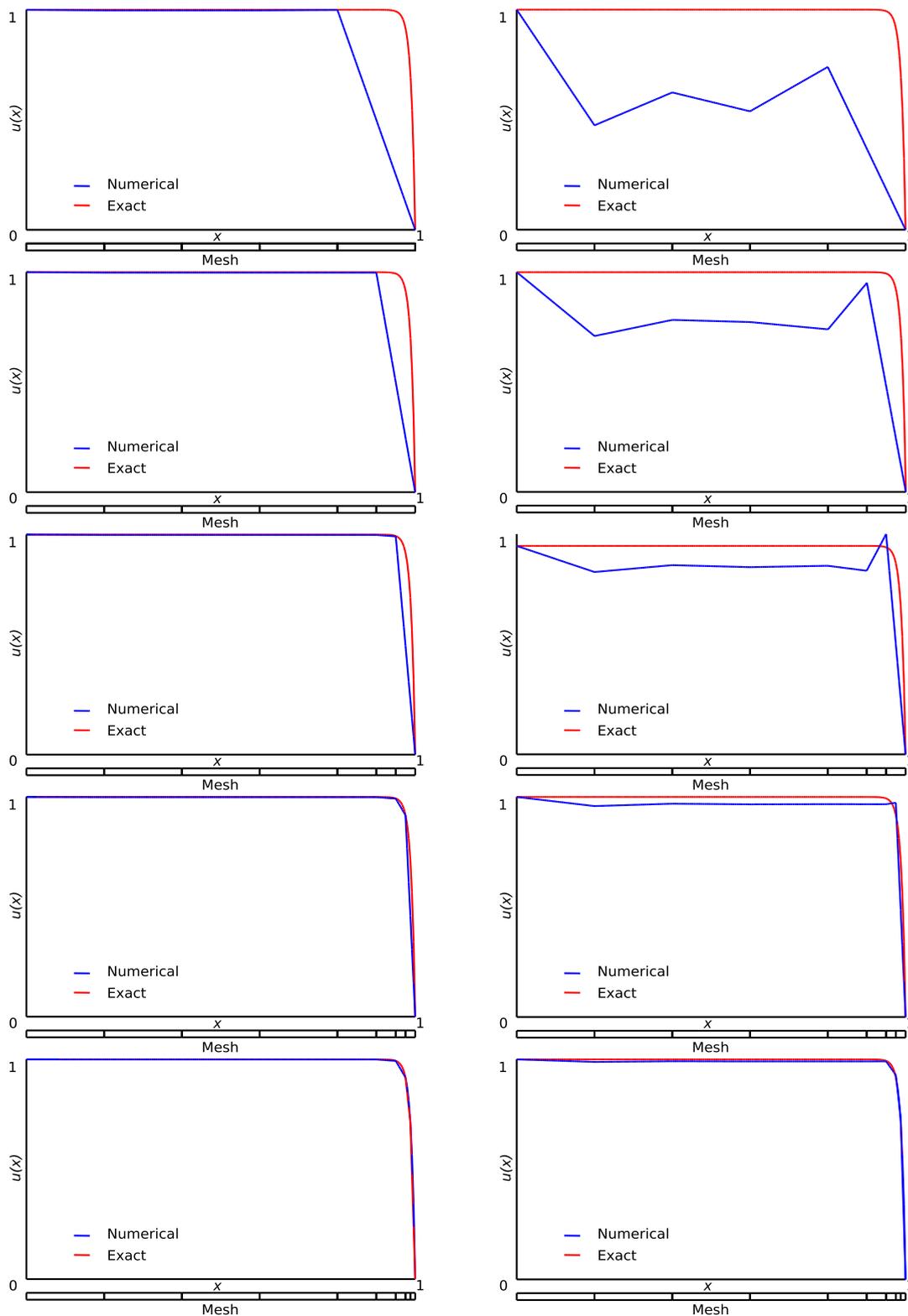


Fig. 7. Evolution of the numerical solution using $\|\cdot\|_{app,v}$ (Left) and $\|\cdot\|_{eng,v}$ (Right) for the test norms to solve the nonlocal convection-dominated diffusion problem with the manufactured solution given in eq. (47). Adaptive h -refinements, $p = 1$, $\delta p = 6$, and $\delta = 0.00001$. (For interpretation of the colors in the figure(s), the reader is referred to the web version of this article.)

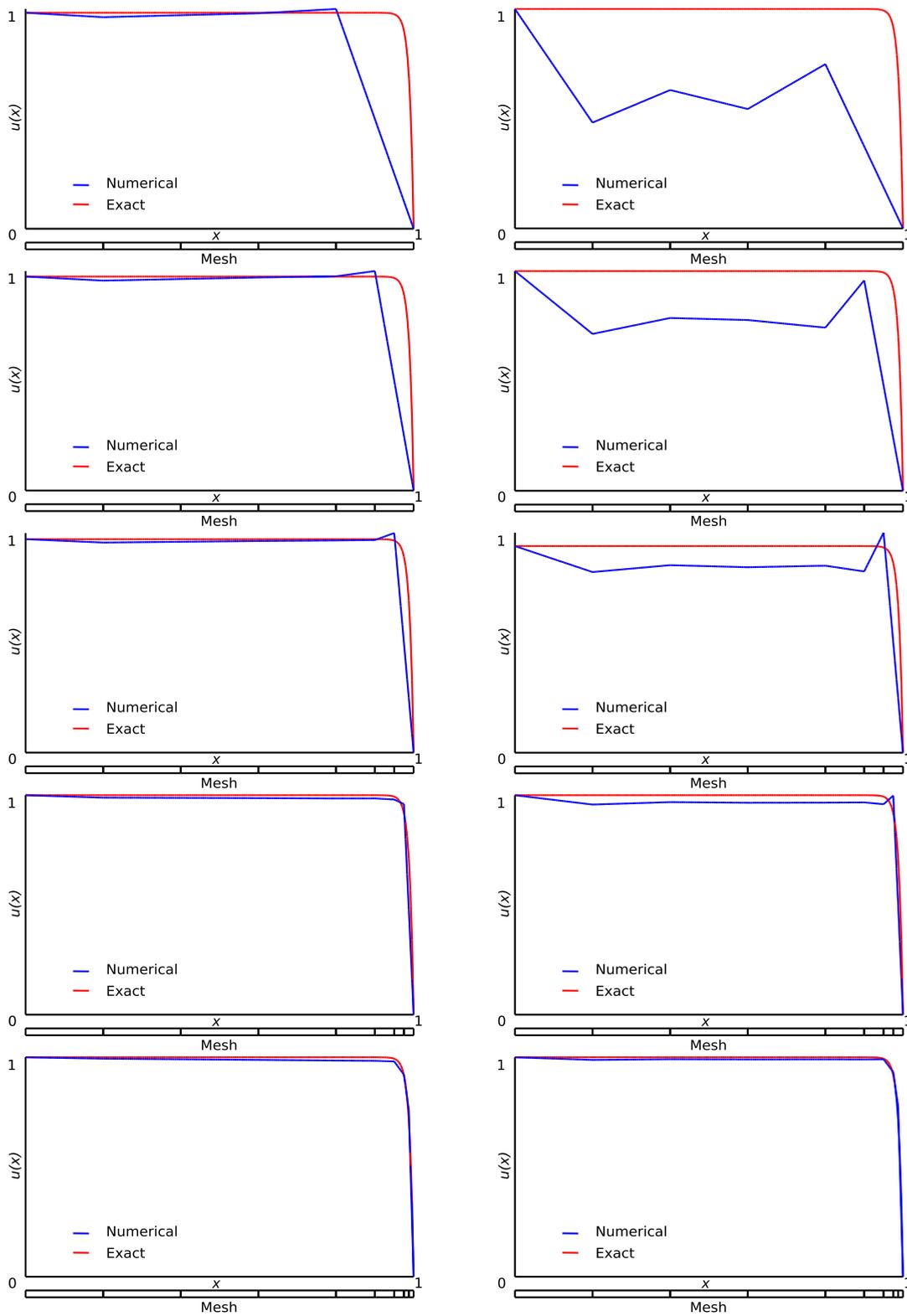


Fig. 8. Evolution of the numerical solution using $\|\cdot\|_{app,v}$ (Left) and $\|\cdot\|_{eng,v}$ (Right) for the test norms to solve the nonlocal convection-dominated diffusion problem with the manufactured solution given in eq. (47). Adaptive h -refinements, $p = 1$, $\delta p = 6$, and $\delta = 0.01$. (For interpretation of the colors in the figure(s), the reader is referred to the web version of this article.)

convergence analysis. The discussions on integration rules for more general kernels and higher dimensions are also critical to guarantee the performance of the PG method as predicted by the theory. Moreover, the perturbation, ϵ , of the diffusion is limited to 0.01 and the polynomial order in test space is chosen ad hoc. Reducing ϵ to smaller values and increasing δ require better practical approximations of the optimal test space norm and more sophisticated strategies, such as the double adaptivity algorithm [17], to choose the polynomial order in the test space so as to guarantee numerical stability.

CRedit authorship contribution statement

- Yu Leng:** Conceptualization, Methodology, Investigation, Writing
- Xiaochuan Tian:** Conceptualization, Methodology, Investigation, Writing, Funding
- Leszek Demkowicz:** Conceptualization, Methodology, Investigation, Writing, Funding
- Hector Gomez:** Funding
- John Foster:** Funding

Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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Appendix A. Manufactured smooth solution

Previous works [60,41] only reported convergence results in L^2 norm. To compare with them and to verify our results, we present additional results of the numerical examples in section 4.4 but the relative errors are measured in L^2 norm.

A.1. Nonlocal limit

This section corresponds to section 4.4.1 for uniform h - and p -, and adaptive h -refinements.

A.1.1. Uniform h -refinements (Tables A.9, A.10)

Table A.9
Relative error in $\|\cdot\|_{L^2(\Omega)}$ and convergence rates using $\|\cdot\|_{app,V}$ for the test norm to solve eq. (44). Uniform h -refinements and $\delta p = 2$. This table corresponds to Table 1.

$10 \times h$	$\delta = 0.1$	$\delta = 0.01$	$\delta = 0.001$	$\delta = 0.0001$
2^1	$7.05 \times 10^{-2} (---)$	$8.76 \times 10^{-2} (---)$	$8.90 \times 10^{-2} (---)$	$8.91 \times 10^{-2} (---)$
2^0	$1.62 \times 10^{-2} (1.82)$	$2.03 \times 10^{-2} (1.80)$	$2.20 \times 10^{-2} (1.72)$	$2.23 \times 10^{-2} (1.71)$
2^{-1}	$3.02 \times 10^{-3} (2.24)$	$4.41 \times 10^{-3} (2.04)$	$5.54 \times 10^{-3} (1.85)$	$5.66 \times 10^{-3} (1.84)$
2^{-2}	$6.64 \times 10^{-4} (2.11)$	$8.89 \times 10^{-4} (2.23)$	$1.37 \times 10^{-3} (1.95)$	$1.43 \times 10^{-3} (1.91)$
2^{-3}	$1.56 \times 10^{-4} (2.06)$	$1.88 \times 10^{-4} (2.20)$	$3.37 \times 10^{-4} (1.98)$	$3.53 \times 10^{-4} (1.98)$
2^{-4}	$3.77 \times 10^{-5} (2.03)$	$4.14 \times 10^{-5} (2.16)$	$8.12 \times 10^{-5} (2.03)$	$8.83 \times 10^{-5} (1.98)$
2^{-5}	$9.27 \times 10^{-6} (2.01)$	$9.55 \times 10^{-6} (2.11)$	$1.89 \times 10^{-5} (2.09)$	$2.20 \times 10^{-5} (1.99)$
2^{-6}	$2.30 \times 10^{-6} (2.01)$	$2.32 \times 10^{-6} (2.04)$	$4.18 \times 10^{-6} (2.17)$	$5.42 \times 10^{-6} (2.02)$
2^{-7}	$5.73 \times 10^{-7} (2.00)$	$5.74 \times 10^{-7} (2.01)$	$9.42 \times 10^{-7} (2.15)$	$1.36 \times 10^{-6} (1.99)$

Table A.10
Relative error in $\|\cdot\|_{L^2(\Omega)}$ and convergence rates using $\|\cdot\|_{eng,V}$ for the test norm to solve eq. (44). Uniform h -refinements and $\delta p = 2$. This table corresponds to Table 2.

$10 \times h$	$\delta = 0.1$	$\delta = 0.01$	$\delta = 0.001$	$\delta = 0.0001$
2^1	$8.69 \times 10^{-2} (---)$	$1.05 \times 10^{-1} (---)$	$1.06 \times 10^{-1} (---)$	$1.07 \times 10^{-1} (---)$
2^0	$1.68 \times 10^{-2} (2.03)$	$2.69 \times 10^{-2} (1.68)$	$2.78 \times 10^{-2} (1.66)$	$2.79 \times 10^{-2} (1.65)$
2^{-1}	$3.11 \times 10^{-3} (2.26)$	$6.44 \times 10^{-3} (1.91)$	$7.04 \times 10^{-3} (1.84)$	$7.03 \times 10^{-3} (1.84)$
2^{-2}	$6.71 \times 10^{-4} (2.13)$	$1.44 \times 10^{-3} (2.08)$	$1.77 \times 10^{-3} (1.92)$	$1.71 \times 10^{-3} (1.96)$
2^{-3}	$1.56 \times 10^{-4} (2.07)$	$2.86 \times 10^{-4} (2.29)$	$4.34 \times 10^{-4} (1.99)$	$4.43 \times 10^{-4} (1.92)$
2^{-4}	$3.77 \times 10^{-5} (2.03)$	$5.15 \times 10^{-5} (2.45)$	$1.00 \times 10^{-4} (2.10)$	$1.14 \times 10^{-4} (1.94)$
2^{-5}	$9.27 \times 10^{-6} (2.01)$	$1.04 \times 10^{-5} (2.30)$	$2.25 \times 10^{-5} (2.15)$	$2.71 \times 10^{-5} (2.06)$
2^{-6}	$2.30 \times 10^{-6} (2.01)$	$2.38 \times 10^{-6} (2.12)$	$4.55 \times 10^{-6} (2.30)$	$6.48 \times 10^{-6} (2.06)$
2^{-7}	$5.73 \times 10^{-7} (2.00)$	$5.78 \times 10^{-7} (2.04)$	$9.27 \times 10^{-7} (2.29)$	$1.66 \times 10^{-6} (1.97)$

A.1.2. Uniform p -refinements (Tables A.11–A.14)

Table A.11

Relative error in $\|\cdot\|_{L^2(\Omega)}$ and convergence rates using $\|\cdot\|_{\text{app},V}$ for the test norm to solve eq. (44). Uniform p -refinements and $\delta p = 2$. This table corresponds to Table 3.

N	$\delta = 0.1$	$\delta = 0.01$	$\delta = 0.001$	$\delta = 0.0001$
4	7.05×10^{-2} (--)	8.76×10^{-2} (--)	1.29×10^{-1} (--)	1.29×10^{-1} (--)
9	4.59×10^{-3} (3.37)	4.01×10^{-3} (3.80)	6.07×10^{-3} (3.77)	6.07×10^{-3} (3.77)
14	9.13×10^{-5} (8.87)	1.06×10^{-4} (8.23)	3.12×10^{-4} (6.72)	3.12×10^{-4} (6.72)
19	1.87×10^{-6} (12.73)	2.0414×10^{-6} (12.94)	2.05×10^{-6} (16.46)	2.05×10^{-6} (16.46)

Table A.12

Relative error in $\|\cdot\|_{L^2(\Omega)}$ and convergence rates using $\|\cdot\|_{\text{app},V}$ for the test norm to solve eq. (44). Uniform p -refinements and $\delta p = 3$. This table corresponds to Table 4.

N	$\delta = 0.1$	$\delta = 0.01$	$\delta = 0.001$	$\delta = 0.0001$
4	6.87×10^{-2} (--)	8.62×10^{-2} (--)	1.26×10^{-1} (--)	1.26×10^{-1} (--)
9	4.67×10^{-3} (3.32)	4.00×10^{-3} (3.79)	5.84×10^{-3} (3.79)	5.83×10^{-3} (3.79)
14	9.18×10^{-5} (8.89)	1.09×10^{-4} (8.16)	3.02×10^{-4} (6.70)	3.02×10^{-4} (6.70)
19	1.88×10^{-6} (12.74)	2.02×10^{-6} (13.06)	2.03×10^{-6} (16.38)	2.03×10^{-6} (16.37)

Table A.13

Relative error in $\|\cdot\|_{L^2(\Omega)}$ and convergence rates using $\|\cdot\|_{\text{eng},V}$ for the test norm to solve eq. (44). Uniform p -refinements and $\delta p = 2$. This table corresponds to Table 5.

N	$\delta = 0.1$	$\delta = 0.01$	$\delta = 0.001$	$\delta = 0.0001$
4	8.69×10^{-2} (--)	1.05×10^{-1} (--)	1.54×10^{-1} (--)	1.54×10^{-1} (--)
9	5.06×10^{-3} (3.51)	7.22×10^{-3} (3.30)	8.99×10^{-3} (3.50)	8.98×10^{-3} (3.50)
14	9.71×10^{-5} (8.95)	1.72×10^{-4} (8.45)	5.01×10^{-4} (6.54)	5.00×10^{-4} (6.54)
19	1.85×10^{-6} (12.97)	1.74×10^{-6} (14.87)	1.84×10^{-6} (18.36)	1.84×10^{-6} (18.35)

Table A.14

Relative error in $\|\cdot\|_{L^2(\Omega)}$ and convergence rates using $\|\cdot\|_{\text{eng},V}$ for the test norm to solve eq. (44). Uniform p -refinements and $\delta p = 3$. This table corresponds to Table 6.

N	$\delta = 0.1$	$\delta = 0.01$	$\delta = 0.001$	$\delta = 0.0001$
4	8.52×10^{-2} (--)	1.04×10^{-1} (--)	1.54×10^{-1} (--)	1.54×10^{-1} (--)
9	5.01×10^{-3} (3.49)	7.20×10^{-3} (3.30)	8.99×10^{-3} (3.50)	8.98×10^{-3} (3.50)
14	9.76×10^{-5} (8.91)	1.72×10^{-4} (8.45)	5.01×10^{-4} (6.54)	5.00×10^{-4} (6.54)
19	1.85×10^{-6} (12.99)	1.84×10^{-6} (14.85)	1.84×10^{-6} (18.35)	1.84×10^{-6} (18.35)

A.1.3. Adaptive h -refinements (Fig. A.9)

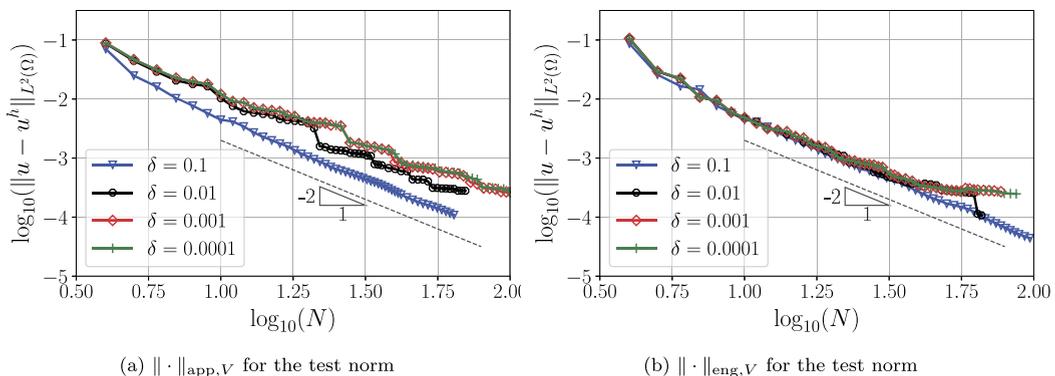


Fig. A.9. Convergence profile (relative error) using $\|\cdot\|_{\text{app},V}$ and $\|\cdot\|_{\text{eng},V}$ for the test norms to solve eq. (44). Adaptive h -refinements and $\delta p = 2$. This figure corresponds to Fig. 2.

A.2. Local limit

This section corresponds to section 4.4.2 (see Tables A.15, A.16).

Table A.15
Relative error in $\|\cdot\|_{L^2(\Omega)}$ and convergence rates using $\|\cdot\|_{\text{opt},V}$ for the test norm to solve eq. (46). Uniform h -refinements. Uniform p -refinements and $\delta p = 2$. This table corresponds to Table 7.

$10 \times h$	$\delta = h$	$\delta = 2h$	$\delta = h^2$	$\delta = \sqrt{h}$
2^1	$2.28 \times 10^{-1}(-)$	$1.59 \times 10^0(-)$	$7.97 \times 10^{-2}(-)$	$7.40 \times 10^0(-)$
2^0	$4.68 \times 10^{-2}(1.95)$	$2.25 \times 10^{-1}(2.41)$	$2.02 \times 10^{-2}(1.69)$	$2.82 \times 10^0(1.19)$
2^{-1}	$9.73 \times 10^{-3}(2.10)$	$3.51 \times 10^{-2}(2.49)$	$5.30 \times 10^{-3}(1.79)$	$9.88 \times 10^{-1}(1.40)$
2^{-2}	$1.86 \times 10^{-3}(2.30)$	$7.29 \times 10^{-3}(2.18)$	$1.39 \times 10^{-3}(1.86)$	$2.98 \times 10^{-1}(1.67)$
2^{-3}	$3.42 \times 10^{-4}(2.40)$	$1.63 \times 10^{-3}(2.13)$	$3.51 \times 10^{-4}(1.95)$	$1.12 \times 10^{-1}(1.39)$
2^{-4}	$7.05 \times 10^{-5}(2.26)$	$3.64 \times 10^{-4}(2.14)$	$9.16 \times 10^{-5}(1.92)$	$4.44 \times 10^{-2}(1.32)$
2^{-5}	$1.61 \times 10^{-5}(2.12)$	$8.68 \times 10^{-5}(2.06)$	$2.30 \times 10^{-5}(1.98)$	$1.92 \times 10^{-2}(1.21)$
2^{-6}	$3.88 \times 10^{-6}(2.05)$	$2.14 \times 10^{-5}(2.01)$	$5.77 \times 10^{-6}(1.99)$	$8.77 \times 10^{-3}(1.13)$
2^{-7}	$9.52 \times 10^{-7}(2.02)$	$5.34 \times 10^{-6}(2.00)$	$1.44 \times 10^{-6}(2.00)$	$4.17 \times 10^{-3}(1.07)$

Table A.16
Relative error in $\|\cdot\|_{L^2(\Omega)}$ and convergence rates using $\|\cdot\|_{\text{eng},V}$ for the test norm to solve eq. (46). Uniform h -refinements. Uniform p -refinements and $\delta p = 2$. This table corresponds to Table 8.

$10 \times h$	$\delta = h$	$\delta = 2h$	$\delta = h^2$	$\delta = \sqrt{h}$
2^1	$1.56 \times 10^{-1}(-)$	$1.27 \times 10^0(-)$	$1.01 \times 10^{-1}(-)$	$7.04 \times 10^0(-)$
2^0	$3.15 \times 10^{-2}(1.97)$	$1.83 \times 10^{-1}(2.39)$	$2.69 \times 10^{-2}(1.63)$	$2.41 \times 10^0(1.32)$
2^{-1}	$6.42 \times 10^{-3}(2.13)$	$2.78 \times 10^{-2}(2.52)$	$6.97 \times 10^{-3}(1.81)$	$9.26 \times 10^{-1}(1.28)$
2^{-2}	$1.37 \times 10^{-3}(2.15)$	$5.57 \times 10^{-3}(2.23)$	$1.79 \times 10^{-3}(1.89)$	$2.88 \times 10^{-1}(1.63)$
2^{-3}	$3.21 \times 10^{-4}(2.06)$	$1.34 \times 10^{-3}(2.02)$	$4.49 \times 10^{-4}(1.96)$	$1.09 \times 10^{-1}(1.38)$
2^{-4}	$7.92 \times 10^{-5}(2.00)$	$3.41 \times 10^{-4}(1.96)$	$9.97 \times 10^{-5}(2.15)$	$4.34 \times 10^{-2}(1.31)$
2^{-5}	$1.98 \times 10^{-5}(1.99)$	$8.69 \times 10^{-5}(1.96)$	$2.64 \times 10^{-5}(1.91)$	$1.88 \times 10^{-2}(1.20)$
2^{-6}	$4.95 \times 10^{-6}(1.99)$	$2.20 \times 10^{-5}(1.98)$	$6.83 \times 10^{-6}(1.95)$	$8.65 \times 10^{-3}(1.12)$
2^{-7}	$1.24 \times 10^{-6}(2.00)$	$5.52 \times 10^{-6}(1.99)$	$1.74 \times 10^{-6}(1.97)$	$4.13 \times 10^{-3}(1.07)$

Appendix B. Manufactured solution with a sharp gradient transition

Additional convergence results measured in L^2 norm of the numerical examples in section 4.5 are shown in this section.

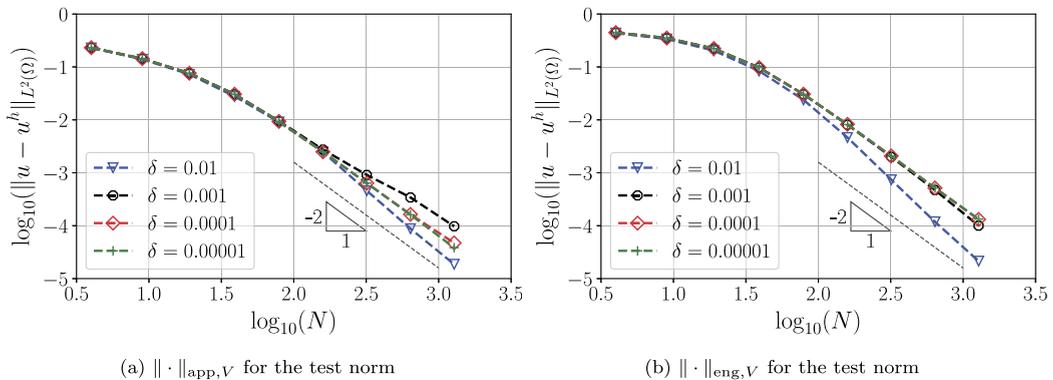


Fig. B.10. Convergence profile (relative error) using $\|\cdot\|_{\text{app},V}$ and $\|\cdot\|_{\text{eng},V}$ for the test norms to solve the nonlocal convection-dominated diffusion problem with the manufactured solution given in eq. (47). Uniform h -refinements and $\delta p = 6$. This figure corresponds to Fig. 4.

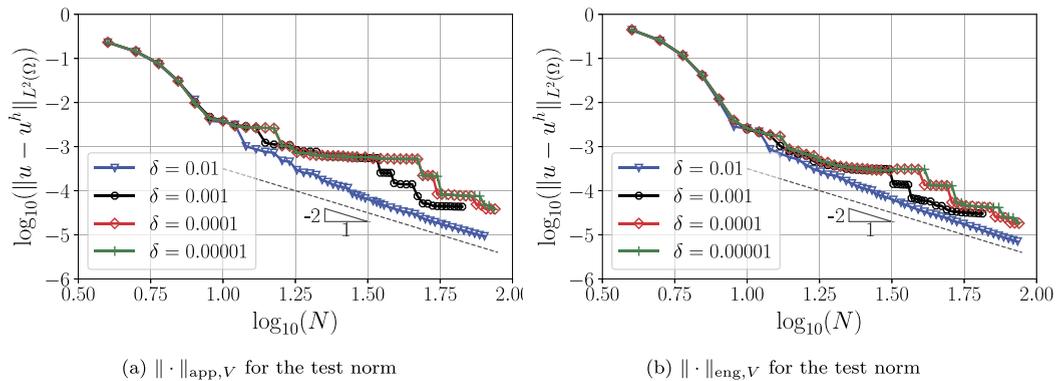


Fig. B.11. Convergence profile (relative error) using $\|\cdot\|_{\text{app},V}$ and $\|\cdot\|_{\text{eng},V}$ for the test norms to solve the nonlocal convection-dominated diffusion problem with the manufactured solution given in eq. (47). Adaptive h -refinements and $\delta p = 6$. This figure corresponds to Fig. 5.

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