

AutomaDeD: Automata-Based Debugging for Dissimilar Parallel Tasks

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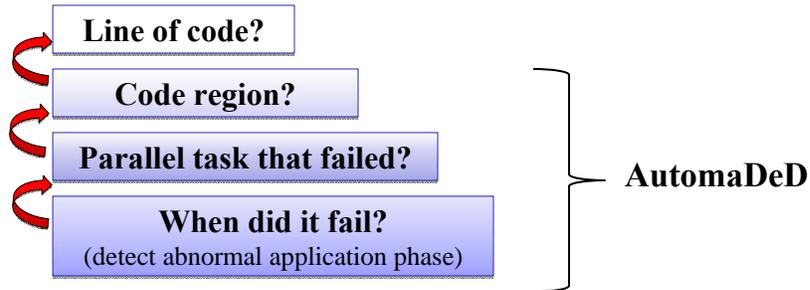
Debugging Large-Scale Parallel Applications is Challenging

- Large systems will have millions of cores in near future
 - Increased difficulty for developing correct HPC applications
 - Traditional debuggers don't perform well at this scale
- Faults come from various sources
 - Hardware: soft errors, physical degradation, design bugs
 - Software: coding bugs, misconfigurations



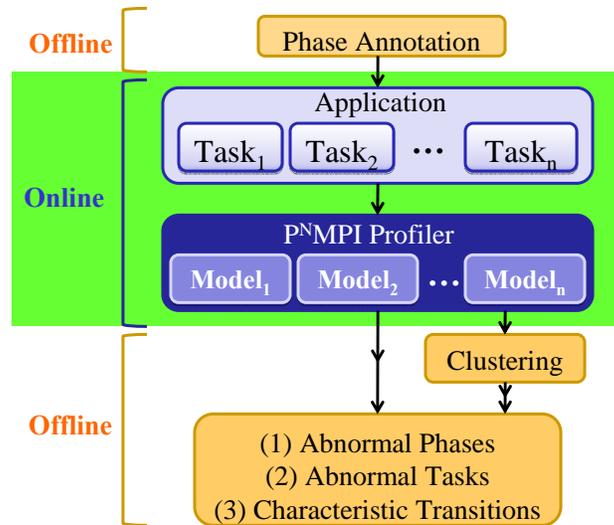
Developer Steps When Debugging a Parallel Application

Questions a developer has to answer when an application fails:

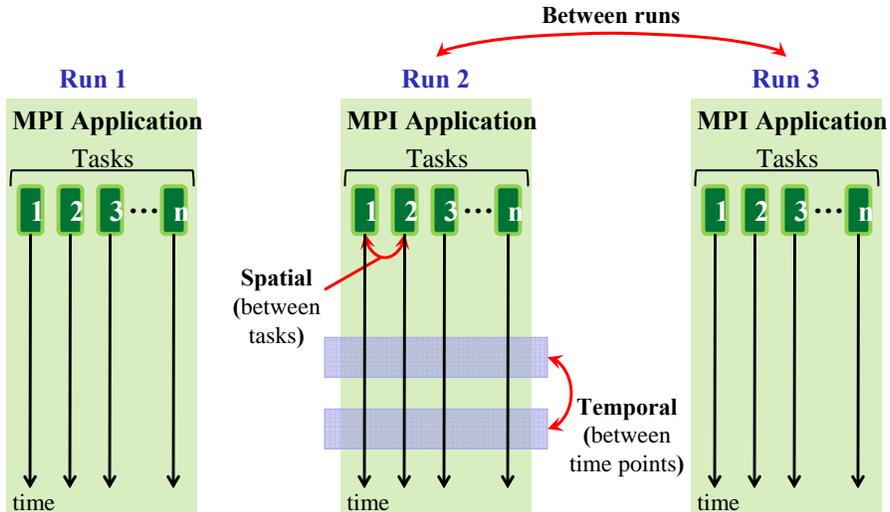


- Need for tools to help developers find root cause quickly

AutomaDeD's Error Detection Approach

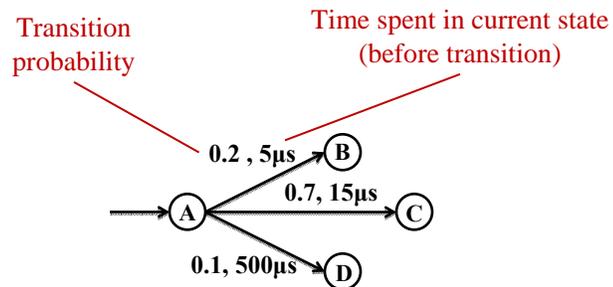


Types of Behavioral Differences



Semi-Markov Models (SMM)

- Like a Markov model but with *time* between transitions
 - Nodes: *application states*
 - Edges: *transitions from one state to another*



SMM Represents Task Control Flow

- States correspond to:
 - Calls to MPI routines
 - Code between MPI routines

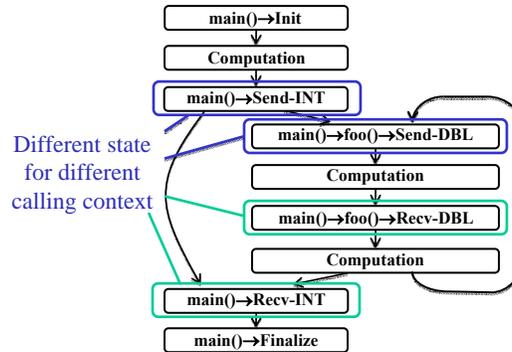
Application Code

```

main() {
  MPI_Init()
  ... Computation ...
  MPI_Send(..., 1, MPI_INTEGER, ...);
  for(...)
    foo();
  MPI_Recv(..., 1, MPI_INTEGER, ...);
  MPI_Finalize();
}

foo() {
  MPI_Send(..., 1024, MPI_DOUBLE, ...);
  ...Computation...
  MPI_Recv(..., 1024, MPI_DOUBLE, ...);
  ...Computation...
}
    
```

Semi-Markov Model

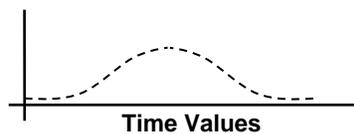


Two Approaches for Time Density Estimation: Parametric and Non-parametric



Gaussian Distribution
(Parametric model)

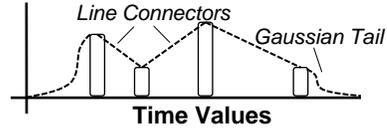
Density Function



- Cheaper
- Lower Accuracy

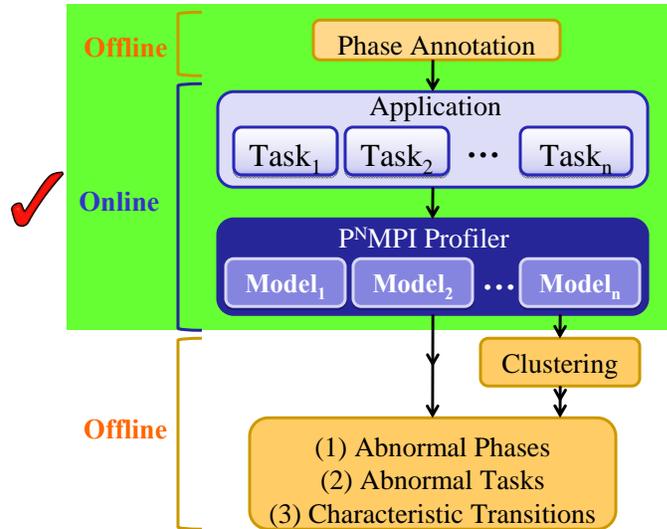
Histograms
(Non-parametric model)

Bucket Counts



- More Expensive
- Greater Accuracy

AutomaDeD's Error Detection Approach



User's Phase Annotations

Sample Code:

```

main() {
  MPI_Init()
  ... Computation ...
  MPI_Send(..., MPI_INTEGER, ...);
  MPI_Pcontrol();
  for(...) {
    MPI_Send(..., MPI_DOUBLE, ...);
    ...Computation...
    MPI_Recv(..., MPI_DOUBLE, ...);
  }
  MPI_Pcontrol();
  ...Computation...
  MPI_Recv(..., MPI_INTEGER, ...);
  MPI_Finalize();
  MPI_Pcontrol();
}
  
```

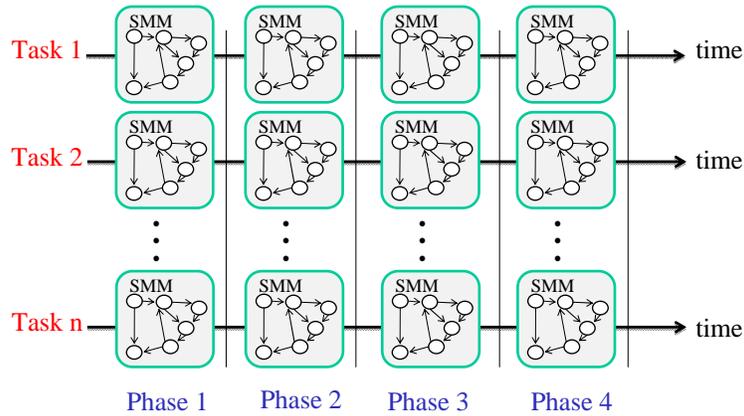
Phase 1

Phase 2

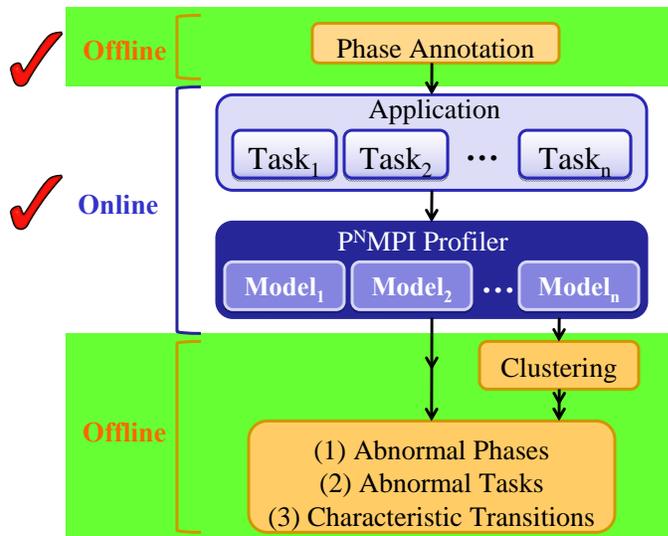
Phase 3

- Phases denote dynamically repeated regions of execution
- Developers annotate phases in the code
 - MPI_Pcontrol is intercepted by wrapper library

A Semi-Markov Model per Task, per Phase



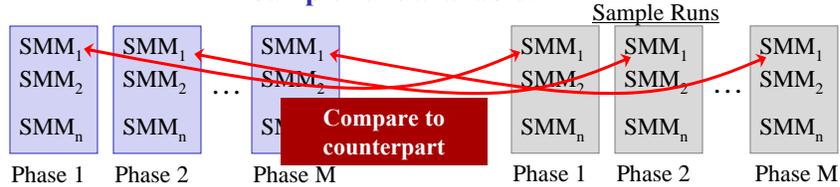
AutomaDeD's Error Detection Approach



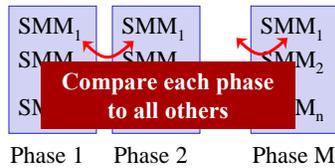
Faulty Phase Detection: Find the Time Period of Abnormal Behavior

- **Goal:** find phase that differs the most from other phases

Sample runs available:



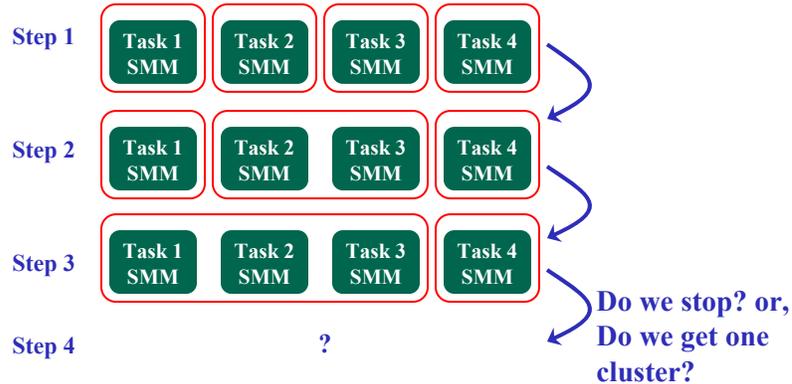
Without sample runs:



Clustering Tasks' Models: Hierarchical Agglomerative Clustering (HAC)

$$Diss(SMM_1, SMM_2) = L2 \text{ Norm (Transition prob.)} + L2 \text{ Norm (Time prob.)}$$

Each task starts in its own cluster



We need a *threshold* to decide when to stop

How To Select The Number Of Clusters

Option 1:

- User provides application's natural cluster count k

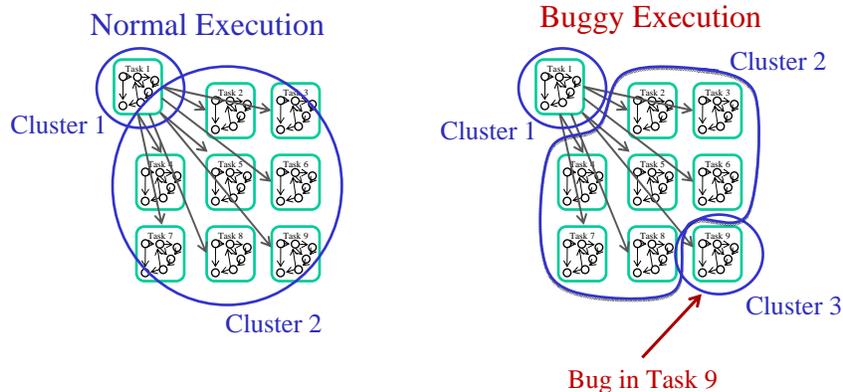
Option 2:

- Use sample runs to compute clustering threshold τ that produces k clusters
 - Use sample runs if available
 - Otherwise, compute τ from start of execution
 - Threshold based on highest increased in dissimilarity
- During real runs, cluster tasks using threshold τ

Cluster Isolation Example

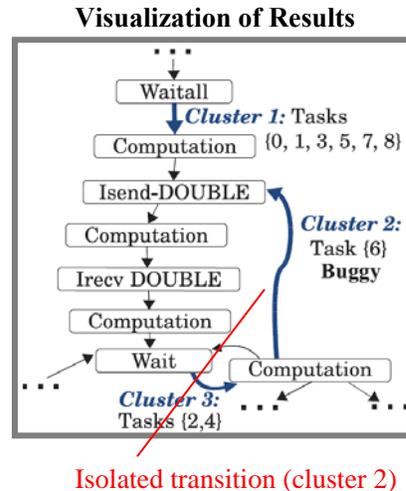
Cluster Isolation: *to separate buggy task in unusual cluster*

Master-Worker Application Example



Transition Isolation: Erroneous Code Region Detection

- **Method 1:**
 - Find *edge* that distinguishes faulty cluster from the others
 - **Recall:** SMM dissimilarity is based on L2 norm of edge's parameters
- **Method 2:**
 - Find *unusual individual edge*
 - Edge that takes unusual amount of time (compared to observed times)



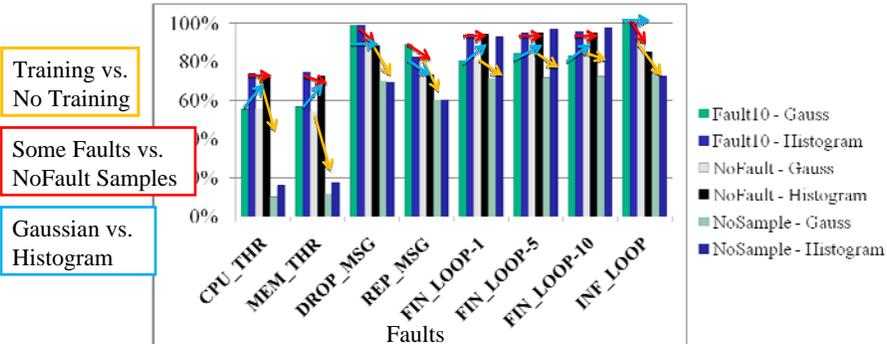
Fault Injection

- **NAS Parallel Benchmarks:**
 - BT, CG, FT, MG, LU and SP
 - 16 tasks, Class A (input)
- **2000 injection experiments per application:**

Name	Description
FIN_LOOP	Local livelock/deadlock (delay 1,5, 10 sec)
INF_LOOP	Transient stall (infinite loop)
DROP_MESG	MPI message loss
REP_MESG	MPI message duplication
CPU_THR	CPU-intensive thread
MEM_THR	Memory-intensive thread

Phase Detection Accuracy

- ~90% for Loops and Message drops
- ~60% for Extra threads
 - Training = sample runs available
 - Training significantly better than no training
 - Histograms better than Gaussians

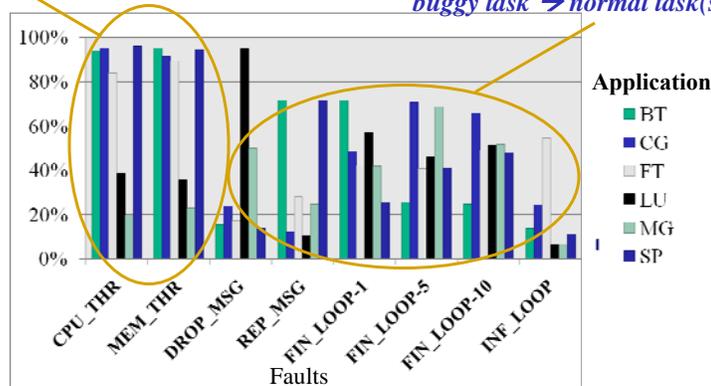


Cluster Isolation Accuracy: Isolating the abnormal task(s)

- Results assume phase detected accurately
- Accuracy of *Cluster Isolation* highly variable

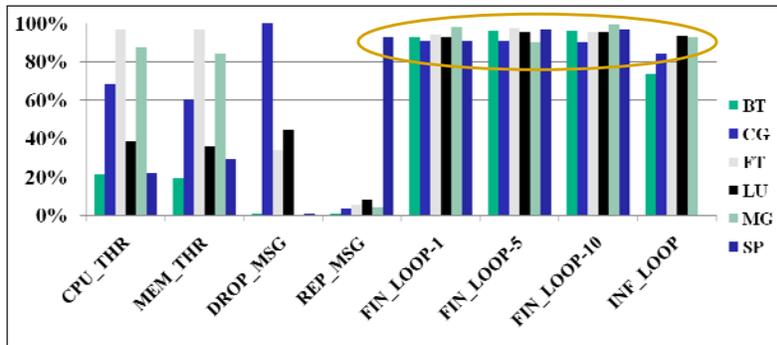
Accuracy up to 90% for extra threads

Poor detection elsewhere because of fault propagation: *buggy task* → *normal task(s)*



Transition Isolation

- Injected transition in top 5 candidates
 - Accuracy ~90% for loop faults
 - Highly variable for others
 - Less variable if event order information is used



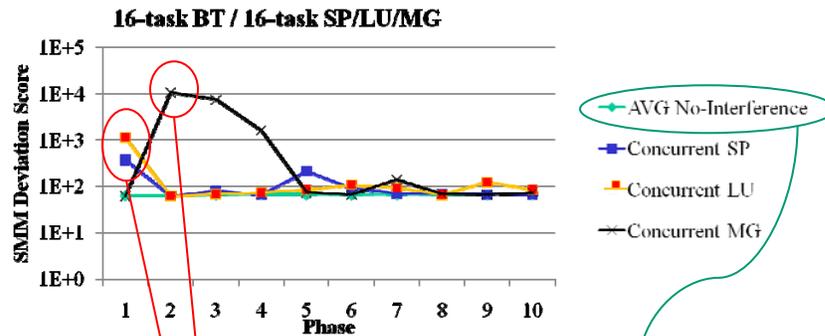
MVAPICH Bug

- Job execution script failed to clean up at job end
 - MPI tasks executer (`mpirun`, version 0.9.9)
 - Left runaway processes on nodes
- Simulation:
 - Execute **BT** (affected application)
 - Run concurrently runaway applications (**LU**, **MG** or **SP**)
 - Runaway tasks interfere with normal **BT** execution



MVAPICH Bug Results: SMMs Deviation Scores in Affected Application

Affected application: BT benchmark
Interfering applications: SP, LU, MG benchmarks



Abnormal phase detected in phase 1 in SP and LU, and in phase 2 in MG

Constant (average) SMM difference in regular BT runs

Concluding Remarks

- **Contributions:**
 - Novel way to model and compare parallel tasks' behavior
 - Focuses debugging efforts on time period, tasks and code region where bug is first manifested
 - Accuracy up to ~90% for phase detection, cluster and transition isolation (delays and hangs)
- **Ongoing work:**
 - Scaling implementation to work on millions of tasks
 - Improving accuracy through different statistical models (e.g., Kernel Density Estimation, Gaussian Mixture Models)