

Sleep/Wake Aware Local Monitoring (SLAM)

Issa Khalil , Saurabh Bagchi, Ness Shroff

Dependable Computing Systems Lab (DCSL) &
Center for Wireless Systems and Applications (CWSA)
School of Electrical and Computer Engineering
Purdue University



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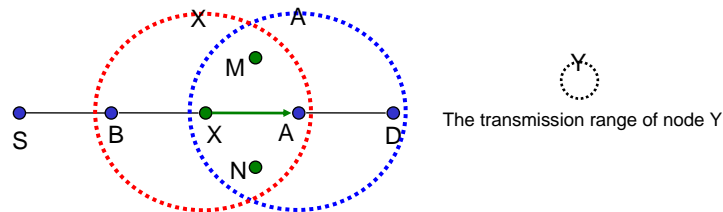
Outline

- **Introduction**
 - Motivation
 - Background: local monitoring
 - Goal and challenge
 - Solution approach
- Sleep/wake aware local monitoring (SLAM)
 - Assumptions and Sleep-Wake Mechanisms
 - On-demand SLAM: Protocol Description
 - Protocol analysis
 - Simulation results Conclusion

Motivation

- Overhearing in wireless media serves as a primitive building block for collecting information and evidence about network activities
- Target: **Wireless Ad Hoc and Sensor (WAHAS) Networks**
- Overhearing is used for many security applications in WAHAS networks
 - Intrusion detection
 - Building trust and reputation among nodes
 - Building secure routing protocols
 - Local monitoring (our work)

Background: Local Monitoring

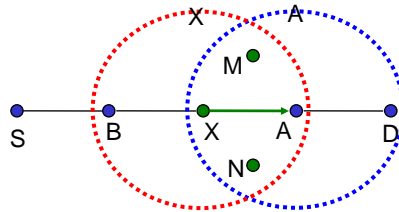


- A collaborative detection strategy in which a node monitors the traffic going in and out of its neighbors.
- Assumptions
 - Each node knows its first-hop and second-hop neighbors
 - Requires each node to include the ID of the prev-hop in the forwarded packet
- A *guard* of a node A over the link $X \rightarrow A$ is any node that lies within the transmission range of both X and A
 - Example: M, X, and N are the guards of node A for the link from X to A

Background: Local Monitoring

- Local monitoring can be used to detect different kinds of attacks by different kinds of checks on the incoming and outgoing traffic
- Local monitoring provides the building block for detecting the following malicious actions

- Fabrication
- Modification
- Delay
- Drop
- Misrouting



Goal and Challenge

- Overhearing in local monitoring incurs listening energy cost
 - Guards have to be awake all the time
 - Listening energy is a dominant source of energy consumption and is therefore critical in energy constrained WAAAS networks
- Goal of this work: Minimize energy overhead of monitoring
- Challenge: Perform the sleep/wake of guards securely and efficiently
 - Required guards to monitor a communication should be woken up
 - Quality of detection should not be significantly affected

Solution Approach

- We design a protocol called **Sleep/wake Aware Local Monitoring (SLAM)**
 - Wake up guards only when needed
 - Verify that a node is waking up guards as needed
- **Contributions**
 - Conserve energy through sleep/wake aware local monitoring
 - Provide on-demand sleep/wake algorithm
 - Demonstrate the security coverage is not reduced due to the energy conserving mode of SLAM
 - Evaluate SLAM through extensive simulations and analysis

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Assumptions & Attack Model

- **System assumptions**
 - Static network
 - Bi-directional links
 - Existing key management protocol that can distributed pairwise symmetric keys to any two nodes
 - Each node is equipped with passive or low-power wakeup antenna
- **Attack Model**
 - The adversary may not follow the sleep/wake protocol
 - The adversary may not provide the detection according to local monitoring
 - Adversary nodes may collude
 - The adversary can be more powerful than legitimate nodes
 - Physical layer attacks (DoS against wakeup antenna, jamming) are out of scope

Sleep/Wake Mechanisms

- **Synchronized sleep/wake**
 - All the nodes wake up and go to sleep in a synchronized manner
 - Examples: S-MAC and SPAN
 - Require accurate time synchronization
 - Wastage of energy in scenarios with rare events
 - **Adaptation:** Guards naturally sleep and wake up when there may be traffic to monitor
- **Application-specific sleep/wake**
 - Protocol for maintaining specific network properties such as k -connectivity or k -coverage
 - **Adaptation:** Change parameters of sleep/wake algorithm, e.g., increase k
- **On-demand sleep/wake**
 - Sleeping nodes are triggered to wake up when needed for communication
 - Requires low-power or passive wakeup antenna
 - **Adaptation:** On-Demand SLAM – Forms the topic of the rest of this presentation

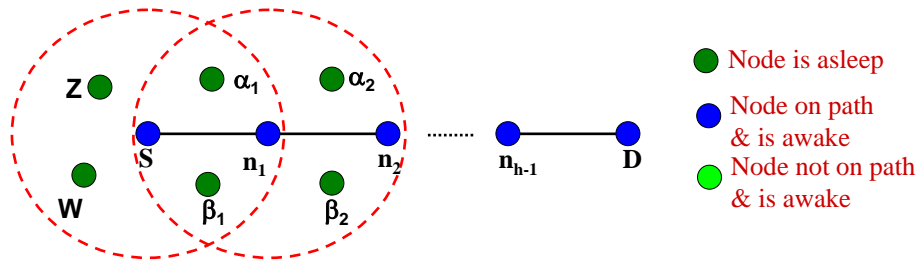
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On-Demand SLAM

- **Node wake up does not depend on assumption of a specific communication pattern**
 - Nodes can be woken up when there is communication
 - Most energy efficient mode of communication
- **Each node has two antennas**
 - **Wakeup antenna**
 - Low-power or passive
 - Low bandwidth
 - Remains awake at all times
 - Available commercially and in research labs
 - **Regular antenna**
 - Always asleep except when triggered for sending/receiving data
 - Used for data communication and has higher power consumption

On-Demand SLAM: Overview



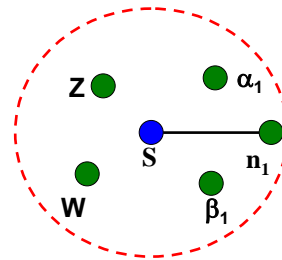
- Initially all the nodes are sleeping
- S wants to send a packet, S wakes up
- S sends a wakeup signal to its one-hop neighbors
- All the one-hop neighbors of S wake up
- Non-guards go back to sleep
- S sends the packet to n_1
- n_1 wakes up its neighbors
- n_1 sends the packet to n_2
- Guards go back to sleep
- The process continues until the packet reaches D

Security of SLAM: Rules of the Guard

- In baseline local monitoring, the responsibility of a guard of n_i over a given link is to verify that:
 - n_i forwards the packet within a time threshold (delay/drop)
 - n_i does not modify the packet it is forwarding (modification)
 - n_i forwards the data to the correct next hop (misrouting)
 - n_i only forwards if a packet is sent on the $n_{i-1} \rightarrow n_i$ link (fabric.)
- SLAM introduces a fifth responsibility
 - n_i should wake up the guards for the communication on the $n_i \rightarrow n_{i+1}$ link *before* forwarding the packet on that link

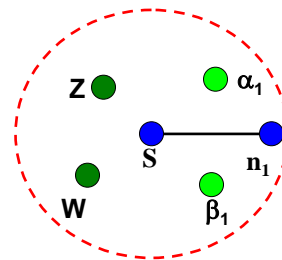
SLAM Variant 1: All-neighbors SLAM (A-SLAM)

- * Wakeup signal broadcast to all the first-hop neighbors
- + Simple communication of wakeup signal
- + Knowledge of node location is not required
- Extra energy wasted in waking up irrelevant nodes



SLAM Variant 2: Guards-only SLAM (G-SLAM)

- * Wakeup signal sent only to the relevant nodes (next-hop & guards)
- + More energy efficient
- Requires the knowledge of node locations within twice the transmission range
- Sophisticated wakeup signals and wake up hardware



Reducing End-to-End Delay

- Wakeup antenna has warm-up time which may increase end-to-end delay
- Send the wakeup signal at the earliest possible time
 - Pipeline the process of sending wakeup signal and data traffic
 - Increase the listening energy
- Definitions
 - T_{control} : time to send the wakeup signal
 - T_{warmup} : time to warm-up (sleep to wake)
 - T_{data} : time to send a packet (the worst case time which includes time to send the packet and channel contention)
 - T_w : time a node continues to be awake after being woken up

Reducing End-to-End Delay

- Two different cases
 - Case 1: $T_{\text{control}} + T_{\text{warmup}} < T_{\text{data}}$ (common case)
$$\Omega_{\text{SLAM-Add}}(h) = \Omega_{\text{SLAM}}(h) - \Omega_{\text{Base-LM}}(h) = T_{\text{control}} + T_{\text{warmup}}$$
 - Delay is constant independent of number of hops
 - Case 2: $T_{\text{control}} + T_{\text{warmup}} > T_{\text{data}}$
$$\Omega_{\text{SLAM-Add}}(h) = \Omega_{\text{SLAM}}(h) - \Omega_{\text{Base-LM}}(h) = h \cdot \tau + T_{\text{data}}$$
 - Delay is the product of the number of hops and the difference in time between $(T_{\text{control}} + T_{\text{warmup}})$ and T_{data}

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SLAM Coverage: Proof Sketch

- $S \rightarrow n_1 \rightarrow n_2 \rightarrow n_3 \rightarrow \dots \rightarrow n_{h-1} \rightarrow D$
- *Proposition:* SLAM does not cause loss in detection coverage
- *Lemma:* For each n_i in the path from $S \rightarrow D$
 - The guards of n_i (g_i) are awake and monitoring
- *Base case:* S is honest, thus g_1 is awake
- *Inductive hypothesis:* $g_1 \dots g_i$ are woken up
- *Prove:* g_{i+1} is woken up
 - If n_i is honest it wakes up g_{i+1}
 - Else, g_i will wake up g_{i+1}
- *Result:* The required guards are always woken up either directly or indirectly

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 - › Protocol analysis
 - **Simulation results**
 - Simulation setup
 - Effect of fraction of data monitored (f_{dat}) on output metrics
 - Effect of number of malicious nodes (M) on output metrics
 - Effect of traffic load ($1/\mu$) on output metrics
 - Energy savings
- › Conclusion

Simulations: Simulation Setup

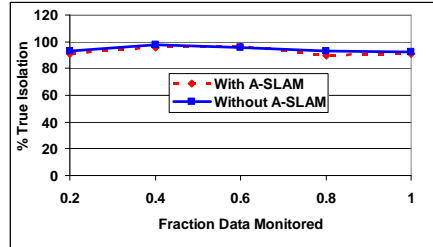
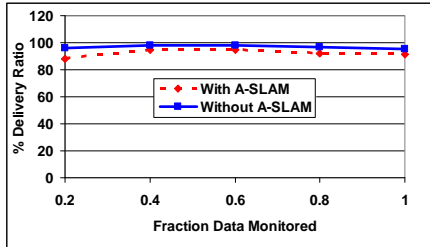
- **Data communication model: any node to any node**
- **Node distribution: Randomly on a fixed-size field**
- **Attack model**
 - Attacker nodes are internal compromised nodes randomly selected from network
 - Colluding nodes establish a wormhole, then perform selective forwarding
- **Two scenarios**
 - Local monitoring with A-SLAM
 - Local monitoring without A-SLAM (baseline)
- **The network simulator ns-2 is used**
- **The output parameters are measured at the end of simulation time (1500 s)**

Effect of Fraction of Data Monitored (f_{dat})

% Delivery ratio = % (Packets received/Packets sent)

% True Isolation = % (# malicious nodes completely isolated/# malicious nodes)

Inputs: $M = 4$; $N = 100$; $1/\mu = 0.1$ packets/s; $T_{\text{warmup}} = 5\text{ms}$, $T_w = 30\text{ms}$



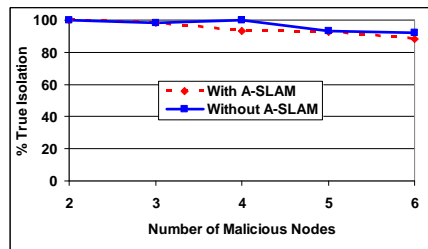
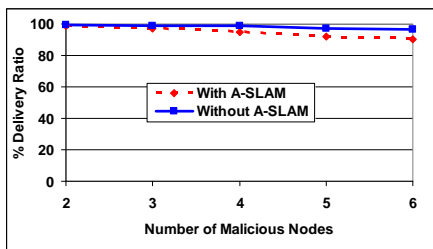
- High delivery ratio & high detection coverage even with the existence of attack
- Changing f_{dat} does not significantly change output metrics due to adaptive detection strategy
- Applying sleeping through SLAM does not significantly degrade the coverage or the delivery ratio

Effect of # Malicious Nodes (M)

% Delivery ratio = % (Packets received/Packets sent)

% True Isolation = % (# malicious nodes completely isolated/# malicious nodes)

Inputs: $f_{\text{dat}} = 0.6$; $N = 100$; $1/\mu = 0.1$ packets/s; $T_{\text{warmup}} = 5\text{ms}$, $T_w = 30\text{ms}$



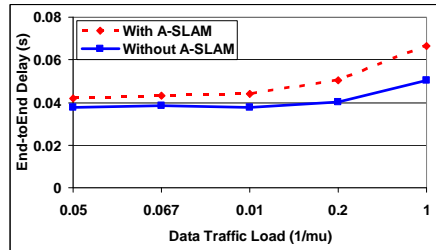
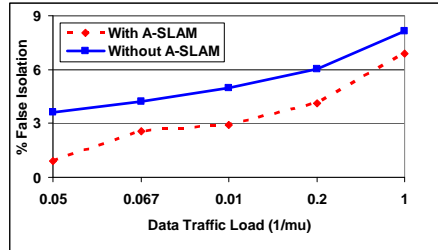
- As M increases, delivery ratio slightly decreases due to the increase in the traffic dropped by malicious nodes before being detected
- As M increases, coverage slightly decreases due to less number of good guards and increase in the probability that a malicious node is at the network's edge
- SLAM performs comparably to baseline local monitoring

Effect of Traffic Load ($1/\mu$)

% False isolation = % (# good nodes isolated/# nodes)

End-to-end delay = time of receive – time of transmit

Inputs: $M = 4$; $N = 100$; $f_{\text{dat}} = 0.6$ packets/s; $T_{\text{warmup}} = 5\text{ms}$, $T_w = 30\text{ms}$

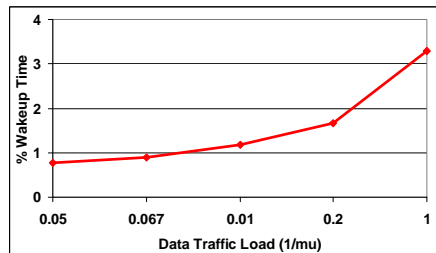
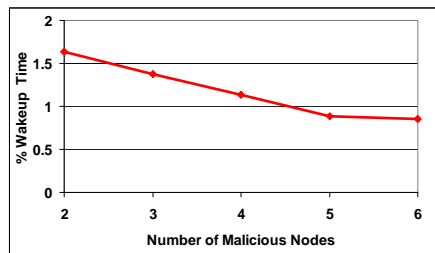


- As traffic load increases, false isolation increases due to increasing collisions
- As traffic load increases, end-to-end delay increases due to increasing channel contention
- SLAM has lower false isolation since some of the packets that may falsely identify a node as malicious may be dropped due to *erroneous sleep*
- End-to-end delay increases in SLAM with higher contention due to increase in the warm-up time

Listening Energy due to A-SLAM

% Wakeup time = % (time a node spent wake up solely for monitoring/total simulation time)

Inputs: $f_{\text{dat}} = 0.6$; $M = 4$; $N = 100$; $1/\mu = 0.1$ packets/s; $T_{\text{warmup}} = 5\text{ms}$, $T_w = 30\text{ms}$



- The wakeup fraction is very small with SLAM
- As M increases, the wakeup time decrease due to the decrease in the number of packets that require monitoring
- As the traffic load increases, the wakeup time increases due to the increase in the number of packets that require monitoring

Conclusion

- Present a modified version of local monitoring
 - Sleep/wake aware local monitoring
 - On-demand sleep/wake mechanism called SLAM proposed
- Provide security analysis of SLAM
 - Does not weaken network security
- Provide end-to-end delay and energy analysis of SLAM
 - Fixed increase in the end-to-end delay may be achieved
 - Considerable energy savings compared to the vanilla version
- Provide extensive simulations to evaluate SLAM performance
 - Comparable performance with the vanilla version
- Future work: Enabling local monitoring based detection and isolation to multi-channel wireless networks

Thanks

Questions?



Backup Slides

WAHAS Networks

- **Wireless Ad-Hoc and Sensor networks**
- Autonomous system of nodes with no static infrastructure
- All or subset of nodes may move
- Nodes communicate wirelessly in multi-hop fashion
- Often subject to rapid deployment in environments where natural or malicious errors are likely
- Especially attractive in scenarios where it is infeasible or expensive to deploy significant networking infrastructure
- Application examples include: battle field surveillance, medical monitoring, biological detection, home security, disaster recovery

Challenges to Providing Dependability

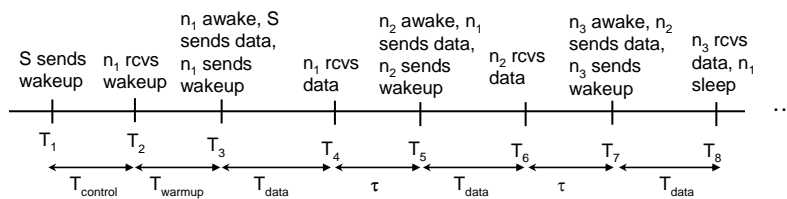
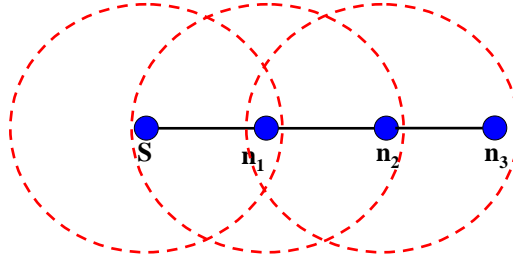
- **Open communication media**
 - Snooping is easy
- **Hostile environment**
 - Attackers everywhere
- **Limited resources**
 - Bandwidth and energy resources are constrained
 - Can not tolerate high overhead measures
 - Easy to launch attacks (cheap devices, no tamper-proof)
- **Lack of infrastructure and difficult-to-reach deployments**
 - Difficult to manage and control
 - Nodes are easy to access and capture by attackers
- **Mobility**
 - Dynamic topology
 - Frequent link failures

Security Attacks

- **Two classes of attacks**
 1. **Attacks that can be defeated by crypto mechanisms**
 - **Eavesdropping: Solved by encryption**
 - **Message tampering: Solved by authentication**
 2. **Attacks that subvert the functionality of the network**
 - **Control attacks: Manipulating control traffic (e.g., routing traffic) to disrupt data traffic**
 - Examples: ID spoofing and Sybil, sinkhole, rushing, wormhole
 - **Data Attacks: Directly manipulate data traffic**
 - Examples: Blackhole, grayhole
 - **This class cannot be prevented by cryptographic mechanisms alone**
- **Throughout this work we have addressed both classes with more focus given to the second class**

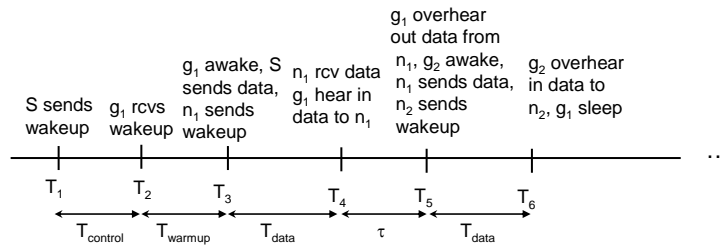
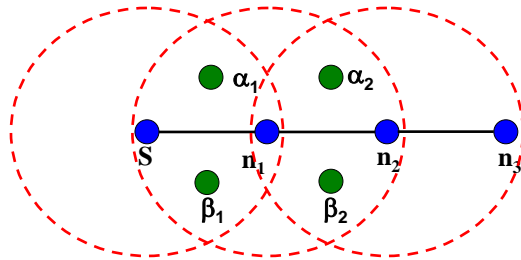
Case 2: $(T_{control} + T_{warmup}) > T_{data}$ – Forwarding node

- $S \rightarrow n_1 \rightarrow n_2 \rightarrow n_3 \rightarrow \dots \rightarrow n_{h-1} \rightarrow D$
- Let $\tau = (T_{control} + T_{warmup}) - T_{data}$
- Three different node role
 - For a node in the route to the destination



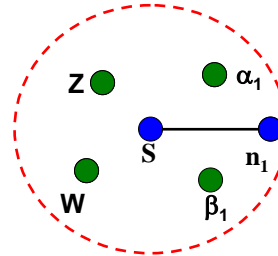
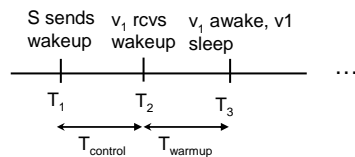
Case 2: $(T_{control} + T_{warmup}) > T_{data}$ – Guard node

- $S \rightarrow n_1 \rightarrow n_2 \rightarrow n_3 \rightarrow \dots \rightarrow n_{h-1} \rightarrow D$
- Three different node types
 - For a guard node



Case 2: $(T_{control} + T_{warmup}) > T_{data}$ – Non-guard node

- $S \rightarrow n_1 \rightarrow n_2 \rightarrow n_3 \rightarrow \dots \rightarrow n_{n-1} \rightarrow D$
- Three different node types
 - For a neighbor to the route but is not a guard



Case II: $(T_{control} + T_{warmup}) \leq T_{data}$

- The timing schedule can be generated in a similar way
- Please refer to the report

Energy Consumption

- SLAM is compared to an on-demand sleep/wake algorithm with no local monitoring support
- Three different nodes considered
 - Forwarding node
 - Guard node
 - Non-guard node
- The worst case additional energy of SLAM for each node is respectively (single flow, per packet)
 - Forwarding node: $T_w \cdot A_{active}$
 - Guard node: $T_{warmup} \cdot A_{warmup} + T_{data} \cdot A_{active} + T_w \cdot A_{active}$
 - Non-guard node: $T_{warmup} \cdot A_{warmup}$ or 0 for G-SLAM