

1.

(a)

$$1 \text{ kW} = 1.34 \text{ HP}$$

$$\therefore 2 \text{ HP} = \frac{2}{1.34} = 1.492 \text{ kW}$$

Back induced e.m.f. during idling

$$\begin{aligned} V_i &= k_b n = 1 (V \cdot s)(600 \text{ rpm}) \left( \frac{1 \text{ min}}{60 \text{ sec}} \right) \left( 2\pi \text{ rad/sec} \right) \\ &= 20\pi \cdot (V) \end{aligned}$$

Power consumption during idling

$$\begin{aligned} P &= V_A \cdot I_A \\ &= (R_A \cdot I_A + V_i) I_A = 1,492 \\ R_A I_A^2 + (20\pi) I_A - 1,492 &= 0 \\ \therefore I_A &= \frac{-10\pi \pm \sqrt{(10\pi)^2 + 10 \times 1492}}{10} = 9.47 (\text{Amp}). \end{aligned}$$

For speed control,  $I_A$  is maintained at a constant level and so is  $T_{\max}$ .

$$\begin{aligned} T_{\max} &= K_T \cdot I_A = 1 \left( \frac{\text{kg} \cdot \text{m}}{\text{A}} \right) \cdot 9.47 (\text{A}) \\ &= 9.47 \text{ kg} \cdot \text{m} = 92.8 \text{ N} \cdot \text{m}. \end{aligned}$$

Maximum acceleration is attained when the motor starts running

$$T_M = J_M \frac{d\omega(t)}{dt} + B\omega(t) + T_L$$

$$\begin{aligned}
 \dot{\omega}_{\max} &= \frac{T_{\max}}{J_m} \\
 &= \frac{9.47(kg \cdot m)}{0.1(kg \cdot m^2)} = \frac{9.47 \times 9.8(kgm \cdot m^2/sec^2)}{0.1(kgm \cdot m^2)} \\
 &= 928(rad/sec^2) = 147.7(rev/sec^2)
 \end{aligned}$$

- (b). During idling, the power generated by the motor is consumed to overcome this dissipative energy due to damping

$$\begin{aligned}
 P &= T_m \cdot \omega \\
 &= \left( J_m \frac{d\omega(t)}{dt} + B \cdot \omega(t) + \mathcal{F}_L \right) \omega(t) \\
 B &= \frac{P}{\omega(t)^2} = \frac{1,492(W)}{(20\pi)^2} = 0.38 N \cdot m / rad / sec.
 \end{aligned}$$

- (c).

$$\begin{aligned}
 V_A &= R_A I_A + V_i \\
 &= R_A I_A + K_b \omega(t) \\
 \therefore \omega(t) &= \frac{V_A - R_A I_A}{K_b} \\
 \omega_{\max} &= \frac{250 - 10 \times 9.47}{1} = 155.3 rad/sec = 1,483 rpm \\
 P_{\max} &= V_{A \max} \cdot I_{A \max} \\
 &= 250 \times 9.47 = 2,368 W \\
 &= 3.17 HP
 \end{aligned}$$

2. A brush type DC motor is used to drive an NC table. The torque constant  $K_T=2 \text{ kg}\cdot\text{m}/\text{A}$  and the voltage constant  $K_b=1 \text{ V}\cdot\text{s}$ . The electric resistance of the rotor circuit is 4 ohms and the total equivalent moment of inertia of the shaft-table is  $6 \text{ kg}\cdot\text{m}^2$ . Ignore the effect of inductance in the armature circuit.

- (a) Determine the maximum torque available from this motor with the rotor input voltage of 100V.

$$V_A = R_A \cdot (I_A)_{\max}$$

$$(I_A)_{\max} = \frac{V_A}{R_A} = \frac{100}{4} = 25(\text{Amp})$$

$$T_{\max} = K_T \cdot (I_A)_{\max} = 2 \times 25 = 50 \text{ kg} \cdot \text{m} = 490 \text{ N} \cdot \text{m}$$

- (b) The motor is required to deliver a constant torque up to 2,000 rpm by armature control. If the armature current is maintained at a constant level calculated in (a), determine the rotor voltage increase needed to increase the speed from 0 to 2,000 rpm.

$$\Delta V_A = \Delta V_i$$

$$= K_b \times n = 1 \times \frac{2000 \times 2\pi}{60} = 209 \text{ V}$$

- (c) Calculate the maximum acceleration achievable by this motor-table unit under no external load.

$$\left. \frac{dn(t)}{dt} \right|_{\max} = \frac{T_{\max}}{J} = \frac{50 \times (9.8)}{6(\text{kg} \cdot \text{m}^2)} = 81.6 \text{ rad/sec}^2$$

$$= 12.998 \text{ rev/sec}^2$$

- (d) What percentage of stator current increase or reduction is needed to further increase the speed of the motor to 3000 rpm by field control? Determine the torque at this speed.

For field control

$$V_i = K\phi n : \text{constant}$$

$$K\phi_1 n_1 = K\phi_2 n_2$$

$$\frac{\phi_1}{\phi_2} = \frac{2000}{3000} \text{ reduction of } 33.3\%$$

$$T_{n=3000} = T_{\max} \times \frac{2}{3} = 327 \text{ N} \cdot \text{m}$$

3.

$$R_r = 10\Omega \quad L_r = 0.06H \quad V_f = 220V \quad n=1, \quad p=3$$

$$\omega_p = 60 \times 2\pi \text{ rad/sec} = (376 \text{ rad/sec})$$

$$\omega_f = \frac{\omega_p}{n} = 60 \times 2\pi \text{ rad/sec}$$

$$\begin{aligned} T_m &= \frac{p \cdot n V^2 s R_r}{\omega_p (R_r^2 + s^2 \omega_p^2 L_r^2)} \\ &= \frac{3 \times 1 \times (220)^2 \cdot (10) \cdot s}{(60 \times 2\pi) [10^2 + s^2 \cdot (60 \times 2\pi)^2 \times (0.06)^2]} \\ &= \frac{1,452,000 \cdot s}{37,699 + 192,884 s^2} = \frac{38.5s}{1 + 511 s^2} \end{aligned}$$

$$s = 1 - \frac{\omega_m}{\omega_p} \cdot n = 1 - \frac{\omega_m}{\omega_p}$$

$$\text{or } \omega_m = (1-s)\omega_p$$

