

Homework 2 Solutions

93 points

Problem 2.4.1 (18 points, 3 per part)

Given

Wave equation: $\frac{\partial^2 y}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = 0$

Find

By direct substitution, show that each of the following is a solution of the wave equation:

- a) $f_1(x - ct)$
- b) $\ln[a(ct - x)]$
- c) $a(ct - x)^2$
- d) $\cos[a(ct - x)]$

Similarly, show that each of the following is not a solution of the wave equation:

- e) $a(ct - x^2)$
- f) $at(ct - x)$

Solution

Solution works if $\frac{\partial^2 y}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = 0$

a) $y = f_1(x - ct)$

$$\frac{\partial^2 y}{\partial x^2} = \frac{\partial^2}{\partial x^2} f_1(x - ct) = f_1''(x - ct)$$

$$\frac{\partial^2 y}{\partial t^2} = \frac{\partial^2}{\partial t^2} f_1(x - ct) = \frac{\partial}{\partial t} [-c f_1'(x - ct)] = (-c)^2 f_1''(x - ct) = c^2 f_1''(x - ct)$$

$$\frac{\partial^2 y}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = f_1''(x - ct) - \frac{1}{c^2} [c^2 f_1''(x - ct)] = f_1''(x - ct) - f_1''(x - ct) = 0$$

Solution checks

b) $y = \ln[a(ct - x)]$

$$\begin{aligned} \frac{\partial^2 y}{\partial x^2} &= \frac{\partial^2}{\partial x^2} \ln[a(ct - x)] = \frac{\partial}{\partial x} \left[\frac{-a}{a(ct-x)} \right] = -\frac{\partial}{\partial x} (ct - x)^{-1} = -(-1)^2 (ct - x)^{-2} \\ &= -(ct - x)^{-2} \end{aligned}$$

$$\begin{aligned} \frac{\partial^2 y}{\partial t^2} &= \frac{\partial^2}{\partial t^2} \ln[a(ct - x)] = \frac{\partial}{\partial t} \left[\frac{ac}{a(ct-x)} \right] = c \frac{\partial}{\partial t} (ct - x)^{-1} = (-c^2) (ct - x)^{-2} \\ &= -c^2 (ct - x)^{-2} \end{aligned}$$

$$\frac{\partial^2 y}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = -(ct - x)^{-2} - \frac{1}{c^2} \{-c^2 (ct - x)^{-2}\} = -(ct - x)^{-2} + (ct - x)^{-2} = 0$$

Solution checks

c) $y = a(ct - x)^2$

$$\frac{\partial^2 y}{\partial x^2} = \frac{\partial^2}{\partial x^2} a(ct - x)^2 = a \frac{\partial}{\partial x} 2(-1)(ct - x) = -2a \frac{\partial}{\partial x} (ct - x) = -2a(-1) = 2a$$

$$\frac{\partial^2 y}{\partial t^2} = \frac{\partial^2}{\partial t^2} a(ct - x)^2 = a \frac{\partial}{\partial t} 2c(ct - x) = 2ac \frac{\partial}{\partial t} (ct - x) = 2ac(c) = 2ac^2$$

$$\frac{\partial^2 y}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = 2a - \frac{1}{c^2} (2ac^2) = 2a - 2a = 0$$

Solution checks

d) $y = \cos[a(ct - x)]$

$$\begin{aligned} \frac{\partial^2 y}{\partial x^2} &= \frac{\partial^2}{\partial x^2} \cos[a(ct - x)] = -a \frac{\partial}{\partial x} \{-\sin[a(ct - x)]\} = (-a)^2 \{-\cos[a(ct - x)]\} \\ &= -a^2 \cos[a(ct - x)] \end{aligned}$$

$$\begin{aligned} \frac{\partial^2 y}{\partial t^2} &= \frac{\partial^2}{\partial t^2} \cos[a(ct - x)] = ac \frac{\partial}{\partial x} \{-\sin[a(ct - x)]\} = (ac)^2 \{-\cos[a(ct - x)]\} \\ &= -(ac^2) \cos[a(ct - x)] \end{aligned}$$

$$\begin{aligned} \frac{\partial^2 y}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} &= -a^2 \cos[a(ct - x)] - \frac{1}{c^2} \{-(ac^2) \cos[a(ct - x)]\} \\ &= -a^2 \cos[a(ct - x)] + a^2 \cos[a(ct - x)] = 0 \end{aligned}$$

Solution checks

e) $y = a(ct - x^2)$

$$\frac{\partial^2 y}{\partial x^2} = \frac{\partial^2}{\partial x^2} a(ct - x^2) = a \frac{\partial}{\partial x} (-2x) = -2a$$

$$\frac{\partial^2 y}{\partial t^2} = \frac{\partial^2}{\partial t^2} a(ct - x^2) = a \frac{\partial}{\partial t} c = 0$$

$$\frac{\partial^2 y}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = -2a - \frac{1}{c^2} (0) = -2a \neq 0$$

Solution does not check

f) $y = at(ct - x)$

$$\frac{\partial^2 y}{\partial x^2} = \frac{\partial^2}{\partial x^2} at(ct - x) = at \frac{\partial}{\partial x} (-1) = 0$$

$$\frac{\partial^2 y}{\partial t^2} = \frac{\partial^2}{\partial t^2} at(ct - x) = \frac{\partial}{\partial t} [a(ct - x) + at(c)] = ac + ac = 2ac$$

$$\frac{\partial^2 y}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = 0 - \frac{1}{c^2} (2ac) = -\frac{2a}{c} \neq 0$$

Solution does not check

Problem 2.8.1 (10 points)

Given

Waveform $y = 4 \cos(3t - 2x)$

Propagates on string of linear density $\rho_L = 0.1 \text{ g/cm}$

Units: y and x in cm, t in seconds

Find

- A, c, f, λ, k
- $u(0,0)$

Solution

a) $y = A \cos(\omega t - kx) = 4 \cos(3t - 2x)$

$$\boxed{A = 4 \text{ cm}}$$

$$\boxed{k = 2 \text{ cm}^{-1}}$$

$$f = \frac{1}{2\pi} \omega = \frac{1}{2\pi} (3 \text{ rad/s}) = 0.477 \text{ Hz} \quad \boxed{f = 0.477 \text{ Hz}}$$

$$k = \frac{\omega}{c} \rightarrow c = \frac{\omega}{k} = \frac{3 \text{ rad/s}}{2 \text{ cm}^{-1}} = \frac{3}{2} \text{ cm/s} \quad \boxed{c = 1.5 \text{ cm/s}}$$

$$k = \frac{2\pi}{\lambda} \rightarrow \lambda = \frac{2\pi}{k} = \frac{2\pi}{2 \text{ cm}^{-1}} = \pi \text{ cm} \quad \boxed{\lambda = \pi \text{ cm}}$$

b) $u = \frac{\partial y}{\partial t} = \frac{\partial}{\partial t} A \cos(\omega t - kx) = -\omega A \sin(\omega t - kx)$

$$u(0,0) = -\omega A \sin(\omega(0) - k(0)) = -\omega A \sin(0) = 0$$

$$\boxed{u(0,0) = 0 \text{ cm/s}}$$

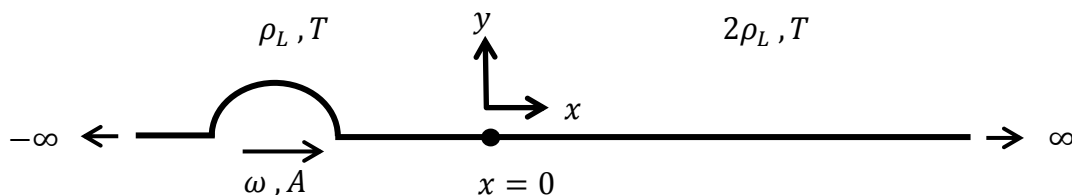
Problem 2.8.2 (15 points)

Given

Infinite string ($-\infty < x \leq 0$) with density ρ_L under tension T

Attached at $x = 0$ to another infinite string ($0 < x < \infty$) with density $2\rho_L$ under tension T

Wave of angular frequency ω and amplitude A traveling in the $+x$ direction on the first string



Find

Amplitude of the wave traveling on the second string

Solution

Original wave: $y_1(x, t) = Ae^{j(\omega t - k_1 x)}$

Wave reflects at transfer point $x = 0$

Thus, $y_1(x, t) = Ae^{j(\omega t - k_1 x)} + Be^{j(\omega t + k_1 x)}$

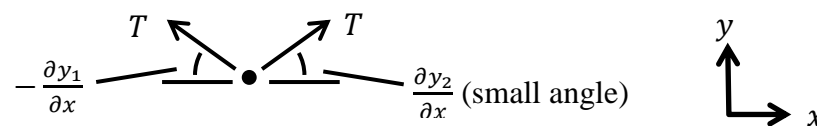
A wave also transfers into the right string: $y_2(x, t) = Ce^{j(\omega t - k_2 x)}$

Displacement continuity BC: $y_1(0, t) = y_2(0, t)$

$$Ae^{j\omega t} + Be^{j\omega t} = Ce^{j\omega t}$$

$$B = C - A$$

Force balance BC:



$$\sum F_y = -T \left. \frac{\partial y_1}{\partial x} \right|_{x=0} + T \left. \frac{\partial y_2}{\partial x} \right|_{x=0} = 0$$

$$\left. \frac{\partial y_1}{\partial x} \right|_{x=0} = \left. \frac{\partial y_2}{\partial x} \right|_{x=0}$$

$$\left. \frac{\partial y_1}{\partial x} \right|_{x=0} = -jk_1 A e^{j\omega t} + jk_1 B e^{j\omega t} = -jk_1 A e^{j\omega t} + jk_1 (C - A) e^{j\omega t} = jk_1 (C - 2A) e^{j\omega t}$$

$$\left. \frac{\partial y_2}{\partial x} \right|_{x=0} = -jk_2 C e^{j\omega t}$$

Substituting: $jk_1 (C - 2A) e^{j\omega t} = -jk_2 C e^{j\omega t}$

$$k_1 (C - 2A) = -k_2 C$$

$$\text{Note that } k_1 = \frac{\omega}{c_1} = \omega \sqrt{\frac{\rho_{L1}}{T}} = \omega \sqrt{\frac{\rho_L}{T}}$$

$$k_2 = \frac{\omega}{c_2} = \omega \sqrt{\frac{\rho_{L2}}{T}} = \omega \sqrt{\frac{2\rho_L}{T}} = \sqrt{2} \left(\omega \sqrt{\frac{\rho_L}{T}} \right) = \sqrt{2} k_1$$

$$k_1 (C - 2A) = -\sqrt{2} k_1 C$$

$$(C - 2A) = -\sqrt{2} C$$

$$C(1 + \sqrt{2}) = 2A$$

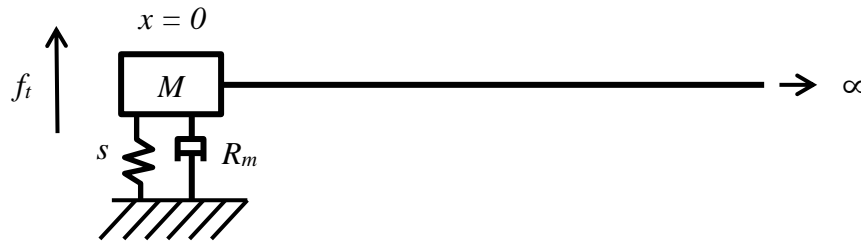
$$C = \frac{2}{1 + \sqrt{2}} A \left(\frac{\sqrt{2} - 1}{\sqrt{2} - 1} \right) = \frac{2(\sqrt{2} - 1)}{2 - 1} A = 2(\sqrt{2} - 1)A$$

$$\boxed{C = \frac{2}{1 + \sqrt{2}} A = 2(\sqrt{2} - 1)A}$$

Problem 2.9.2 (10 points)

Given

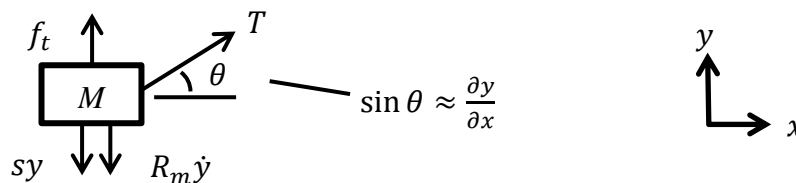
Simple harmonic oscillator with an infinite string extending transversely from the mass
 Force applied to the oscillator



Find

z_{m0}
 (assume $f_t = Fe^{j\omega t}$)

Solution



$$\text{Force balance equation: } \sum F_y = f_t + T \left. \frac{\partial y}{\partial x} \right|_{x=0} - sy|_{x=0} - R_m \dot{y}|_{x=0} = m \ddot{y}|_{x=0}$$

Wave equation: $y = Ae^{j(\omega t - kx)}$ (only travels in $+x$ direction)

$$\left. \frac{\partial y}{\partial x} \right|_{x=0} = \left. \frac{\partial}{\partial x} Ae^{j(\omega t - kx)} \right|_{x=0} = -jkAe^{j(\omega t - kx)}|_{x=0} = -jkAe^{j\omega t}$$

$$y(0, t) = Ae^{j(\omega t - kx)}|_{x=0} = Ae^{j\omega t}$$

$$\dot{y}(0, t) = \left. \frac{\partial}{\partial t} Ae^{j(\omega t - kx)} \right|_{x=0} = j\omega Ae^{j(\omega t - kx)}|_{x=0} = j\omega Ae^{j\omega t}$$

$$\ddot{y}(0, t) = \left. \frac{\partial^2}{\partial t^2} Ae^{j(\omega t - kx)} \right|_{x=0} = -\omega^2 Ae^{j(\omega t - kx)}|_{x=0} = -\omega^2 Ae^{j\omega t}$$

Substitute into force balance equation:

$$Fe^{j\omega t} + T(-jkAe^{j\omega t}) - s(Ae^{j\omega t}) - R_m(j\omega Ae^{j\omega t}) = m(-\omega^2 Ae^{j\omega t})$$

$$F - jkTA - sA - j\omega R_m A = -m\omega^2 A$$

$$F = jkTA + sA + j\omega R_m A - m\omega^2 A$$

$$\text{Remember } k = \frac{\omega}{c}, \quad T = \rho_L c^2$$

$$F = j \left(\frac{\omega}{c} \right) (\rho_L c^2) A + sA + j\omega R_m A - m\omega^2 A = A[j\omega(\rho_L c + R_m) + (s - m\omega^2)]$$

$$A = \frac{F}{j\omega(\rho_L c + R_m) + (s - m\omega^2)}$$

$$z_{m0} = \frac{f_t}{\dot{y}(0,t)} = \frac{F e^{j\omega t}}{j\omega A e^{j\omega t}} = \frac{F}{j\omega} A^{-1} = \frac{F}{j\omega} \left[\frac{j\omega(\rho_L c + R_m) + (s - m\omega^2)}{F} \right] = (\rho_L c + R_m) + \frac{1}{j} \left(\frac{s}{\omega} - \omega m \right)$$

$$= (\rho_L c + R_m) - j \left(\frac{s}{\omega} - \omega m \right) = (\rho_L c + R_m) + j \left(\omega m - \frac{s}{\omega} \right)$$

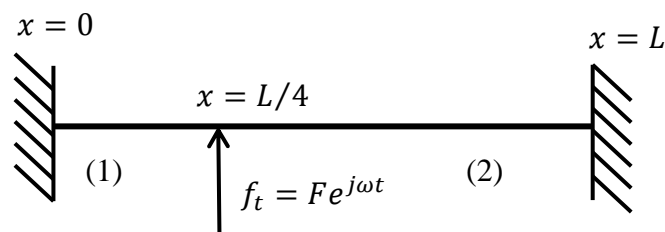
$$\boxed{z_{m0} = \rho_L c + R_m + j \left(\omega m - \frac{s}{\omega} \right)}$$

Problem 2.9.3a (edited) (20 points)

Given

Fixed-fixed string of length L

Driving force $F e^{j\omega t}$ located at $x = L/4$



Find

Input mechanical impedance at $x = L/4$

(assume uniform T, ρ_L)

Solution

Sector 1: $y_1(x, t) = A e^{j(\omega t - kx)} + B e^{j(\omega t + kx)}$

Sector 2: $y_2(x, t) = C e^{j(\omega t - kx)} + D e^{j(\omega t + kx)}$

Fixed-end boundary condition (BC) at $x = 0$:

$$y_1(0, t) = A e^{j\omega t} + B e^{j\omega t} = 0$$

$$B = -A$$

Substituting, $y_1(x, t) = A e^{j(\omega t - kx)} - A e^{j(\omega t + kx)} = A e^{j\omega t} (e^{-jkx} - e^{jkx}) = -2jA \sin(kx) e^{j\omega t}$

Fixed-end BC at $x = L$:

$$y_2(L, t) = C e^{j(\omega t - kL)} + D e^{j(\omega t + kL)} = 0$$

$$C e^{-jkL} = -D e^{jkL}$$

$$D = -C e^{-2jkL}$$

Substituting: $y_2(x, t) = C e^{j(\omega t - kx)} - (C e^{-2jkL}) e^{j(\omega t + kx)}$

$$= C e^{j\omega t} (e^{-jkx} - e^{-2jkL} e^{jkx})$$

$$= C e^{j\omega t} e^{-jkL} (e^{jkL} e^{-jkx} - e^{-jkL} e^{jkx})$$

$$= C e^{j(\omega t - kL)} (e^{jk(L-x)} - e^{-jk(L-x)})$$

$$= 2jC e^{j(\omega t - kL)} \sin k(L - x)$$

Displacement continuity BC at $x = L/4$:

$$y_1(L/4, t) = y_2(L/4, t)$$

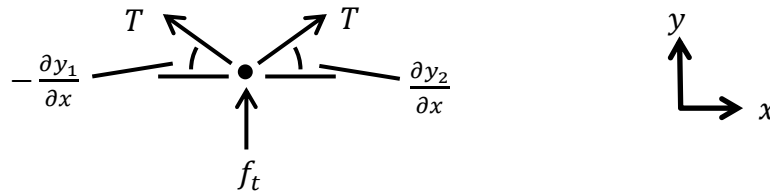
$$-2jA \sin\left(\frac{kL}{4}\right) e^{j\omega t} = 2jC e^{j\omega t} e^{-jkL} \sin k\left(L - \frac{L}{4}\right)$$

$$-A \sin\left(\frac{kL}{4}\right) = C e^{-jkL} \sin\left(\frac{3kL}{4}\right)$$

$$C e^{-jkL} = -A \sin\left(\frac{kL}{4}\right) \csc\left(\frac{3kL}{4}\right)$$

Substituting into y_2 : $y_2(x, t) = -2jA \sin\left(\frac{kL}{4}\right) \csc\left(\frac{3kL}{4}\right) \sin k(L - x) e^{j\omega t}$

Force balance BC at $x = L/4$:



$$\sum F_y = f_t - T \frac{\partial y_1}{\partial x} \Big|_{x=L/4} + T \frac{\partial y_2}{\partial x} \Big|_{x=L/4} = 0$$

$$\frac{\partial y_1}{\partial x} \Big|_{x=L/4} = \frac{\partial}{\partial x} \left[-2jA \sin(kx) e^{j\omega t} \right]_{x=L/4} = -2jkA \cos(kx) e^{j\omega t} \Big|_{x=L/4} = -2jkA \cos\left(\frac{kL}{4}\right) e^{j\omega t}$$

$$\frac{\partial y_2}{\partial x} \Big|_{x=L/4} = \frac{\partial}{\partial x} \left[-2jA \sin\left(\frac{kL}{4}\right) \csc\left(\frac{3kL}{4}\right) \sin k(L - x) e^{j\omega t} \right]_{x=L/4}$$

$$= 2jkA \sin\left(\frac{kL}{4}\right) \csc\left(\frac{3kL}{4}\right) \cos k(L - x) e^{j\omega t} \Big|_{x=L/4}$$

$$= 2jkA \sin\left(\frac{kL}{4}\right) \csc\left(\frac{3kL}{4}\right) \cos k\left(L - \frac{L}{4}\right) e^{j\omega t}$$

$$= 2jkA \sin\left(\frac{kL}{4}\right) \cot\left(\frac{3kL}{4}\right) e^{j\omega t}$$

$$F e^{j\omega t} - T \left[-2jkA \cos\left(\frac{kL}{4}\right) e^{j\omega t} \right] + T \left[2jkA \sin\left(\frac{kL}{4}\right) \cot\left(\frac{3kL}{4}\right) e^{j\omega t} \right] = 0$$

$$F + 2jkTA \cos\left(\frac{kL}{4}\right) + 2jkTA \sin\left(\frac{kL}{4}\right) \cot\left(\frac{3kL}{4}\right) = 0$$

$$\frac{F}{2jkTA} + \cos\left(\frac{kL}{4}\right) + \sin\left(\frac{kL}{4}\right) \cot\left(\frac{3kL}{4}\right) = 0$$

$$\frac{F}{2jkTA \sin(kL/4)} = -\cot\left(\frac{3kL}{4}\right) - \cot\left(\frac{kL}{4}\right)$$

$$A = -\frac{F}{2jkT \sin\left(\frac{kL}{4}\right) \left[\cot\left(\frac{kL}{4}\right) + \cot\left(\frac{3kL}{4}\right) \right]}$$

$$\text{Remember } k = \frac{\omega}{c}, \quad T = \rho_L c^2$$

$$= -\frac{F}{2j\left(\frac{\omega}{c}\right)(\rho_L c^2) \sin\left(\frac{kL}{4}\right) \left[\cot\left(\frac{kL}{4}\right) + \cot\left(\frac{3kL}{4}\right) \right]} = -\frac{F}{2j\omega(\rho_L c) \sin\left(\frac{kL}{4}\right) \left[\cot\left(\frac{kL}{4}\right) + \cot\left(\frac{3kL}{4}\right) \right]}$$

Solve for z_{m0} using either y_1 or y_2

$$\begin{aligned} \text{From } y_1: z_{m0} &= \frac{f_t}{u_1(L/4,t)} = \frac{f_t}{j\omega y_1(L/4,t)} = \frac{F e^{j\omega t}}{j\omega [-2jA \sin(kx) e^{j\omega t}]_{x=L/4}} = \frac{F}{2\omega A \sin(kL/4)} \\ &= \frac{F}{2\omega \sin(kL/4)} \left\{ -\frac{2j\omega(\rho_L c) \sin\left(\frac{kL}{4}\right) \left[\cot\left(\frac{kL}{4}\right) + \cot\left(\frac{3kL}{4}\right) \right]}{F} \right\} = -j\rho_L c \left[\cot\left(\frac{kL}{4}\right) + \cot\left(\frac{3kL}{4}\right) \right] \end{aligned}$$

$$\begin{aligned} \text{From } y_2: z_{m0} &= \frac{f_t}{u_2(L/4,t)} = \frac{f_t}{j\omega y_2(L/4,t)} = \frac{F e^{j\omega t}}{j\omega \left[-2jA \sin\left(\frac{kL}{4}\right) \csc\left(\frac{3kL}{4}\right) \sin k(L-x) e^{j\omega t} \right]_{x=L/4}} \\ &= \frac{F}{2\omega A \sin\left(\frac{kL}{4}\right) \csc\left(\frac{3kL}{4}\right) \sin k\left(L-\frac{L}{4}\right)} = \frac{F}{2\omega A \sin(kL/4)} = \dots \text{ (remaining steps are same as in } y_1 \text{ case)} \end{aligned}$$

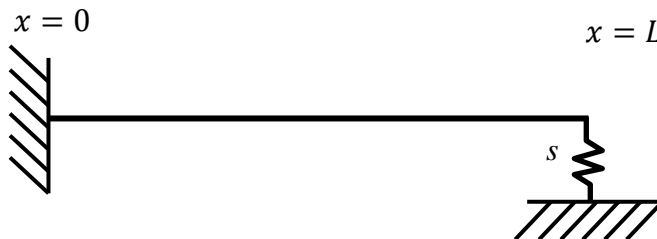
$$\boxed{z_{m0} = -j\rho_L c \left[\cot\left(\frac{kL}{4}\right) + \cot\left(\frac{3kL}{4}\right) \right]}$$

Problem 2.11.1 (10 points)

Given

Fixed, spring-loaded string (assume fixed at $x = 0$, spring-loaded at $x = L$)

$$T = sL$$



Find

Identify kL for the normal modes

Sketch the waveforms for the fundamental and for the first overtone

Solution

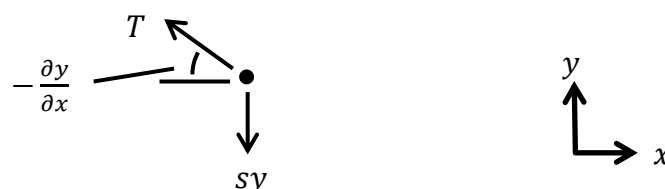
$$y(x, t) = A e^{j(\omega t - kx)} + B e^{j(\omega t + kx)}$$

$$\text{Fixed end BC: } y(0, t) = A e^{j\omega t} + B e^{j\omega t} = 0$$

$$B = -A$$

$$y(x, t) = A e^{j\omega t} (e^{-jkx} - e^{jkx}) = -2jA \sin(kx) e^{j\omega t}$$

Spring-loaded end BC:



$$\sum F_y = -T \left. \frac{\partial y}{\partial x} \right|_{x=L} - sy(L, t) = 0$$

$$\left. \frac{\partial y}{\partial x} \right|_{x=L} = \frac{\partial}{\partial x} [-2jA \sin(kx) e^{j\omega t}]_{x=L} = -2jkA \cos(kx) e^{j\omega t} \Big|_{x=L} = -2jkA \cos(kL) e^{j\omega t}$$

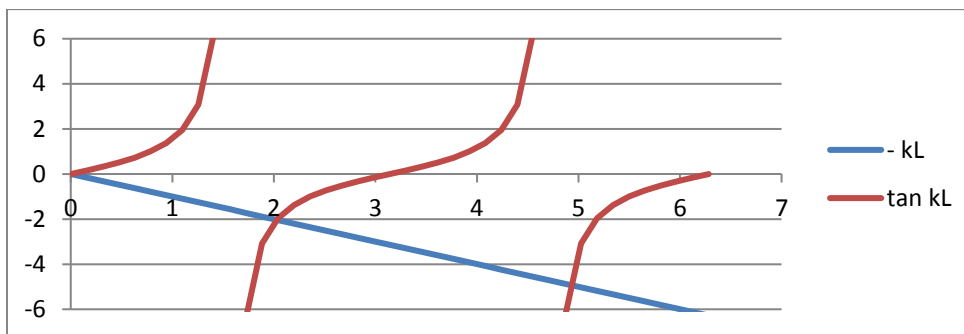
$$\text{Thus, } (-T)[-2jAk \cos(kL) e^{j\omega t}] - s[-2jAs \sin(kL) e^{j\omega t}] = 0$$

$$kT \cos(kL) + s \sin(kL) = 0$$

$$\tan(kL) = -\frac{kT}{s} = -\frac{k(sL)}{s} = -kL$$

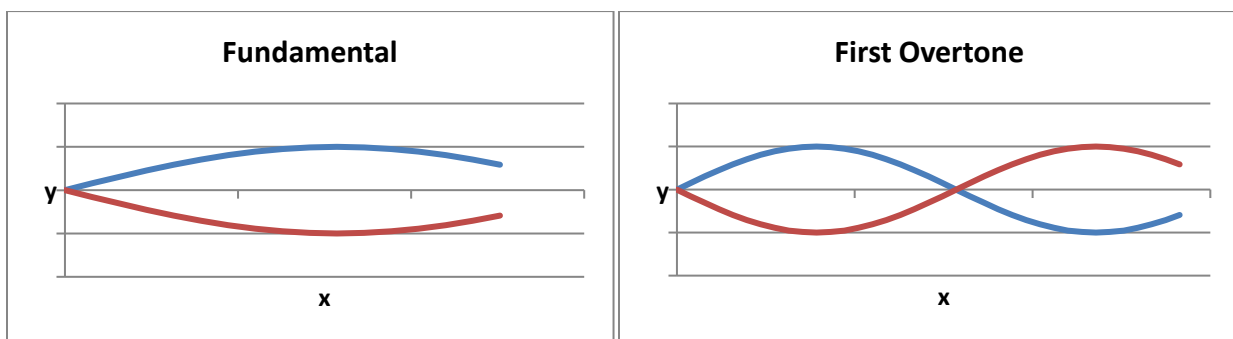
Characteristic equation: $\boxed{\tan(kL) = -kL}$

Solve for kL numerically. I will begin by plotting $-kL$ and $\tan(kL)$ in Excel.



I see from this plot that $k_1L \approx 2$ and $k_2L \approx 5$. To find the exact values, I set up two equations for $x = kL + \tan(kL)$ in Excel, make initial guesses of $kL = 2$ and 5 , and run the Solver tool.

$$\boxed{\begin{matrix} k_1L = 2.029 \\ k_2L = 4.913 \end{matrix}}$$



Problem 2.11.1 (addendum) (10 points)

Guitar string

$$\rho_L = 8 \cdot 10^{-4} \text{ kg/m}$$

$$T = 50 \text{ N}$$

$$L = 0.66 \text{ m}$$

Find

- ω_1 (assume fixed-fixed)
- Minimum stiffness of the transverse string (**misprint: spring?**) required to ensure that ω_1 is reduced by no more than 1% (assume $T = sL$ in this case, rather than 50 N)

Solution

$$y(x, t) = Ae^{j(\omega t - kx)} + Be^{j(\omega t + kx)}$$

Fixed end BC at $x = 0$: $y(0, t) = Ae^{j\omega t} + Be^{j\omega t} = 0$

$$B = -A$$

$$y(x, t) = Ae^{j\omega t}(e^{-jkx} - e^{jkx}) = -2jA \sin(kx) e^{j\omega t}$$

- Fixed end BC at $x = L$: $y(L, t) = -2jA \sin(kL) e^{j\omega t} = 0$

Characteristic equation: $\sin(kL) = 0$

$$k_1 L = \pi$$

$$k_1 L = \frac{\omega_1}{c} L = \pi$$

$$\omega_1 = \frac{\pi}{L} c = \frac{\pi}{L} \sqrt{\frac{T}{\rho_L}} = \frac{\pi}{0.66 \text{ m}} \sqrt{\frac{50 \text{ N}}{8 \cdot 10^{-4} \text{ kg/m}}} = 1.19 \cdot 10^3 \text{ rad/s}$$

$$\boxed{\omega_1 = 1.19 \cdot 10^3 \text{ rad/s}}$$

- From Problem 2.11.1 above, for a fixed, spring-loaded string, $\tan(kL) = -\frac{kT}{s} = -\frac{T}{sL} kL$

$$\omega_{1b} = \frac{(k_1 L)_b}{L} \sqrt{\frac{T}{\rho_L}} = \frac{(k_1 L)_b}{L} c = 0.99 \omega_{1a}$$

Remember $\omega_{1a} = \frac{\pi}{L} c$

$$\frac{\omega_{1b}}{\omega_{1a}} = \frac{(k_1 L)_b \frac{c}{L}}{\frac{\pi}{L} c} = \frac{(k_1 L)_b}{\pi} = 0.99$$

$$(k_1 L)_b = 0.99\pi$$

Substituting, $\tan(0.99\pi) = -\frac{T}{sL} (0.99\pi)$

$$s = -\frac{0.99\pi T}{L \tan(0.99\pi)} = -\frac{0.99\pi(50 \text{ N})}{(0.66 \text{ m}) \tan(0.99\pi)} = 7.50 \cdot 10^3 \text{ N/m}$$

$$\boxed{s = 7.50 \cdot 10^3 \text{ N/m}}$$