

MB 513 Homework No. 2

Solution

2.4.1.

Wave equation:  $\frac{\partial^2 y}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = 0$

or  $\frac{\partial^2 y}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2}$ .

(a)  $f_1(x-ct) = f_1(\xi)$

LHS =  $\frac{\partial}{\partial x} \left( \frac{df_1}{d\xi} \frac{\partial \xi}{\partial x} \right) = \frac{\partial}{\partial x} \left( \frac{df_1}{d\xi} \right) = \frac{d^2 f_1}{d\xi^2} \frac{\partial \xi}{\partial x} = \frac{d^2 f_1}{d\xi^2}$ .

RHS =  $\frac{1}{c^2} \frac{\partial}{\partial t} \left( \frac{df_1}{d\xi} \frac{d\xi}{dt} \right) = \frac{1}{c^2} \frac{\partial}{\partial t} \left( -c \frac{df_1}{d\xi} \right)$

$= \frac{1}{c^2} (-c) \frac{d^2 f_1}{d\xi^2} \frac{d\xi}{dt} = \frac{d^2 f_1}{d\xi^2}$ .

$\therefore$  LHS = RHS. Satisfied.

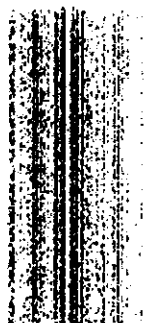
(b).  $\ln[a(ct-x)]$ .

LHS =  $\frac{\partial^2 y}{\partial x^2} = \frac{\partial}{\partial x} \left[ \frac{-a}{a(ct-x)} \right] = - \frac{1}{(x-ct)^2}$ .

RHS =  $\frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = \frac{1}{c^2} \frac{\partial}{\partial t} \left[ \frac{ac}{a(ct-x)} \right] = \frac{1}{c^2} \frac{\partial}{\partial t} \left[ \frac{1}{t-\frac{x}{c}} \right]$

$= \frac{1}{c^2} \left[ - \frac{1}{(t-\frac{x}{c})^2} \right] = - \frac{1}{(x-ct)^2}$ .

$\therefore$  LHS = RHS. Satisfied.



$$(c). a(ct-x)^2$$

$$LHS = \frac{\partial^2 y}{\partial x^2} = \frac{\partial}{\partial x} [2a(ct-x)] = 2a.$$

$$RHS = \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = \frac{1}{c^2} \frac{\partial}{\partial t} [2a(ct-x) \cdot c] \\ = \frac{1}{c^2} 2ac^2 = 2a.$$

$\therefore LHS = RHS.$  satisfied.

$$(d). \cos[a(ct-x)].$$

$$LHS = \frac{\partial^2 y}{\partial x^2} = \frac{\partial}{\partial x} [-\sin[a(ct-x)] \cdot (-a)] \\ = a \cos[a(ct-x)] \cdot (-a) \\ = -a^2 \cos[a(ct-x)].$$

$$RHS = \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = \frac{1}{c^2} \frac{\partial}{\partial t} [-\sin[a(ct-x)] \cdot ac] \\ = \frac{1}{c^2} (-ac) \cos[a(ct-x)] \cdot ac \\ = -a^2 \cos[a(ct-x)].$$

$\therefore LHS = RHS.$  Satisfied.

$$(e). a(ct - x^2)$$

$$LHS = \frac{\partial^2 y}{\partial x^2} = \frac{\partial}{\partial x} [-a \cdot 2x] = -2a.$$

$$RHS = \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = \frac{1}{c^2} \frac{\partial}{\partial t} [ac] = 0.$$

LHS  $\neq$  RHS. Wave equation not satisfied.

$$(f). at(ct - x).$$

$$LHS = \frac{\partial^2 y}{\partial x^2} = \frac{\partial}{\partial x} [-at] = 0.$$

$$RHS = \frac{1}{c^2} \frac{\partial^2 y}{\partial t^2} = \frac{1}{c^2} \frac{\partial}{\partial t} [2act - ax] \\ = \frac{1}{c^2} \cdot 2ac = \frac{2a}{c}.$$

$\therefore$  LHS  $\neq$  RHS. wave equation not satisfied.

2.8.1.

(a). Amplitude 4 cm.  
Phase speed 1.5 cm/s  
Frequency  $\frac{3}{2\pi} = 0.48 \text{ Hz}$   
Wavelength  $\frac{1.5}{3} \cdot 2\pi = \pi$   
Wavenumber  $\frac{2\pi}{\pi} = 2$ .

(b).  $u = \frac{dy}{dt} \Big|_{x=0, t=0}$   
 $= -12 \sin(3t - 2x) \Big|_{x=0, t=0}$   
 $= 0$ .

Since solution has general form

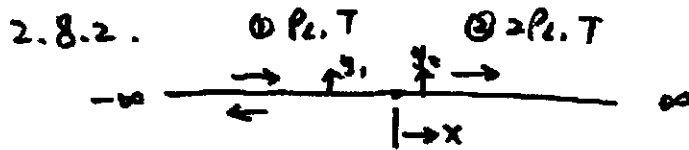
$$y = A \cos(\omega t - kx)$$

by identification  $\omega = 3 \text{ rad/s}$

$$k = 2 \text{ rad/cm}$$

since  $k = \omega/c$   $c = \omega/k = 1.5$





Two wave equations:

$$\frac{\partial^2 y_1}{\partial x^2} + k_1^2 y_1 = 0.$$

$$\frac{\partial^2 y_2}{\partial x^2} + k_2^2 y_2 = 0.$$

The B.C.s are:

at  $x=0$ ,  $y_1 = y_2$  — (1)

Draw FBD for  $x=0$ .

we have:



$$T_1 \sin \theta_1 + T_2 \sin \theta_2 = 0$$

$$\Rightarrow -T_1 \frac{dy_1}{dx} + T_2 \frac{dy_2}{dx} = 0 \Rightarrow \frac{dy_1}{dx} = \frac{dy_2}{dx} \quad \text{--- (2)}$$

Assume the solutions to the wave equations are:

$$y_1 = A e^{-jk_1 x} e^{j\omega t} + B e^{jk_1 x} e^{j\omega t}$$

$$y_2 = C e^{-jk_2 x} e^{j\omega t}$$

where:  $k_1 = \frac{\omega}{c_1} = \frac{\omega}{\sqrt{T/\rho_1}}$ ,  $k_2 = \frac{\omega}{c_2} = \frac{\omega}{\sqrt{T/\rho_2}} = \sqrt{2} k_1$

Substitute into (1)

$$\Rightarrow A + B = C \quad \text{--- (3)}$$

Substitute into (2):

$$\Rightarrow -Aj k_1 + Bj k_1 = -Cj k_2.$$

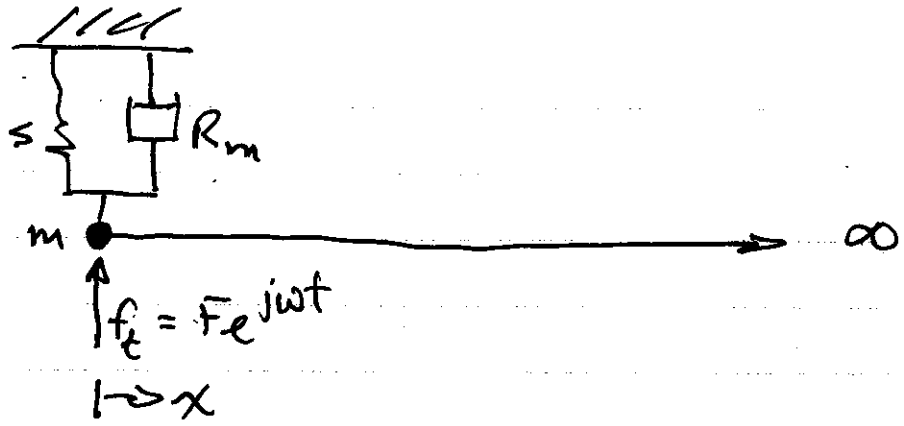
$$\Rightarrow (A-B)k_1 = \sqrt{2} C k_1,$$

$$\Rightarrow A - B = \sqrt{2} C \quad - (4).$$

Solve (3) & (4) for B, C in terms of A:

$$\Rightarrow \begin{cases} C = \frac{1}{2}(\sqrt{2}-1)A \\ B = (2\sqrt{2}-3)A. \end{cases}$$

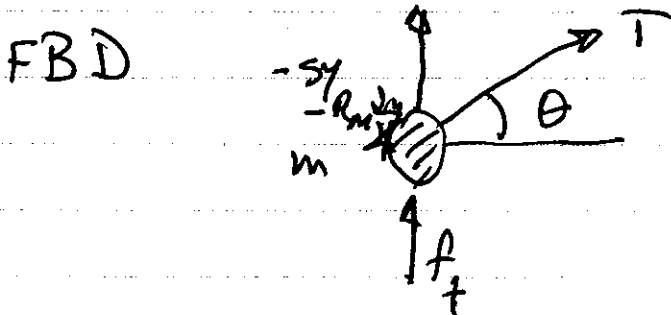
2.9.2



Semi-infinite string - nothing coming back from the +ve  $x$ -direction!  
 So, assumed solution

$$y(x, t) = A e^{j(\omega t - kx)} \quad k = \frac{\omega}{c} \quad c = \sqrt{\frac{T}{\rho}}$$

to determine  $A$ , apply b.c. at  $x=0$



$$\sum f_y = ma \Big|_{x=0}$$

$$T \sin \theta \Big|_{x=0} - sy \Big|_{x=0} - R_m \frac{dy}{dt} \Big|_{x=0} + f_t = m \frac{d^2 y}{dt^2} \Big|_{x=0}$$

$$\frac{T dy}{dx} \Big|_{x=0} - sy \Big|_{x=0} - R_m \frac{dy}{dt} \Big|_{x=0} + f_t = m \frac{d^2 y}{dt^2} \Big|_{x=0}$$

$$\frac{dy}{dx} = -jkA e^{j(\omega t - kx)}$$

$$\frac{dy}{dt} = j\omega A e^{j(\omega t - kx)}$$

$$\frac{d^2y}{dx^2} = -\omega^2 A e^{j(\omega t - kx)}$$

$$\begin{aligned} -jkTA e^{j\omega t} - sA e^{j\omega t} - j\omega R_m A e^{j\omega t} + F e^{j\omega t} \\ = -\omega_m^2 A e^{j\omega t} \end{aligned}$$

$$F = (jkT + s + j\omega R_m - \omega_m^2) A$$

$$A = \frac{F}{jkT + s + j\omega R_m - \omega_m^2}$$

$$= \frac{F}{j\omega \left( \frac{kT}{\omega} - \frac{j s}{\omega} + R_m + j\omega m \right)}$$

$$k = \frac{\omega}{c}$$

$$c = \sqrt{\frac{T}{\rho_L}} \Rightarrow T = c^2 \rho_L$$

$$A = \frac{F}{j\omega (\rho_L c + R_m + j\omega m - j \left( \frac{s}{\omega} \right))}$$



$$y(x,t) = A e^{j(\omega t - kx)}$$

Mechanical Impedance at drive point

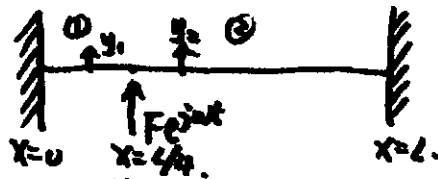
$$Z_{mo} = \frac{\text{driving force}}{\text{complex velocity}} \Big|_{x=0}$$

$$\frac{dy}{dt} = j\omega A e^{j(\omega t - kx)}$$

$$\therefore Z_{mo} = \frac{F e^{j\omega t}}{\frac{j\omega F e^{j\omega t}}{j\omega (f_c + R_m + j\omega m - j(\frac{s}{\omega}))}}$$

$$\approx f_c + R_m + j\omega m - j\left(\frac{s}{\omega}\right)$$

2.9.3.



The wave equations are:

(assume  $\rho, T$  in both segments).

$$\frac{\partial^2 y_1}{\partial x^2} + k^2 y_1 = 0$$

$$\frac{\partial^2 y_2}{\partial x^2} + k^2 y_2 = 0$$

The B.C.s are:

$$\text{At } x=0 \quad y_1(0, t) = 0 \quad - (1)$$

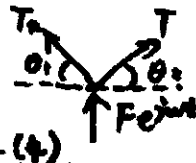
$$\text{At } x=L \quad y_2(L, t) = 0 \quad - (2)$$

$$\text{At } x=L/4, \quad y_1 = y_2 \quad - (3)$$

Draw FBD.

$$T \sin \theta_1 + T \sin \theta_2 + F_0 e^{j\omega t} = 0$$

$$\Rightarrow T \left( \frac{dy_1}{dx} - \frac{dy_2}{dx} \right) + F_0 e^{j\omega t} = 0 \quad - (4)$$



Assume the solutions are in the form,

$$y_1(x, t) = (A e^{-jkx} + B e^{jkx}) e^{j\omega t}$$

$$y_2(x, t) = (C e^{-jkx} + D e^{jkx}) e^{j\omega t}$$

substitute into the B.C.s. we get:

$$(5) \quad A + B = 0$$

$$(6) \quad Ce^{-jkL} + De^{jkL} = 0$$

$$(7) \quad Ae^{-jkL/4} + Be^{jkL/4} = Ce^{-jkL/4} + De^{jkL/4}$$

$$(8) \quad Ce^{-jkL/4} - De^{jkL/4} - Ae^{-jkL/4} + Be^{jkL/4} = \frac{F}{2jkT}$$

Express B, C, D in terms of A:

$$B = -A$$

$$D = -e^{-2jkL} C = \frac{-e^{-jkL/4} + e^{-jkL/4}}{e^{-jkL/4} - e^{-jkL/4}} A$$

$$C = \frac{e^{-jkL/4} - e^{jkL/4}}{e^{-jkL/4} - e^{-jkL/4}} A$$

Then substitute into (8), solving for A:

$$A = \frac{F}{2jkT} \frac{e^{-jkL/4} - e^{-jkL/4}}{e^{-jkL/4} - 1}$$

$$\Rightarrow B = -A \frac{e^{-jkL/4} - e^{-jkL/4}}{e^{-jkL/4} - 1}$$

$$D = \frac{F}{2jkT} \frac{e^{-jkL/4} - 1}{e^{-jkL/4} - 1}$$

$$C = \frac{F}{2jkT} \frac{e^{-jkL/4} - e^{jkL/4}}{e^{-jkL/4} - 1}$$

substitute back into  $y_2(x, t)$ :

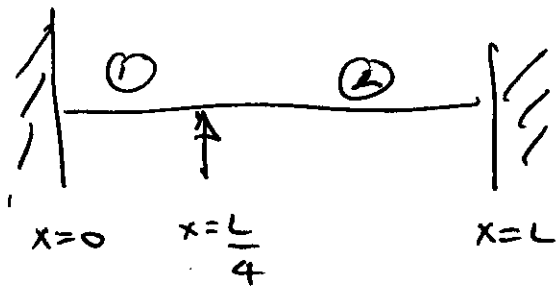
$$\begin{aligned}
 y_2 &= (C e^{-jkx} + D e^{jkx}) e^{j\omega t} \\
 &= \frac{F}{2jkT} \frac{e^{j\omega t}}{e^{-jk2L} - 1} \left[ (e^{-jkL/4} - e^{jkL/4}) e^{-jkx} \right. \\
 &\quad \left. + (e^{-jk7L/4} - e^{-jk9L/4}) e^{jkx} \right] \\
 &= \frac{F}{2jkT} \frac{e^{-jkL/4} - e^{jkL/4}}{e^{-jk2L} - 1} e^{j\omega t} \left[ e^{-jkx} - e^{-jk2L} e^{jkx} \right] \\
 &\quad F e^{j\omega t}
 \end{aligned}$$

(a).  $z = \frac{\text{Transverse velocity}}{F e^{j\omega t}}$

$$\frac{\partial y_2}{\partial t} \Big|_{x=L/4} = \frac{F}{2jkT} \frac{e^{-jkL/4} - e^{jkL/4}}{e^{-jk2L} - 1} \left[ e^{-jkL/4} - e^{-jk7L/4} \right] \cdot j\omega e^{j\omega t}$$

$$\begin{aligned}
 \Rightarrow z &= \frac{F e^{j\omega t}}{\frac{\partial y_2}{\partial t} \Big|_{x=L/4}} \\
 &= \frac{2\rho_2 c (e^{-jk2L} - 1)}{(e^{-jkL/4} - e^{jkL/4})(e^{-jkL/4} - e^{-jk7L/4})} \\
 &= -j\rho_2 c \left[ \cot \frac{kL}{4} + \cot \frac{3kL}{4} \right].
 \end{aligned}$$

## 2.9.3 (Alternative)



$$y_1 = A e^{-ikx} + B e^{ikx}$$

① at  $x=0$   $y_1 = 0$

$$0 = A + B$$

$$B = -A$$

$$y_1 = A (e^{-ikx} - e^{+ikx})$$

$$= -2j A \sin kx$$

$$y_2 = C e^{-ikx} + D e^{ikx}$$

② at  $x=L$   $y_2 = 0$

$$0 = C e^{-ikL} + D e^{ikL}$$

$$D e^{ikL} = -C e^{-ikL}$$

$$D = -C e^{-2ikL}$$

$$y_2 = C e^{-ikx} - C e^{-2ikL} e^{ikx}$$

$$= e^{-ikL} C (e^{-ikx} e^{ikL} - e^{-2ikL} e^{ikx})$$

$$= e^{-ikL} C (e^{ik(L-x)} - e^{-ik(L-x)})$$

$$= 2j e^{-ikL} C \sin k(L-x)$$

$$(3) \quad \text{at } x = \frac{L}{4} \quad y_1 = y_2$$

$$-2jA \sin k \frac{L}{4} = 2j e^{-ikL} C \sin k(L - \frac{L}{4})$$

$$-A \sin \frac{kL}{4} = e^{-ikL} C \sin \frac{3kL}{4}$$

$$-A \frac{\sin \frac{kL}{4} e^{+ikL}}{\sin \frac{3kL}{4}} = C$$

$$C = -A \frac{\sin \frac{kL}{4} e^{+ikL}}{\sin \frac{3kL}{4}}$$

$$y_1 = -2jA \sin kx$$

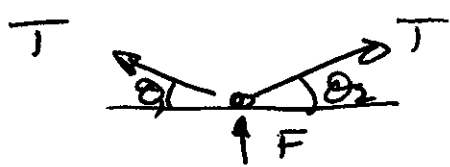
$$y_2 = -2j e^{-ikL} A \frac{\sin \frac{kL}{4} e^{+ikL}}{\sin \frac{3kL}{4}} \sin k(L-x)$$

$$= -2jA \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \sin k(L-x)$$

$$\frac{dy_1}{dx} = -2jkA \cos kx$$

$$\frac{dy_2}{dx} = +2jkA \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \cos k(L-x)$$

④ at  $x = \frac{L}{4} \quad \sum f_y = 0$



$$F + T \sin \theta_1 + T \sin \theta_2 = 0$$

$$F - T \frac{dy_1}{dx} + T \frac{dy_2}{dx} = 0$$

$$F + 2jkTA \cos \frac{kL}{4} + 2jkTA \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \cos \frac{3kL}{4} = 0$$

$$F + 2jkTA \left( \cos \frac{kL}{4} + \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \cos \frac{3kL}{4} \right) = 0$$

$$2jkTA \left( \cos \frac{kL}{4} + \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \cos \frac{3kL}{4} \right) = -F$$

$$A = - \frac{F}{2jkT \left[ \cos \frac{kL}{4} + \frac{\sin \frac{kL}{4}}{\sin \frac{3kL}{4}} \cos \frac{3kL}{4} \right]}$$

⑤ Drive point impedance

$$Z_{no} = \frac{F}{j\omega Y_1|_{x=\frac{L}{4}}}$$

$$Y_1 = +Z_j \frac{F}{Z_j KT \left[ \cos \frac{KL}{4} + \frac{\sin \frac{KL}{4}}{\sin \frac{3KL}{4}} \cos \frac{3KL}{4} \right]} \sin kx$$

$$\frac{dY_1}{dx} = \frac{j\omega F}{KT} \frac{1}{\cos \frac{KL}{4} + \frac{\sin \frac{KL}{4}}{\sin \frac{3KL}{4}} \cos \frac{3KL}{4}} \sin kx$$

$$Z_{no} = \frac{F}{\frac{j\omega F}{KT} \frac{1}{\cos \frac{KL}{4} + \frac{\sin \frac{KL}{4}}{\sin \frac{3KL}{4}} \cos \frac{3KL}{4}} \sin \frac{KL}{4}}$$

=

$$\frac{F}{\frac{j\omega F}{KT} \frac{1}{\frac{\cos \frac{KL}{4}}{\sin \frac{KL}{4}} + \frac{\cos \frac{3KL}{4}}{\sin \frac{3KL}{4}}}}$$

=

$$= -j \rho c \left( \cot \frac{KL}{4} + \cot \frac{3KL}{4} \right)$$

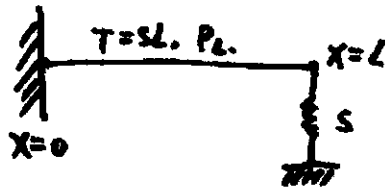
$$c = \sqrt{\frac{T}{\rho}}$$

$$\rho c^2 = T$$

$$k = \frac{\omega}{c}$$



2.11.1.



The wave equation is  $\frac{\partial^2 y}{\partial x^2} + k^2 y = 0$ .

The B.C.s are:

at  $x=0$ ,  $y=0$  (1)

at  $x=L$

$T \sin \theta - S y = 0$ .

$\Rightarrow T \frac{dy}{dx} + S y = 0$  (2).



Assume the solution is:

$y(x,t) = (A e^{-j k x} + B e^{j k x}) e^{j \omega t}$

substitute into B.C.s.

$A + B = 0$  (3)

$T[-j k A e^{-j k L} + j k B e^{j k L}] + S[A e^{-j k L} + B e^{j k L}] = 0$ .

(4)

From (3)  $\Rightarrow B = -A$ . substitute into (4).  
and rearrange, obtain:

$\tan(kL) = -kL$  (5)

(5) is solved graphically, we get:

$$(kL)_1 \approx 0.65\pi.$$

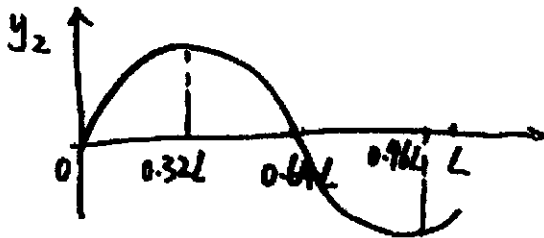
$$(kL)_2 \approx 1.57\pi.$$

$$(kL)_3 \approx 2.54\pi.$$

The fundamental is  $\sin \frac{(kL)_1}{L} x = \sin \frac{0.65\pi}{L} x$ .



First overtone:  $\sin \frac{(kL)_2}{L} x = \sin \frac{1.57\pi}{L} x$ .



2.11.1.

