Michael Williamson Tabango

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EDUCATION

P.h.D., Mechanical Engineering, Purdue University, West Lafayette, IN

Expected May 2026

Specialization: Human-Machine Interactions

Advisor: Dr. Neera Jain Funding: Ross Fellowship

B.S., Mechanical Engineering, Brigham Young University, Provo, UT

Apr 2022

RESEARCH EXPERIENCE

Graduate Research Assistant, Purdue University

June 2022-Present

Cognitive State Modeling Project

- Developed a novel method for matching fixations to dynamic Areas of Interest (AOIs).
- Defined the experimental protocol for a between subject experiment.
- Wrote scripts to import and analyze raw data from psychophysiological sensors.
- Mentored undergraduate student working on driving simulation development and sensor integration.
- Interviewed undergraduate students and assisted in making hiring decisions.
- Prepared materials for annual report to sponsor.
- Submitted an IRB protocol for human subject studies.
- Submitted poster for student conference outlining experimental design.

Undergraduate Research Assistant, Brigham Young University

Oct 2020-April 2022

LLNL Boat Landing Project

- Developed a trajectory following lab demo for use in motion capture room.
- Assisted with flight tests.
- Implemented complementary filter to estimate attitude of platform and tuned using motion capture data as ground truth.
- Tuned multirotor controllers.
- Assisted new students with learning ROS and other onboarding procedures.
- Wrote sections of a conference paper disseminating results.

Archer Aviation Project

- Researched various signals of opportunity localization solutions for project sponsored by Archer Aviation
 with the objective of developing a localization solution for use in urban landings that is robust to GPS
 failure.
- Produced plots demonstrating feasibility of method with simulated data.
- Selected hardware for multirotor to be used by Archer project to test our EKF in hardware and built it.

WORK EXPERIENCE

Civil Engineering Department

Aug 2020-May 2021

Teaching Assistant

Provo, UT

- Taught Recitations twice a week.
- Held exam reviews and TA hours.
- Audited student self-graded homework.

Capstone

Aug 2021-April 2022

Rocket Attitude Control Team

Provo, UT

Researched various methods of rocket attitude control and used a design matrix to make a final decision to

- Researched various methods of rocket attitude control and used a design matrix to make a final decision to use canard fins.
- Wrote estimation and controls algorithms that would run on Raspberry Pi.
- Successfully launched system three times.

PUBLICATIONS

1. A. D. Jordan, M. Rydalch, T. McLain, and **M. Williamson**, "Precision Maritime Localization and Landing with Real-time Kinematic GNSS," *AIAA Scietech Forum*, National Harbor, MD, USA, Jan 23-27, 2023. https://arc.aiaa.org/doi/abs/10.2514/6.2023-0488.

SKILLS

- Programming Languages: Python, MATLAB, C++, Bash, ROS
- Sensor Fusion: Asymptotic observers, EKFs, UKFs, grid mapping, EKF SLAM, computer vision-based localization.