PURDUE UNIVERSITY REQUEST FOR ADDITION, EXPIRATION, OR REVISION OF A GRADUATE COURSE (500-600 LEVEL)

57-06

DEPARTMENT ECE			EFFECTIVE SE	SSION Spr08			
INSTRUCTIONS: Please check the iter	ms below which o	describe the purpose of t	his request.				٦
	a supporting doo irse offered at a ourse se number se title	cuments (complete pr			8. 9. 10. 11.	Change in course attributes Change in instructional hours Change in course description Change in course requisites Change in semesters offered Transfer from one department to another	
PROPOSED:		EXISTING:				TERMS OFFERED	
Subject Abbreviation Course Number Long Title CONTROL OF ROBOT MAI Short Title CONTRL ROBOT M Abbreviated title will be entered in CREDIT TYPE 1. Fixed Credit: Cr. Hrs. 2. Variable Credit Range:	MANIPULTRS by the Office of the Re	Subject Abbreviation Course Number	COUR	682 SE ATTRIBUTE 7. Registra	tion Ap	Check All That Apply: Summer Fall Spring CAMPUS(ES) INVOLVED Calumet N. Central Cont Ed Tech Statewide Ft. Wayne W. Lafayette Indianapolis	
Minimum Cr. Hrs (Check One) To Or Maximum Cr. Hrs 3. Equivalent Credit: Yes No		2. Satisfactory/Orisatisfactory 3. Repeatable Maximum Repeatable 4. Credit by Examination 5. Designator Required 6. Special Fees Weeks % of Credit Offered Allocated			Title al Privile pus Ex Mediur	ege	
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COURSE DESCRIPTION (INCLUDE REQUI		School School Dags				,	
Calumet Department riead	Date (Calumet School Dean		Date	Calur	net Undergrad Curriculm Committee Da	.e
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Indianapolis Department Head	Date I	ndianapolis School Dean		Date	Unde	rgrad Curriculm Committee Da	ιe
North Central Department Head Market RM Jal	Date 1	North Central Chancellor	in stay	Date	Date	Approved by Graduate Council	
West Lafayette Départment Head	Date V	West Lafayette College/Sch	ool Dean	Date	Grad	uate Council Secretary Da	te
Graduate Area Committee Convener	Date (Graduate Dean		Date	West	Lafayette Registrar Da	te

TO: The Faculty of the College of Engineering

FROM: The Faculty of the School of Electrical and Computer Engineering

RE: Deletion of ECE 682

The faculty of the School of Electrical and Computer Engineering has approved the deletion of the following course. This action is now submitted to the Engineering Faculty with a recommendation for approval.

ECE 682 Control of Robot Manipulators

Sem. 2. Class 3, cr. 3. (Offered in alternate years.)
Prerequisite: ECE 569, ECE 602. Authorized equivalent courses or consent of instructor may be used in satisfying course pre- and corequisites.

The dynamical models to design controllers for the manipulator motion are discussed in Lagrange's and Newton-Euler's formulations. To make the manipulator motion track a desired trajectory, the system will be designed using PID-controllers, eigenvalue assignment, and adaptive self-tuning control. The design of these controllers for compliant motion of the manipulators also is discussed in detail. The implementation of the foregoing controllers is outlined.

Reason:

Course has not been taught for an extended period of time. Course has been deleted from the curriculum.

Mark J.T. Smith, Head School of Electrical & Computer Engineering

APPROVED FOR THE FACULTY
OF THE SCHOOLS OF ENGINEERING
BY THE ENGINEERING
CURRICULUM COMMITTEE

ECC Minutes #10

Date _/2-3-07

Chairman ECC Wishal of tou