

L_0 -Minimization

The problem:

$$\begin{aligned} \min \|x\|_0 \\ \text{s.t. } Ax = b \end{aligned} \quad \text{--- (P}_0\text{)}$$

Remark: if we relax the constraint to $\|Ax - b\|^2 \leq \varepsilon$, then under appropriate choices of ε and λ ,

$$\begin{aligned} \min \|x\|_0 \\ \text{s.t. } \|Ax - b\| \leq \varepsilon \end{aligned} = \min_x \|Ax - b\|^2 + \lambda \|x\|_0$$

Meaning of (P_0) : We know that there are infinitely many solutions for (P_0) . But there is one with the fewest non-zero. Our goal is to find out this solution.

Compare (P_0) with LASSO: Typically in LASSO, we assume $y \cong X\beta + \varepsilon$. There is nothing called "infinitely many solution" because the goal is to find approximation (or fitting) to y .

What is $\|x\|_0$? Note that $\|x\|_0$ is only a quasi-norm, and is not a norm.

Triangle inequality: (Yes)

$$\|x+y\|_0 \leq \|x\|_0 + \|y\|_0$$

Scalar multiplication: (No)

$$\|tx\|_0 \neq t\|x\|_0$$

Properties of L_0 -Minimization

Mutual Coherence

Two-ortho System

$A = [\Psi, \Phi]$,
where Ψ and Φ orthonormal

$$\mu(A) \stackrel{\text{def}}{=} \max_{i,j} |\psi_i^T \phi_j|$$

General System

Any A

$$\mu(A) \stackrel{\text{def}}{=} \max_{i,j} \frac{|a_i^T a_j|}{\|a_i\|_2 \|a_j\|_2}$$

Why care about mutual coherence?

- We need a way to quantify the solution of (P_0) .
- $\mu(A)$ provides some measurable method for this purpose.

Important Theorem (Elad 2.1)

Let α and β be such that

$$y = \Psi \alpha \quad \text{and} \quad y = \Phi \beta,$$

then

$$\|\alpha\|_0 + \|\beta\|_0 \geq \frac{2}{\mu(A)}, \quad \text{where } A = [\Psi, \Phi].$$

Why is this result important?

- α and β are the "sub-solution" to (P_0) .
- Theorem says the sparsity of the solution cannot be arbitrarily low.

So do we want $\mu(A)$ large or small?

Small $\mu(A) \Rightarrow \|\alpha\|_0 + \|\beta\|_0 \geq \text{large \#}$.

So # non-zero will be large, i.e. Not sparse.

Large $\mu(A) \Rightarrow \text{fewer \# non-zero}$.
i.e. sparse.

Property of $\mu(A)$

if $A = [\Psi, \Phi]$, then

$$\frac{1}{\sqrt{n}} \leq \mu(A) \leq 1$$

proof: " $\mu(A) \leq 1$ ":

(optional) $|\psi_i^T \phi_j|^2 \leq \|\psi_i\|^2 \|\phi_j\|^2$, by Cauchy
 $= 1, \quad \forall i, j.$

$$\text{So } \max_{ij} |\psi_i^T \phi_j| \leq 1.$$

" $\mu(A) \geq \frac{1}{\sqrt{n}}$ "

Suppose $\mu(A) < \frac{1}{\sqrt{n}}$, then $\max_{ij} |\psi_i^T \phi_j| < \frac{1}{\sqrt{n}} \quad \forall i, j$

$$\Rightarrow |\psi_i^T \phi_j| < \frac{1}{\sqrt{n}} \quad \forall i, j$$

choose $\phi_j = [0 \dots \underset{j+n}{1} \dots 0]$, then $|\psi_i^T \phi_j| = |\psi_{ij}|$

Since $|\psi_i^T \phi_j| < \frac{1}{\sqrt{n}} \quad \forall i, j$, we have $|\psi_{ij}| < \frac{1}{\sqrt{n}}$.

choose $\Phi = \text{Fourier}$. Then

$$\|\psi_i\|^2 = \sum_{j=1}^n \psi_{ij}^2 < \sum_{j=1}^n \left(\frac{1}{\sqrt{n}}\right)^2 = 1. \text{ Contradiction. So must have } \mu(A) \geq \frac{1}{\sqrt{n}}.$$

The result of Theorem Elad 2.1 is not enough.

(i) it is about "sub-solutions" of a system

(ii) it does not address the "most sparse solution" problem who is the

Theorem Elad 2.3

$$A = [\Phi, \bar{\Phi}]$$

if a solution $Ax = y$ has ~~#~~ less than $\frac{1}{\mu(A)}$ non-zeros, then it is necessarily the sparsest solution

proof: (outline) First assume that α and β are both

~~$\Phi\alpha = y$ and $\bar{\Phi}\beta = y$~~
Solutions. Then

$$A\alpha = y \quad \text{and} \quad A\beta = y$$

$$\Rightarrow A(\alpha - \beta) = 0, \quad \text{then we let } e = \alpha - \beta, \quad \text{and } e \in \text{Null}(A).$$

$$\Rightarrow \begin{bmatrix} \Phi & \bar{\Phi} \end{bmatrix} \begin{bmatrix} e_\Phi \\ e_{\bar{\Phi}} \end{bmatrix} = 0$$

$$\Rightarrow \underbrace{\Phi e_\Phi = -\bar{\Phi} e_{\bar{\Phi}}}_{\text{"something"}} \quad \text{So by Elad 2.1 we have}$$

$$\|e_\Phi\|_0 + \|e_{\bar{\Phi}}\|_0 \geq \frac{2}{\mu(A)}.$$

$$= \|e\|_0 \quad \text{because } e = \begin{bmatrix} e_\Phi \\ e_{\bar{\Phi}} \end{bmatrix}$$

and then

$$\|e\|_0 \leq \|\alpha\|_0 + \|\beta\|_0 \quad \text{by triangle inequality.}$$

So we have

$$\|\alpha\|_0 + \|\beta\|_0 \geq \frac{2}{\mu(A)}.$$

Now, if $\|\alpha\|_0 \leq \frac{1}{\mu(A)}$, then $\|\beta\|_0 \geq \frac{1}{\mu(A)}$.

So ~~that~~ α is the most sparse solution.

Is mutual coherence good?

- Not quite. Limited to two-ortho so far.

Spark

The spark of a matrix A is the smallest number of columns that are linearly dependent

spark VS rank:

rank = largest number of columns that are linearly independent.

Computing spark is NP-hard!!

Theorem Elad 2.4

If a system $Ax = y$ has a solution such that $\|x\|_0 < \text{spark}(A)/2$, then x is necessarily the most sparse solution.

Good thing about Elad 2.4:

- works for any matrix A
- global optimal certificate

Bad thing:

- NP hard to verify not necessarily (Φ, Φ) .

For any matrix A ,

$$\text{spark}(A) \geq 1 + \frac{1}{\mu(A)}. \quad (*)$$

Theorem 2.5 Elad

If a system has a solution x s.t.

$$\|x\|_0 < \frac{1}{2} \left(1 + \frac{1}{\mu(A)} \right), \text{ then}$$

x is necessarily the most sparse solution

proof: x is most sparse if

$$\|x\|_0 < \text{spark}(A)/2.$$

~~So if $\|x\|_0 < \text{spark}(A)/2$~~ Now, since

$$\text{spark}(A) \geq 1 + \frac{1}{\mu(A)},$$

so if $\|x\|_0 < \frac{1}{2} \left(1 + \frac{1}{\mu(A)} \right)$ then $\|x\|_0 < \frac{\text{spark}(A)}{2}$.

Summary

- ① (P_0) is NP hard problem. Solution exists, but very difficult to find.
- ② $\mu(A)$ and $\text{Spark}(A)$ are quantities to verify whether a solution is the most sparse or not.
- ③ $\mu(A)$ is easier to compute.
 $\text{Spark}(A)$ is NP hard to compute.