

Resilient UAVs Traffic Operation Using Fluid Queueing Models

Jiazhen Zhou

Advisors: Profs. Dengfeng Sun, Xiao Wang

November 8, 2019

PURDUE
ENGINEERING

Background and Motivation

- ▶ Background
 - ▶ Increasing amount of activities of UAVs in the civil aviation domain.
 - ★ Over one million UAVs have been registered.
 - ★ 7 million UAVs will be registered as estimated and 2 million for commercial use.
 - ▶ Large companies have initiated projects on UAVs delivery and transportation service.
 - ★ Amazon: Prime Air
 - ★ Uber: Uber Elevate



Figure: Prime Air



Figure: Uber Elevate

- ▶ Motivation
 - ▶ Recent transportation research has been focused on UAVs assisted traffic, but UAVs themselves can cause traffic congestions with increasing volume.
 - ▶ UAVs are sensitive to weather uncertainty. Congestion control under weather uncertainty brings more challenges.
 - ▶ Models that capture the characteristics of UAVs traffic is needed. Tools need to be developed to analyze the congestion of the UAVs traffic under uncertainties.

- ▶ Develop realistic and tractable models for UAV traffic under weather uncertainty
 - ▶ the **system level** model of UAV traffic: **aggregated flow**
 - ▶ the **change** of the weather conditions
 - ▶ the **impact** of weather change
- ▶ Analyze the system level of performance of UAV traffic in the merits of resilience
 - ▶ **define resilience** for UAV traffic
 - ▶ **derive conditions** for the UAV traffic to be resilient
 - ▶ improve the traffic **efficiency**

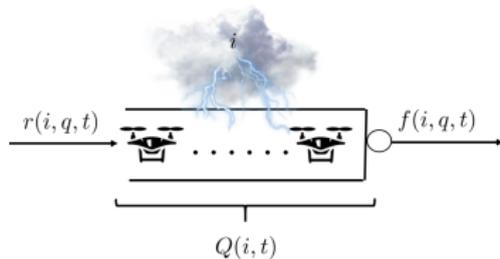


Figure: Single Fluid Queuing Model

Fluid Queuing model for UAV traffic:

$$\begin{aligned}\dot{Q}(i, q, t) &= r(i, q, t) - f(i, q, t), \\ f(i, q, t) &= \min(s(i, q, t), c_i).\end{aligned}$$

States:

Q : stochastic queue length,
 q : realization of queue length,
 I : stochastic mode,
 i : realization of mode,
 r : receiving flow
 s : sending flow
 f : outflow
 c_i : saturation rate(capacity)

Weather Uncertainty:

Continuous Markov Process with governing transition matrix: Λ

Assume: process is irreducible and ergodic:
steady state distribution: $p\Lambda = 0, |p| = 1$

More Models

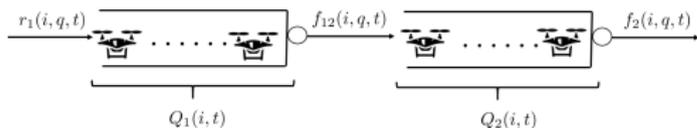


Figure: Tandem Fluid Queuing Model

$$\begin{aligned}
 r_1 &= a, \\
 s_1(i, q) &= \min(vq_1, c_{1i}), \\
 r_2(q) &= w(\theta - q_2), \\
 f_{12}(i, q) &= \min(s_1, r_2), \\
 f_2(i, q) &= \min(vq_2, c_{2i}).
 \end{aligned}$$

Observation(fundamental diagram):

- ▶ More traffic flow can be sent to downstream if there is more traffic in upstream.
- ▶ Less traffic flow can be sent to downstream if there is more traffic in downstream.
- ▶ No flow can be sent to downstream if downstream is congested.

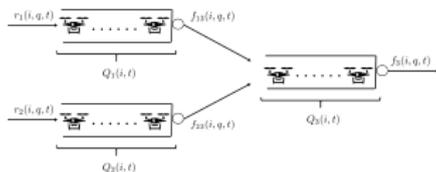


Figure: Merge Fluid Queuing Model

$$\begin{aligned}
 r_1 &= a_1, \\
 r_2 &= a_2, \\
 s_{13}(i, q) &= \min\{vq_1, c_{1i}\}, \\
 r_{13}(i, q) &= \frac{q_1}{q_1 + q_2} w(\theta - q_3), \\
 f_{13}(iq) &= \min\{s_{13}, r_{13}\}, \\
 s_{23}(i, q) &= \min\{vq_2, c_{2i}\}, \\
 r_{23}(i, q) &= \frac{q_2}{q_1 + q_2} w(\theta - q_3), \\
 f_{23}(iq) &= \min\{s_{23}, r_{23}\} \\
 f_3(i, q) &= \min\{vq_3, c_{3i}\}.
 \end{aligned}$$

- ▶ Quantity of Interest
 - ▶ Stability: the long run boundedness of the queueing system
 - ★ Mathematical Definition:

$$\limsup_{t \rightarrow \infty} \frac{1}{t} \int_0^t \mathbb{E}[\exp(|Q(\tau)|)] d\tau \leq C. \quad (1)$$

- ▶ Efficiency: maximum throughput of the queueing system
 - ★

$$\begin{aligned} & \underset{a}{\text{maximize}} && |a|, \\ & \text{subject to} && (1). \end{aligned} \quad (2)$$

- ▶ Some intuitive results:

If the tandem queue is stable, then $a \leq \sum_{i=1}^m c_{ji}p_i$, $j = 1, 2$.

If the merge queue is stable, then $a_j \leq \sum_{i=1}^m c_{ji}p_i$, for $j = 1, 2$, and $a_1 + a_2 \leq \sum_{i=1}^m c_{3i}p_i$.

- ▶ Some not so intuitive result:

If there exist positive constants $\alpha_1, \alpha_2 \dots \alpha_m$ and β such that:

$$\forall i \in \mathcal{I}, \alpha_i \beta (2a_1 + 2a_2 - \tilde{F}_m(i)) + \sum_{j \in \mathcal{I}} \lambda_{ij} (\alpha_j - \alpha_i) \leq -1$$

*merge queue system is stable.*¹

¹See details at: "Resilient UAV Traffic Congestion Control using Fluid Queuing Models" (Under Review)

Numerical Experiments

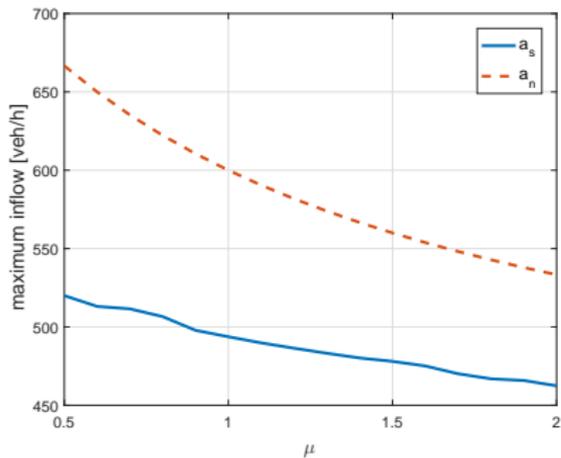


Figure: Effect of Transitional Intensity

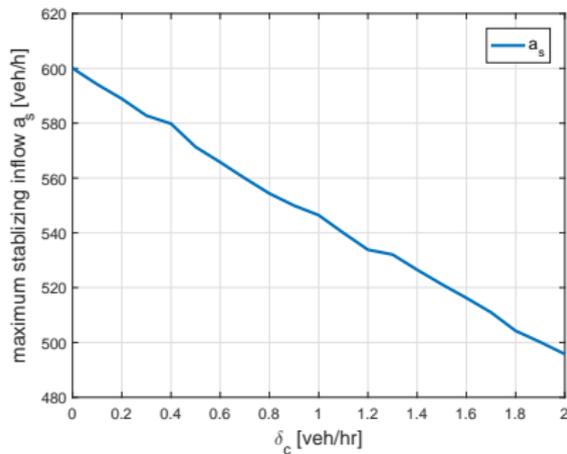


Figure: Effect of Capacity Fluctuation

- ▶ Stochastic fluid queueing models can also be applied to other types of traffic.
- ▶ Discrete version of the results can also be derived.
- ▶ Feedback control policies can be developed for more models.