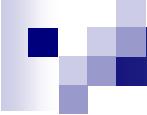


# Lecture 10: Multi-Objective Optimization Exercises



# Multi-Objective Optimization in GOSET

- GOSET employ an **elitist GA** for the multi-objective optimization problem
- **Diversity control algorithms** are also employed to prevent over-crowding of the individuals in a specific region of the solution space
- The non-dominated solutions are identified using the recursive algorithm proposed by **Kung et al.**

# Schaffer's problem

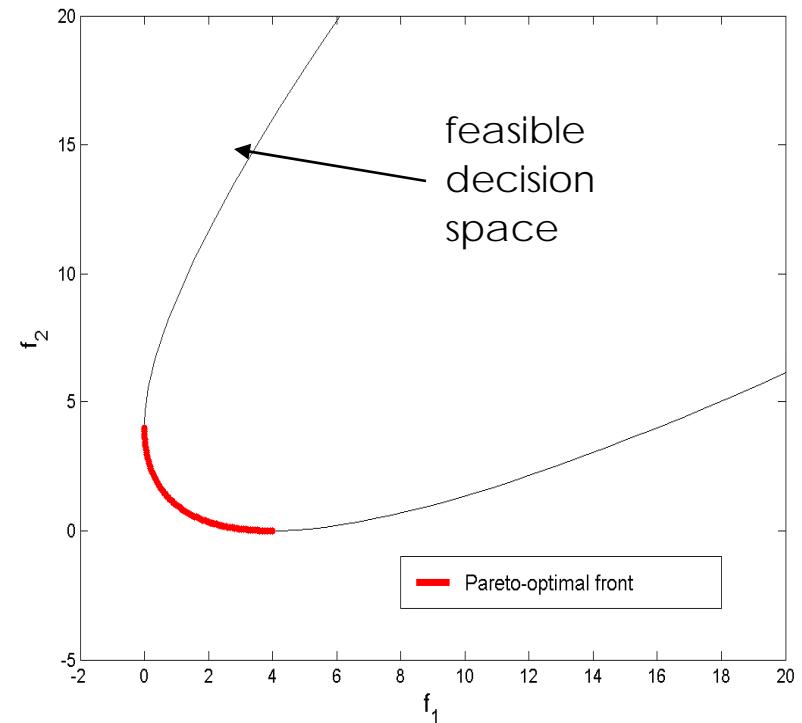
# Problem Statement

- Schaffer's problem is a single variable problem with two objectives to be minimized

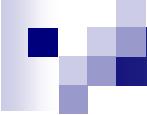
$$\min f_1(x) = x^2$$

$$\min f_2(x) = (x - 2)^2$$

$$-10 < x < 10$$



- The Schaffer's problem has Pareto optimal solutions  $x \in [0, 2]$



# Fitness Function

- Two objectives have positive values and they are to be minimized
- The fitness function values are defined to be the negative of the objective function values

# **schaffer.m**

```
% Schaffer's problem
```

```
function [ f ] = schaffer ( x )
```

```
f ( 1 , 1 ) = -x ( 1 ) ^ 2 ;
```

```
f ( 2 , 1 ) = - ( x ( 1 ) - 2 ) ^ 2 ;
```

# schaffer\_problem.m

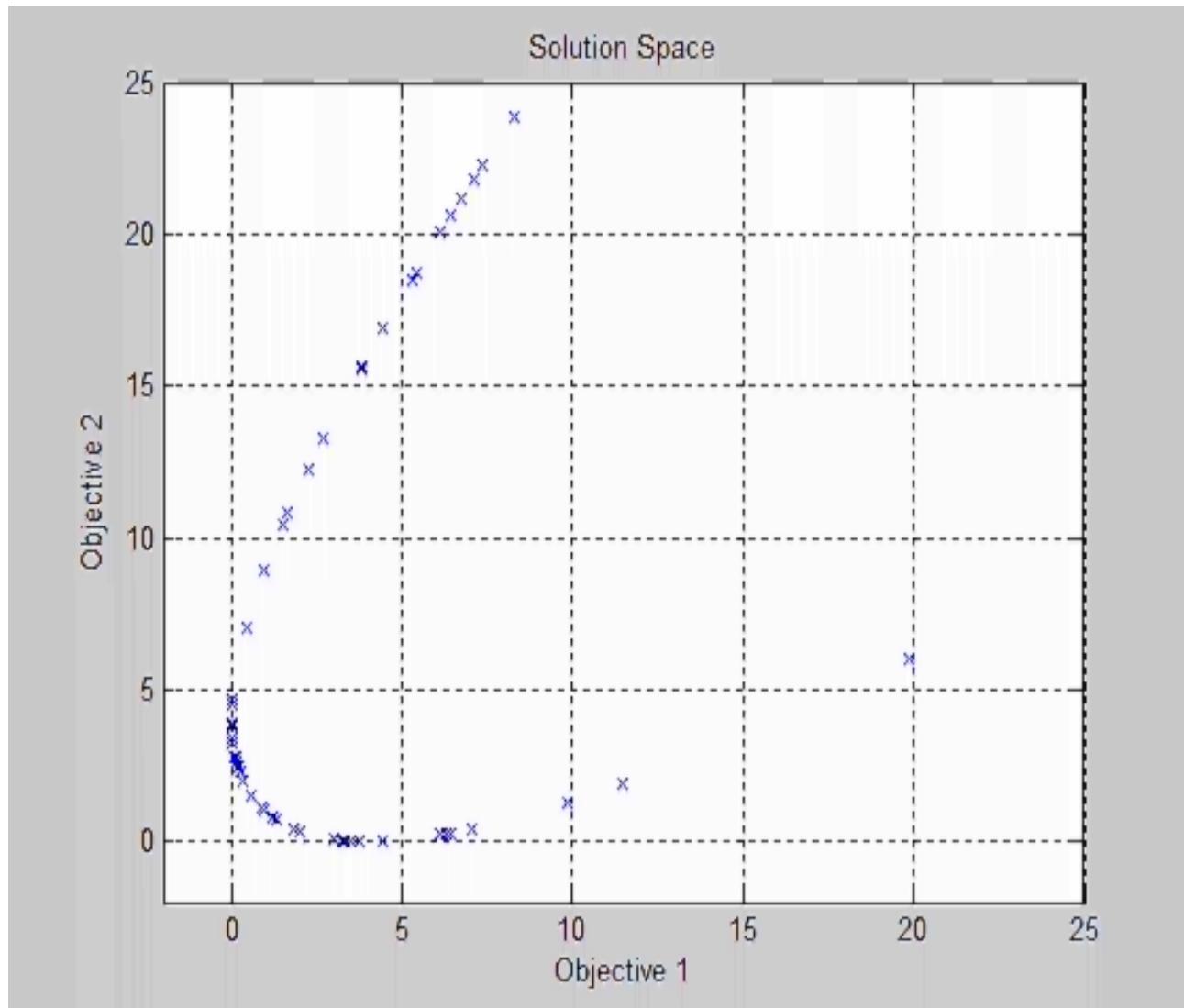
```
% Optimization of Schaffer's Problem

% Initialize the parameters
GAP = gapdefault(2);
GAP.fp_ngen = 20;
GAP.fp_obj = 0;
GAP.sc_alg = 1;
GAP.op_list = [];
GAP.pp_list = [1 2];
GAP.pp_style = [1 1];
GAP.pp_sign = [-1 -1];
GAP.pp_axis = [-2 25 -2 25];

%
% gene
%      x1
%      1
GAP.gd_min = [ -10 ];
GAP.gd_max = [ 10 ];
GAP.gd_type = [ 2 ];
GAP.gd_cid = [ 1 ];

[P,GAS]=gaoptimize(@schaffer_fit,GAP,[],[],[],[]);
```

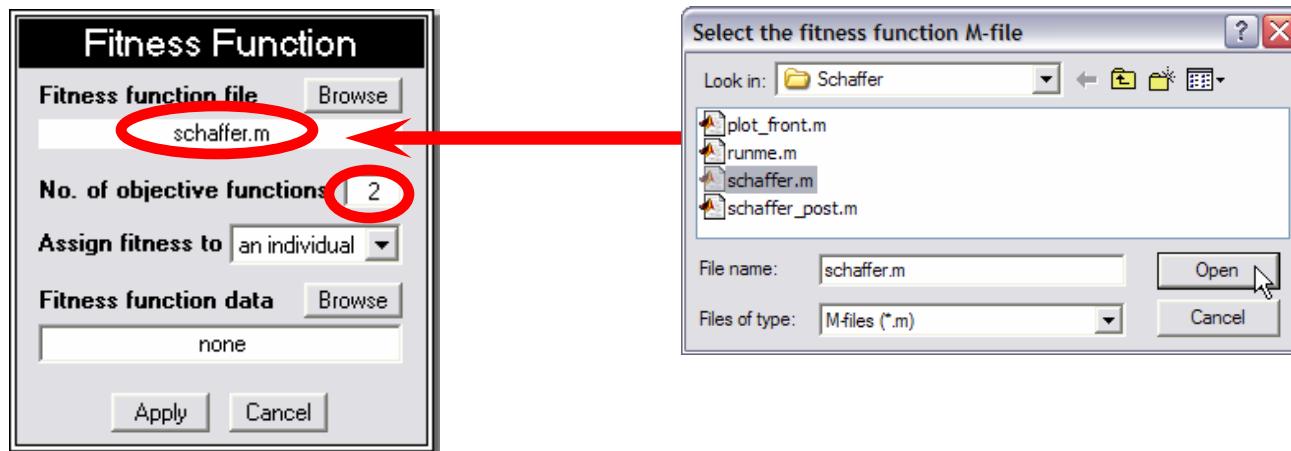
# Pareto Plot (100 Generations)



# GUI approach

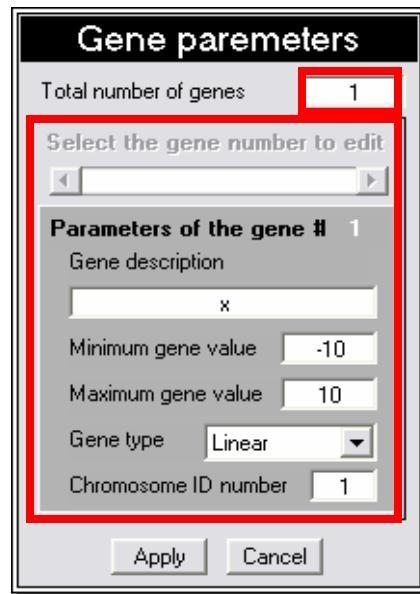
## ■ Define the fitness function

- In the fitness function window, browse and select the fitness function ‘schaffer.m’ defined in the command line approach
- Schaffer’s problem has two objective functions and thus the number of objective functions is set to 2



## ■ Define the gene parameters

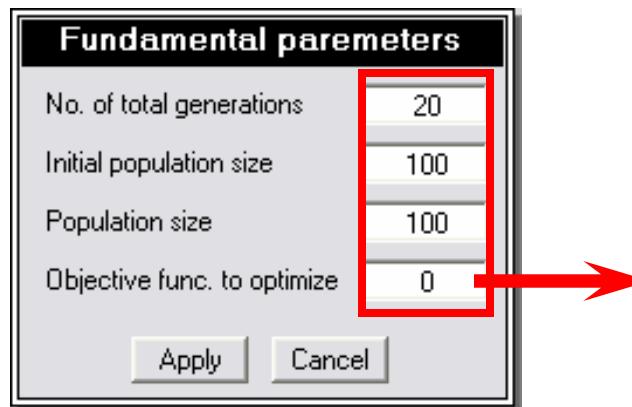
- There are only 1 parameter values in this problem, so set the total number of genes to 1



- The minimum and maximum gene value for  $x$  are to -10 and 10, 'Linear' gene type is used

## ■ Define the fundamental parameters

- In the fundamental parameter input field, set the number of total generations to **20**, the initial population size to **100**, the population size to **100**
- As there are two objective functions, ‘objective function to optimize’ is set to **0** then click ‘apply’

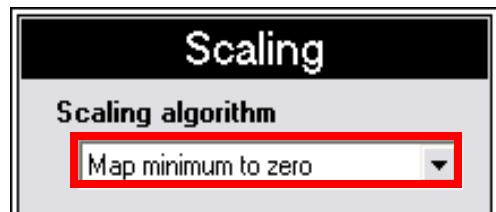


**Caution!!!**

Set ‘Objective function to optimize to 0 for multi-objective optimization problem

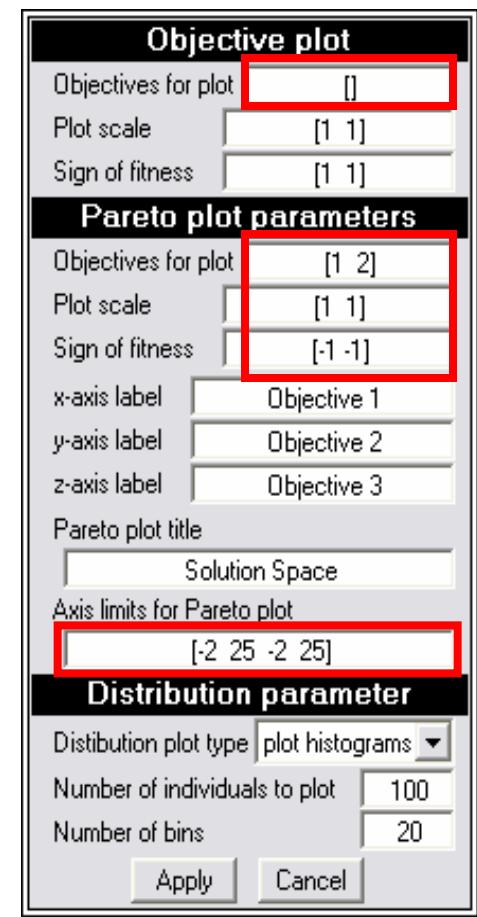
## ■ Define the scaling parameters

- The scaling algorithm is set to ‘Map minimum to zero’



## ■ Define the plotting parameters

- To display the Pareto plot, ‘Objectives for plot’ for the objective plot is set to ‘[ ]’ and the ‘Objectives for plot’ for the Pareto plot is set to ‘[1 2]’
- ‘Plot scale’ for the Pareto plot parameters are linear for all objectives
- Sign of fitness is set to -1 for both objectives
- Axis limits are defined as [ -2 25 -2 25]



## ■ Define the output reporting level

- For the text and graphical report, check the reporting option is set to ‘Text and plot’



## ■ Start GOSET



# Tanaka Problem

# Problem Statement

- Tanaka problem is a constrained optimization problem with two objectives to be minimized

$$\min f_1(x_1, x_2) = x_1$$

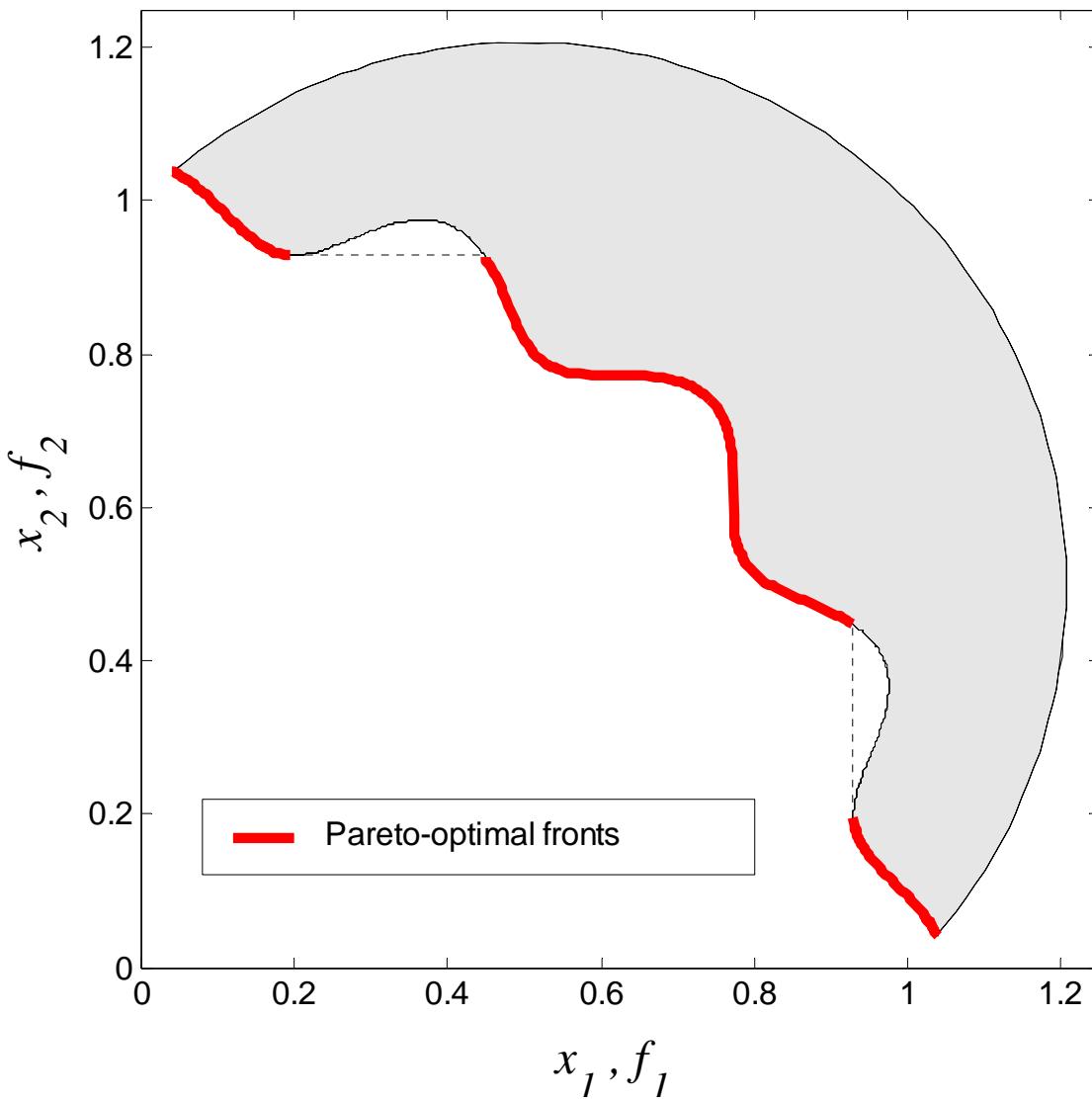
$$\min f_2(x_1, x_2) = x_2$$

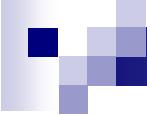
subject to  $C_1(x_1, x_2) = x_1^2 + x_2^2 - 1 - 0.1 \cos\left(16 \arctan \frac{x_1}{x_2}\right) \geq 0, \quad 0 \leq x_1 \leq \pi,$

$C_2(x_1, x_2) = (x_1 - 0.5)^2 + (x_2 - 0.5)^2 \leq 0.5, \quad 0 \leq x_2 \leq \pi.$

- Note the variable space is also the objective space

# Tanaka Problem





# Fitness Function

- Two objectives have positive values and they are to be minimized
- The fitness function values are defined to be the negative of the objective function values
- Infeasible solutions are assigned with -10 to reduce the chance of surviving

# tanaka.m

```
% Tanaka problem (1995)

function [f] = tanaka(x)

C1 = x(1)^2+x(2)^2-1-0.1*cos(16*atan(x(1)/x(2))) >= 0;
C2 = (x(1)-0.5)^2+(x(2)-0.5)^2 <= 0.5;

if C1 & C2
    f(1,1) = -x(1);
    f(2,1) = -x(2);
else
    f(1,1) = -10;
    f(2,1) = -10;
end
```

# tanaka\_problem.m

```
% Initialize the parameters
GAP = gapdefault(2);

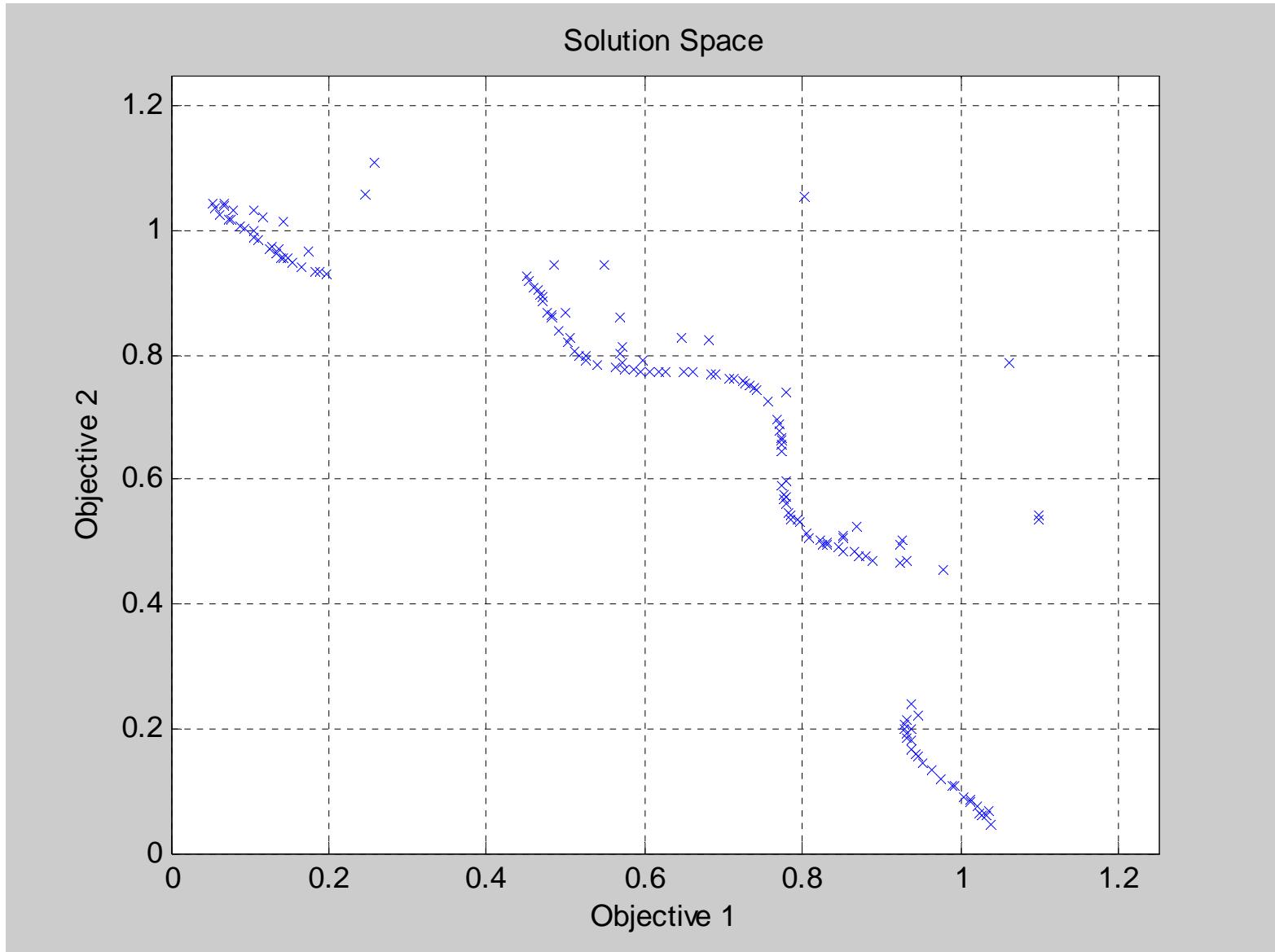
GAP.fp_ipop = 200;
GAP.fp_npop = 200;
GAP.fp_ngen = 200;
GAP.fp_obj = 0;
GAP.sc_alg = 6;           % sigma-truncation
GAP.op_list = [];         % list of objectives for objective plots
GAP.pp_list = [1,2];      % list parameters for Pareto plot
GAP.pp_sign = [-1,-1];   % sign of fitness for each objective
GAP.pp_axis=[0 1.25 0 1.25];    % axis limits for Pareto plot

%
% gene          x1      x2
% gene          1       2
GAP.gd_min  = [ 0     0     ];
GAP.gd_max  = [ pi    pi    ];
GAP.gd_type = [ 2     2     ];
GAP.gd_cid  = [ 1     1     ];

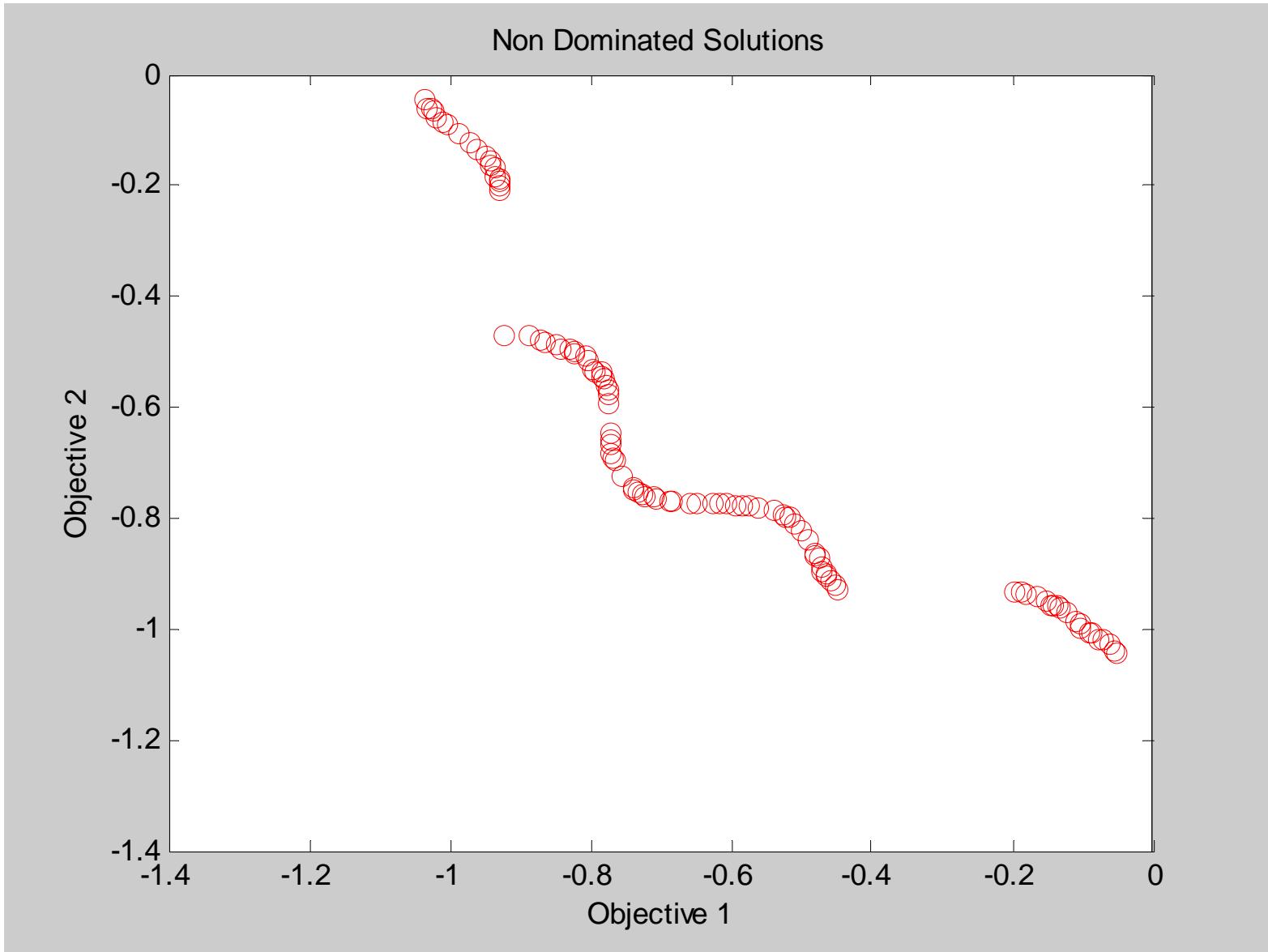
% perform optimization
[P,GAS]=gaoptimize(@tanaka,GAP,[],[],[],[]);

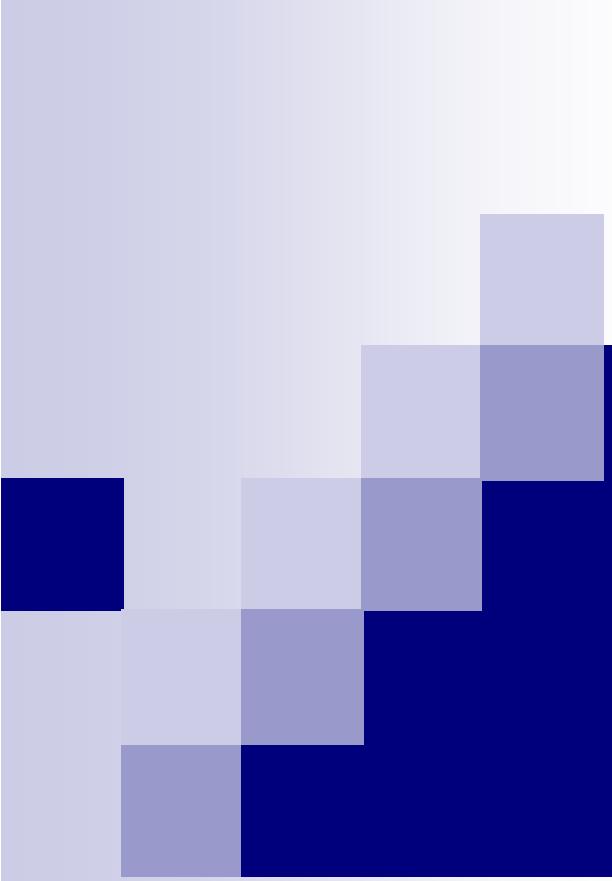
% find the nondominated set
nd=nondom(P.mfit,1);
ndi=find(nd==1);
figure(2);
plot(P.mfit(1,ndi),P.mfit(2,ndi),'ro');
title('Non Dominated Solutions');
xlabel('Objective 1');
ylabel('Objective 2');
```

# Pareto Plot



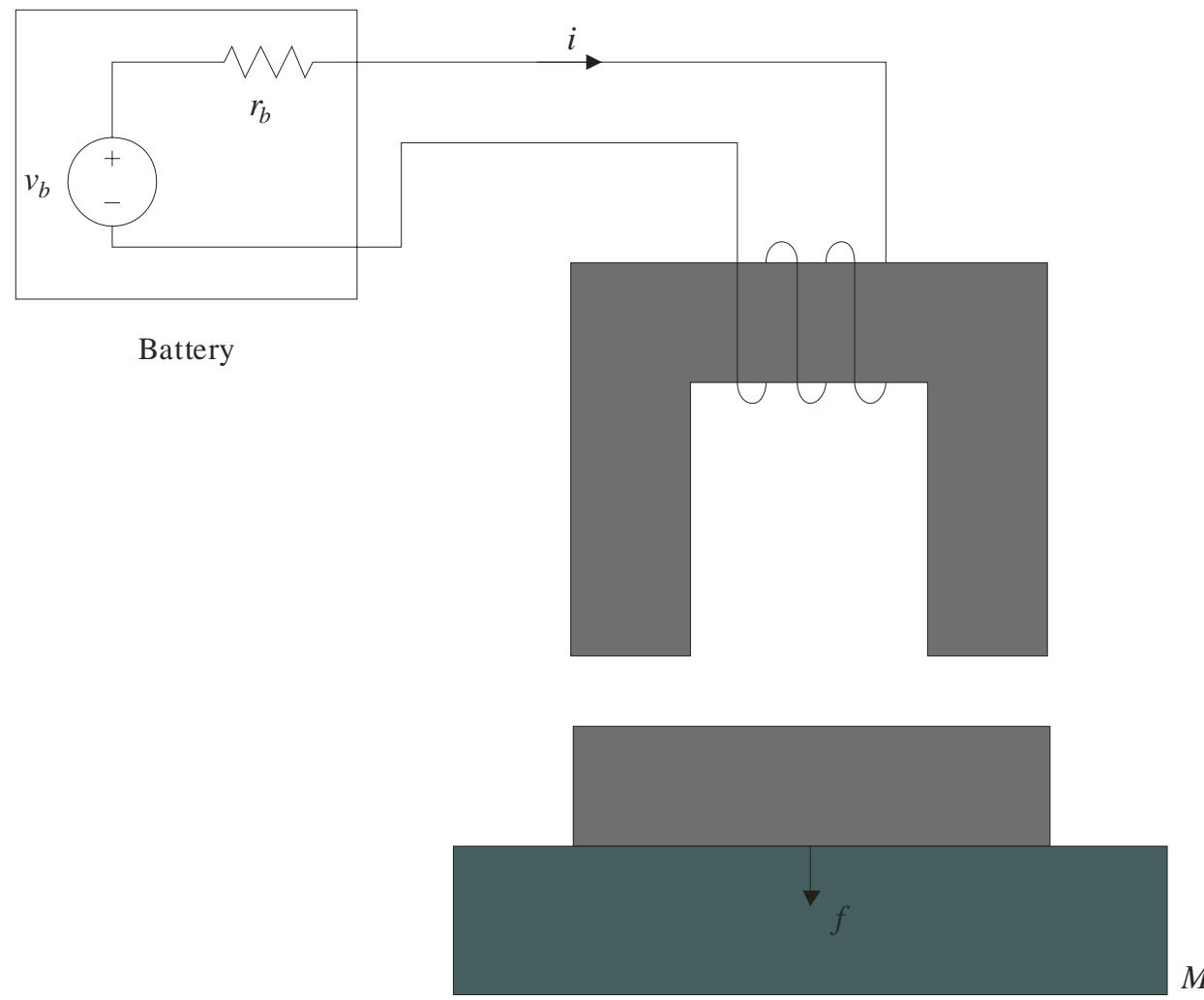
# Non Dominated Solutions





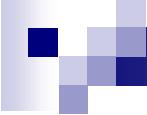
# Return of the ... Electromagnet

# Recall Our Electromagnet Design



# Multi Objective Fitness Function

$$\mathbf{f} = \begin{cases} \begin{bmatrix} 1 \\ \frac{m_1 + \varepsilon}{1} \\ \frac{1}{i + \varepsilon} \end{bmatrix} & c = 1 \\ \left( \sum_{c=1}^{10} c_i - 10 \right) \begin{bmatrix} 1 \\ 1 \end{bmatrix} & c < 1 \end{cases}$$



# New Matlab Files

- Electromagnet\_MultiObjective\_Fitness.m
- Electromagnet\_MultiObjective\_Design.m
- Electromagnet\_MultiObjective\_Design\_Review.m

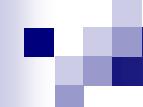
# Fitness Function Changes

## ■ Electromagnet\_Fitness

```
% compute the fitness
if (cmin == 1)
    fitness = 1/(m1+1e-6);
else
    fitness = sum(c)-length(c);
end
```

## ■ Electromagnet\_MultiObjective\_Fitness

```
% compute the fitness
if (cmin == 1)
    fitness = [1/(m1+1e-6); 1/(i+1e-6)];
else
    fitness = (sum(c)-length(c))*[1; 1];
end
```



# Electromagnet\_MultiObjective\_Design.m

```
% Electromagnet Design
%
% Written by:
% Ricky Chan for S.D. Sudhoff
% School of Electrical and Computer Engineering
% 1285 Electrical Engineering Building
% West Lafayette, IN 47907-1285
% E-mail: sudhoff@ecn.purdue.edu

% Set Up Population
GAP = gapdefault(2);
GAP.fp_ngen = 2500;
GAP.fp_ipop = 500;
GAP.fp_npop = 500;
GAP.mc_alg = 4.0;
GAP.dt_alg = 3;

% Set Up Reporting
GAP.op_list=[]; % No objective plot
GAP.pp_list=[1,2]; % Pareto plot
GAP.pp_xl='Inverse Mass'; % Axis labels
GAP.pp_yl='Inverse Current';
GAP.pp_axis=[0.0 2 0.0 1]; % Axis limits

% Set Up Migrations
GAP.mg_nreg=5; % number of regions
GAP.mg_tmig=100; % mean time between migrations
GAP.mg_pmig=0.05; % probability of a individual migrating

% Units
mm=1.0e-3;
cm=1.0e-2;
```

# Electromagnet\_MultiObjective\_Design.m

```
% Problem Requirement Data
Psi.M      = 10;                                % Mass of object (Kg)
Psi.G      = 9.8;                               % Gravity (m/s2)
Psi.g      = 0.5*cm;                            % Gap Width (m)
Psi.rhow   = [ 8900;    2701];                  % Wire - Kg/m3
Psi.sigmax = [ 58.0;    35.4]*1e6;             % Wire - A/Ohm
Psi.jmaxw  = [ 7.62;    6.14]*1e6;             % Wire - A/m2
Psi.descw  = ['Copper'; 'Aluminum'];            % Wire - Description
Psi.bmaxm  = [ 1.4;     0.7;          1.2];      % Steel - Bsat, T
Psi.rhom   = [ 7064.1; 8069.4;    7892.1];      % Steel - Density Kg/m3
Psi.myum   = [ 15000;   6000;      3500];        % Steel - Perm., (relative)
Psi.descm  = ['Microsil'; ...;
              'Superperm 80'; ...
              'Superperm 49'];                % Steel - Description
Psi.imax   = 6;                                 % Maximum current, A
Psi.lmax   = 10e-2;                            % Maximum length
Psi.pfmax  = 0.7;                             % Maximum packing factor
Psi.vb     = 12;                               % Battery Voltage
Psi.rb     = 0.5;                             % Battery Resistance

% Genetic Mapping
%           mw   ac   N   mm   ws   rww   ds   rdw   we   rwi   rwb   d
GAP.gd_min = [ 1  1e-8  10  1  1*cm  0.1  1*mm  0.1  1*mm  0.2  0.2  1*mm];
GAP.gd_max = [ 2  1e-4  1e3 3  10*cm  1.0  20*cm  1.0  5*cm  2.0  2.0  10*cm];
GAP.gd_type = [ 1  3  3  1  3  3  3  3  3  3  3  3 ];
GAP.gd_cid = [ 1  1  1  1  1  1  1  1  1  1  1  1 ];

% Solve Problem
[fP,GAS]= gaoptimize(@Electromagnet_MultiObjective_Fitness,GAP,Psi,[],[],[]);

% Save run
s=input('Type 1 to Save Run ');
if (s==1)
    save sample_multi_objective_run
end
```

# Electromagnet\_MultiObjective\_Design\_Review.m

```
% Electromagnet Design Review  
% Illustrates the evolution of the electromagnet design  
%  
% Written by:  
% S.D. Sudhoff  
% School of Electrical and Computer Engineering  
% 1285 Electrical Engineering Building  
% West Lafayette, IN 47907-1285  
% E-mail: sudhoff@ecn.purdue.edu
```

```
clear all
```

```
load sample_multi_objective_run
```

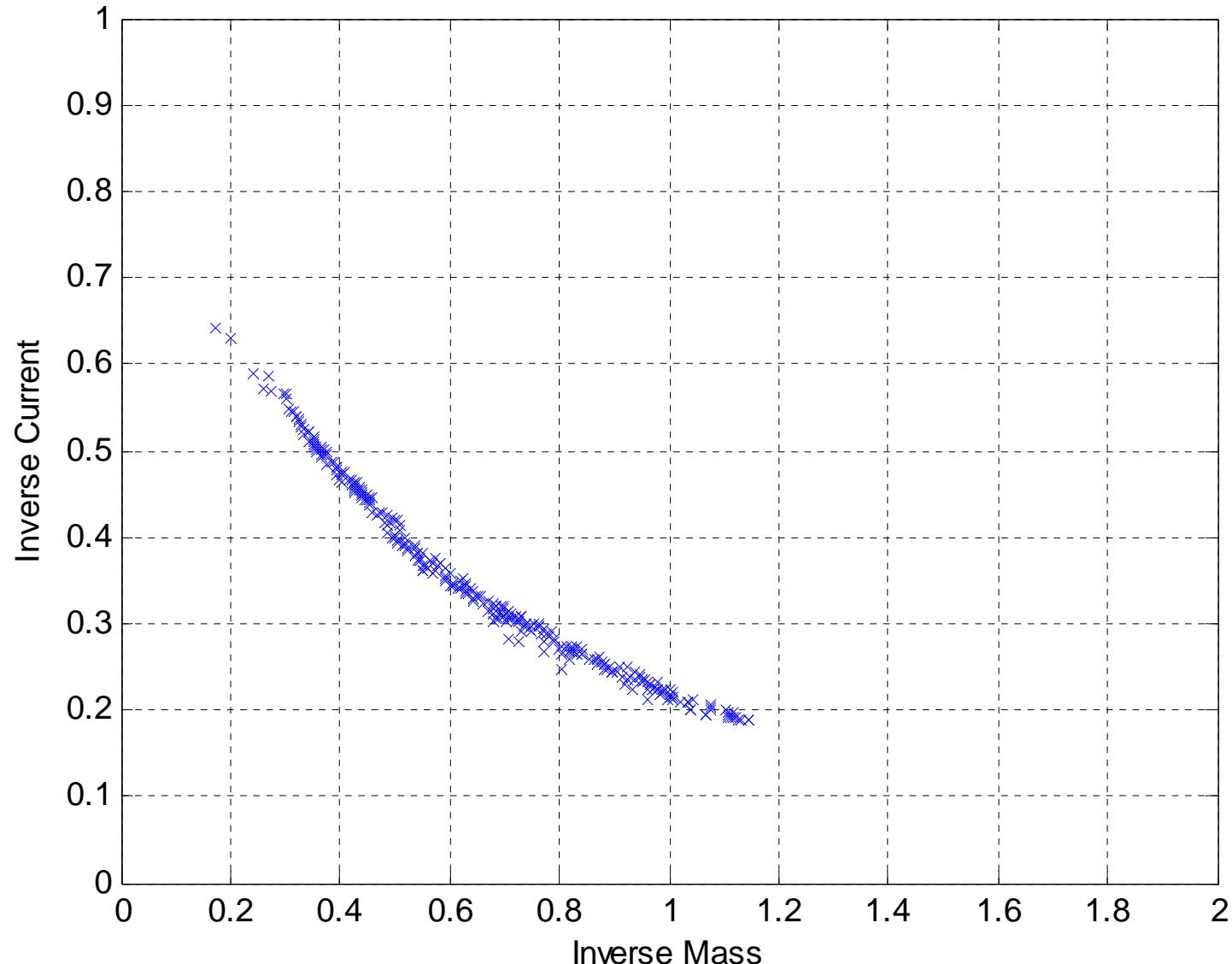
```
% Plot Pareto Optimal Front in Objective Space  
non_dominated_status=nondom(fP.mfit,1);  
non_dominated_indices=find(non_dominated_status==1);  
Mass=1./fP.mfit(1,non_dominated_indices)-1e-6;  
Current=1./fP.mfit(2,non_dominated_indices)-1e-6;  
figure(2)  
plot(Mass,Current,'ro');  
xlabel('Mass, kg');  
ylabel('Current, A');  
title('Trade Off Between Mass and Current Draw');
```

```
% Minimum Mass Design  
mmd=GAS.bestgenes(:,GAS.cg,1);  
Electromagnet_MultiObjective_Fitness(mmd,Psi,3);
```

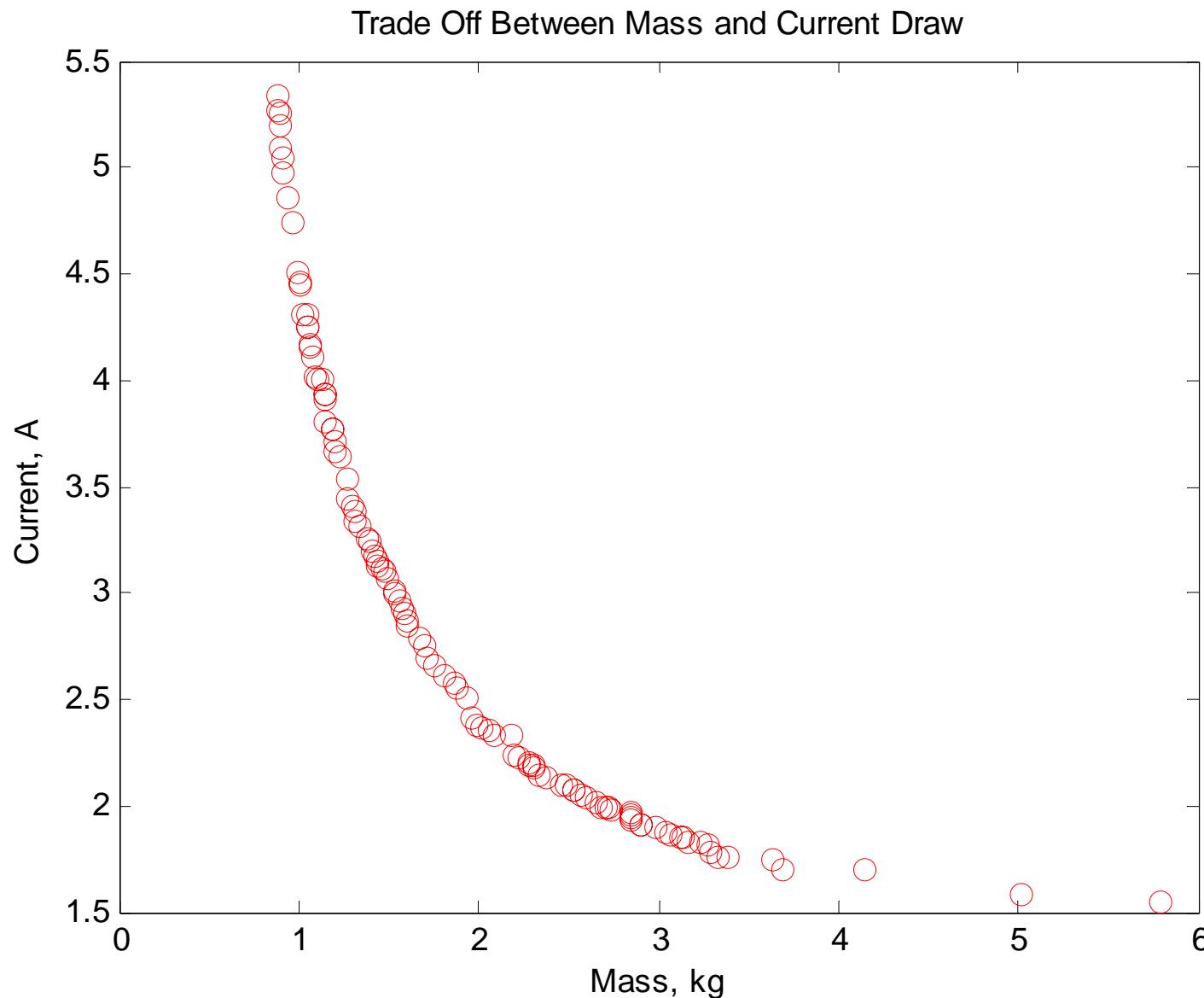
```
% Minimum Current Design  
mcd=GAS.bestgenes(:,GAS.cg,2);  
Electromagnet_MultiObjective_Fitness(mcd,Psi,5);
```

# Pareto Plot

Solution Space



# Design Space



# Design Extremes

- Design 1

  - Mass: 0.874 kg

  - Current: 5.33 A

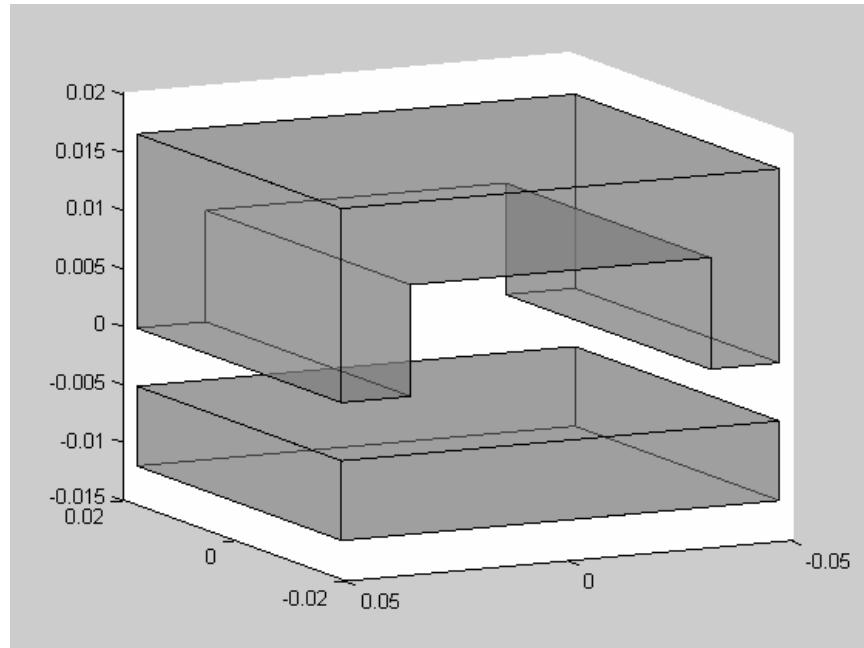
- Design 2

  - Mass: 5.79 kg

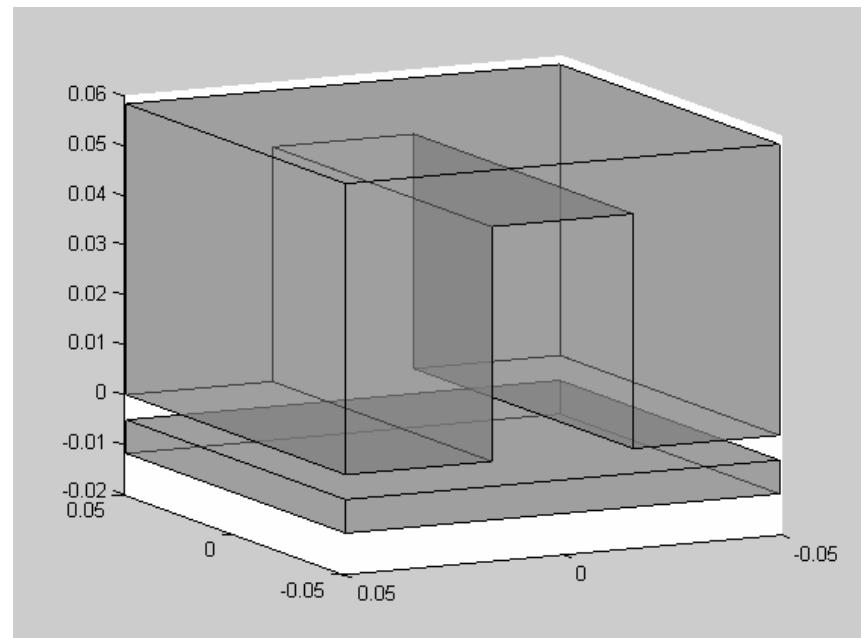
  - Current: 1.56 A

# Design Extremes

Design 1

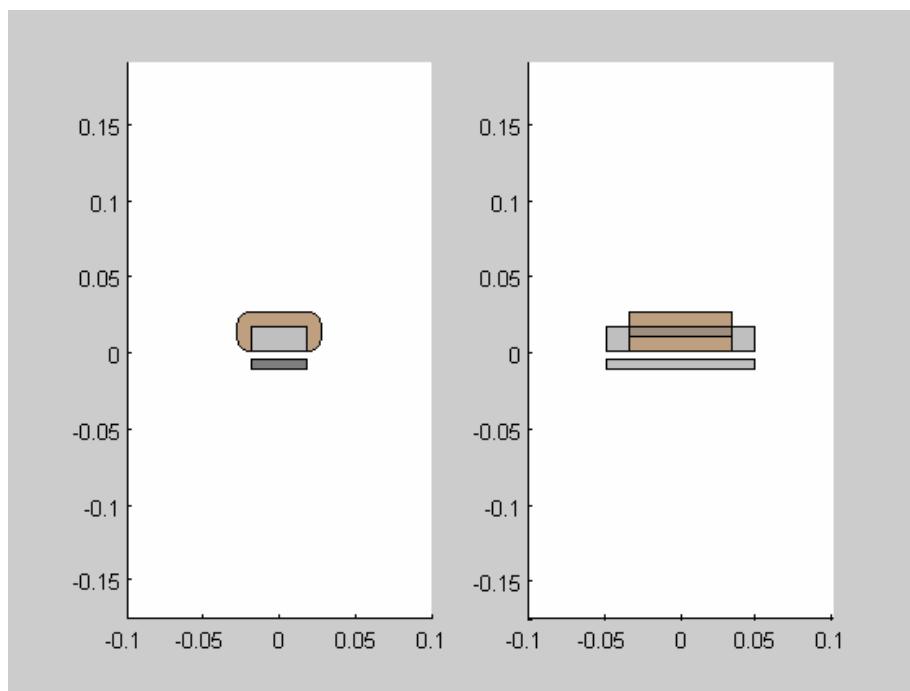


Design 2



# Design Extremes

Design 1



Design 2

