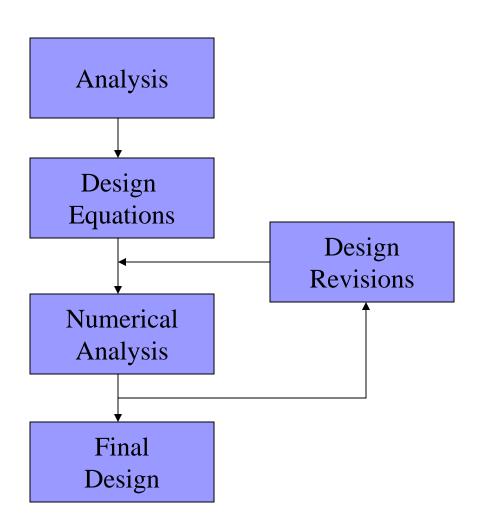
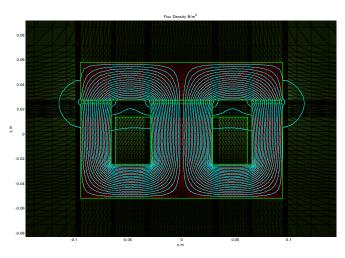
ECE 630 – Special Topics: Engineering Analysis and Design Using Genetic Algorithms

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Summer 2007

Manual Design Approach







Evolutionary Design Approach

Evolutionary Environment

Detailed Analysis

Fitness Function







Optimization Based Design and Analysis (Evolutionary or Otherwise)

- Pose Design Problem As An Optimization Problem
 - □ Can be single or multi-objective
 - Systematically encode design constraints and objectives into fitness functions
- Reality Check: Problem Properties Not Always Friendly
 - □ Not differentiable
 - □ Not convex
 - ☐ Many local extrema
 - □ No unique global optimum



Optimization Methods

- Classic Methods
 - □ Newton's Method
 - ☐ Gradient Methods
 - ☐ Conjugate Direction Methods
 - □ Quasi-Newton Methods
 - □ Nedler-Mead Simplex Method
- Populations Based Methods
 - Monte-Carlo
 - □ Population Based Classical Methods
 - **☐** Genetic Algorithms
 - □ Swarm Algorithms

Electric Machine Design

Rotor Material Type: Superflux Stator Material Type: Superflux

Permanent Magnet Type: NdFeB-30

Current Phase Advance (Degrees): -56.9791

Permanent Magnet Fraction (Percent): 94.9762

Rotor Iron Radius (cm): 2.5304

Permanent Magnet Depth (cm): 0.12325

Air Gap (mm): 0.35252 Slot Depth (cm): 1.075

Depth of Backiron (cm): 0.60912

Active Length (cm): 5.1814

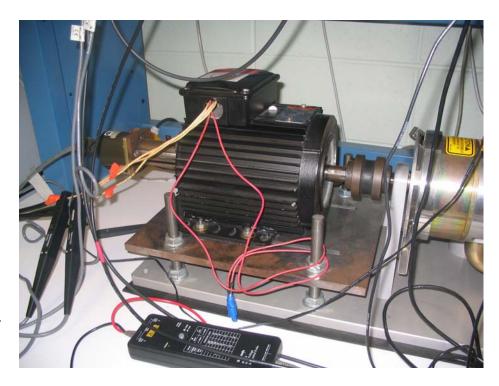
Number of Slots: 32

Fundamental Turns Density (turns/rad): 0.6194

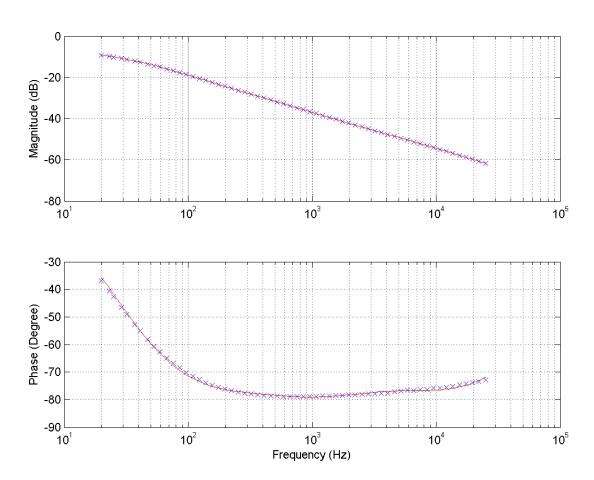
3rd Harmonic Turns Density (percent): 41.112

Conductor Type: Copper

Conductor Area (mm²): 1.3129

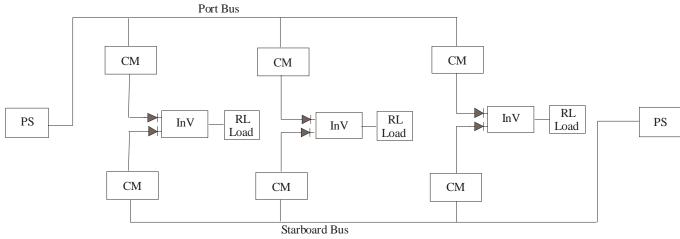


Transfer Function Identification



NCS/IFTP Control Design

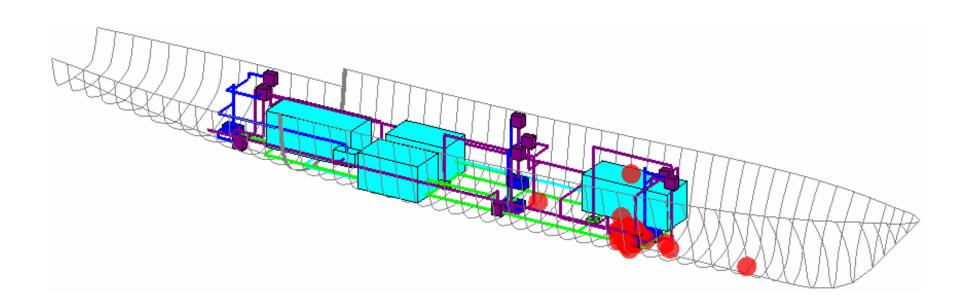




 $\theta_{\rm c} = [K_{pv} \ K_{iv} \ K_{ii} \ \tau_{invc} \ \tau_{invout} \ \tau_{iniout} \ K_{sf} \ \tau_{sf1} \ \tau_{sf2} \ K_{v} \ \tau_{v} \ K_{ip} \ K_{id}]^{\rm T}$



Vulnerability Assessment





Course Outline

- Lecture 1: Biological Genetics and Evolution
- Lecture 2: Canonical Genetic Algorithms
- Lecture 3: Schema Theory
- Lecture 4: Real Coded Genetic Algorithms
- Lecture 5: <u>Genetic Optimization System Engineering Tool</u>
- Lecture 6: Single Objective GA Exercises
- Lecture 7: GOSET Graphical User Interface
- Lecture 8: A Design Example: An Electromagnet
- Lecture 9: Multi-Objective Optimization
- Lecture 10: Multi-Objective Optimization Exercises



Acknowledgements

- Office of Naval Research Grant N00014-02-1-0990
- Office of Naval Research Grant N00014-02-1-0623



- Dr. Yonggon Lee, United States Naval Academy
- Dr. Ed Zivi, United States Naval Academy



■ Dr. Stanislaw Żak, Purdue University





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For Credit Grading

- 4 Homeworks (10 % of grade, each)
- 1 Final Exam (60 % of grade)