

# Automatic Differentiation of Functional Programs and its use for Probabilistic Programming

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Part of this talk covers joint work with Barak A. Pearlmutter.



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## Seventh European Workshop on AD



### Seventh European Workshop on Automatic Differentiation Monday 24th - Tuesday 25th November 2008 Oxford-Man Institute of Quantitative Finance Oxford University Oxford, UK

This two day workshop is the seventh in a series providing a forum for the presentation of theoretical developments in, and applications of, Automatic Differentiation (AD) and adjoint methods. It will be informal, with no published proceedings, so allowing for the discussion of work in progress and presentations by those new to the subject. The workshop is kindly being hosted by Prof. Mike Giles of the [Oxford-Man Institute of Quantitative Finance](#).

We welcome every researcher who wishes to present their work on any aspect of AD or its applications. However, at this workshop we would encourage contributions in the area of



#### Applications and Challenges in Economics and Finance

Confirmed speakers include:  
**Luca Capriotti** - CREDIT SUISSE  
**Oliver Pironneau** - Université Paris VI  
**Luca Guerrieri** - US Federal Reserve Bank  
**Benjamin Skrainka** - University College London

If you are interested in giving a 25 minute talk on any aspect of AD, or any applications you think suitable for AD then please contact Dr Martin Buecker at [buecker@sc.rwth-aachen.de](mailto:buecker@sc.rwth-aachen.de). We particularly welcome contributions from research students and those new to AD.

#### URGENT

Accommodation for this workshop has been arranged at Linton Lodge, Oxford which must be booked in the next few days -- see details under [Travel and Accomodation](#)

Username:

Password:

login

Contact: [webmaster@autodiff.org](mailto:webmaster@autodiff.org)



# The Essence

```
(define (f x) 2x3)
```

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`(define (f x) 2x3)`      $\rightsquigarrow$      `(define (f' x) 6x2)`

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(define (g x) sinf(x))
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$$\max_x \min_y f(x, y)$$

# The Essence of Forward-Mode AD

$$f(c + \varepsilon) = \frac{f(c)}{0!} + \frac{f'(c)}{1!}\varepsilon + \frac{f''(c)}{2!}\varepsilon^2 + \dots + \frac{f^{(i)}(c)}{i!}\varepsilon^i + \dots$$

Taylor, B. (1715). *Methodus Incrementorum Directa et Inversa*. London.

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$(\mathcal{D}f)$  is  $\mathcal{O}(1)$  relative to  $f$  (both space and time).

$$a + bi$$

Hamilton, W. R. (1837). *Theory of conjugate functions, or algebraic couples; with a preliminary and elementary essay on algebra as the science of pure time*. Transactions of the Royal Irish Academy, **17**(1):293–422.

# Arithmetic on Complex Numbers

$$a + bi$$

$$i^2 = -1$$

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$$(x_1 + x'_1\varepsilon) + (x_2 + x'_2\varepsilon) = (x_1 + x_2) + (x'_1 + x'_2)\varepsilon$$

$$(x_1 + x'_1\varepsilon) \times (x_2 + x'_2\varepsilon) = (x_1 \times x_2) + (x_1 \times x'_2 + x_2 \times x'_1)\varepsilon + (x'_1 + x'_2)\varepsilon^2$$

Clifford, W. K. (1873). *Preliminary Sketch of Bi-quaternions*. Proceedings of the London Mathematical Society, **4**:381–95.

# Arithmetic on Dual Numbers

$$x + x'\varepsilon$$

$$\varepsilon^2 = 0, \text{ but } \varepsilon \neq 0$$

$$(x_1 + x'_1\varepsilon) + (x_2 + x'_2\varepsilon) = (x_1 + x_2) + (x'_1 + x'_2)\varepsilon$$

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$$\langle x, x' \rangle$$

Clifford, W. K. (1873). *Preliminary Sketch of Bi-quaternions*. Proceedings of the London Mathematical Society, **4**:381–95.

# Arithmetic on Dual Numbers

$$x + x'\varepsilon$$
$$\varepsilon^2 = 0, \text{ but } \varepsilon \neq 0$$

$$(x_1 + x'_1\varepsilon) + (x_2 + x'_2\varepsilon) = (x_1 + x_2) + (x'_1 + x'_2)\varepsilon$$
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$$\langle x, x' \rangle$$

$$\langle x_1, x'_1 \rangle + \langle x_2, x'_2 \rangle = \langle (x_1 + x_2), (x'_1 + x'_2) \rangle$$
$$\langle x_1, x'_1 \rangle \times \langle x_2, x'_2 \rangle = \langle (x_1 \times x_2), (x_1 \times x'_2 + x_2 \times x'_1) \rangle$$

Clifford, W. K. (1873). *Preliminary Sketch of Bi-quaternions*. Proceedings of the London Mathematical Society, **4**:381–95.

# Dynamic Overloading: SCMUTILS

```
(define-structure bundle primal tangent)
(define (primal p) (if (bundle? p) (bundle-primal p) p))
(define (tangent p) (if (bundle? p) (bundle-tangent p) 0))

(define +
  (let ((+ +))
    (lambda (x1 x2)
      (make-bundle (+ (primal x1) (primal x2))
                   (+ (tangent x1) (tangent x2))))))

(define *
  (let ((+ +) (* *))
    (lambda (x1 x2)
      (make-bundle (* (primal x1) (primal x2))
                   (+ (* (primal x1) (tangent x2))
                      (* (tangent x1) (primal x2))))))

(define ((D f) x) (tangent (f (make-bundle x 1))))
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(define ((D f) x) (tangent (f (make-bundle x 1))))

(define (f x) (* 2 (* x (* x x))))
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(define (f x) (* 2 (* x (* x x))))

(D f)
```

# Dynamic Overloading: SCMUTILS

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(define ((D f) x) (tangent (f (make-bundle x 1))))

(define (f x) (* 2 (* x (* x x))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ...)) ...)
```

# Dynamic Overloading: SCMUTILS

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# Dynamic Overloading: SCMUTILS

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      (make-bundle (* (primal x1) (primal x2))
                   (+ (* (primal x1) (tangent x2))
                      (* (tangent x1) (primal x2))))))

(define ((D f) x) (tangent (f (make-bundle x 1))))

(define (f x) (* 2 (* x (* x x))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ...) ...)
```

## Convenient

# Dynamic Overloading: SCMUTILS

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      (make-bundle (+ (primal x1) (primal x2))
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      (make-bundle (* (primal x1) (primal x2))
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(define ((D f) x) (tangent (f (make-bundle x 1))))

(define (f x) (* 2 (* x (* x x))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ...)) ...)
```

Convenient but **slow**

# Dynamic Overloading: SCMUTILS

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    (lambda (x1 x2)
      (make-bundle (+ (primal x1) (primal x2))
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  (let ((+ +) (* *))
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      (make-bundle (* (primal x1) (primal x2))
                    (+ (* (primal x1) (tangent x2))
                       (* (tangent x1) (primal x2))))))

(define ((D f) x) (tangent (f (make-bundle x 1))))

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(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ...)) ...)
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  (let ((+ +) (* *))
    (lambda (x1 x2)
      (make-bundle (* (primal x1) (primal x2))
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                      (* (tangent x1) (primal x2))))))

(define ((D f) x) (tangent (f (make-bundle x 1))))

(define (f x) (* 2 (* x (* x x))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ...)) ...)
```

Convenient but **slow**

# Dynamic Overloading: SCMUTILS

```
(define-structure bundle primal tangent)
(define (primal p) (if (bundle? p) (bundle-primal p) p))
(define (tangent p) (if (bundle? p) (bundle-tangent p) 0))

(define ((D f) x)
  (fluid-let ((+ (lambda (x1 x2)
                   (make-bundle (+ (primal x1) (primal x2))
                                  (+ (tangent x1) (tangent x2))))))
    (* (lambda (x1 x2)
         (make-bundle (* (primal x1) (primal x2))
                      (+ (* (primal x1) (tangent x2))
                          (* (tangent x1) (primal x2)))))))
      (tangent (f (make-bundle x 1))))))

(define (f x) (* 2 (* x (* x x))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ...) ...)
```

Convenient but **slow**

# Dynamic Overloading: SCMUTILS

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(define-structure bundle primal tangent)
(define (primal p) (if (bundle? p) (bundle-primal p) p))
(define (tangent p) (if (bundle? p) (bundle-tangent p) 0))

(define ((D f) x)
  (fluid-let ((+ (lambda (x1 x2)
                  (make-bundle (+ (primal x1) (primal x2))
                                (+ (tangent x1) (tangent x2))))))
    (* (lambda (x1 x2)
        (make-bundle (* (primal x1) (primal x2))
                    (+ (* (primal x1) (tangent x2))
                      (* (tangent x1) (primal x2)))))))
    (tangent (f (make-bundle x 1))))

(define (f x) (* 2 (* x (* x x))))

(D f)
(D (D f))
(D (lambda (x) ... (D (lambda (y) ...) ...) ...)) ...)
```

Convenient but **slow**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

Fast

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

AD\_TOP = f

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
AD_TOP = f
AD_IVARS = x
AD_DVARS = f
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
AD_TOP = f
AD_IVARS = x
AD_DVARS = f
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
AD_TOP = f
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function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
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Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

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AD_TOP = f
AD_IVARS = x
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```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

```
AD_TOP = gf
AD_IVARS = x, gx
AD_DVARS = gf, gresult
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
AD_TOP = f
AD_IVARS = x
AD_DVARS = f
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

```
AD_TOP = gf
AD_IVARS = x, gx
AD_DVARS = gf, gresult
```

```
function ggf(x, gx, gx, ggx, gresult, ggresult, gresult)
double precision x, gx, gx, ggx, ggf, gresult, gresult, ggresult
ggf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
gresult = 6.0d0*x*x*gx
ggresult = 6.0d0*x*x*ggx+12.0d0*x*gx*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
AD_TOP = f
AD_IVARS = x
AD_DVARS = f
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

```
AD_TOP = gf
AD_IVARS = x, gx
AD_DVARS = gf, gresult
```

```
function ggf(x, gx, gx, ggx, gresult, ggresult, gresult)
double precision x, gx, gx, ggx, ggf, gresult, gresult, ggresult
ggf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
gresult = 6.0d0*x*x*gx
ggresult = 6.0d0*x*x*ggx+12.0d0*x*gx*gx
end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
AD_TOP = f
AD_IVARS = x
AD_DVARS = f
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

```
AD_TOP = gf
AD_IVARS = x, gx
AD_DVARS = gf, gresult
```

```
function ggf(x, gx, gx, ggx, gresult, ggresult, gresult)
double precision x, gx, gx, ggx, ggf, gresult, gresult, ggresult
ggf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
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Fast but **inconvenient**

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function f(x)
double precision x, f
f = 2.0d0*x*x*x
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```
AD_TOP = f
AD_IVARS = x
AD_DVARS = f
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
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```
AD_TOP = gf
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function ggf(x, gx, gx, ggx, gresult, ggresult, gresult)
double precision x, gx, gx, ggx, ggf, gresult, gresult, ggresult
ggf = 2.0d0*x*x*x
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end
```

Fast but **inconvenient**

# Preprocessor: ADIFOR and TAPENADE

```
function f(x)
double precision x, f
f = 2.0d0*x*x*x
end
```

```
AD_TOP = f
AD_IVARS = x
AD_DVARS = f
```

```
function gf(x, gx, gresult)
double precision x, gx, gf, gresult
gf = 2.0d0*x*x*x
gresult = 6.0d0*x*x*gx
end
```

```
AD_TOP = gf
AD_IVARS = x, gx
AD_DVARS = gf, gresult
AD_PREFIX = h
```

```
function hgf(x, hx, gx, hgx, gresult, hgresult, hresult)
double precision x, hx, gx, hgx, hgf, hresult, gresult, hgresult
hgf = 2.0d0*x*x*x
hresult = 6.0d0*x*x*hx
gresult = 6.0d0*x*x*gx
hgresult = 6.0d0*x*x*hgx+12.0d0*x*gx*hx
end
```

Fast but **inconvenient**

# Static Overloading: FADBAD++

```
double f(double x) {return 2*x*x*x;}  
double x;  
... f(x) ...
```

# Static Overloading: FADBAD++

```
double f(double x) {return 2*x*x*x;}  
double x;  
... f(x) ...
```

```
F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
x.diff(0, 1);  
... f(x).d(0) ...
```

# Static Overloading: FADBAD++

```
double f(double x) {return 2*x*x*x;}  
double x;  
... f(x) ...
```

```
F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
x.diff(0, 1);  
... f(x).d(0) ...
```

```
F<F<double> > f(F<F<double> > x) {return 2*x*x*x;}  
F<F<double> > x;  
x.diff(0, 1);  
x.diff(0, 1).diff(0,1);  
... f(x).d(0).d(0) ...
```

# Static Overloading: FADBAD++

```
double f(double x) {return 2*x*x*x;}  
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F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
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```
F<F<double> > f(F<F<double> > x) {return 2*x*x*x;}  
F<F<double> > x;  
x.diff(0, 1);  
x.diff(0, 1).diff(0,1);  
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```

Slow

# Static Overloading: FADBAD++

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double f(double x) {return 2*x*x*x;}  
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Slow

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F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
x.diff(0, 1);  
... f(x).d(0) ...
```

```
F<F<double> > f(F<F<double> > x) {return 2*x*x*x;}  
F<F<double> > x;  
x.diff(0, 1);  
x.diff(0, 1).diff(0,1);  
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```

Slow

# Static Overloading: FADBAD++

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double f(double x) {return 2*x*x*x;}  
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F<double> f(F<double> x) {return 2*x*x*x;}  
F<double> x;  
x.diff(0, 1);  
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Slow

# Static Overloading: FADBAD++

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Slow and **inconvenient**

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Slow and **inconvenient**

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Slow and **inconvenient**

# Static Overloading: FADBAD++

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Slow and **inconvenient**

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Slow and **inconvenient**

Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overline{\mathbb{R}^h}$

# Our API for Functional Forward AD

$$\text{bundle} : \mathbb{R}^n \times \overline{\mathbb{R}^h} \rightarrow (\mathbb{R}^n \triangleright \overline{\mathbb{R}^h})$$

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Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overline{\mathbb{R}^h}$   
 $j^*$  maps a **function** to its *push forward*

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Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overline{\mathbb{R}^n}$   
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Generalize to arbitrary types

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Differential geometry bundles points  $\mathbb{R}^n$  in a manifold with tangent vectors  $\overline{\mathbb{R}^n}$

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Generalize to arbitrary types

What is the tangent of a discrete value or a function?

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Can abbreviate  $\tau \triangleright \overline{\tau}$  as  $\overline{\tau}^{\rightarrow}$

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Sometimes write  $j_*$  as  $\overrightarrow{\mathcal{J}}$

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(define ((D f) x) (tangent ((j* f) (bundle x 1))))
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Convenient

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Convenient and **fast**

# A property

# A property

$x : \mathbb{R}^n$

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$$\overline{x} : \mathbb{R}^n$$

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$$f : \mathbb{R}^n \rightarrow \mathbb{R}^m$$

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$$((\mathcal{J} f) x)[i, j] = \frac{\partial f(x)[i]}{\partial x[j]}$$

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$$((\mathcal{J} f) \overline{x}) : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

# A property

$$\begin{aligned}x &: \mathbb{R}^n & \bar{x} &: \mathbb{R}^n & f &: \mathbb{R}^n \rightarrow \mathbb{R}^m \\((\mathcal{J} f) x)[i,j] &= \frac{\partial f(x)[i]}{\partial x[j]} & ((\mathcal{J} f) x) &: \mathbb{R}^{m \times n} & ((\mathcal{J} f) x) &: \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m \\(\text{primal } ((j^* f) (\text{bundle } x \bar{x}))) &= (f x)\end{aligned}$$

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$$\begin{aligned}x &: \mathbb{R}^n & \bar{x} &: \mathbb{R}^n & f &: \mathbb{R}^n \rightarrow \mathbb{R}^m \\((\mathcal{J}f) x)[i,j] &= \frac{\partial f(x)[i]}{\partial x[j]} & ((\mathcal{J}f) x) &: \mathbb{R}^{m \times n} & ((\mathcal{J}f) x) &: \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m \\(\text{primal } ((j^* f) (\text{bundle } x \bar{x}))) &= (f x) \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= ((\mathcal{J}f) x) \times \bar{x} \\(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) &= (((\mathcal{J}f) x) \bar{x}) \\((j^* f) x) &= (\text{bundle } (f (\text{primal } x)) (((\mathcal{J}f) (\text{primal } x)) (\text{tangent } x)))\end{aligned}$$

# A property

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$$f : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

0/1 matrix, every row has exactly one 1

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$$f : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

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$$((\mathcal{J} f) x) = \frac{\partial f(x)[i]}{\partial x[j]}$$

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when  $f$  is a rearrangement function

$$((j^* f) x) = (\text{bundle } (f (\text{primal } x)) (f (\text{tangent } x)))$$

# A property

$$x : \mathbb{R}^n \quad \bar{x} : \mathbb{R}^n \quad f : \mathbb{R}^n \rightarrow \mathbb{R}^m$$
$$((\mathcal{J}f) x)[i,j] = \frac{\partial f(x)[i]}{\partial x[j]} \quad ((\mathcal{J}f) x) : \mathbb{R}^{m \times n} \quad ((\mathcal{J}f) x) : \mathbb{R}^n \xrightarrow{L} \mathbb{R}^m$$

$$(\text{primal } ((j^* f) (\text{bundle } x \bar{x}))) = (f x)$$

$$(\text{tangent } ((j^* f) (\text{bundle } x \bar{x}))) = ((\mathcal{J}f) x) \times \bar{x}$$

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Problem avoided if we take  $\overline{\#t} = \#t$

# What is $(j^* \ j^*)$ ?

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bundle, primal, tangent, and  $j^*$  are rearrangement functions

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bundle, primal, tangent, and  $j^*$  are rearrangement functions

$$((j^* \text{bundle}) x) = (\text{bundle } (\text{bundle } (\text{primal } x)) \ (\text{bundle } (\text{tangent } x)))$$

$$((j^* \text{primal}) x) = (\text{bundle } (\text{primal } (\text{primal } x)) \ (\text{primal } (\text{tangent } x)))$$

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$$((j^* j^*) x) = (\text{bundle } (j^* (\text{primal } x)) \ (j^* (\text{tangent } x)))$$

# Modularity

 $\nabla f \mathbf{x}$ 

$$\triangleq \frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$$

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$$\nabla f \mathbf{x} \triangleq \frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$$

$$\text{GRADIENTDESCENT } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$$

# Modularity

$\nabla f \mathbf{x}$	$\triangleq$	$\frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$
<code>GRADIENTDESCENT</code> $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
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$\nabla f \mathbf{x}$	$\triangleq$	$\frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$
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NEUTRONFLUX $r$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;"><i>classified</i></span>

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$\nabla f \mathbf{x}$	$\triangleq$	$\frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$
GRADIENTDESCENT $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
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DEVIATION $r$	$\triangleq$	$((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$

# Modularity

$\nabla f \mathbf{x}$	$\triangleq$	$\frac{\partial f(\mathbf{x})}{\partial x_1}, \dots, \frac{\partial f(\mathbf{x})}{\partial x_n}$
GRADIENTDESCENT $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
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Fermi, E. (1946). *The Development of the first chain reaction pile*.  
Proceedings of the American Philosophy Society, **90**:20–4.

# Breaking Modularity

$\nabla f \mathbf{x}$	$\triangleq$	$(\vec{f} \mathbf{x} \triangleright \vec{e}_1), \dots, (\vec{f} \mathbf{x} \triangleright \vec{e}_n)$
GRADIENTDESCENT $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
argmin $f$	$\triangleq$	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX $r$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
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# Breaking Modularity

$$\nabla \vec{f} \mathbf{x} \triangleq (\vec{f} \mathbf{x} \triangleright \vec{e}_1), \dots, (\vec{f} \mathbf{x} \triangleright \vec{e}_n)$$

$$\text{GRADIENTDESCENT } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$$

$$\text{argmin } f \triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\text{classified}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

$$r^* \triangleq \text{argmin DEVIATION}$$

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Proceedings of the American Philosophy Society, **90**:20–4.

# Breaking Modularity

$$\nabla \vec{f} \mathbf{x} \triangleq (\vec{f} \mathbf{x} \triangleright \vec{e}_1), \dots, (\vec{f} \mathbf{x} \triangleright \vec{e}_n)$$

$$\text{GRADIENTDESCENT } f \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \vec{f} \mathbf{x}_i \dots$$

$$\text{argmin } f \triangleq \dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\text{classified}}$$

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$$\text{NEUTRONFLUX } r \triangleq \boxed{\text{classified}}$$

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# Breaking Modularity

$$\nabla \vec{f} \mathbf{x} \triangleq (\vec{f} \mathbf{x} \triangleright \vec{e}_1^T), \dots, (\vec{f} \mathbf{x} \triangleright \vec{e}_n^T)$$

$$\text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \triangleq \dots \mathbf{x}_{i+1} := \dots \nabla \vec{f} \mathbf{x}_i \dots$$

$$\text{argmin } \vec{f} \triangleq \dots \text{GRADIENTDESCENT } \vec{f} \mathbf{x}_0 \dots$$

$$\text{NEUTRONFLUX } r \triangleq \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX} \xrightarrow[\rightsquigarrow]{\text{ADIFOR}} \overline{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION } r \triangleq ((\text{NEUTRONFLUX } r) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

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$$\text{NEUTRONFLUX } \mathbf{r} \triangleq \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX} \xrightarrow[\rightsquigarrow]{\text{ADIFOR}} \overline{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION } \mathbf{r} \triangleq ((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

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# Breaking Modularity

$\nabla \overrightarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{f} \mathbf{x} \dots$
GRADIENTDESCENT $\overrightarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overrightarrow{f} \mathbf{x}_i \dots$
argmin $\overrightarrow{f}$	$\triangleq$	$\dots \text{GRADIENTDESCENT } \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\xrightarrow[\rightsquigarrow]{\text{ADIFOR}}$	$\overrightarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\xrightarrow[\rightsquigarrow]{\text{ADIFOR}}$	$\overrightarrow{\text{DEVIATION}}$
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$$\text{NEUTRONFLUX } \mathbf{r} \quad \triangleq \quad \boxed{\text{classified}}$$

$$\text{NEUTRONFLUX} \quad \xrightarrow[\rightsquigarrow]{\text{ADIFOR}} \quad \overline{\text{NEUTRONFLUX}}$$

$$\text{DEVIATION } \mathbf{r} \quad \triangleq \quad ((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$$

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$\nabla \overleftarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{f} \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
argmin $\overrightarrow{f}$	$\triangleq$	$\dots \text{GRADIENTDESCENT } \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\xrightarrow[\rightsquigarrow]{\text{ADIFOR}}$	$\overrightarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\xrightarrow[\rightsquigarrow]{\text{ADIFOR}}$	$\overrightarrow{\text{DEVIATION}}$
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GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
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NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\xrightarrow{\text{ADIFOR}}$	$\overrightarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\xrightarrow{\text{ADIFOR}}$	$\overrightarrow{\text{DEVIATION}}$
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$\nabla \overleftarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{f} \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
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NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\xrightarrow[\rightsquigarrow]{\text{ADIFOR}}$	$\overline{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\xrightarrow[\rightsquigarrow]{\text{ADIFOR}}$	$\overline{\text{DEVIATION}}$
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NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\overset{\text{ADIFOR}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{ADIFOR}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
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$\nabla \overleftarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{f} \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin $\overleftarrow{f}$	$\triangleq$	$\dots \text{GRADIENTDESCENT } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
$\mathbf{r}^*$	$\triangleq$	argmin $\overleftarrow{\text{DEVIATION}}$

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$\nabla \overleftarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} f \mathbf{x}$	$\triangleq$	
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin $\overleftarrow{f}$	$\triangleq$	$\dots \text{NEWTONSMETHOD } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
$\mathbf{r}^*$	$\triangleq$	argmin $\overleftarrow{\text{DEVIATION}}$

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$\mathcal{H} f \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{\overleftarrow{f}} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin $\overleftarrow{f}$	$\triangleq$	$\dots \text{NEWTONSMETHOD } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
$\mathbf{r}^*$	$\triangleq$	argmin $\overleftarrow{\text{DEVIATION}}$

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$\mathcal{H} \overrightarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin $\overleftarrow{f}$	$\triangleq$	$\dots \text{NEWTONSMETHOD } \overleftarrow{f} \mathbf{x}_0 \dots$
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DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
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# Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin $\overleftarrow{f}$	$\triangleq$	$\dots \text{NEWTONSMETHOD } \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
$\mathbf{r}^*$	$\triangleq$	argmin $\overleftarrow{\text{DEVIATION}}$

Fermi, E. (1946). *The Development of the first chain reaction pile*.  
 Proceedings of the American Philosophy Society, **90**:20–4.

# Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin $\overleftarrow{f}$	$\triangleq$	$\dots \text{NEWTONSMETHOD} \overleftarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
$\mathbf{r}^*$	$\triangleq$	argmin $\overleftarrow{\text{DEVIATION}}$

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# Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin $\overleftarrow{f}$	$\triangleq$	$\dots \text{NEWTONSMETHOD} \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
$\mathbf{r}^*$	$\triangleq$	argmin $\overleftarrow{\text{DEVIATION}}$

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# Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin $\overleftarrow{f} \overrightarrow{f}$	$\triangleq$	$\dots \text{NEWTONSMETHOD} \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
$\mathbf{r}^*$	$\triangleq$	argmin $\overleftarrow{\text{DEVIATION}}$

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# Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
argmin $\overleftarrow{f} \overrightarrow{f}$	$\triangleq$	$\dots \text{NEWTONSMETHOD} \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\overset{\text{TAPENADE}}{\rightsquigarrow}$	$\overleftarrow{\text{DEVIATION}}$
$\mathbf{r}^*$	$\triangleq$	argmin $\overleftarrow{\text{DEVIATION}} \overrightarrow{\text{DEVIATION}}$

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# Breaking Modularity

$\nabla \overleftarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overleftarrow{f} \mathbf{x} \dots$
$\mathcal{H} \overrightarrow{f} \mathbf{x}$	$\triangleq$	$\dots \overrightarrow{f} \dots \mathbf{x} \dots$
GRADIENTDESCENT $\overleftarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots$
NEWTONSMETHOD $\overleftarrow{f} \overrightarrow{f} \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla \overleftarrow{f} \mathbf{x}_i \dots \mathcal{H} \overrightarrow{f} \mathbf{x}_i \dots$
$\operatorname{argmin} \overleftarrow{f} \overrightarrow{f}$	$\triangleq$	$\dots \operatorname{NEWTNSMETHOD} \overleftarrow{f} \overrightarrow{f} \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
NEUTRONFLUX	$\xrightarrow{\text{TAPENADE}} \rightsquigarrow$	$\overleftarrow{\text{NEUTRONFLUX}}$
$\overleftarrow{\text{NEUTRONFLUX}}$	$\xrightarrow{\text{TAPENADE}} \rightsquigarrow$	$\overrightarrow{\text{NEUTRONFLUX}}$
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
DEVIATION	$\xrightarrow{\text{TAPENADE}} \rightsquigarrow$	$\overleftarrow{\text{DEVIATION}}$
$\overleftarrow{\text{DEVIATION}}$	$\xrightarrow{\text{TAPENADE}} \rightsquigarrow$	$\overrightarrow{\text{DEVIATION}}$
$\mathbf{r}^*$	$\triangleq$	$\operatorname{argmin} \overleftarrow{\text{DEVIATION}} \overrightarrow{\text{DEVIATION}}$

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# Restoring Modularity

$\nabla f \mathbf{x}$	$\triangleq$	
$\mathcal{H} f \mathbf{x}$	$\triangleq$	
GRADIENTDESCENT $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin $f$	$\triangleq$	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;"><i>classified</i></span>
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
$\mathbf{r}^*$	$\triangleq$	argmin DEVIATION

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# Restoring Modularity

$\nabla f \mathbf{x}$	$\triangleq$	$((\vec{\mathcal{J}} f) \mathbf{x} \triangleright \vec{\mathbf{e}}_1'), \dots, ((\vec{\mathcal{J}} f) \mathbf{x} \triangleright \vec{\mathbf{e}}_n')$
$\mathcal{H} f \mathbf{x}$	$\triangleq$	
GRADIENTDESCENT $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin $f$	$\triangleq$	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;"><i>classified</i></span>
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
$\mathbf{r}^*$	$\triangleq$	argmin DEVIATION

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# Restoring Modularity

$\nabla f \mathbf{x}$	$\triangleq$	$\dots (\overleftarrow{\mathcal{J}} f) \mathbf{x} \dots$
$\mathcal{H} f \mathbf{x}$	$\triangleq$	
GRADIENTDESCENT $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin $f$	$\triangleq$	$\dots \text{GRADIENTDESCENT } f \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
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# Restoring Modularity

$\nabla f \mathbf{x}$	$\triangleq$	$\dots (\overleftarrow{\mathcal{J}} f) \mathbf{x} \dots$
$\mathcal{H} f \mathbf{x}$	$\triangleq$	$\dots (\overrightarrow{\mathcal{J}} (\overleftarrow{\mathcal{J}} f)) \dots \mathbf{x} \dots$
GRADIENTDESCENT $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots$
NEWTONSMETHOD $f \mathbf{x}_0$	$\triangleq$	$\dots \mathbf{x}_{i+1} := \dots \nabla f \mathbf{x}_i \dots \mathcal{H} f \mathbf{x}_i \dots$
argmin $f$	$\triangleq$	$\dots \text{NEWTONSMETHOD } f \mathbf{x}_0 \dots$
NEUTRONFLUX $\mathbf{r}$	$\triangleq$	<span style="border: 1px solid black; padding: 2px;">classified</span>
DEVIATION $\mathbf{r}$	$\triangleq$	$((\text{NEUTRONFLUX } \mathbf{r}) - \text{NEUTRONFLUX}_{\text{critical}})^2$
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# Having your cake and eating it too

- Convenient

- Fast



# Having your cake and eating it too

- Convenient
  - $\mathcal{D}$  formulated as a higher-order function in the language
  - no arbitrary restrictions
    - applies to all data types and constructs in the language, including code produced by  $\mathcal{D}$  and even  $\mathcal{D}$  itself
  
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- higher-order derivatives
  - $(\mathcal{D} (\mathcal{D} f))$

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  - applies to all data types and constructs in the language, including code produced by  $\mathcal{D}$  and even  $\mathcal{D}$  itself
- higher-order derivatives
  - $(\mathcal{D} (\mathcal{D} f))$
- nesting
  - $(\mathcal{D} (\text{lambda } (...) \dots (\mathcal{D} (\text{lambda } (...) \dots)) \dots))$

- Fast

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- $\mathcal{D}$  formulated as a higher-order function in the language
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  - $(\mathcal{D} (\mathcal{D} f))$
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- $\mathcal{D}$  implemented by reflective transformation of environments and code associated with closures

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- $\mathcal{D}$  formulated as a higher-order function in the language
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- higher-order derivatives
  - $(\mathcal{D} (\mathcal{D} f))$
- nesting
  - $(\mathcal{D} (\text{lambda } (...) \dots (\mathcal{D} (\text{lambda } (...) \dots)) \dots))$

- Fast

- $\mathcal{D}$  implemented by reflective transformation of environments and code associated with closures
- compile away reflection with partial evaluation implemented by flow analysis

# Monovariant Flow Analysis: 0-CFA

```
(define ( $\mathcal{D}$  f)  
...)
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f)  
  ...)
```

```
(D (lambda (x) 2x3))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f: ( $\lambda x$   $2x^3$ ))  
  ...)
```

```
(D (lambda (x)  $2x^3$ ))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x 2x^3$ ))  
  ...:( $\lambda x 6x^2$ ))  
  
(D (lambda (x)  $2x^3$ ))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x 2x^3$ ))  
  ...:( $\lambda x 6x^2$ ))
```

```
(D (lambda (x)  $2x^3$ )):( $\lambda x 6x^2$ )
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x 2x^3$ ))  
  ...:( $\lambda x 6x^2$ ))
```

```
(D (lambda (x)  $2x^3$ )):( $\lambda x 6x^2$ )
```

```
(D (lambda (x)  $3x^4$ ))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f : (lambda (x) 2x3) U (lambda (x) 3x4))  
  ... : (lambda (x) 6x2))
```

```
(D (lambda (x) 2x3)) : (lambda (x) 6x2)
```

```
(D (lambda (x) 3x4))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f : (λx 2x3) ∪ (λx 3x4))  
  ... : (λx 6x2) ∪ (λx 12x3))
```

```
(D (lambda (x) 2x3)) : (λx 6x2)
```

```
(D (lambda (x) 3x4))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x 2x^3$ )  $\cup$  ( $\lambda x 3x^4$ ))  
  ...:( $\lambda x 6x^2$ )  $\cup$  ( $\lambda x 12x^3$ ))
```

```
(D (lambda (x)  $2x^3$ )):( $\lambda x 6x^2$ )
```

```
(D (lambda (x)  $3x^4$ )):( $\lambda x 12x^3$ )
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x 2x^3$ )  $\cup$  ( $\lambda x 3x^4$ ))  
  ...:( $\lambda x 6x^2$ )  $\cup$  ( $\lambda x 12x^3$ ))
```

```
(D (lambda (x)  $2x^3$ )) : ( $\lambda x 6x^2$ )  $\cup$  ( $\lambda x 12x^3$ )
```

```
(D (lambda (x)  $3x^4$ )) : ( $\lambda x 6x^2$ )  $\cup$  ( $\lambda x 12x^3$ )
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f: ( $\lambda x$   $2x^3$ )  $\cup$  ( $\lambda x$   $3x^4$ ))  
  ...: ( $\lambda x$   $6x^2$ )  $\cup$  ( $\lambda x$   $12x^3$ ))
```

```
(D (lambda (x)  $2x^3$ )) : ( $\lambda x$   $6x^2$ )  $\cup$  ( $\lambda x$   $12x^3$ )
```

```
(D (lambda (x)  $3x^4$ )) : ( $\lambda x$   $6x^2$ )  $\cup$  ( $\lambda x$   $12x^3$ )
```

# Monovariant Flow Analysis: 0-CFA

```
(define ( $\mathcal{D}$  f)  
  ...)
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f)  
  ...)
```

```
(D (D (lambda (x) e2x)))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ )  
...)
```

```
(D (D (lambda (x)  $e^{2x}$ )))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ )
...:( $\lambda x 2e^{2x}$ ))

(D (D (lambda (x)  $e^{2x}$ )))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ )  
...:( $\lambda x 2e^{2x}$ ))
```

```
(D (D (lambda (x)  $e^{2x}$ )):( $\lambda x 2e^{2x}$ ))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ )  $\cup$  ( $\lambda x 2e^{2x}$ ))  
  ...:( $\lambda x 2e^{2x}$ ))
```

```
(D (D (lambda (x)  $e^{2x}$ )):( $\lambda x 2e^{2x}$ ))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ )  $\cup$  ( $\lambda x 2e^{2x}$ ))  
  ...:( $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ ))
```

```
(D (D (lambda (x)  $e^{2x}$ )):( $\lambda x 2e^{2x}$ ))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ )  $\cup$  ( $\lambda x 2e^{2x}$ ))  
...:( $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ ))
```

```
(D (D (lambda (x)  $e^{2x}$ ))):(  $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ )
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:(λx e2x) ∪ (λx 2e2x) ∪ (λx 4e2x))  
  ...:(λx 2e2x) ∪ (λx 4e2x))
```

```
(D (D (lambda (x) e2x))):(λx 2e2x) ∪ (λx 4e2x))
```

# Monovariant Flow Analysis: 0-CFA

```
(define (D f:( $\lambda x e^{2x}$ )  $\cup$  ( $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ )  $\cup$  ...)
...:( $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ )  $\cup$  ...)
```

```
(D (D (lambda (x) e2x)) : ( $\lambda x 2e^{2x}$ )  $\cup$  ( $\lambda x 4e^{2x}$ )  $\cup$  ...)
```

# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define ( $\mathcal{D}$  f) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define ( $\mathcal{D}$  f) ...)
```

```
(define (g ...) ... ( $\mathcal{D}$  (lambda (x)  $2x^3$ )) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define ( $\mathcal{D}_g$  f) ...)
```

```
(define (g ...) ... ( $\mathcal{D}$  (lambda (x)  $2x^3$ )) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define ( $\mathcal{D}_g$  f:( $\lambda x$   $2x^3$ )) ...)
```

```
(define (g ...) ... ( $\mathcal{D}$  (lambda (x)  $2x^3$ )) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3) ...:(λx 6x2))
```

```
(define (g ...) ... (D (lambda (x) 2x3)) ...)
```

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# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3) ...:(λx 6x2))
```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3) ...:(λx 6x2))
```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

```
(define (h ...) ... (D (lambda (x) 3x4)) ...)
```

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# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3) ...:(λx 6x2))
```

```
(define (Dh f) ...)
```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

```
(define (h ...) ... (D (lambda (x) 3x4)) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3)) ...:(λx 6x2))
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# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3) ...:(λx 6x2))
```

```
(define (Dh f:(λx 3x4) ...:(λx 12x3))
```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

```
(define (h ...) ... (D (lambda (x) 3x4)) ...)
```

Shivers, III, O. G. (1991). *Control-Flow Analysis of Higher-Order Languages or Taming Lambda*. Ph.D. thesis, CMU.

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with Bounded Context Sensitivity

```
(define (Dg f:(λx 2x3) ...:(λx 6x2))
```

```
(define (Dh f:(λx 3x4) ...:(λx 12x3))
```

```
(define (g ...) ... (D (lambda (x) 2x3)):(λx 6x2) ...)
```

```
(define (h ...) ... (D (lambda (x) 3x4)):(λx 12x3) ...)
```

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# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

```
(define ((compose n f) x)
  (if (zero? n) x ((compose (- n 1) f) (f x))))
```

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# Polyvariant Flow Analysis: $k$ -CFA

with Bounded Context Sensitivity

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(define ((compose n f) x)
  (if (zero? n) x ((compose (- n 1) f) (f x))))

((compose k  $\mathcal{D}$ ) g)
```

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```
((compose k  $\mathcal{D}$ ) g)
```

```
(define ( $\mathcal{D}_{\text{compose}}$  f:g) ...)
```

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```

```
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```

```
(define ( $\mathcal{D}_{\text{compose}}$  f:g) ...)
```

```
(define ( $\mathcal{D}_{\text{compose:compose}}$  f:g') ...)
```

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```
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```

```
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⋮

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# Polyvariant Flow Analysis

with Unbounded Context Sensitivity

$$\mathcal{E} : e \times \sigma \rightarrow v$$

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$$v ::= \#t \mid \#f \mid () \mid \mathbb{R} \mid (v_1, v_2) \mid \langle \sigma, e \rangle$$

$$\sigma ::= \{x_1 \mapsto v_1, \dots\}$$

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Memoize  $\bar{\mathcal{E}}$  indexed (by suitable equivalence relations on)  $e$  and  $\bar{\sigma}$ .

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Side benefit: union-free

No tags, tag checking, tag dispatching, indirect calls

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Side benefits: union-free, no cyclic abstract values

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Side benefits: union-free, no cyclic abstract values

No tags, tag checking, tag dispatching, indirect calls

Allows complete unboxing: no allocation, reclamation, indirection

			$B$			
		$b_1$	$\dots$	$b_j$	$\dots$	$b_n$
	$a_1$					
	$\vdots$		$\ddots$	$\vdots$		
$A$	$a_i$	$\dots$	$\text{PAYOFF}(a_i, b_j)$	$\dots$		
	$\vdots$		$\vdots$		$\ddots$	
	$a_m$					

von Neumann, J. and Morgenstern, O. (1944). *Theory of Games and Economic Behavior*. Princeton University Press, Princeton, NJ.

			$B$		
	$b_1$	$\dots$	$b_j$	$\dots$	$b_n$
$a_1$					
$\vdots$		$\ddots$	$\vdots$		
$A$	$a_i$	$\dots$	PAYOFF( $a_i, b_j$ )	$\dots$	
$\vdots$			$\vdots$		$\ddots$
$a_m$					

$$\max_{a \in A} \min_{b \in B} \text{PAYOFF}(a, b)$$

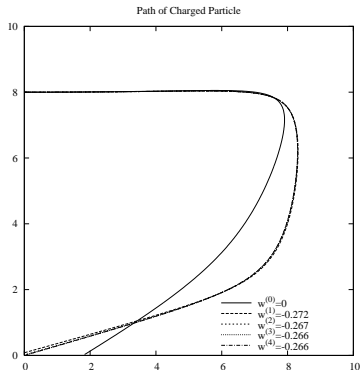
von Neumann, J. and Morgenstern, O. (1944). *Theory of Games and Economic Behavior*. Princeton University Press, Princeton, NJ.

		$\mathbb{R}^n$	
		...	<b>b</b>
		...	...
$\mathbb{R}^m$	<b>a</b>	...	PAYOFF( <b>a</b> , <b>b</b> )
⋮		⋮	⋮
⋮		⋮	⋮
		⋮	⋮
		⋮	⋮

$$\max_{\mathbf{a} \in \mathbb{R}^m} \min_{\mathbf{b} \in \mathbb{R}^n} \text{PAYOFF}(\mathbf{a}, \mathbf{b})$$

von Neumann, J. and Morgenstern, O. (1944). *Theory of Games and Economic Behavior*. Princeton University Press, Princeton, NJ.

# Cathode Ray Tubes



$$\text{potential: } p(\mathbf{x}; w) = \|\mathbf{x} - (10, 10 - w)\|^{-1} + \|\mathbf{x} - (10, 0)\|^{-1}$$

$$\ddot{\mathbf{x}}(t) = -\nabla_{\mathbf{x}} p(\mathbf{x})|_{\mathbf{x}=\mathbf{x}(t)}$$

$$\dot{\mathbf{x}}(t + \Delta t) = \dot{\mathbf{x}}(t) + \Delta t \ddot{\mathbf{x}}(t)$$

$$\mathbf{x}(t + \Delta t) = \mathbf{x}(t) + \Delta t \dot{\mathbf{x}}(t)$$

$$\text{When: } x_1(t + \Delta t) \leq 0$$

$$\text{let: } \Delta t_f = -x_1(t) / \dot{x}_1(t)$$

$$t_f = t + \Delta t_f$$

$$\mathbf{x}(t_f) = \mathbf{x}(t) + \Delta t_f \dot{\mathbf{x}}(t)$$

$$\text{Error: } E(w) = x_0(t_f)^2$$

$$\text{Find: } \underset{w}{\operatorname{argmin}} E(w)$$

Sprague, C. S. and George, R. H. (1939). *Cathode Ray Deflecting Electrode*. US Patent 2,161,437.

George, R. H. (1940). *Cathode Ray Tube*. US Patent 2,222,942.

# Performance Comparison

	particle				saddle			
	FF	FR	RF	RR	FF	FR	RF	RR
STALIN $\nabla$	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
ADIFOR	1.52	■	■	■	2.07	■	■	■
TAPENADE	3.40	■	■	■	2.56	■	■	■
FADBAD++	65.69	■	■	■	22.44	■	■	■
MLTON	53.89	88.88	16.08	28.06	40.39	51.21	1.86	2.67
OCAML	160.50	340.35	147.91	263.66	107.71	156.33	6.75	13.51
SML/NJ	106.21	182.45	105.04	185.15	84.38	106.01	3.55	6.31
GHC	165.22	■	■	■	121.18	■	■	■
BIGLOO	505.90	761.40	104.81	228.56	423.69	440.25	15.77	24.59
CHICKEN	1120.37	2026.31	425.60	1872.85	889.58	1144.65	35.73	68.94
GAMBIT	444.13	752.63	138.34	256.30	362.65	420.48	14.08	23.87
IKARUS	192.07	312.28	61.79	114.87	158.88	205.97	6.75	11.40
LARCENY	726.59	1108.18	144.55	270.14	571.81	613.65	19.14	29.77
MIT SCHEME	1472.26	2500.00	309.66	591.36	1243.26	1428.57	51.36	79.10
MzC	2073.26	3434.64	340.30	655.83	2436.26	1996.40	72.45	150.02
MzSCHEME	2344.70	4076.16	409.95	843.68	2000.89	2332.43	80.78	134.00
SCHEME->C	391.42	605.26	109.77	198.43	324.95	328.84	12.74	18.28
SCMUTILS	3321.20	■	■	■	2800.71	■	■	■
STALIN	208.10	366.08	51.84	91.86	166.96	212.93	7.68	11.40

- not implemented but could implement
- not implemented in existing tool
- can't implement

# Gradient-Based Optimization

```
(define (e i n)
  (if (zero? n)
      '()
      (cons (if (zero? i) 1.0 0.0)
            (e (- i 1) (- n 1)))))
```

# Gradient-Based Optimization

```
(define (e i n)
  (if (zero? n)
      '()
      (cons (if (zero? i) 1.0 0.0)
            (e (- i 1) (- n 1)))))

(define ((gradient f) x)
  (let ((n (length x)))
    (map (lambda (i) (tangent ((j* f) (bundle x (e i n))))
         (iota n)))))
```

# Gradient-Based Optimization

```
(define (e i n)
  (if (zero? n)
      '()
      (cons (if (zero? i) 1.0 0.0)
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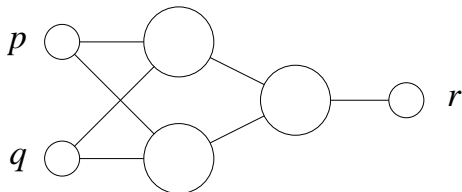
(define ((gradient f) x)
  (let ((n (length x)))
    (map (lambda (i) (tangent ((j* f) (bundle x (e i n))))
         (iota n))))

(define (gradient-ascent f x0 n eta)
  (if (zero? n)
      (list x0 (f x0) ((gradient f) x0))
      (gradient-ascent f
                       (zip (lambda (xi gi) (+ xi (* eta gi)))
                            x0
                            ((gradient f) x0))
                       (- n 1)
                       eta)))
```

# Gradient-Based Optimization

```
(define ((gradient f) x) (cdr ((cdr ((*j f) (*j x))) 1.0)))
```

```
(define (gradient-ascent f x0 n eta)
  (if (zero? n)
      (list x0 (f x0) ((gradient f) x0))
      (gradient-ascent f
                       (zip (lambda (xi gi) (+ xi (* eta gi)))
                            x0
                            ((gradient f) x0))
                       (- n 1)
                       eta)))
```



$p$	$q$	$r$
0	0	0
0	1	1
1	0	1
1	1	0

Rumelhart, D. E., Hinton, G. E., and Williams, R. J. (1986). *Learning representations by back-propagating errors*. *Nature*, **323**:533–6.

# Neural Networks in VLAD

```
(define ((sum-activities activities) bias ws)
  ((fold + bias) (zip * ws activities)))
```

# Neural Networks in VLAD

```
(define ((sum-activities activities) bias ws)
  ((fold + bias) (zip * ws activities)))

(define (sum-layer activities ws-layer)
  (map (sum-activities activities) ws-layer))
```

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```
(define ((sum-activities activities) bias ws)
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(define (sigmoid x) (/ 1 (+ (exp (- 0 x)) 1)))
```

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```
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(define (sum-layer activities ws-layer)
  (map (sum-activities activities) ws-layer))

(define (sigmoid x) (/ 1 (+ (exp (- 0 x)) 1)))

(define ((forward-pass ws-layers) in)
  (if (null? ws-layers)
      in
      ((forward-pass (cdr ws-layers))
       (map sigmoid (sum-layer in (car ws-layers))))))
```

# Neural Networks in VLAD

```
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  (map (sum-activities activities) ws-layer))

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(define ((forward-pass ws-layers) in)
  (if (null? ws-layers)
      in
      ((forward-pass (cdr ws-layers))
       (map sigmoid (sum-layer in (car ws-layers))))))

(define ((error-on-dataset dataset) ws-layers)
  ((fold + 0)
   (map (lambda ((list in target))
         (* 0.5 (magnitude-squared (v- ((forward-pass ws-layers) in) target))))
        dataset)))
```

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(define ((error-on-dataset dataset) ws-layers)
  ((fold + 0)
   (map (lambda ((list in target))
          (* 0.5 (magnitude-squared (v- ((forward-pass ws-layers) in) target)))
         dataset)))

(gradient-descent (error-on-dataset '(((0 0) (0))
                                       ((0 1) (1))
                                       ((1 0) (1))
                                       ((1 1) (0))))
                  '(((0 -0.284227 1.16054) (0 0.617194 1.30467))
                    ((0 -0.084395 0.648461)))
                  1000.0
                  0.3)
```

# Performance Comparison

	backprop		
	Fs	Fv	R
STALIN $\nabla$	1.00	■	1.00
ADIFOR	11.84	2.68	■
TAPENADE	11.35	4.33	6.24
ADIC	16.33	3.93	■
ADOL-C	12.34	3.89	35.53
CPPAD	42.15	■	23.69
FADBAD++	98.96	33.15	53.03
MLTON	73.94	■	37.94
OCAML	157.75	■	149.14
SML/NJ	142.71	■	94.97
GHC	■	■	■
BIGLOO	577.45	■	306.60
CHICKEN	1391.75	■	971.91
GAMBIT	545.20	■	341.73
IKARUS	216.42	■	147.49
LARCENY	955.98	■	486.64
MIT SCHEME	1900.04	■	1141.22
MzC	2439.93	■	1571.52
MZSCHEME	3477.86	■	1866.28
SCHEME->C	484.24	■	233.75
SCMUTILS	4544.48	■	■
STALIN	832.68	■	367.84

- not implemented but could implement
- not implemented in existing tool
- can't implement

# Probabilistic Lambda Calculus

$P = \mathbf{if } x_0 \mathbf{ then } 0 \mathbf{ else if } x_1 \mathbf{ then } 1 \mathbf{ else } 2$

Koller, D., McAllester, D. , and Pfeffer, A. (1997). *Effective Bayesian Inference for Stochastic Programs*. Proceedings of the 14th National Conference on Artificial Intelligence (AAAI), pp. 740–7.

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$$\prod_{v \in \{0,1,2,2\}} \Pr(\mathcal{E}(P) = v | p_0, p_1) = p_0(1 - p_0)^3 p_1(1 - p_1)^2$$

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# Probabilistic Prolog

$p(0).$

$p(X) :- q(X).$

$q(1).$

$q(2).$

# Probabilistic Prolog

$$\Pr(\mathfrak{p}(0) \text{ .}) = p_0$$

$$\Pr(\mathfrak{p}(X) : \neg \mathfrak{q}(X) \text{ .}) = 1 - p_0$$

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(define (evaluate expression environment)
  (cond
    ((constant-expression? expression)
     (singleton-tagged-distribution
      (constant-expression-value expression)))
    ((variable-access-expression? expression)
     (lookup-value
      (variable-access-expression-variable expression) environment))
    ((lambda-expression? expression)
     (singleton-tagged-distribution
      (lambda (tagged-distribution)
        (evaluate
         (lambda-expression-body expression)
         (cons (make-binding (lambda-expression-variable expression)
                             tagged-distribution)
               environment))))))
    (else (let ((tagged-distribution
                  (evaluate (application-argument expression)
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                (list  $\Pr(x_0 \mapsto \mathbf{true}) = p_0$   $\Pr(x_0 \mapsto \mathbf{false}) = 1 - p_0$ 
                     $\Pr(x_1 \mapsto \mathbf{true}) = p_1$   $\Pr(x_1 \mapsto \mathbf{false}) = 1 - p_1$ 
                    ...)))
    (map-reduce
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     (lambda (value)
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# Probabilistic Prolog

```
(define (proof-distribution term clauses)
  (let ((offset ...))
    (map-reduce
      append
      '()
      (lambda (clause)
        (let ((clause (alpha-rename clause offset)))
          (let loop ((p (clause-p clause))
                     (substitution (unify term (clause-term clause)))
                     (terms (clause-terms clause)))
            (if (boolean? substitution)
                '()
                (if (null? terms)
                    (list (make-double p substitution))
                    (map-reduce
                      append
                      '()
                      (lambda (double)
                        (loop (* p (double-p double))
                              (append substitution (double-substitution double))
                              (rest terms))))
                    (proof-distribution
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      (lambda (clause)
        (let ((clause (alpha-rename clause offset)))
          (let loop ((p (clause-p clause))
                     (substitution (unify term (clause-term clause)))
                     (terms (clause-terms clause)))
            (if (boolean? substitution)
                '()
                (if (null? terms)
                    (list (make-double p substitution))
                    (map-reduce
                      append
                      '()
                      (lambda (double)
                        (loop (* p (double-p double))
                              (append substitution (double-substitution double))
                              (rest terms))))
                    (proof-distribution
                     (apply-substitution substitution (first terms)) clauses)))))))
    clauses)))
```

# Probabilistic Prolog

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(define (proof-distribution term clauses)
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                    (map-reduce
                      append
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                      (lambda (double)
                        (loop (* p (double-p double))
                            (append substitution (double-substitution double))
                            (rest terms))))
                    (proof-distribution
                     (apply-substitution substitution (first terms)) clauses)))))))
    clauses)))
```

# Probabilistic Prolog

```
(gradient-ascent
 (lambda (p)
  (let ((clauses (list Pr(p(0).) = p0
                       Pr(p(X):-q(X).) = 1 - p0
                       Pr(q(1).) = p1
                       Pr(q(2).) = 1 - p1))))
    (map-reduce
     *
     1.0
     (lambda (query)
      (likelihood (proof-distribution query clauses)))
     '(p(0) p(1) p(2) p(2))))
 '(0.5 0.5)
 1000.0
 0.1)
```

# Probabilistic Prolog

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     '(p(0) p(1) p(2) p(2))))
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     1.0
     (lambda (query)
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     '(p(0) p(1) p(2) p(2))))
 '(0.5 0.5)
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    (map-reduce
     *
     1.0
     (lambda (query)
      (likelihood (proof-distribution query clauses)))
     '(p(0) p(1) p(2) p(2))))
 '(0.5 0.5)
 1000.0
 0.1)
```

# Generated Code

```
static void f2679(double a_f2679_0,double a_f2679_1,double a_f2679_2,double a_f2679_3){
    int t272381=((a_f2679_2==0.)?0:1);
    double t272406;
    double t272405;
    double t272404;
    double t272403;
    double t272402;
    if((t272381==0)){
        double t272480=(1.-a_f2679_0);
        double t272572=(1.-a_f2679_1);
        double t273043=(a_f2679_0+0.);
        double t274185=(t272480*a_f2679_1);
        double t274426=(t274185+0.);
        double t275653=(t272480*t272572);
        double t275894=(t275653+0.);
        double t277121=(t272480*t272572);
        double t277362=(t277121+0.);
        double t277431=(t277362*1.);
        double t277436=(t275894*t277431);
        double t277441=(t274426*t277436);
        double t277446=(t273043*t277441);
        ...
        double t1777107=(t1774696+t1715394);
        double t1777194=(0.-t1745420);
        double t1778533=(t1777194+t1419700);
        t272406=a_f2679_0;
        t272405=a_f2679_1;
        t272404=t277446;
        t272403=t1778533;
        t272402=t1777107;}
    else {...}
    r_f2679_0=t272406;
    r_f2679_1=t272405;
    r_f2679_2=t272404;
    r_f2679_3=t272403;
    r_f2679_4=t272402;}
```

# Performance Comparison

	probabilistic-lambda-calculus		probabilistic-prolog	
	F	R	F	R
STALIN $\nabla$	1.00	1.00	1.00	1.00
MLTON	106.45	124.95	789.41	483.47
OCAML	215.73	538.68	1207.13	1534.61
SML/NJ	197.75	272.45	2448.02	1471.94
GHC	■	■	■	■
BIGLOO	832.92	1048.11	14422.16	8286.06
CHICKEN	2305.98	3283.00	66948.70	37792.84
GAMBIT	879.88	1153.86	24316.03	13649.81
IKARUS	437.46	531.10	8242.92	4845.86
LARCENY	1651.01	1673.22	25589.62	14833.53
MIT SCHEME	3491.10	4130.19	85819.57	48335.38
MzC	5289.17	5929.14	154206.95	83480.27
MzSCHEME	6235.78	7134.71	166129.12	91630.70
SCHEME->C	682.15	794.31	10530.66	5980.27
SCMUTILS	6456.99	■	80100.23	■
STALIN	1240.73	1137.41	22511.79	10986.43

- not implemented but could implement, including FORTRAN, C, and C++
- not implemented in existing tool
- can't implement

*It is, of course, not excluded that the range of arguments or range of values of a function should consist wholly or partly of functions. The derivative, as this notion appears in the elementary differential calculus, is a familiar mathematical example of a function for which both ranges consist of functions.*

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Gottfried Leibniz  
|  
Jacob Bernoulli  
|  
Johann Bernoulli  
|  
Leonhard Euler  
|  
Joseph Louis Lagrange  
|  
Simeon Poisson  
|  
Michel Chasles  
|  
Hubert Anson Newton  
|  
Eliakim Hastings Moore  
|  
Oswald Veblen  
|  
Alonzo Church