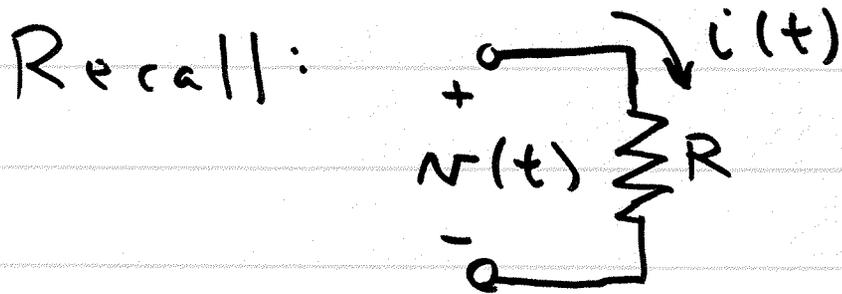


Signal Basics

Signal: $x(t)$

$$\text{Energy: } E_x = \int_{-\infty}^{\infty} x^2(t) dt$$



Energy dissipated in resistor:

$$\int_{-\infty}^{\infty} \frac{v^2(t)}{R} dt = \int_{-\infty}^{\infty} i^2(t) R dt$$

Can kind of view our definition of energy
as energy per unit resistance

Transformations of Time-Variable

Time-Shift: $x(t-t_0)$

Time-Scaling: $x(at)$
 $a > 0$

$a > 1$: compression
 $a < 1$: expansion

Time-Reversal: $x(-t)$

Combination of the above:

$$x(at + b) \quad \text{or} \quad x(\alpha(t - \beta))$$

• steps must be done in proper order

$x(at+b)$: 1. shift to left by b
2. if $a < 0$, flip about $t=0$ (time-reverse)
3. compress by a factor of $|a|$
(if $|a| < 1$, actually an expansion)

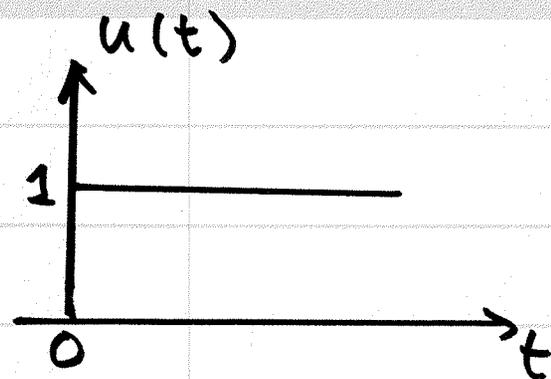
$x(\alpha(t-\beta))$: 1. if $\alpha < 0$, flip about $t=0$
2. if $|\alpha| > 1$, compress by a factor of α
if $|\alpha| < 1$, expand by $1/|\alpha|$
3. shift to right by β

See textbook examples and homework problems

See also matlab examples

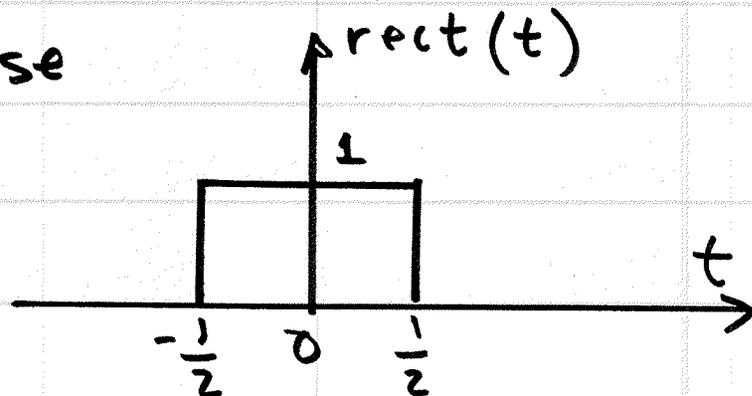
Basic signals

unit step: $u(t) = \begin{cases} 1, & t > 0 \\ 0, & t < 0 \end{cases}$



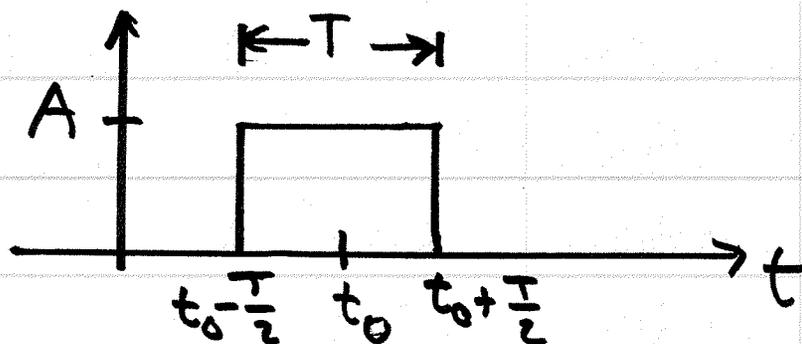
rectangle function: not defined in text, but we will use throughout course

$$\text{rect}(t) = \begin{cases} 1, & |t| < 1/2 \\ 0, & |t| > 1/2 \end{cases}$$



$$\text{rect}(t) = u(t + 1/2) - u(t - 1/2)$$

$A \text{rect}\left(\frac{t-t_0}{T}\right)$:



Supplementary Notes on Time-Invariance

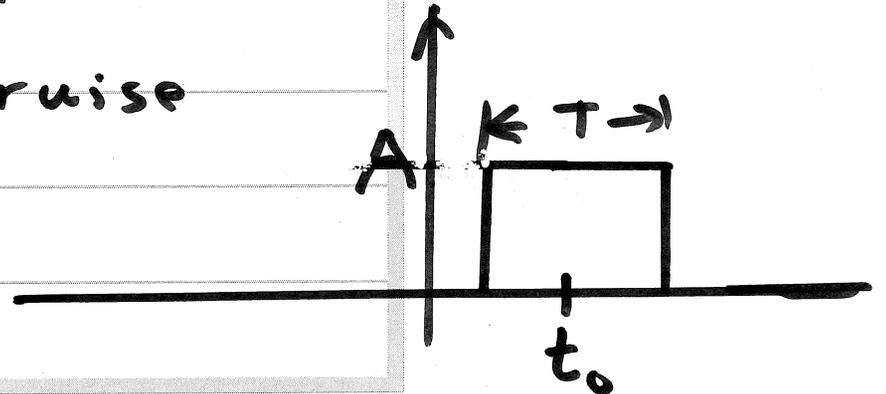
$$\text{rect}(t) = \begin{cases} 1, & -0.5 < t < 0.5 \\ 0, & \text{otherwise} \end{cases}$$

$$\text{rect}\left(\frac{t-t_0}{T}\right) = 1 \quad -\frac{1}{2} < \frac{t-t_0}{T} < \frac{1}{2}$$

multiply "both" sides by T : $-\frac{T}{2} < t-t_0 < \frac{T}{2}$

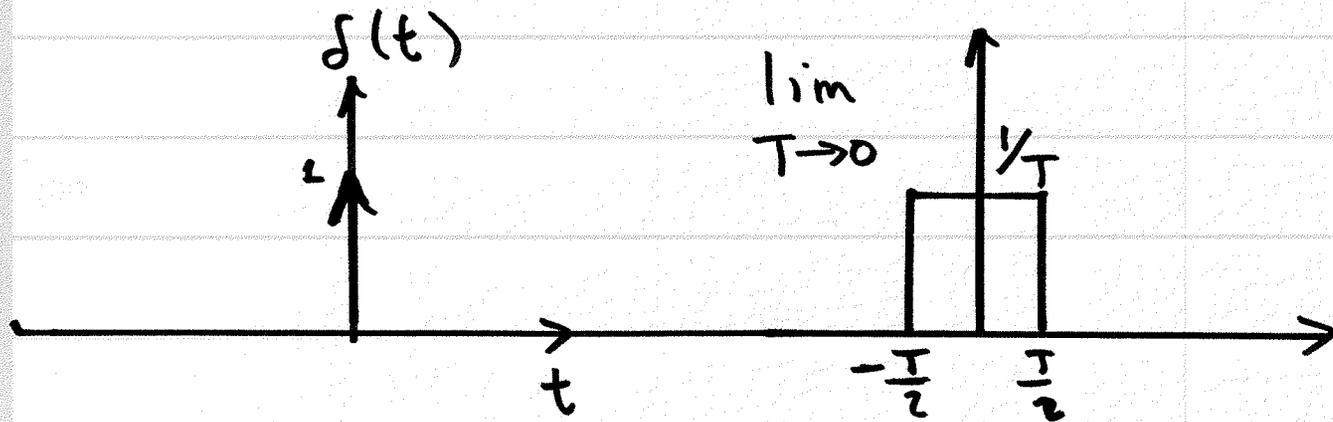
add t_0 to "both" sides: $t_0 - \frac{T}{2} < t < t_0 + \frac{T}{2}$

$$A \text{rect}\left(\frac{t-t_0}{T}\right) = \begin{cases} A, & t_0 - \frac{T}{2} < t < t_0 + \frac{T}{2} \\ 0, & \text{otherwise} \end{cases}$$



Dirac Delta Function

$$\delta(t) = \lim_{T \rightarrow 0} \frac{1}{T} \text{rect}\left(\frac{t}{T}\right)$$



Properties of $\delta(t)$:

$$\int_{-\infty}^{\infty} \delta(t) dt = 1 = \int_{0^-}^{0^+} \delta(t) dt$$

$$x(t) \delta(t - t_0) = x(t_0) \delta(t - t_0) \quad \left\{ \begin{array}{l} \text{sifting} \\ \text{property} \end{array} \right.$$

$$\delta(t) = \frac{d u(t)}{dt}$$

see Text book

Exponential Signals

$$x(t) = e^{-at} u(t)$$

- a : can be real-valued, complex-valued, or purely imaginary \Rightarrow last case corresponds to sinewave and considered on next page
- Consider a real-valued and positive
- Compute energy of $x(t)$:

$$\begin{aligned} E_x &= \int_{-\infty}^{\infty} x^2(t) dt = \int_{-\infty}^{\infty} e^{-2at} dt = \left. \frac{-1}{2a} e^{-2at} \right]_0^{\infty} \\ &= \frac{1}{2a} \left(\underbrace{e^{-\infty}}_{=0} - e^0 \right) = \frac{1}{2a} \end{aligned}$$

Other properties of $\delta(t)$ will be proved later

Sinewaves $x(t) = e^{j\omega_0 t} = \cos(\omega_0 t) + j \sin(\omega_0 t)$

$\omega_0 = 2\pi f_0$, f_0 is frequency in Hz (cycles per sec.)

period: $e^{j\omega_0(t+T)} = e^{j\omega_0 t} = e^{j\omega_0 t} e^{j2\pi}$

$$\omega_0 T = 2\pi \Rightarrow \omega_0 = \frac{2\pi}{T}$$

$$\Rightarrow f_0 = \frac{1}{T} \quad \text{or} \quad T = \frac{1}{f_0}$$

See textbook for plots

By Euler's Formula, we have:

$$\cos(\omega_0 t) = \frac{1}{2} e^{j\omega_0 t} + \frac{1}{2} e^{-j\omega_0 t}$$

$$\sin(\omega_0 t) = \frac{1}{2j} e^{j\omega_0 t} - \frac{1}{2j} e^{-j\omega_0 t}$$

The nice thing about complex sinewaves is that the phase factors out as part of a complex amplitude:

$$x(t) = A e^{j(\omega t + \theta)} = A e^{j\theta} e^{j\omega t}$$

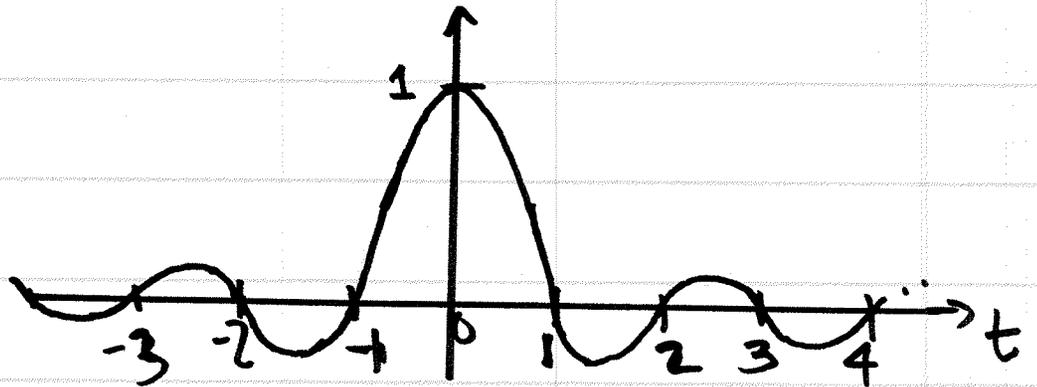
Of course, this is not true for a real-valued sinewave:

$$\begin{aligned} \cos(\omega t + \theta) &\neq \cos(\omega t) \cos(\theta) \\ &= \cos(\theta) \cos(\omega t) - \sin(\theta) \sin(\omega t) \end{aligned}$$

Hence, why you solved circuits the way you did in ECE 201

Sinc function : very important function in many different fields of engineering (physics)

$$\text{sinc}(t) = \frac{\sin(\pi t)}{\pi t}$$



Can use L'Hospital's Rule to find value at $t=0$

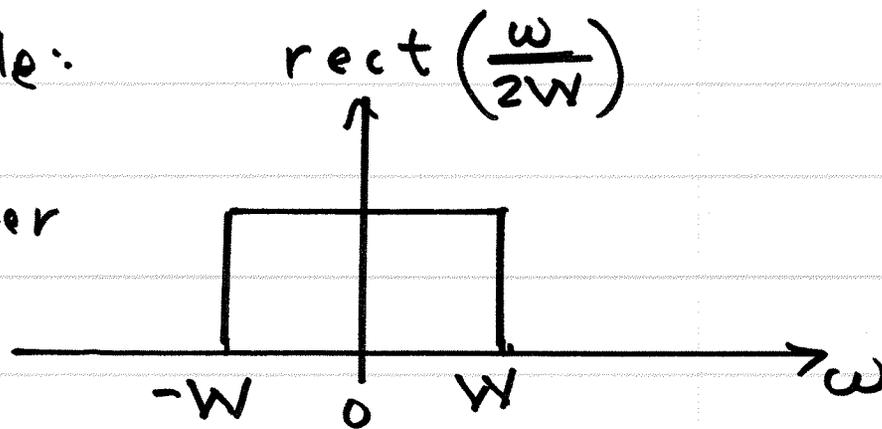
OR: approximate $\sin(x)$ for $x \ll 1$ with first term in Taylor series expansion: $\sin(x)$.

$$\sin(x) \approx x \quad \text{for } x \ll 1$$

$$\text{Thus: } \lim_{t \rightarrow 0} \frac{\sin(\pi t)}{\pi t} = \frac{\pi t}{\pi t} = 1$$

- For each of the previously defined functions the independent variable could be something other than time t .
- e.g., could be position $x \Rightarrow \text{sinc}(x)$
- later they will also be used as functions of frequency ω
- a very different interpretation when the independent variable is ω
- for example:

lowpass filter
frequency
response



Even and Odd Signals

10

- even: $x(-t) = x(t)$

- example:

$$x(t) = \cos(\omega_0 t)$$

} Symmetric

about

$t=0$

- odd-signal: $x(-t) = -x(t)$

- example:

$$x(t) = \sin(\omega_0 t)$$

} anti-symmetric

about

$t=0$

- can decompose arbitrary signal into even and odd parts: $x(t) = x_e(t) + x_o(t)$

$$x_e(t) = \text{Ev}\{x(t)\} = \frac{1}{2} \{x(t) + x(-t)\}$$

$$x_o(t) = \text{Od}\{x(t)\} = \frac{1}{2} \{x(t) - x(-t)\}$$