

Practical D/A Conversion

①

In practice: digitally increase sampling rate by integer amount just prior to DAC so that ZOH (interpolating fn is rectangle) or linear Interpolation (interpolating fn is a triangle) works well

Recall: assume $\omega_s = \frac{2\pi}{T_s} > 2\omega_M$

$$x_a(t) = \sum_{n=-\infty}^{\infty} x[nT_s] h_{LP}(t - nT_s)$$

$$h_{LP}(t) = \frac{\sin\left(\frac{\omega_s}{2}t\right)}{\omega_s/2} \quad \text{OR}$$

$$h_{LP}(t) = \frac{\sin\left(\frac{\omega_s}{2}t\right)}{\frac{\omega_s}{2}t} \frac{\sin\left(\left(\frac{\omega_s}{2} - \omega_M\right)t\right)}{\left(\frac{\omega_s}{2} - \omega_M\right)t}$$

Change dummy variable of summation and define $x[n] = x_a(nT_s)$ (2)

$$x_a(t) = \sum_{k=-\infty}^{\infty} x[k] h_{LP}(t - kT_s)$$

• Now, "sample" $x(t)$ at a rate

$$\omega_{s_{\text{new}}} = L \omega_s \Rightarrow \text{replace } t \text{ by } n \frac{T_s}{L}$$

• sample at L times original rate

$$\begin{aligned} y[n] &= x_a\left(n \frac{T_s}{L}\right) = \sum_{k=-\infty}^{\infty} x[k] h_{LP}\left(\frac{nT_s}{L} - kT_s\right) \\ &= \sum_{k=-\infty}^{\infty} x[k] h_{LP}\left((n - kL) \frac{T_s}{L}\right) \end{aligned}$$

where, for example: $\left(\omega_s = \frac{2\pi}{T_s}\right)$ (3)

$$h[n] = h_{LP}\left(n \frac{T_s}{L}\right) \Rightarrow \omega_s T_s = 2\pi$$
$$= \frac{\sin\left(\frac{\omega_s}{2} n \frac{T_s}{L}\right)}{\frac{\omega_s}{2} n \frac{T_s}{L}} = \frac{\sin\left(\frac{\pi}{L} n\right)}{\frac{\pi}{L} n}$$

Thus:

$$y[n] = x_a\left(n \frac{T_s}{L}\right) = \sum_{k=-\infty}^{\infty} x[k] \frac{\sin\left(\frac{\pi}{L}(n-kL)\right)}{\frac{\pi}{L}(n-kL)}$$

- Center a DT sinc function at every integer multiple of $L \Rightarrow$ at $n=kL$ scale by $x[k]$ ($= x_a(kT_s)$)

④

- This is something we can do in Matlab
- i.e., this is something we can do in software or digital hardware just prior to D/A conversion so that ZOH or linear Interpolation (linearly connect successive samples) works well
- Still may want to do preemphasis \Rightarrow Fig. 7.8 in Text
- One possible implementation:

note: $h[n-kL] = h[n] * \delta[n-kL]$

Thus:

$$y[n] = \left\{ \sum_{k=-\infty}^{\infty} x[k] \delta[n-kL] \right\} * h[n]$$

- This mimics the theoretical way to reconstruct the signal: See Fig. 7.4 (5)

$$x_a(t) = \left\{ \sum_{k=-\infty}^{\infty} x_a(kT_s) \delta(t - kT_s) \right\} * h_{LP}(t)$$

- Here, to increase sampling DIGITALLY in discrete-time prior to D/A conversion

$$y[n] = x_a\left(n\frac{T_s}{L}\right) = \left\{ \sum_{k=-\infty}^{\infty} x[k] \delta[n - kL] \right\} * h[n]$$

$$x[k] = x_a(kT_s) \quad h[n] = h_{LP}\left(n\frac{T_s}{L}\right)$$

and $\delta(t)$ is Dirac-Delta function

$\delta[n]$ is Kronecker Delta function

Ideal D/A :

$$x_a(t) = \sum_{n=-\infty}^{\infty} \underbrace{x_a(nT_s)}_{x[n]} \frac{\sin\left(\frac{\pi}{T_s}(t-nT_s)\right)}{\frac{\pi}{T_s}(t-nT_s)}$$

Digital Up-Sampling :

$$y[n] = x_a\left(n\frac{T_s}{L}\right) \quad \left(\text{replace summation } n \text{ variable above by } k\right)$$

$$= \sum_{k=-\infty}^{\infty} x[k] \frac{\sin\left(\frac{\pi}{T_s}\left(n\frac{T_s}{L} - kT_s\right)\right)}{\frac{\pi}{T_s}\left(n\frac{T_s}{L} - kT_s\right)}$$

$$= \sum_{k=-\infty}^{\infty} x[k] \frac{\sin\left(\frac{\pi}{L}(n - kL)\right)}{\frac{\pi}{L}(n - kL)}$$

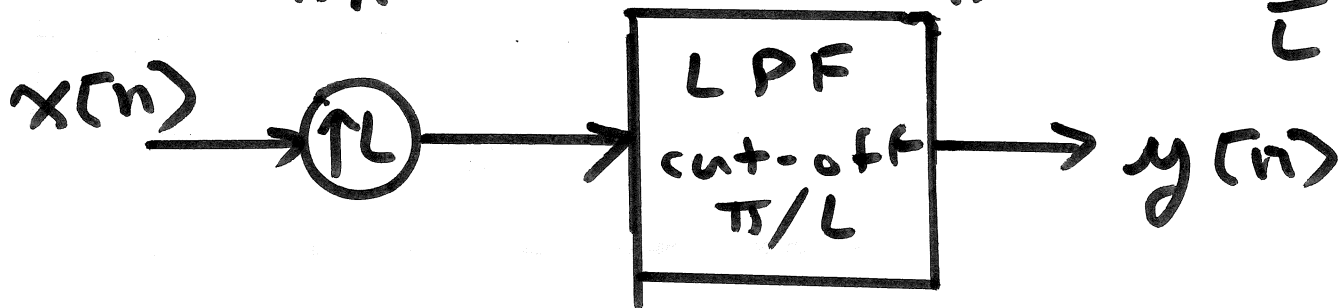
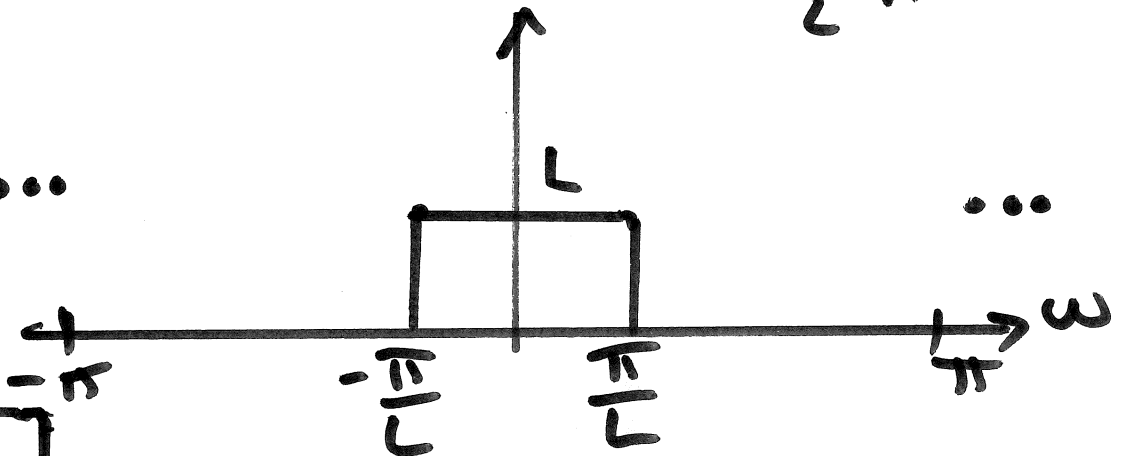
$$y[n] = \left\{ \sum_{k=-\infty}^{\infty} x[k] \delta[n-kL] \right\} * \frac{\sin\left(\frac{\pi}{L}n\right)}{\frac{\pi}{L}n}$$

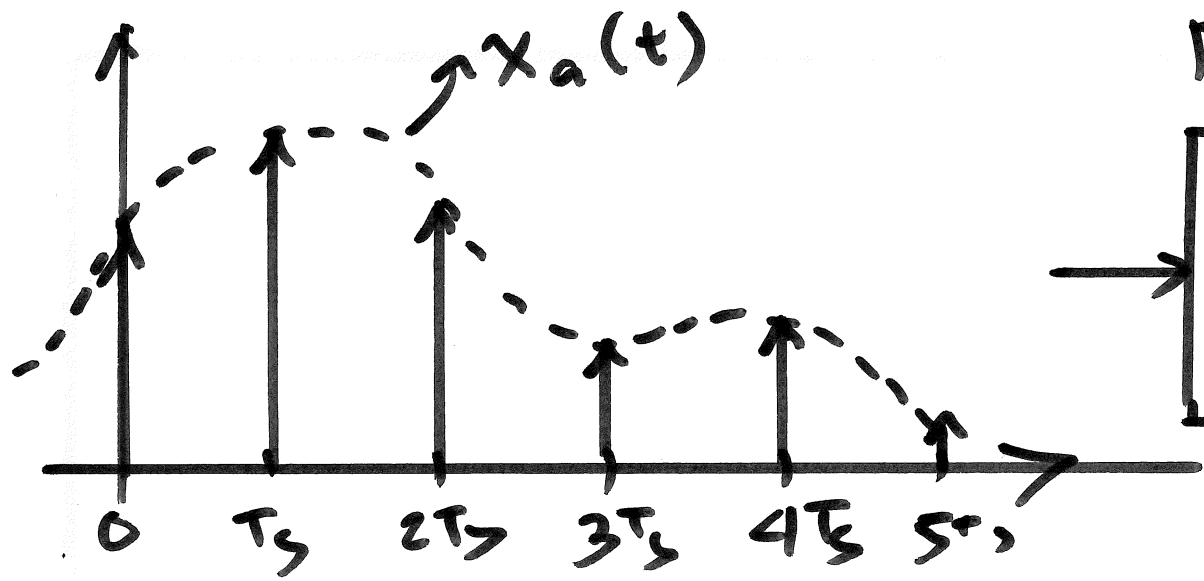
$$y[n] = x_a\left(n\frac{T_s}{L}\right) \quad x[n] = x_a(nT_s)$$

Since: $\frac{\sin\left(\frac{\pi}{L}(n-kL)\right)}{\frac{\pi}{L}(n-kL)} = \delta[n-kL] * \frac{\sin\left(\frac{\pi}{L}n\right)}{\frac{\pi}{L}n}$

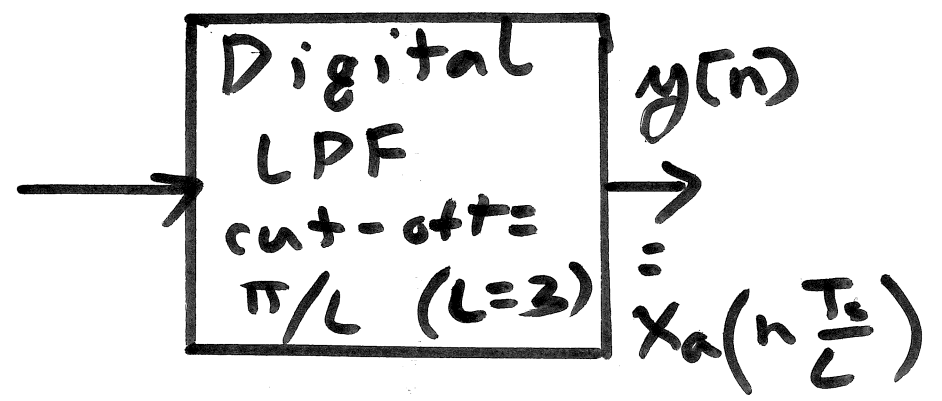
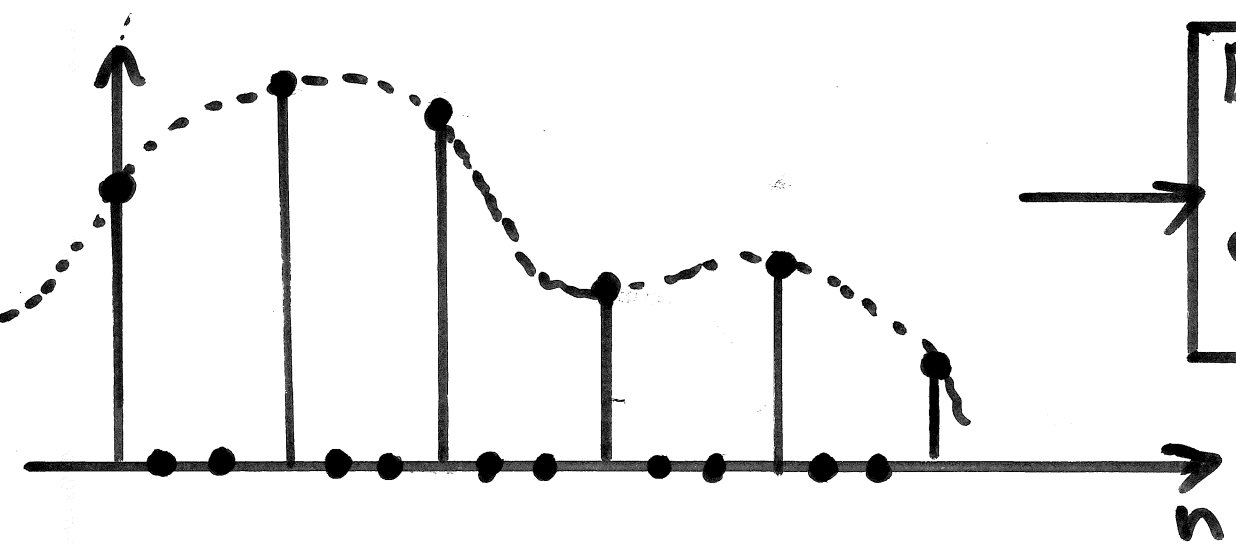
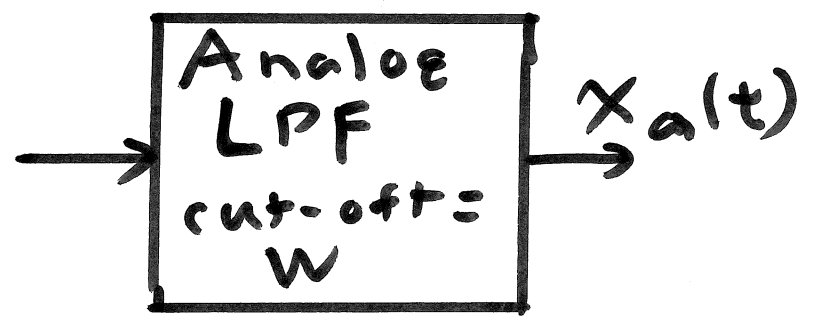
From Table 4.2

$$L \frac{\sin\left(\frac{\pi}{L}n\right)}{\frac{\pi}{L}n} \xleftrightarrow{\text{DTFT} \dots}$$

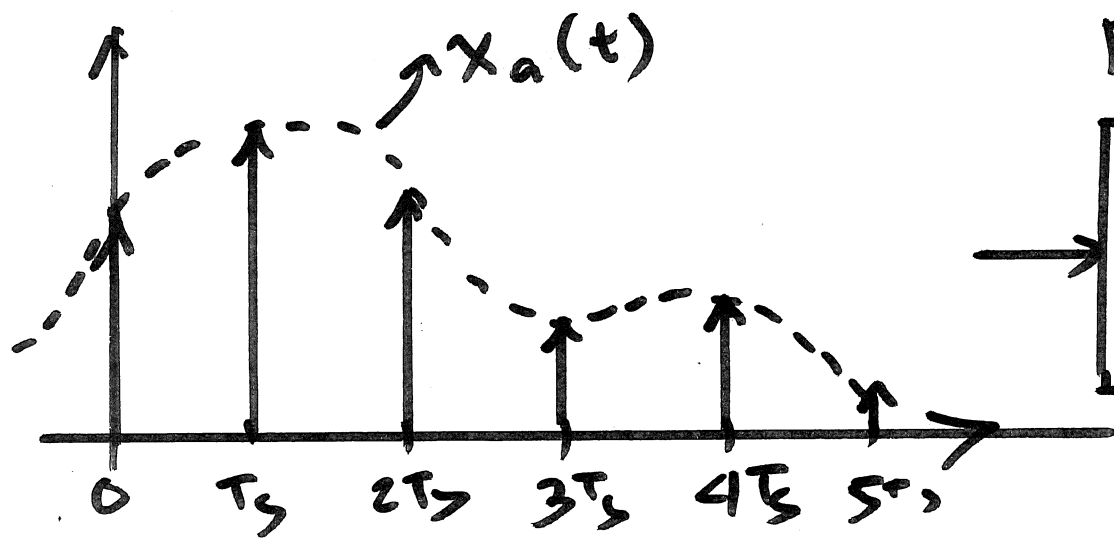




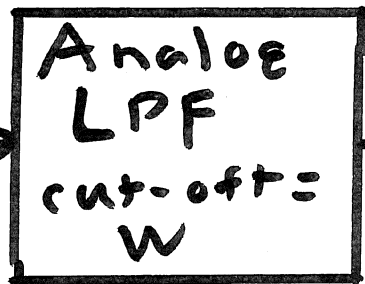
$$F_s > 2W$$



$L=3$
for picture

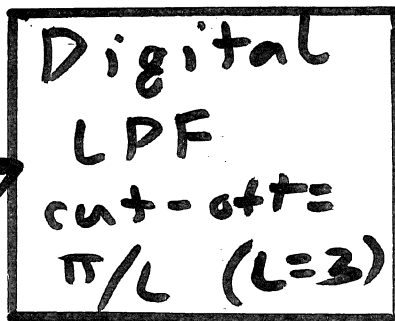
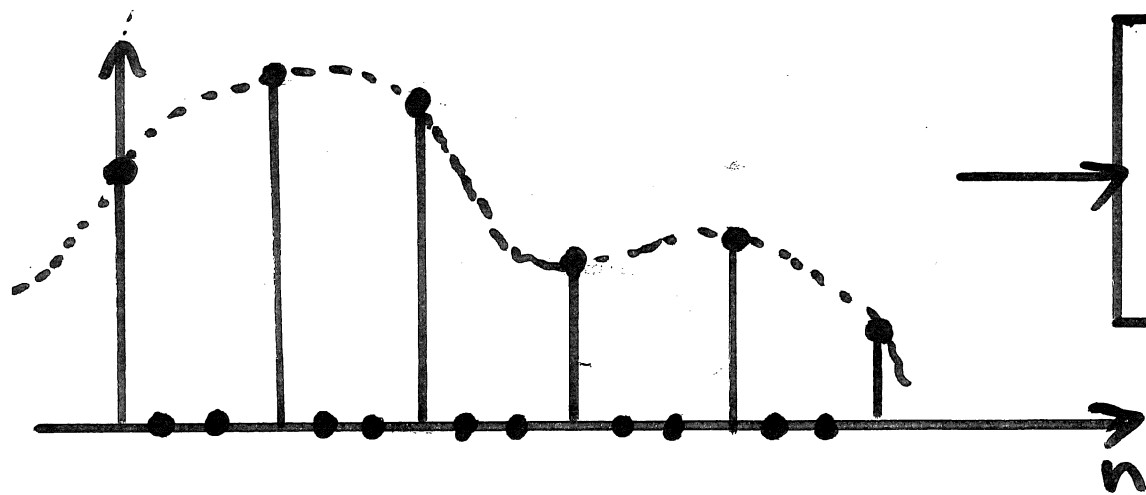


$$F_s > 2W$$



$x_a(t)$

$$h_{LP}(t) = \frac{\sin\left(\pi \frac{t}{T_s}\right)}{\pi \frac{t}{T_s}}$$



$y[n]$

$$x_a\left(n \frac{T_s}{L}\right)$$

$$L=3$$

for picture

$$h_{LP}[n] = \frac{\sin\left(\frac{\pi}{L} n\right)}{\frac{\pi}{L} n}$$

$$h_{LP}[n] = h_{LP}(t) \Big|_{t = n \frac{T_s}{L}}$$